## Chapter 17

## Network Flows

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### 17.0.0.1 Everything flows

Panta rei - everything flows (literally).
Heraclitus (535-475 BC)

### 17.1 Network Flows: Introduction and Setup

### 17.1.0.2 Transportation/Road Network


17.1.0.3 Internet Backbone Network
17.1.0.4 Common Features of Flow Networks
(A) Network represented by a (directed) graph $G=(V, E)$.
(B) Each edge $e$ has a capacity $c(e) \geq 0$ that limits amount of traffic on $e$.
(C) Source (s) of traffic/data.
(D) Sink(s) of traffic/data.
(E) Traffic flows from sources to sinks.

(F) Traffic is switched/interchanged at nodes.
(G) Flow abstract term to indicate stuff (traffic/data/etc) that flows from sources to sinks.

### 17.1.0.5 Single Source/Single Sink Flows

Simple setting:
(A) Single source $s$ and single sink $t$.
(B) Every other node $v$ is an internal node.
(C) Flow originates at $s$ and terminates at $t$.

(A) Each edge $e$ has a capacity $c(e) \geq 0$.
(B) Sometimes assume:

Source $s \in V$ has no incoming edges, and sink $t \in V$ has no outgoing edges.
(A) Assumptions: All capacities are integer, and every vertex has at least one edge incident to it.

### 17.1.0.6 Definition of Flow

(A) Two ways to define flows...
(B) edge based, or
(C) path based.
(D) Essentially equivalent but have different uses.
(E) Edge based definition is more compact.

### 17.1.0.7 Edge Based Definition of Flow

Definition 17.1.1. Flow in network $G=(V, E)$, is function $f: E \rightarrow \mathbb{R}^{\geq 0}$ s.t.

(A) Capacity Constraint: For each edge e, $f(e) \leq$ $c(e)$.
Conservation Constraint: For each vertex $v \neq s, t$.

$$
\sum_{e \text { into } v} f(e)=\sum_{e \text { out of } v} f(e)
$$

(C) Value of flow= (total flow out of source) (total flow in to source).

Figure 17.1: Flow with value.

### 17.1.0.8 Flow...

Conservation of flow law is also known as Kirchhoff's law.

### 17.1.0.9 More Definitions and Notation

Notation
(A) The inflow into a vertex $v$ is $f^{\text {in }}(v)=\sum_{e}$ into $v f(e)$ and the outflow is $f^{\text {out }}(v)=$ $\sum_{e}$ out of $v f(e)$
(B) For a set of vertices $A, f^{\text {in }}(A)=\sum_{e}$ into $A f(e)$. Outflow $f^{\text {out }}(A)$ is defined analogously

Definition 17.1.2. For a network $G=(V, E)$ with source $s$, the value of flow $f$ is defined as $v(f)=f^{\text {out }}(s)-f^{\text {in }}(s)$.

### 17.1.0.10 A Path Based Definition of Flow

Intuition: Flow goes from source $s$ to $\operatorname{sink} t$ along a path.
$\mathcal{P}$ : set of all paths from $s$ to $t$. $|\mathcal{P}|$ can be exponential in $n$.
Definition 17.1.3 (Flow by paths.). A flow in network $G=(V, E)$, is function $f: \mathcal{P} \rightarrow$ $\mathbb{R}^{\geq 0}$ s.t.
(A) Capacity Constraint: For each edge e, total flow on $e$ is $\leq c(e)$.

$$
\sum_{p \in \mathcal{P}: e \in p} f(p) \leq c(e)
$$

(B) Conservation Constraint: No need! Automatic.

Value of flow: $\sum_{p \in \mathcal{P}} f(p)$.

### 17.1.0.11 Example



$$
\begin{aligned}
& \mathcal{P}=\left\{p_{1}, p_{2}, p_{3}\right\} \\
& p_{1}: s \rightarrow u \rightarrow t \\
& p_{2}: s \rightarrow u \rightarrow v \rightarrow t \\
& p_{3}: s \rightarrow v \rightarrow t \\
& f\left(p_{1}\right)=10, f\left(p_{2}\right)=4, f\left(p_{3}\right)=6
\end{aligned}
$$



### 17.1.0.12 Path based flow implies edge based flow

Lemma 17.1.4. Given a path based flow $f: \mathcal{P} \rightarrow \mathbb{R}^{\geq 0}$ there is an edge based flow $f^{\prime}: E \rightarrow$ $\mathbb{R}^{\geq 0}$ of the same value.

Proof: For each edge $e$ define $f^{\prime}(e)=\sum_{p: e \in p} f(p)$.
Exercise: Verify capacity and conservation constraints for $f^{\prime}$.
Exercise: Verify that value of $f$ and $f^{\prime}$ are equal

### 17.1.0.13 Example



$$
\begin{aligned}
& \mathcal{P}=\left\{p_{1}, p_{2}, p_{3}\right\} \\
& p_{1}: s \rightarrow u \rightarrow t \\
& p_{2}: s \rightarrow u \rightarrow v \rightarrow t \\
& p_{3}: s \rightarrow v \rightarrow t \\
& f\left(p_{1}\right)=10, f\left(p_{2}\right)=4, f\left(p_{3}\right)=6 \\
& f^{\prime}(s \rightarrow u)=14 \\
& f^{\prime}(u \rightarrow v)=4 \\
& f^{\prime}(s \rightarrow v)=6 \\
& f^{\prime}(u \rightarrow t)=10 \\
& f^{\prime}(v \rightarrow t)=10
\end{aligned}
$$

### 17.1.1 Flow Decomposition

### 17.1.1. 1 Edge based flow to Path based Flow

Lemma 17.1.5. Given an edge based flow $f_{1}: E \rightarrow \mathbb{R} \geq 0$, there is a path based flow $f$ : $\mathcal{P} \rightarrow \mathbb{R}^{\geq 0}$ of same value. Moreover, $f$ assigns non-negative flow to at most $m$ paths where $|E|=m$ and $|V|=n$. Given $f_{1}$, the path based flow can be computed in $O(m n)$ time.

### 17.1.2 Flow Decomposition

### 17.1.2.1 Edge based flow to Path based Flow

Proof:[Proof Idea]
(A) Remove all edges with $f_{1}(e)=0$.
(B) Find a path $p$ from $s$ to $t$.
(C) Assign $f(p)$ to be $\min _{e \in p} f_{1}(e)$.
(D) Reduce $f_{1}(e)$ for all $e \in p$ by $f(p)$.
(E) Repeat until no path from $s$ to $t$.
(F) In each iteration at least on edge has flow reduced to zero.
(G) Hence, at most $m$ iterations. Can be implemented in $O(m(m+n))$ time. $O(m n)$ time requires care.

### 17.1.2.2 Example



### 17.1.2.3 Example




(1) (4)

(2) (5) $\xrightarrow[0 / 10]{ }$
(1) (4)


### 17.1.3 Path flow decomposition

17.1.3.1 Do not have to be efficient...


### 17.1.3.2 Edge vs Path based Definitions of Flow

(A) Edge based flows:
(A) compact representation, only $m$ values to be specified, and
(B) need to check flow conservation explicitly at each internal node.
(B) Path flows:
(A) in some applications, paths more natural,
(B) not compact,
(C) no need to check flow conservation constraints.
(C) Equivalence shows that we can go back and forth easily.

### 17.1.3.3 The Maximum-Flow Problem

(A) The network flow problem: Problem

Input A network $G$ with capacity $c$ and source $s$ and $\operatorname{sink} t$.
Goal Find flow of maximum value.
(B) Question: Given a flow network, what is an upper bound on the maximum flow between source and sink?

### 17.1.3.4 Cuts

Definition 17.1.6 (s-t cut). Given a flow network an s-t cut is a set of edges $E^{\prime} \subset E$ such that removing $E^{\prime}$ disconnects $s$ from $t$ : in other words there is no directed $s \rightarrow t$ path in $E-E^{\prime}$.

The capacity of a cut $E^{\prime}$ is $c\left(E^{\prime}\right)=\sum_{e \in E^{\prime}} c(e)$.


## Caution:

(A) Cut may leave $t \rightarrow s$ paths!
(B) There might be many $s$ - $t$ cuts.

### 17.1.4 $s-t$ cuts

17.1.4.1 A death by a thousand cuts


### 17.1.4.2 Minimal Cut

Definition 17.1.7 (Minimal $\boldsymbol{s}$ - $\boldsymbol{t}$ cut.). Given a s-t flow network $G=(V, E), E \subseteq E$ is a minimal cut if for all $e \in E$, if $E \backslash\{e\}$ is not a cut.

Observation: given a cut $E^{\prime}$, can check efficiently whether $E^{\prime}$ is a minimal cut or not. How?


### 17.1.4.3 Cuts as Vertex Partitions

(A) Let $A \subset V$ such that
(A) $s \in A, t \notin A$, and
(B) $B=V \backslash A$ (hence $t \in B$ ).
(B) The cut $(A, B)$ is the set of edges $(A, B)=$ $\{(u, v) \in E \mid u \in A, v \in B\}$.
Cut $(A, B)$ is set of edges leaving $A$.


Claim 17.1.8. $(A, B)$ is an s-t cut.
Proof: Let $P$ be any $s \rightarrow t$ path in $G$. Since $t$ is not in $A, P$ has to leave $A$ via some edge $(u, v)$ in $(A, B)$.

### 17.1.4.4 Cuts as Vertex Partitions

Lemma 17.1.9. Suppose $E^{\prime}$ is an $s$ - $t$ cut. Then there is a cut $(A, B)$ such that $(A, B) \subseteq E^{\prime}$.
Proof: $E^{\prime}$ is an $s$ - $t$ cut implies no path from $s$ to $t$ in $\left(V, E-E^{\prime}\right)$.
(A) Let $A$ be set of all nodes reachable by $s$ in $\left(V, E-E^{\prime}\right)$.
(B) Since $E^{\prime}$ is a cut, $t \notin A$.
(C) $(A, B) \subseteq E^{\prime}$. Why?If some edge $(u, v) \in(A, B)$ is not in $E^{\prime}$ then $v$ will be reachable by $s$ and should be in $A$, hence a contradiction.

Corollary 17.1.10. Every minimal $s$-t cut $E^{\prime}$ is a cut of the form $(A, B)$.

### 17.1.4.5 Minimum Cut

Definition 17.1.11. Given a flow network an $s$ - $t$ minimum cut is a cut $E^{\prime}$ of smallest capacity among all s-t cuts.

Observation: exponential number of $s$ - $t$ cuts and no "easy" algorithm to find a minimum cut.

### 17.1.4.6 The Minimum-Cut Problem

Problem
Input A flow network $G$
Goal Find the capacity of a minimum $s-t$ cut

### 17.1.4.7 Flows and Cuts

Lemma 17.1.12. For any $s$ - $t$ cut $E^{\prime}$, maximum $s$ - $t$ flow $\leq$ capacity of $E^{\prime}$.
Proof:
(A) Formal proof easier with path based definition of flow.
(B) Suppose $f: \mathcal{P} \rightarrow \mathbb{R}^{\geq 0}$ is a max-flow.
(C) Every path $p \in \mathcal{P}$ contains an edge $e \in E^{\prime}$. Why?
(D) Assign each path $p \in \mathcal{P}$ to exactly one edge $e \in E^{\prime}$.
(E) Let $\mathcal{P}_{e}$ be paths assigned to $e \in E^{\prime}$. Then

$$
v(f)=\sum_{p \in \mathcal{P}} f(p)=\sum_{e \in E^{\prime}} \sum_{p \in \mathcal{P}_{e}} f(p) \leq \sum_{e \in E^{\prime}} c(e) .
$$

### 17.1.4.8 Flows and Cuts

Lemma 17.1.13. For any $s-t$ cut $E^{\prime}$, maximum $s$-t flow $\leq$ capacity of $E^{\prime}$.
Corollary 17.1.14. Maximum s-t flow $\leq$ minimum s-t cut.

### 17.1.4.9 Max-Flow Min-Cut Theorem

Theorem 17.1.15. In any flow network:
(value of maximum s-t flow $)=($ capacity of minimum s-t cut $)$.
(A) Can compute minimum-cut from maximum flow and vice-versa!
(B) Proof coming shortly.
(C) Many applications:
(A) optimization
(B) graph theory
(C) combinatorics

### 17.1.4.10 The Maximum-Flow Problem

Problem
Input A network $G$ with capacity $c$ and source $s$ and $\operatorname{sink} t$.
Goal Find flow of maximum value from $s$ to $t$.
Exercise: Given $G, s, t$ as above, show that one can remove all edges into $s$ and all edges out of $t$ without affecting the flow value between $s$ and $t$.

## Bibliography

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