More Approximation Algorithms

Lecture 23 April 29, 2021

Most slides are courtesy Prof. Chekuri

Formal definition of approximation algorithm

An algorithm ${\cal A}$ for an optimization problem ${\it X}$ is an ${\it \alpha}$ -approximation algorithm if the following conditions hold:

- for each instance I of X the algorithm $\mathcal A$ correctly outputs a valid solution to I
- ullet is a polynomial-time algorithm
- Letting OPT(I) and $\mathcal{A}(I)$ denote the values of an optimum solution and the solution output by \mathcal{A} on instances I, $OPT(I)/\mathcal{A}(I) \leq \alpha$ and $\mathcal{A}(I)/OPT(I) \leq \alpha$. Alternatively:
 - If $m{X}$ is a minimization problem: $m{\mathcal{A}(I)}/m{\mathit{OPT}(I)} \leq lpha$
 - If **X** is a maximization problem: $OPT(I)/\mathcal{A}(I) \leq \alpha$

Definition ensures that $\alpha \geq 1$

To be formal we need to say $\alpha(n)$ where n = |I| since in some cases the approximation ratio depends on the size of the instance.

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Approach: Lower Bound OPT

Part 1

Approximation for Load Balancing

Load Balancing

Given n jobs J_1, J_2, \ldots, J_n with sizes s_1, s_2, \ldots, s_n and m identical machines M_1, \ldots, M_m assign jobs to machines to minimize maximum load (also called makespan).

Problem sometimes referred to as multiprocessor scheduling. **Example: 3** machines and **8** jobs with sizes **4**, **3**, **1**, **2**, **5**, **6**, **9**, **7**.

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Formally, an assignment is a mapping $f: \{1, 2, ..., m\} \rightarrow \{1, ..., m\}$.

- The load $\ell_f(j)$ of machine M_j under f is $\sum_{i:f(i)=j} s_i$
- Goal is to find f to minimize $\max_{j} \ell_f(j)$.

Greedy List Scheduling

List-Scheduling

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Let J_1, J_2, \ldots, J_n be an ordering of jobs
for i=1 to n do
Schedule job J_i on the currently least loaded machine
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Different list: 9, 7, 6, 5, 4, 3, 2, 1

Two lower bounds on OPT

OPT is the optimum load

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• average load: $OPT \ge \sum_{i=1}^{n} s_i/m$. Why?

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Lower bounds on OPT:

- average load: $OPT \ge \sum_{i=1}^{n} s_i/m$. Why?
- maximum job size: $OPT \ge \max_{i=1}^n s_i$. Why?

Analysis of Greedy List Scheduling

Theorem

Let **L** be makespan of Greedy List Scheduling on a given instance. Then $L \leq (2-1/m)OPT$ where OPT is the optimum makespan for that instance.

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Let **L** be makespan of Greedy List Scheduling on a given instance. Then $\mathbf{L} \leq (2-1/m)OPT$ where OPT is the optimum makespan for that instance.

- Let M_h be the machine which achieves the load L for Greedy List Scheduling.
- Let J_i be the job that was last scheduled on M_h .
- Why was J_i scheduled on M_h ? It means that M_h was the least loaded machine when J_i was considered. Implies all machines had load at least $L s_i$ at that time.

Analysis continued

Lemma

$$L-s_i\leq (\textstyle\sum_{\ell=1}^{i-1}s_\ell)/m.$$

Proof.

Since all machines had load at least $L-s_i$ it means that $m(L-s_i) \leq \sum_{\ell=1}^{i-1} s_\ell$ and hence

$$L-s_i\leq (\sum_{\ell=1}^{i-1}s_\ell)/m.$$



Analysis continued

But then

$$L \leq \left(\sum_{\ell=1}^{i-1} s_{\ell}\right)/m + s_{i}$$

$$\leq \left(\sum_{\ell=1}^{n} s_{\ell}\right)/m + \left(1 - \frac{1}{m}\right)s_{i}$$

$$\leq$$

Analysis continued

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$$\leq \left(\sum_{\ell=1}^{n} s_{\ell}\right)/m + \left(1 - \frac{1}{m}\right)s_{i}$$

$$\leq OPT + \left(1 - \frac{1}{m}\right)OPT$$

$$= \left(2 - \frac{1}{m}\right)OPT$$

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- If the list has large job at end the Greedy will give makespan of m + m - 1 = 2m - 1.

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Obvious heuristic: Order jobs in decreasing size order and then use Greedy.

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Theorem

Greedy List Scheduling with jobs sorted from largest to smallest gives a 4/3-approximation and this is essentially tight.

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Need another lower bound

Lemma

Suppose jobs are sorted, that is $s_1 \ge s_2 \ge ... \ge s_n$ and n > m then $OPT \ge s_m + s_{m+1} \ge 2s_{m+1}$.

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 $OPT \ge \text{Load}$ on that machine $\ge \text{the sum of the smallest two job}$ sizes in the first m+1 jobs

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As before let M_j be the machine achieving the makespan L and let J_i be the last job assigned to M_j . we have

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 - Together, we have $L \leq OPT + s_i \leq 3OPT/2$.

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Since M_i had a job before s_i we have $i \geq (m+1)$. Why?

Since jobs are sorted by decreasing size, $s_i \leq s_{m+1}$. Since $2s_{m+1} \leq OPT$, we have $s_i \leq s_{m+1} \leq OPT/2$.

Part II

Approximation for Set Cover

Set Cover

Input: Universe \mathcal{U} of n elements and m subsets S_1, S_2, \ldots, S_m such that $\bigcup_i S_i = \mathcal{U}$.

Goal: Pick fewest number of subsets to cover all of \mathcal{U} (equivalently, whose union is \mathcal{U}).

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```
\begin{aligned} & \mathsf{Greedy}(\mathcal{U}, S_1, S_2, \dots, S_m) \\ & \mathsf{Uncovered} = \mathcal{U} \\ & \mathsf{While Uncovered} \neq \emptyset \ \mathsf{do} \\ & \mathsf{Pick set } S_j \ \mathsf{that covers max number of uncovered elements} \\ & \mathsf{Add } S_j \ \mathsf{to solution} \\ & \mathsf{Uncovered} = \mathsf{Uncovered} - S_j \\ & \mathsf{endWhile} \\ & \mathsf{Output chosen sets} \end{aligned}
```

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- Let k^* be minimum number of sets to cover \mathcal{U} . Let k be number of sets chosen by Greedy.
- Let α_i be # new elements covered in iteration i.
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There exists one of those sets that covers at least $|\mathcal{U}_i|/k^*$ elements. Greedy picks the best set and hence covers at least that many elements. Note $|\mathcal{U}_i| = \beta_{i-1}$.

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Hence by induction,

$$\beta_i \leq \beta_0 (1 - 1/k^*)^i = n(1 - 1/k^*)^i.$$

Thus, after $k = k^* \ln n$ iterations number of uncovered elements is at most

$$n(1-1/k^*)^{k^* \ln n} \le ne^{-\ln n} \le 1.$$

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Thus algorithm terminates in at most $k^* \ln n + 1$ iterations. Total number of sets chosen is number of iterations.

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Theorem

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- Can show a tighter bound of $(\ln d + 1)$ where d is maximum set size.

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- Can show a tighter bound of $(\ln d + 1)$ where d is maximum set size.

Theorem

Unless P = NP no $(\ln n + \epsilon)$ -approximation for Set Cover.

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A bad example for Greedy

$$n = 2(1+2+2^2+\cdots+2^p) = 2(2^{p+1}-1), m = 2+(p+1),$$

 $OPT = 2$, Greedy picks $(p+1)$ and hence ratio is $\Omega(\ln n)$.

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Advantage of Greedy

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Example. Covering all the edges of a graph using minimum number of disjoint trees.

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Max k-Cover

Input: Universe \mathcal{U} of n elements and m subsets S_1, S_2, \ldots, S_m and integer k.

Goal: Pick **k** subsets to *maximize* number of covered elements.

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Analysis

Similar to previous analysis.

- Let OPT be max number of covered elements through k subsets.
- Let α_i be number of new elements covered in iteration i.
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- Let $\beta_i = OPT \gamma_i$. Define $\beta_0 = OPT$.

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Proof: Exercise.

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Hence by induction,

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Thus, after k iterations,

$$\beta_k \leq OPT(1-1/k)^k \leq OPT/e$$
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Thus $\gamma_k = OPT - \beta_k \ge (1 - 1/e)OPT$.

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Theorem

Greedy gives a (1 - 1/e)-approximation for Max k-Coverage.

Above theorem generalizes to submodular function maximization and has *many* applications.

Theorem (Feige 1998)

Unless P = NP there is no $(1 - 1/e - \epsilon)$ -approximation for Max k-Coverage for any fixed $\epsilon > 0$.

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