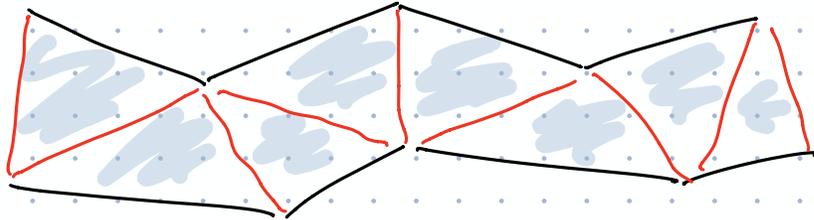


Old and new algorithms for cyclic dynamic programming

Sequence comparisons

- Edit distance
- Longest common subseq / Shortest common superseq
- Dynamic time warping
- Surface interpolation



$$OPT(i,j) = \min \left\{ \begin{array}{l} OPT(i+1, j) + \alpha(i, j) \\ OPT(i, j+1) + \beta(i, j) \\ OPT(i+1, j+1) + \gamma(i, j) \end{array} \right. \Rightarrow \underline{\underline{O(n^2)}}$$

Edit: $\alpha=1$ $\beta=1$ $\gamma(i, j) = [A[i] \neq B[j]]$

Surface: $\alpha = \text{area}(\Delta A[i], A[i+1], B[j])$ $\beta = \dots$
 $\gamma = \infty$

Cyclic sequences

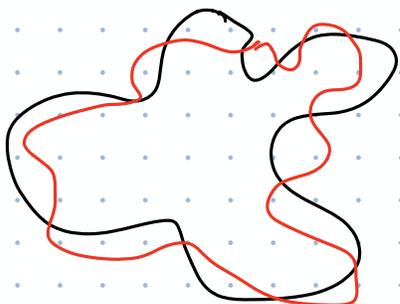
ABRACAPOCUS
DABRAHOCUSCA

$O(n^3)$ time immediate

For $s \leftarrow 1$ to n

compare A with $B[s]$

Shape alignment



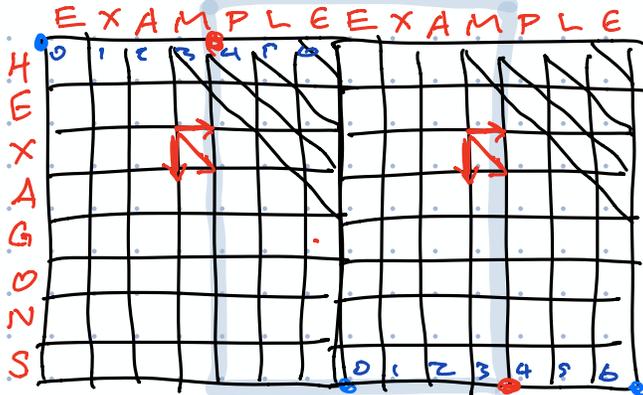
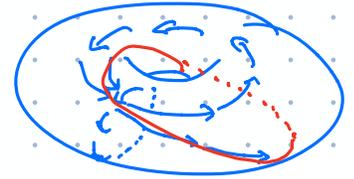
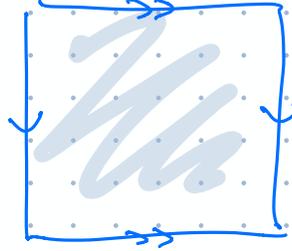
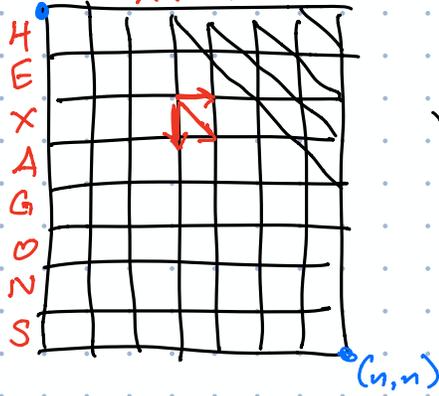
Circular RNA/DNA



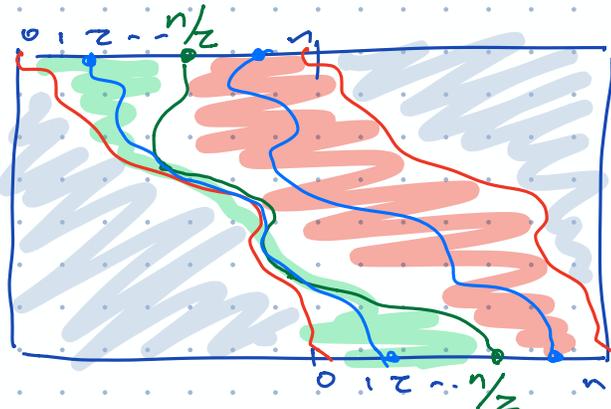
$\tilde{O}(n^2)$ time

Dynamic Programming = Shortest Path in DAG

(0,0) EXAMPLE



Shortest paths
from $(0, i)$ to $(n, n+i)$
for all i



Divide + conquer

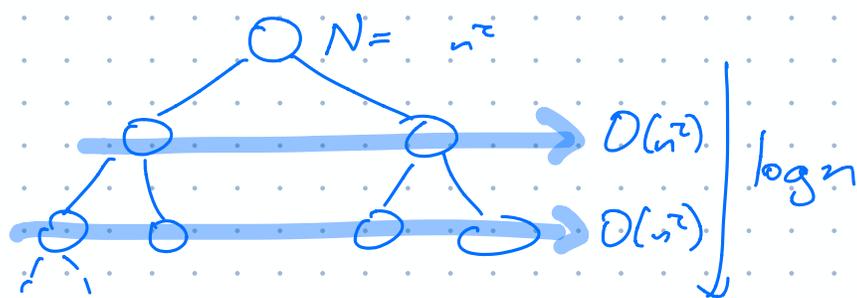
Fuchs Kedem Uselton 77
Maes 90
⋮

(WLOG) Shortest paths don't cross

Compute median path
split graph into $L + R$
recurse in L
recurse in R

$O(N)$
 $T(n/2)$ | depth
 $T(n/2)$ | $O(\log n)$

$O(n^2 \log n)$

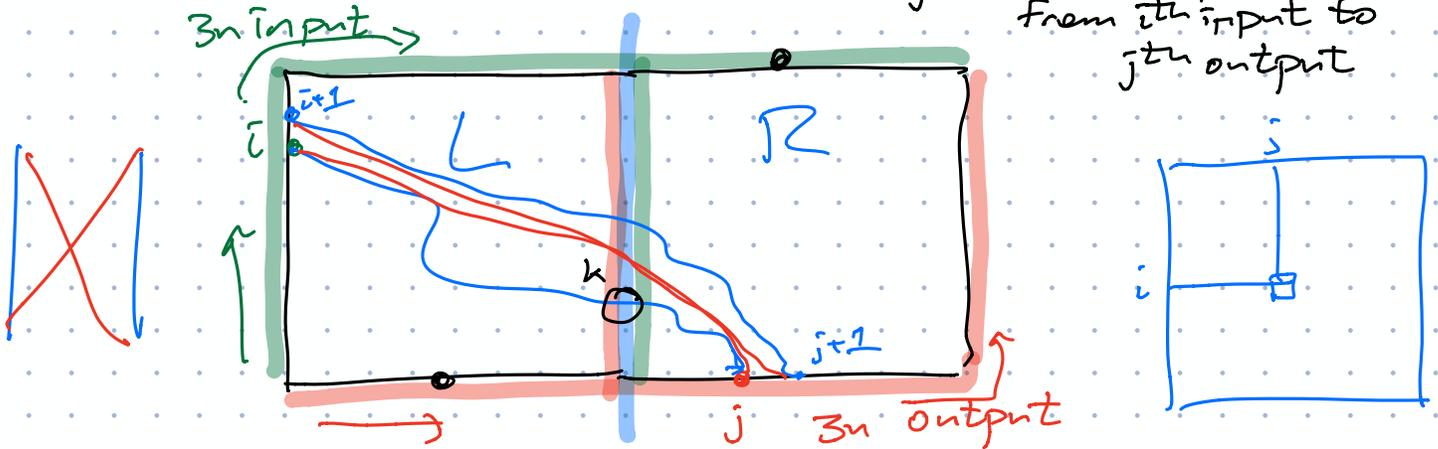


Divide + Conquer

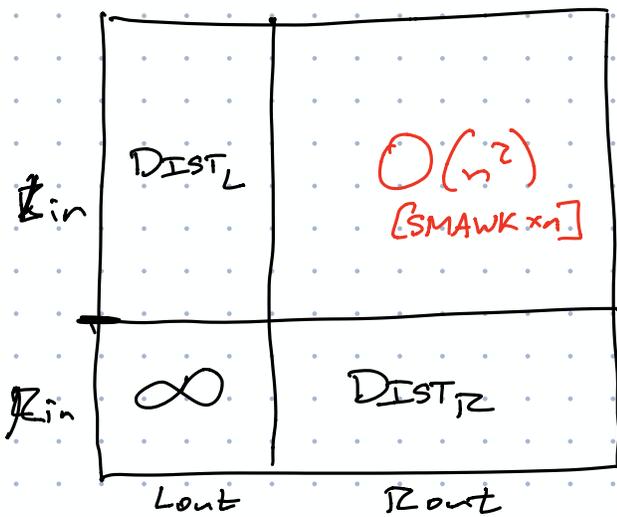
[Apostolico
Attalah
Larmore
McFadden '87]

DIST matrix

$DIST[i,j]$ = shortest path distance from i th input to j th output



Compute $DIST_L$ and $DIST_R$ recursively



$$DIST[i,j] = \min_k (DIST_L[i,k] + DIST_R[k,j])$$

Distance matrix multiplication

DIST is MONGE

$$M[i,j] + M[i+1,j+1] \leq M[i,j+1] + M[i+1,j]$$

SMAWK

\Rightarrow Monge dist mult in $O(n^2)$ time

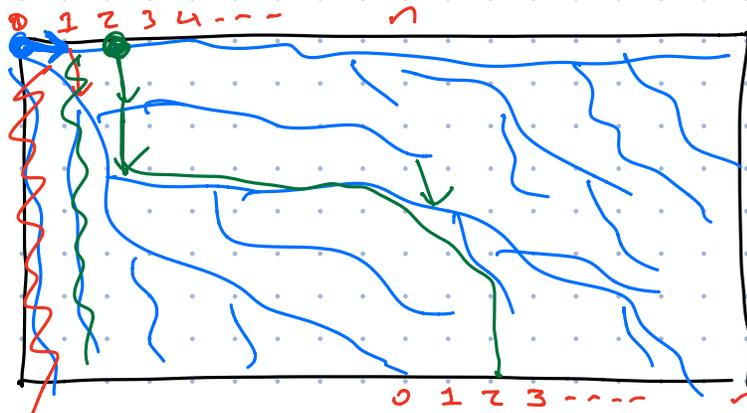
$$T(n, m) = 2T\left(\frac{n}{2}, m\right) + O(nm)$$

$$\Rightarrow O(n^2 \log n)$$

$$T(n) = 4T\left(\frac{n}{2}\right) + O(n^2)$$

Multiple-source shortest paths

[Landan Meyers Schmidt 98]



[Klein 05]
[Cabello Chambers E 08]

- ① compute shortest path tree rooted at 0
- ② drag root across ceiling keep the tree correct

Klein Total #changes = $O(n^2)$

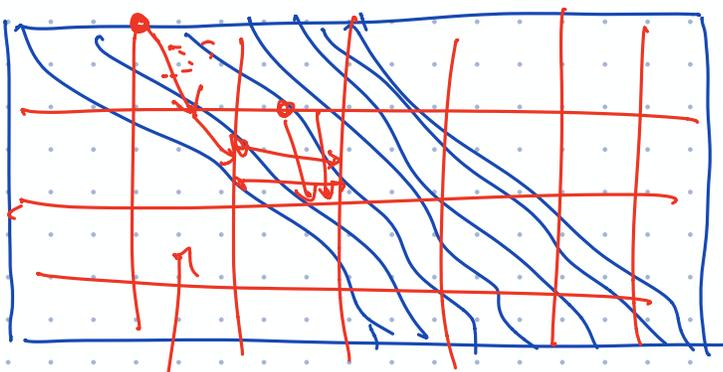
amortized analysis
↓
splay tree
↓
dynamic forest

Every edge enters $T \leq 1$ time
leave $T \leq 1$ time
Proof: Jordan curve thm

Klein $O(\log n)$ per change
[implicit representation]
 $O(\log n)$ query

$O(n^2 \log n)$ time ←

Lots of redundant computation →



"DIST" using MST →

[Italiano Nussbaum
→ Sankowski; Wulff-Nilsen 10]

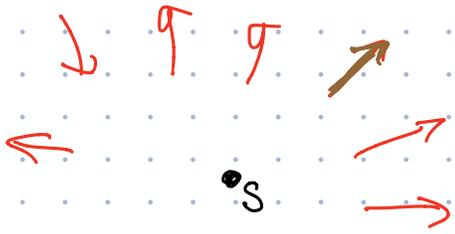
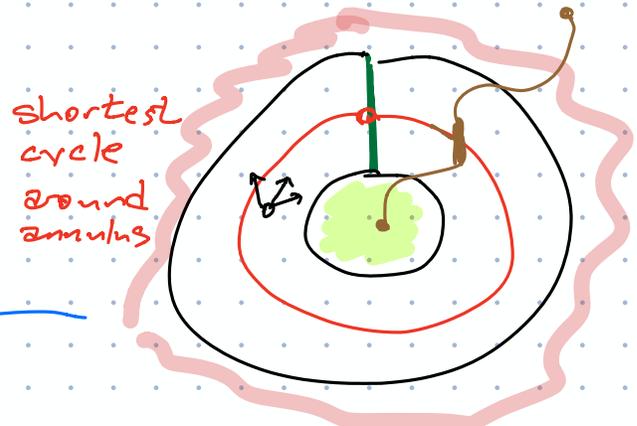
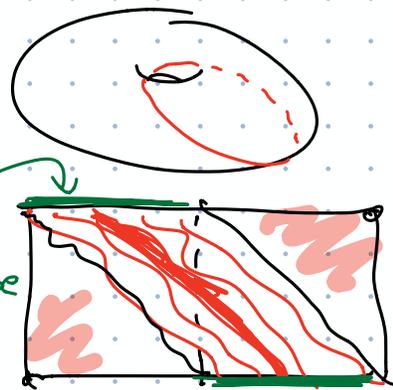
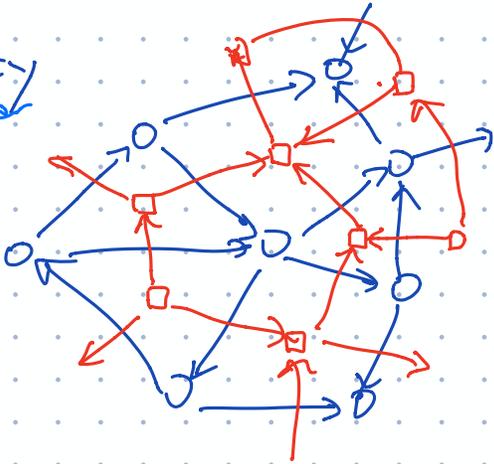
[Fakcharoenphol Rao 01]

$O(n \log \log n)$ time

↓
 $O(n^2)$

But it's really a flow problem

Duality for planar graphs



shortest cycle around annulus

Set of edges partition faces min total cost

Set of edges min total cost partition vertices

$\min(s, t)$ -cut

$\max(s, t)$ -flow

$O(n^2 \log n)$

Borradøile Klein '08
Erickson '10 - MSSP

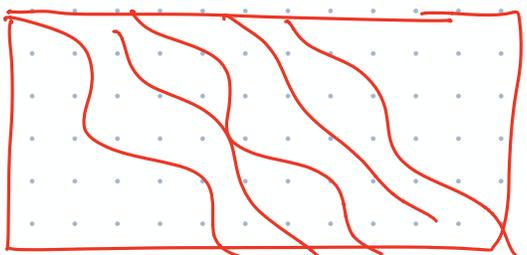
Edit distance

Edge wts all either 1 or 0

SCS

Edge wts all 1 ~~or 0~~

Unweighted \rightarrow directions don't matter!



Edge Disjoint path in undirected planar graph

\rightarrow Flow w/ all cap = 1 edge = disjoint paths

[Brandes Wagner 90]
[Eisenstat Klein 15]

$O(n^2)$

Simple

\rightarrow [Weihe 87] $\rightarrow O(n^2)$