OLD CS 473: Fundamental Algorithms, Spring 2015

Recurrences, Closest Pair and **Selection**

Lecture 7 February 10, 2015

Part I

Recurrences

Solving Recurrences

Two general methods:

- Recursion tree method: need to do sums
 - elementary methods, geometric series
 - integration
- Quess and Verify
 - 1 guessing involves intuition, experience and trial & error
 - verification is via induction

Recurrence: Example I

- ① Consider $T(n) = 2T(n/2) + n/\lg n$.
- 2 Construct recursion tree, and observe pattern.
- ith level has $n_i = 2^i$ nodes.
- oproblem size at node of level i is $n/2^i$.
- **1** work at node of level i is $w_i = \frac{n}{2i} / \lg \frac{n}{2i}$.
- **1** Total work at *i*th level is $n_i \cdot w_i = 2^i \cdot \frac{n}{2^i} / \lg \frac{n}{2^i} = n / \lg \frac{n}{2^i}$
- O Summing over all levels $T(n) = \sum_{i=0}^{\lg n-1} n_i \cdot w_i = \sum_{j=0}^{\lg n-1} \frac{n}{\lg \frac{n}{2^j}}$

$$n \sum_{i=0}^{\lg n-1} \frac{1}{\lg n - i} = n \sum_{j=1}^{\lg n} \frac{1}{j} = n H_{\lg n} = \Theta(n \log \log n)$$

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Recurrence: Example II

- Consider...
- What is the depth of recursion?

$$\sqrt{n}, \sqrt{\sqrt{n}}, \sqrt{\sqrt{\sqrt{n}}}, \ldots, O(1).$$

- 3 Number of levels: $n^{2^{-L}} = 2$ means $L = \log \log n$.
- Number of children at each level is 1, work at each node is 1
- $\bullet \text{ Thus, } T(n) = \sum_{i=0}^{L} 1 = \Theta(L) = \Theta(\log \log n).$

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Recurrence: Example IV

- ① Consider T(n) = T(n/4) + T(3n/4) + n.
- ② Using recursion tree, we observe the tree has leaves at different levels (a *lop-sided* tree).
- **3** Total work in any level is at most n. Total work in any level without leaves is exactly n.
- lacktriangledown Highest leaf is at level $\log_4 n$ and lowest leaf is at level $\log_{4/3} n$
- Thus, $n \log_4 n \le T(n) \le n \log_{4/3} n$, which means $T(n) = \Theta(n \log n)$

Recurrence: Example III

- ① Consider $T(n) = \sqrt{n}T(\sqrt{n}) + n$.
- ② Using recursion trees: number of levels $L = \log \log n$
- **3** Work at each level? Root is n, next level is $\sqrt{n} \times \sqrt{n} = n$, so on. Can check that each level is n.

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Part II

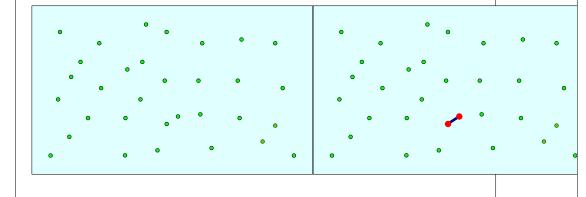
Closest Pair

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Closest Pair - the problem

Input Given a set S of n points on the plane Goal Find $p, q \in S$ such that d(p, q) is minimum



Applications

- Basic primitive used in graphics, vision, molecular modelling
- 2 Ideas used in solving nearest neighbor, Voronoi diagrams, Euclidean MST

Algorithm: Brute Force

- Compute distance between every pair of points and find minimum.
- ② Takes $O(n^2)$ time.
- Can we do better?

Closest Pair: 1-d case

Input Given a set S of n points on a line Goal Find $p, q \in S$ such that d(p, q) is minimum

Algorithm

- Sort points based on coordinate
- 2 Compute the distance between successive points, keeping track of the closest pair.

Running time $O(n \log n)$

- Can we do this in better running time?
- 2 Can reduce Distinct Elements Problem (see lecture 1) to this problem in O(n) time. Do you see how?

Generalizing 1-d case

- Can we generalize **1**-d algorithm to **2**-d?
- 2 Sort according to x or y-coordinate??
- No easy generalization.

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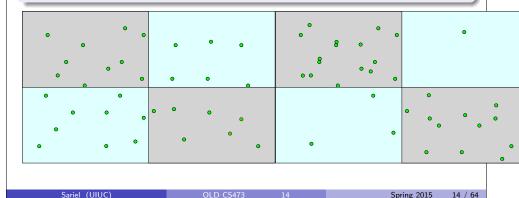
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First Attempt

Divide and Conquer I

- Partition into 4 quadrants of roughly equal size.
- Find closest pair in each quadrant recursively.
- Combine solutions.
- But... How to partition the points in a balanced way?

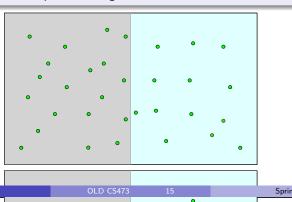


New Algorithm

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Divide and Conquer II

- 1 Divide the set of points into two equal parts via vertical line.
- 2 Find closest pair in each half recursively.
- 3 Find closest pair with one point in each half
- Return the best pair among the above 3 solutions



New Algorithm

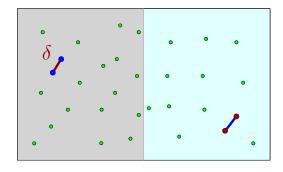
Divide and Conquer II

- Divide the set of points into two equal parts via vertical line
- Find closest pair in each half recursively
- Find closest pair with one point in each half
- Return the best pair among the above 3 solutions
- Sort points based on x-coordinate and pick the median. Time $= O(n \log n)$
- e How to find closest pair with points in different halves? $O(n^2)$ is trivial. Better?

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Combining Partial Solutions

- Does it take $O(n^2)$ to combine solutions?
- 2 Let δ be the distance between closest pairs, where both points belong to the same half.



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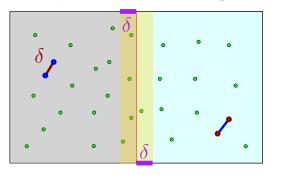
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Combining Partial Solutions

- Let δ be the distance between closest pairs, where both points belong to the same half.
- ② Need to consider points within δ of dividing line



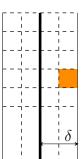
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Sparsity of Band



Divide the band into square boxes of size $\delta/2$

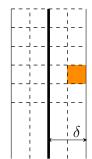
Lemma

Each box has at most one point

Proof.

If not, then there are a pair of points (both belonging to one half) that are at most $\sqrt{2}\delta/2 < \delta$ apart!

Searching within the Band



Lemma

Suppose a, b are both in the band $d(a,b) < \delta$ then a, b have at most two rows of boxes between them.

Proof.

Each row of boxes has height $\delta/2$. If more than two rows then $d(a,b) > 2 \cdot \delta/2$!

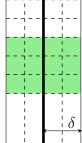
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Searching within the Band

Corollary

Order points according to their y-coordinate. If p, q are such that $d(p,q) < \delta$ then p and q are within 11 positions in the sorted list.



Proof.

- 0 < 2 points between them if p and q in same row.
- consecutive rows.
- \bigcirc \Longrightarrow More than ten points between them in the sorted y order than p and q are more than two rows apart.

The Algorithm

ClosestPair(P):

- 1. Find vertical line L splits P into equal halves: P_1 and P_2
- 2. $\delta_1 \leftarrow \mathsf{ClosestPair}(P_1)$.
- 3. $\delta_2 \leftarrow \mathsf{ClosestPair}(P_2)$.
- 4. $\delta = \min(\delta_1, \delta_2)$
- 5. Delete points from $m{P}$ further than $m{\delta}$ from $m{L}$
- 6. Sort P based on y-coordinate into an array A
- 7. **for** i = 1 to |A| 1 **do**

for i = i + 1 to min $\{i + 11, |A|\}$ do if $(dist(A[i], A[i]) < \delta)$ update δ and closest pair

- Step 1, involves sorting and scanning. Takes $O(n \log n)$ time.
- ② Step 5 takes O(n) time.
- 3 Step 6 takes $O(n \log n)$ time
- \bigcirc Step 7 takes O(n) time.

Running Time

The running time of the algorithm is given by

$$T(n) \leq 2T(n/2) + O(n\log n)$$

Thus, $T(n) = O(n \log^2 n)$.

Improved Algorithm

Avoid repeated sorting of points in band: two options

- Sort all points by y-coordinate and store the list. In conquer step use this to avoid sorting
- 2 Each recursive call returns a list of points sorted by their y-coordinates. Merge in conquer step in linear time.

Analysis: $T(n) < 2T(n/2) + O(n) = O(n \log n)$

Part III

Selecting in Unsorted Lists

Quick Sort

Quick Sort [Hoare]

- Pick a pivot element from array
- 2 Split array into 3 subarrays: those smaller than pivot, those larger than pivot, and the pivot itself. Linear scan of array does it. Time is O(n)
- 3 Recursively sort the subarrays, and concatenate them.

Example:

- **1** array: 16, 12, 14, 20, 5, 3, 18, 19, 1
- **2** pivot: 16
- 3 split into 12, 14, 5, 3, 1 and 20, 19, 18 and recursively sort
- oput them together with pivot in middle

Problem - Selection

Input Unsorted array **A** of **n** integers

Goal Find the *i*th smallest number in *A* (*rank i* number)

Example

 $A = \{4, 6, 2, 1, 5, 8, 7\}$ and j = 4. The jth smallest element is 5.

Median: i = |(n+1)/2|

Time Analysis

- \bigcirc Let k be the rank of the chosen pivot. Then, T(n) = T(k-1) + T(n-k) + O(n)
- ② If $k = \lceil n/2 \rceil$ then T(n) = $T(\lceil n/2 \rceil - 1) + T(\lfloor n/2 \rfloor) + O(n) \leq 2T(n/2) + O(n).$ Then, $T(n) = O(n \log n)$.
 - 1 Theoretically, median can be found in linear time.
- 3 Typically, pivot is the first or last element of array. Then,

$$T(n) = \max_{1 \le k \le n} (T(k-1) + T(n-k) + O(n))$$

In the worst case T(n) = T(n-1) + O(n), which means $T(n) = O(n^2)$. Happens if array is already sorted and pivot is always first element.

Algorithm I

- Sort the elements in A
- 2 Pick *i*th element in sorted order

Time taken = $O(n \log n)$

Do we need to sort? Is there an O(n) time algorithm?

Algorithm II

If j is small or n-j is small then

- Find j smallest/largest elements in A in O(jn) time. (How?)
- 2 Time to find median is $O(n^2)$.

Divide and Conquer Approach

- Pick a pivot element a from A
- Partition A based on a. $A_{\text{less}} = \{x \in A \mid x < a\} \text{ and } A_{\text{greater}} = \{x \in A \mid x > a\}$
- $|A_{less}| = j$: return a
- $|A_{less}| > j$: recursively find jth smallest element in A_{less}
- $|A_{less}| < j$: recursively find kth smallest element in $A_{greater}$ where $k = i - |A_{less}|$.

Time Analysis

- Steps:
 - 1 Partitioning step: O(n) time to scan A
 - 2 How do we choose pivot? Recursive running time?
- ② Suppose we always choose pivot to be A[1].
- 3 Say **A** is sorted in increasing order and j = n.
- **Solution** Exercise: show that algorithm takes $\Omega(n^2)$ time.

A Better Pivot

- Suppose: pivot ℓ th smallest element where $n/4 < \ell < 3n/4$.
- 2 That is pivot is approximately in the middle of **A**.
- If we apply recursion,

$$T(n) \leq T(3n/4) + O(n)$$

Implies T(n) = O(n)!

- Mow do we find such a pivot?
- Randomly? This works! Analysis a little bit later.
- Can we choose pivot deterministically?

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Divide and Conquer Approach

Idea

- **1** Break input **A** into many subarrays: $L_1, \ldots L_k$.
- 2 Find median m_i in each subarray L_i .
- 3 Find the median x of the medians m_1, \ldots, m_k .
- 1 Intuition: The median x should be close to being a good median of all the numbers in **A**.
- **1** Use x as pivot in previous algorithm.

But we have to be...

More specific...

- Size of each group?
- A How to find median of medians?

Algorithm for Selection

```
select(A, i):
Form lists L_1, L_2, ..., L_{\lceil n/5 \rceil}, where L_i = \{A[5i-4], ..., A[5i]\}
Find median b_i of each L_i using brute-force
Find median b of B = \{b_1, b_2, \ldots, b_{\lceil n/5 \rceil}\}
Partition \boldsymbol{A} into \boldsymbol{A}_{less} and \boldsymbol{A}_{greater} using \boldsymbol{b} as pivot
if (|A_{less}|) = j return b
else if (|A_{less}| > j)
       return select (A_{less}, j)
 else
      return select (A_{greater}, j - |A_{less}|)
```

How do we find median of **B**? Recursively!

Choosing the pivot

1 Partition array **A** into $\lceil n/5 \rceil$ lists of **5** items each.

$$L_{1} = \left\{ A[1], A[2], \dots, A[5] \right\}, L_{2} = \left\{ A[6], \dots, A[10] \right\}, \dots, L_{i} = \left\{ A[5i+1], \dots, A[5i-4] \right\}, \dots, L_{\lceil n/5 \rceil} = \left\{ A[5\lceil n/5 \rceil - 4, \dots, A[n] \right\}.$$

- 2 For $i = 1, \dots, n/5$: compute median b_i of L_i
 - ...using brute-force in O(1) time. Total O(n) time
- Let $B = \{b_1, b_2, \dots, b_{\lceil n/5 \rceil}\}$
- Find median b of B

Lemma

Median of B is an approximate median of A. That is, if b is used a pivot to partition A, then $|A_{less}| < 7n/10 + 6$ and $|A_{greater}| < 7n/10 + 6$.

Running time of deterministic median selection

$$T(n) = T(\lceil n/5 \rceil) + \max\{T(|A_{less}|), T(|A_{greater})\} + O(n)$$

From Lemma.

$$T(n) \leq T(\lceil n/5 \rceil) + T(\lfloor 7n/10 + 6 \rfloor) + O(n)$$

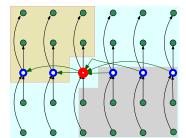
and

$$T(1) = 1$$

Exercise: show that T(n) = O(n)

Median of Medians: The movie

Median of Medians: Proof of Lemma



Proof.

Proposition

medians **b**.

Figure: Shaded elements are all greater than \boldsymbol{b}

At least half of the $\lceil n/5 \rceil$ groups have at least 3 elements larger than \boldsymbol{b} , except for last group and the Figure: Shaded elements are all group containing \boldsymbol{b} . So \boldsymbol{b} is less than

elements greater than the median of

There are at least 3n/10-6

$$3(\lceil (1/2) \lceil n/5 \rceil \rceil - 2) \ge 3n/10 - 6$$

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Median of Medians: Proof of Lemma

Proposition

There are at least 3n/10 - 6 elements greater than the median of medians b.

Corollary

 $|A_{\textit{less}}| \leq 7n/10 + 6.$

Via symmetric argument,

Corollary

 $|A_{greater}| \leq 7n/10 + 6$.

Questions to ponder

- Why did we choose lists of size **5**? Will lists of size **3** work?
- ② Write a recurrence to analyze the algorithm's running time if we choose a list of size k.

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Median of Medians Algorithm Due to: M. Blum, R. Floyd, D. Knuth, V. Pratt, R. Rivest, and R. Tarjan. "Time bounds for selection". Journal of Computer System Sciences (JCSS), 1973. How many Turing Award winners in the author list? All except Vaughn Pratt!

Takeaway Points

- Recursion tree method and guess and verify are the most reliable methods to analyze recursions in algorithms.
- 2 Recursive algorithms naturally lead to recurrences.
- Some times one can look for certain type of recursive algorithms (reverse engineering) by understanding recurrences and their behavior.