# CS 473: Algorithms

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# High Probability Analysis & Universal Hashing

Lecture 09 September 21, 2016

## Outline

## Randomized QuickSort w.h.p.

What is the probability that the algorithm will terminate in **O(n log n)** time?

## Balls & Bins

- Expected bin size.
- Expected max bin size → max size w.h.p.
- Analogy to hashing

Hashing

## Part I

Randomized **QuickSort** (Contd.)

## Randomized QuickSort: Recall

**Input:** Array **A** of **n** distinct numbers. **Output:** Numbers in sorted order.

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- Split array into 2 subarrays: those smaller than pivot (L), and those larger than pivot (R).
- Recursively sort the subarrays, and concatenate them.

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**Note:** On *every* input randomized **QuickSort** takes  $O(n \log n)$  time in expectation. On *every* input it may take  $\Omega(n^2)$  time with some small probability.

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Question: With what probability it takes  $O(n \log n)$  time?

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If n = 100 then this gives  $Pr[Q(A) \le 32n \ln n] \ge 0.99999$ .

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  - Focus on a single element. Prove that it "participates" in  $> 32 \ln n$  levels with probability (w.p.) at most  $1/n^4$ .
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  - 2 By union bound, any of the n elements participates in  $> 32 \ln n$  levels w.p. at most  $1/n^3$ .
  - **3** Therefore, all elements participate in  $\leq$  32 ln n w.p.  $(1-1/n^3)$ .

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An element participates in  $> 32 \ln n$  w.p.  $\le 1/n^4$ .

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- If an array is reduced to at least its 3/4th size every time, then after how many rounds only one element remains?  $\leq 4 \ln n$ .
- If 32 In n splits, then **E**[Balanced-split] = 16 In n. Out of these there are  $< 4 \ln n$  balanced split w.p.  $\le 1/n^4$ .

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- For  $|S_k| = 1$ ,  $\rho = 4 \ln n \ge \log_{4/3} n$  suffices.

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Probability of  $\leq 4 \ln n$  lucky rounds out of  $32 \ln n$  rounds is,

$$\begin{array}{ll} \Pr[\rho \leq 4 \ln n] & = & \Pr[\rho \leq \frac{k}{8}] \\ & = & \Pr[\rho \leq (1 - \delta)\mu] \\ \text{(Chernoff)} & \leq & e^{\frac{-\delta^2 \mu}{2}} \\ & = & e^{-\frac{9k}{64}} \\ & = & e^{-4.5 \ln n} \leq \frac{1}{n^4} \end{array}$$

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• n input elements. Probability that depth of recursion in **QuickSort** > 32 ln n is at most  $\frac{1}{n^4} * n = \frac{1}{n^3}$ .

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## **Theorem**

With high probability (i.e.,  $1 - \frac{1}{n^3}$ ) the depth of the recursion of **QuickSort** is  $\leq 32 \ln n$ . Due to n comparisons in each level, with high probability, the running time of **QuickSort** is  $O(n \ln n)$ .

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Q: How to increase the probability?

# Part II

# Balls and Bins

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- Too many to count!!

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What is the expected maximum bin size?

R.V. 
$$\mathbf{Z} = \max_{j=1}^{n} \mathbf{Y}_{j}$$
. Show  $\mathbf{E}[\mathbf{Z}] \leq \mathbf{O}\left(\frac{\ln n}{\ln \ln n}\right)$ ?

#### Possible Solution

• If  $Pr[Z > \frac{8 \ln n}{\ln \ln n}] \le 1/n^2$ , then: define  $A = \frac{8 \ln n}{\ln \ln n}$ .

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$$\begin{split} \textbf{E}[\textbf{Z}] & \leq & \sum_{k=1}^{A} \text{Pr}[\textbf{Z} = k] \, \textbf{A} + \sum_{k=A+1}^{n} \text{Pr}[\textbf{Z} = k] \, \textbf{n} \\ & \leq & \textbf{A} \cdot \text{Pr}[\textbf{Z} \leq \textbf{A}] + \textbf{n} \cdot \text{Pr}[\textbf{Z} > \textbf{A}] \\ & \leq & \textbf{A} \cdot (1) + \textbf{n} \cdot (1/\textbf{n}^2) = \textbf{O}(\textbf{A}) = \textbf{O}\left(\frac{\ln \textbf{n}}{\ln \ln \textbf{n}}\right) \end{split}$$

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$$\begin{array}{ll} E[Z] & \leq & \sum_{k=1}^A \Pr[Z=k] \, A + \sum_{k=A+1}^n \Pr[Z=k] \, n \\ \\ & \leq & A \cdot \Pr[Z \leq A] + n \cdot \Pr[Z > A] \\ \\ & \leq & A \cdot (1) + n \cdot (1/n^2) = O(A) = O\left(\frac{\ln n}{\ln \ln n}\right) \end{array}$$

Bound 
$$Pr[Z > \frac{8 \ln n}{\ln \ln n}]$$
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Bound  $Pr[Z > \frac{8 \ln n}{\ln \ln n}]$  using Chernoff inequality.

### Chernoff Ineq. We Saw

 $\mathbf{X}_1,\dots,\mathbf{X}_k$  independent binary R.V., and  $\mathbf{X}=\sum_{i=1}^k\mathbf{X}_i,\ \mu=\mathbf{E}[\mathbf{X}],$  then for  $\mathbf{0}<\delta<\mathbf{1}$ 

$$\mathsf{Pr}[\mathsf{X} \geq (1+\delta)\mu] \leq \mathrm{e}^{-\delta^2\mu/3}$$
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### Stronger Versions

- ullet For  $\delta>0$ ,  $\Pr[{\sf X}>(1+\delta)\mu]<\left(rac{{\sf e}^\delta}{(1+\delta)^{(1+\delta)}}
  ight)^\mu.$
- ullet For  $0<\delta<1$  Pr[X  $<(1-\delta)\mu$ ]  $<\left(rac{{
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What is the expected maximum bin size? Let  $\mathbf{Z} = \max_{j=1}^{n} \mathbf{Y}_{j}$ .

Show  $E[Z] \le O(\frac{\ln n}{\ln \ln n})$ .  $\rightarrow$  Show  $Pr[Z > \frac{8 \ln n}{\ln \ln n}] \le 1/n^2$ .

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#### Solution

• Recall:  $\mathbf{Y}_j = \#$  balls in bin  $\mathbf{j}$ ,  $\mathbf{E}[\mathbf{Y}_j] = \mathbf{1}$ , and  $\mathbf{A} = \frac{8 \ln n}{\ln \ln n}$ 

$$\text{Pr}[Y_j > A] = \text{Pr}[Y_j \geq A \, \text{E}[Y]] < \left(\frac{e^{A-1}}{A^A}\right) < \left(\frac{n^{6/\ln\ln n}}{A^A}\right)$$

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$$\mathsf{A}^\mathsf{A} = \left(\frac{8 \ln \mathsf{n}}{\ln \ln \mathsf{n}}\right)^{\frac{\mathsf{g} \ln \mathsf{n}}{\ln \ln \mathsf{n}}} \ge (\sqrt{\ln \mathsf{n}})^{\frac{8 \ln \mathsf{n}}{\ln \ln \mathsf{n}}} = (\ln \mathsf{n})^{\frac{4 \ln \mathsf{n}}{\ln \ln \mathsf{n}}} = \mathsf{e}^{4 \lg \mathsf{n}} = \mathsf{n}^4$$

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$$\text{Pr}[\mathbf{Y}_j > \mathbf{A}] = \text{Pr}[\mathbf{Y}_j \geq \mathbf{A} \, \mathbf{E}[\mathbf{Y}]] < \left(\frac{\mathbf{e}^{\mathbf{A}-1}}{\mathbf{A}^{\mathbf{A}}}\right) < \left(\frac{\mathbf{n}^{6/\ln\ln n}}{\mathbf{A}^{\mathbf{A}}}\right)$$

$$\begin{split} \mathsf{A}^\mathsf{A} &= \left(\frac{8 \ln n}{\ln \ln n}\right)^{\frac{8 \ln n}{\ln \ln n}} \geq (\sqrt{\ln n})^{\frac{8 \ln n}{\ln \ln n}} = (\ln n)^{\frac{4 \ln n}{\ln \ln n}} = e^{4 \lg n} = n^4 \\ \mathsf{Pr} \bigg[ \mathsf{Y}_\mathsf{j} > \frac{8 \ln n}{\ln \ln n} \bigg] < 1/n^3 \end{split}$$

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• Recall:  $Y_j = \#$  balls in bin j.  $E[Y_j] = 1$ .

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What is the expected maximum bin size? Let  $\mathbf{Z} = \max_{j=1}^{n} \mathbf{Y}_{j}$ .

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 $\Omega(\frac{\ln n}{\ln \ln n})$  is a lower bound as well!

### Hashing

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Hashing: throw balls (elements) randomly into **n** bins such that **bin** sizes are small and also lookup is easy!.

# Part III

# Hash Tables

### Dictionary Data Structure

- $oldsymbol{u}$ : universe of keys with total order: numbers, strings, etc.
- $oldsymbol{ ilde{Q}}$  Data structure to store a subset  $oldsymbol{\mathsf{S}} \subseteq \mathcal{U}$
- Operations:
  - **3** Search/lookup: given  $x \in \mathcal{U}$  is  $x \in S$ ?
  - **2** Insert: given  $x \notin S$  add x to S.
  - **3** Delete: given  $x \in S$  delete x from S
- Static structure: S given in advance or changes very infrequently, main operations are lookups.
- Oynamic structure: S changes rapidly so inserts and deletes as important as lookups.

### Dictionary Data Structures

#### Common solutions:

- Static:
  - Store S as a sorted array
  - 2 Lookup: Binary search in O(log |S|) time (comparisons)
- ② Dynamic:
  - Store S in a balanced binary search tree
  - 2 Lookup, Insert, Delete in O(log |S|) time (comparisons)

### Dictionary Data Structures

**Question:** "Should Tables be Sorted?" (also title of famous paper by Turing award winner Andy Yao)

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**Question:** "Should Tables be Sorted?" (also title of famous paper by Turing award winner Andy Yao)

Hashing is a widely used & powerful technique for dictionaries.

#### **Motivation:**

- Universe  $\mathcal{U}$  may not be (naturally) totally ordered.
- Keys correspond to large objects (images, graphs etc) for which comparisons are very expensive.
- Want to improve "average" performance of lookups to O(1) even at cost of extra space or errors with small probability: many applications for fast lookups in networking, security, etc.

### Hashing and Hash Tables

Hash Table data structure:

- A (hash) table/array T of size m (the table size).
- ② A hash function  $h: \mathcal{U} \to \{0, \dots, m-1\}$ .
- **1** Item  $x \in \mathcal{U}$  hashes to slot h(x) in T.

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#### Ideal situation:

- **2** Each element  $x \in S$  hashes to a distinct slot in T. Store x in slot h(x)
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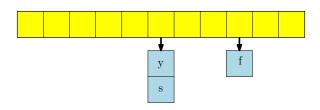
Collisions unavoidable if  $|\mathbf{T}|<|\mathcal{U}|$ . Several techniques to handle them.

## Handling Collisions: Chaining

Collision: h(x) = h(y) for some  $x \neq y$ .

#### Chaining to handle collisions:

- For each slot i store all items hashed to slot i in a linked list.
  T[i] points to the linked list
- **2** Lookup: to find if  $y \in \mathcal{U}$  is in T, check the linked list at T[h(y)]. Time proportion to size of linked list.



This is also known as **Open hashing**.

### Handling Collisions

#### Several other techniques:

- Cuckoo hashing. Every value has two possible locations. When inserting, insert in one of the locations, otherwise, kick stored value to its other location. Repeat till stable. if no stability then rebuild table.
- 2 ...
- Others.

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#### **Questions:**

- Complexity of evaluating h on a given element?
- 2 Relative sizes of the universe  $\mathcal{U}$  and the set to be stored S.
- 3 Size of table relative to size of S.
- Worst-case vs average-case vs randomized (expected) time?
- 6 How do we choose h?

- Complexity of evaluating h on a given element? Should be small.
- **2** Relative sizes of the universe  $\mathcal{U}$  and the set to be stored  $\mathbf{S}$ : typically  $|\mathcal{U}| \gg |\mathbf{S}|$ .
- Size of table relative to size of **S**. The **load factor** of **T** is the ratio  $\mathbf{n}/\mathbf{m}$  where  $\mathbf{n} = |\mathbf{S}|$  and  $\mathbf{m} = |\mathbf{T}|$ . Typically  $\mathbf{n}/\mathbf{m}$  is a small constant smaller than **1**.
  - Also known as the **fill factor**.

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- Size of table relative to size of S. The load factor of T is the ratio n/m where n = |S| and m = |T|. Typically n/m is a small constant smaller than 1.
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#### Main and interrelated questions:

- Worst-case vs average-case vs randomized (expected) time?
- How do we choose h?

### Single hash function

- $\mathcal{U}$ : universe (very large).
- ② Assume  $N = |\mathcal{U}| \gg m$  where m is size of table T. In particular assume  $N \geq m^2$  (very conservative).
- $lackbox{0}$  Fix hash function  $h:\mathcal{U} \to \{0,\ldots,m-1\}$ .
- **0** N items hashed to m slots. By pigeon hole principle there is some  $i \in \{0, \ldots, m-1\}$  such that  $N/m \ge m$  elements of  $\mathcal U$  get hashed to i (!).
- **1** Implies that there is a set  $S \subseteq \mathcal{U}$  where |S| = m such that all of S hashes to same slot. Ooops.

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**Lesson:** For every hash function there is a very bad set. Bad set. Bad.

## How many hash functions are there, anyway?

```
Let \mathcal H be the set of all functions from \mathcal U=\{1,\ldots,\mathsf U\} to \{1,\ldots,\mathsf m\}. The number of functions in \mathcal H is
```

- (A) U + m.
- (B) Um.
- (C) U<sup>m</sup>.
- (D) m<sup>U</sup>.
- (E)  $\binom{U+m}{m}$ .
- (F) The answer is blowing in the wind.

#### How many bits one need?

Let  $\mathcal H$  be a set of functions from  $\mathcal U=\{1,\ldots,U\}$  to  $\{1,\ldots,m\}$ . Specifying a function in  $\mathcal H$  requires:

- (A) O(U + m) bits.
- (B) O(Um) bits.
- (C) O(U<sup>m</sup>) bits.
- (D)  $O(m^U)$  bits.
- (E)  $O(\log |\mathcal{H}|)$  bits.
- (F) Many many bits. At least two.

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#### Parameters: $N = |\mathcal{U}|$ , m = |T|, n = |S|

- **1**  $\mathcal{H}$  is a **family** of hash functions: each function  $\mathbf{h} \in \mathcal{H}$  should be efficient to evaluate (that is, to compute  $\mathbf{h}(\mathbf{x})$ ).
- **b** is chosen randomly from  $\mathcal{H}$  (typically uniformly at random). Implicitly assumes that  $\mathcal{H}$  allows an efficient sampling.
- Randomized guarantee: should have the property that for any fixed set S ⊆ U of size m the expected number of collisions for a function chosen from H should be "small". Here the expectation is over the randomness in choice of h.

**Question:** Why not let  $\mathcal{H}$  be the set of *all* functions from  $\mathcal{U}$  to  $\{0,1,\ldots,m-1\}$ ?

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• Too many functions! A random function has high complexity! # of functions:  $\mathbf{M} = \mathbf{m}^{|\mathcal{U}|}$ . Bits to encode such a function  $\approx \log \mathbf{M} = |\mathcal{U}| \log \mathbf{m}$ .

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**Question:** Are there good and compact families  $\mathcal{H}$ ?

**1** Yes... But what it means for  $\mathcal{H}$  to be good and compact.

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- Second property is stronger than the first and the crucial issue.

#### **Definition**

A family hash function  $\mathcal{H}$  is (2-)universal if for all distinct  $x, y \in \mathcal{U}$ ,  $\Pr_h[h(x) = h(y)] = 1/m$  where m is the table size.

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Note: The set of all hash functions satisfies stronger properties!

- **1** T is hash table of size **m**.
- **2**  $S \subseteq \mathcal{U}$  is a **fixed** set of size  $\leq m$ .
- **I** is chosen randomly from a universal hash family  $\mathcal{H}$ .

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- The time to look up x is the size of the list at T[h(x)]: same as the number of elements in S that collide with x under h.
- ② Let  $\ell(x)$  be this number. We want  $E[\ell(x)]$
- **3** For  $y \in S$  let  $A_y$  be the event that x, y collide and  $D_y$  be the corresponding indicator variable.

Continued...

Number of elements colliding with x:  $\ell(x) = \sum_{y \in S} D_y$ .

$$\Rightarrow \mathsf{E}[\ell(x)] = \sum_{y \in S} \mathsf{E}[D_y] \qquad \text{linearity of expectation}$$
 
$$= \sum_{y \in S} \mathsf{Pr}[h(x) = h(y)]$$
 
$$= \sum_{y \in S} \frac{1}{m} \qquad \text{since } \mathcal{H} \text{ is a universal hash family}$$
 
$$= |S|/m$$
 
$$\leq 1 \quad \text{if } |S| \leq m$$

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Answer: O(n/m).

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#### Comments:

- **0 O**(1) expected time also holds for insertion.
- Analysis assumes static set S but holds as long as S is a set formed with at most O(m) insertions and deletions.
- Worst-case: look up time can be large! How large?
   Ω(log n/ log log n)
   [Lower bound holds even under stronger assumptions.]

#### **Next Lecture**

#### Desired Hash Family 7

 $p > |\mathcal{U}|$  be a prime. Define  $h_{a,b}(x) = (ax + b \mod p) \mod m$ .

$$\mathcal{H} = \{h_{a,b} \mid a \in \{1, \dots, p-1\}, b \in \{0, \dots, p-1\}\}$$

#### Next Lecture

#### Desired Hash Family H

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$$\mathcal{H} = \{h_{a,b} \mid a \in \{1, \dots, p-1\}, b \in \{0, \dots, p-1\}\}$$

- **1**  $h_{a,b}$  can be evaluated in O(1) time.
- Easy to sample.
- Universal!

## Rehashing, amortization and...

.. making the hash table dynamic

So far we assumed fixed **S** of size  $\simeq$  **m**.

Question: What happens as items are inserted and deleted?

- If |S| grows to more than cm for some constant c then hash table performance clearly degrades.
- If |S| stays around ~ m but incurs many insertions and deletions then the initial random hash function is no longer random enough!

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- If |S| grows to more than cm for some constant c then hash table performance clearly degrades.
- ② If |S| stays around ≃ m but incurs many insertions and deletions then the initial random hash function is no longer random enough!

**Solution:** Rebuild hash table periodically!

- Choose a new table size based on current number of elements in table.
- Choose a new random hash function and rehash the elements.
- Oiscard old table and hash function.

Question: When to rebuild? How expensive?

### Rebuilding the hash table

- Start with table size  $\mathbf{m}$  where  $\mathbf{m}$  is some estimate of  $|\mathbf{S}|$  (can be some large constant).
- ② If |S| grows to more than twice current table size, build new hash table (choose a new random hash function) with double the current number of elements. Can also use similar trick if table size falls below quarter the size.
- ① If |S| stays roughly the same but more than c|S| operations on table for some chosen constant c (say 10), rebuild.

The **amortize** cost of rebuilding to previously performed operations. Rebuilding ensures O(1) expected analysis holds even when S changes. Hence O(1) expected look up/insert/delete time *dynamic* data dictionary data structure!