CS 473: Fundamental Algorithms, Fall 2014

More Dynamic Programming

Lecture 9 September 30, 2014

What is the running time of the following?

Consider computing f(x, y) by recursive function + memoization.

$$f(x, y) = \sum_{i=1}^{x+y-1} x * f(x + y - i, i - 1),$$

$$f(0, y) = y \qquad f(x, 0) = x.$$

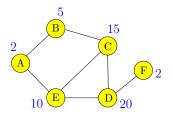
The resulting algorithm when computing f(n, n) would take: (A) O(n) (B) O(n log n) (C) O(n²) (D) O(n³) (E) The function is ill defined - it can not be computed.

Part I

Maximum Weighted Independent Set in Trees

Maximum Weight Independent Set Problem

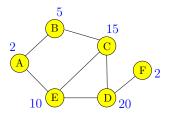
- Input Graph ${\sf G}=({\sf V},{\sf E})$ and weights ${\sf w}({\sf v})\geq 0$ for each ${\sf v}\in{\sf V}$
- Goal Find maximum weight independent set in G



Maximum weight independent set in above graph: {B, D}

Maximum Weight Independent Set Problem

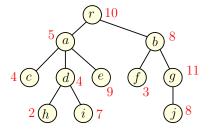
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Maximum weight independent set in above graph: {B, D}

Maximum Weight Independent Set in a Tree

Input Tree T = (V, E) and weights $w(v) \ge 0$ for each $v \in V$ Goal Find maximum weight independent set in T



Maximum weight independent set in above tree: ??

In a tree with **n** nodes, there is always an independent set of size (bigger is better [this is America!])

```
(A) \Omega(1)

(B) \Omega(\log n)

(C) \Omega(\sqrt{n})

(D) n/2

(E) n - 5
```

For an arbitrary graph G:

- Number vertices as v_1, v_2, \ldots, v_n
- ⁽²⁾ Find recursively optimum solutions without v_n (recurse on $G v_n$) and with v_n (recurse on $G v_n N(v_n)$ & include v_n).
- Saw that if graph **G** is arbitrary there was no good ordering that resulted in a small number of subproblems.

What about a tree? Natural candidate for \boldsymbol{v}_n is root \boldsymbol{r} of $\boldsymbol{T}?$

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Natural candidate for \mathbf{v}_n is root \mathbf{r} of \mathbf{T} ? Let \mathcal{O} be an optimum solution to the whole problem.

- Case $\mathbf{r} \notin \mathcal{O}$: Then \mathcal{O} contains an optimum solution for each subtree of **T** hanging at a child of \mathbf{r} .
- Case $\mathbf{r} \in \mathcal{O}$: None of the children of \mathbf{r} can be in \mathcal{O} . $\mathcal{O} \{\mathbf{r}\}$ contains an optimum solution for each subtree of \mathbf{T} hanging at a grandchild of \mathbf{r} .

Subproblems? Subtrees of **T** hanging at nodes in **T**.

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Subproblems? Subtrees of **T** hanging at nodes in **T**.

A Recursive Solution

T(u): subtree of T hanging at node u OPT(u): max weighted independent set value in T(u)

 $OPT(u) = \max \begin{cases} \sum_{v \text{ child of } u} OPT(v), \\ w(u) + \sum_{v \text{ grandchild of } u} OPT(v) \end{cases}$

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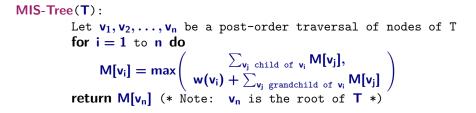
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- What is an ordering of nodes of a tree T to achieve above? Post-order traversal of a tree.

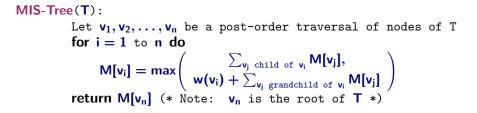
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$$\begin{split} \text{MIS-Tree}(\text{T}): \\ & \text{Let } v_1, v_2, \dots, v_n \text{ be a post-order traversal of nodes of T} \\ & \text{for } i=1 \text{ to } n \text{ do} \\ & \text{M}[v_i] = \max \begin{pmatrix} \sum_{v_j \text{ child of } v_i} M[v_j], \\ & \text{w}(v_i) + \sum_{v_j \text{ grandchild of } v_i} M[v_j] \end{pmatrix} \\ & \text{return } M[v_n] \text{ (* Note: } v_n \text{ is the root of T *)} \end{split}$$

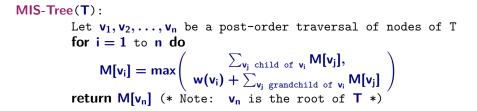
- Naive bound: O(n²) since each M[v_i] evaluation may take O(n) time and there are n evaluations.
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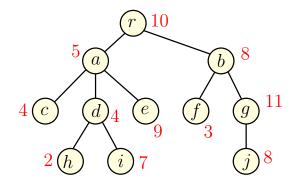
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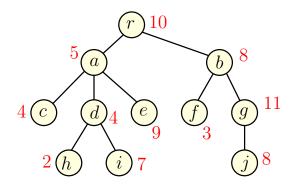
Example



Dominating set

Definition

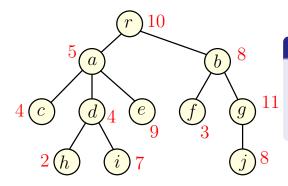
G = (V, E). The set $X \subseteq V$ is a **dominating set**, if any vertex $v \in V$ is either in X or is adjacent to a vertex in X.



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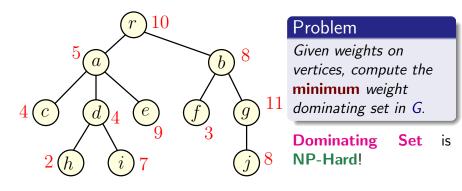
Problem

Given weights on vertices, compute the **minimum** weight dominating set in *G*.

Dominating set

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Minimum weight dominating set in a tree can be computed using the recursive formula...

(A)
$$\mathcal{O}(\mathbf{u}) = \min \begin{cases} \sum_{\mathbf{v} \text{ child of } \mathbf{u}} \mathcal{O}(\mathbf{v}), \\ \mathbf{w}(\mathbf{u}) + \sum_{\mathbf{v} \text{ grandchild of } \mathbf{u}} \mathcal{O}(\mathbf{v}) \end{cases}$$

(B) $\mathcal{O}(\mathbf{u}) = \mathbf{w}(\mathbf{u}) + \min \begin{cases} \sum_{\mathbf{v} \text{ child of } \mathbf{u}} \mathcal{O}(\mathbf{v}), \\ \sum_{\mathbf{v} \text{ grandchild of } \mathbf{u}} \mathcal{O}(\mathbf{v}) \end{cases}$
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(D) $\mathcal{O}(\mathbf{u}) = \mathbf{w}(\mathbf{u}) + \sum_{\mathbf{v} \text{ grandchild of } \mathbf{u}} \mathcal{O}(\mathbf{v}).$
(E) None of the above.

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Part II

DAGs and Dynamic Programming

Recursion and DAGs

Observation

Let **A** be a recursive algorithm for problem Π . For each instance **I** of Π there is an associated DAG **G(I)**.

- Create directed graph G(I) as follows...
- **②** For each sub-problem in the execution of **A** on **I** create a node.
- If sub-problem v depends on or recursively calls sub-problem u add directed edge (u, v) to graph.
- G(I) is a DAG. Why? If G(I) has a cycle then A will not terminate on I.

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Iterative Algorithm for... Dynamic Programming and DAGs

Observation

An iterative algorithm **B** obtained from a recursive algorithm **A** for a problem Π does the following:

For each instance I of Π , it computes a topological sort of G(I) and evaluates sub-problems according to the topological ordering.

- Sometimes the DAG G(I) can be obtained directly without thinking about the recursive algorithm A
- In some cases (not all) the computation of an optimal solution reduces to a shortest/longest path in DAG G(I)
- Topological sort based shortest/longest path computation is dynamic programming!

A quick reminder...

A Recursive Algorithm for weighted interval scheduling

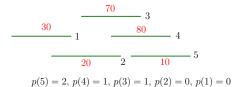
Let **O**_i be value of an optimal schedule for the first **i** jobs.

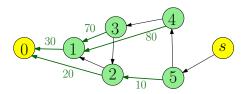
```
\begin{array}{l} \mbox{Schedule}(n): \\ \mbox{if } n=0 \mbox{ then return } 0 \\ \mbox{if } n=1 \mbox{ then return } w(v_1) \\ O_{p(n)} \leftarrow \mbox{Schedule}(p(n)) \\ O_{n-1} \leftarrow \mbox{Schedule}(n-1) \\ \mbox{if } (O_{p(n)}+w(v_n) < O_{n-1}) \mbox{ then } \\ O_n=O_{n-1} \\ \mbox{else} \\ O_n=O_{p(n)}+w(v_n) \\ \mbox{return } O_n \end{array}
```

Given intervals, create a DAG as follows:

- Create one node for each interval, plus a dummy sink node 0 for interval 0, plus a dummy source node s.
- For each interval i add edge (i, p(i)) of the length/weight of v_i.
- Add an edge from \mathbf{s} to \mathbf{n} of length $\mathbf{0}$.
- For each interval i add edge (i, i 1) of length 0.

Example





Relating Optimum Solution

Given interval problem instance I let G(I) denote the DAG constructed as described.

Claim

Optimum solution to weighted interval scheduling instance I is given by longest path from s to 0 in G(I).

Assuming claim is true,

- If I has n intervals, DAG G(I) has n + 2 nodes and O(n) edges. Creating G(I) takes O(n log n) time: to find p(i) for each i. How?
- O(m + n) algorithm for shortest/longest paths in DAGs.

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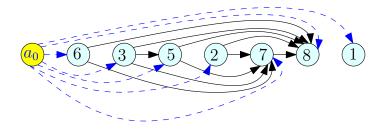
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DAG for Longest Increasing Sequence

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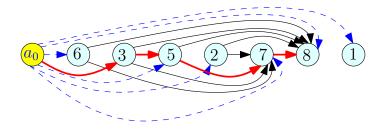
- **(**) add sentinel \mathbf{a}_0 to sequence where \mathbf{a}_0 is less than smallest element in sequence
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Part III

Edit Distance and Sequence Alignment

Spell Checking Problem

Given a string "exponen" that is not in the dictionary, how should a spell checker suggest a *nearby* string?

What does nearness mean?

Question: Given two strings $x_1x_2...x_n$ and $y_1y_2...y_m$ what is a *distance* between them?

Edit Distance: minimum number of "edits" to transform x into y.

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Edit Distance

Definition

Edit distance between two words X and Y is the number of letter insertions, letter deletions and letter substitutions required to obtain Y from X.

Example

The edit distance between FOOD and MONEY is at most 4:

 $\underline{F}OOD \rightarrow MO\underline{O}D \rightarrow MON\underline{O}D \rightarrow MON\underline{E}\underline{D} \rightarrow MONEY$

Edit Distance: Alternate View

Alignment

Place words one on top of the other, with gaps in the first word indicating insertions, and gaps in the second word indicating deletions.

F O O D M O N E Y

Formally, an alignment is a set M of pairs (i, j) such that each index appears at most once, and there is no "crossing": i < i' and i is matched to j implies i' is matched to j' > j. In the above example, this is $M = \{(1, 1), (2, 2), (3, 3), (4, 5)\}$. Cost of an alignment is the number of mismatched columns plus number of unmatched indices in both strings.

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Edit Distance Problem

Problem

Given two words, find the edit distance between them, i.e., an alignment of smallest cost.

Applications

- Spell-checkers and Dictionaries
- Onix diff
- **③** DNA sequence alignment ... but, we need a new metric

Similarity Metric

Definition

For two strings X and Y, the cost of alignment M is

- **(**Gap penalty] For each gap in the alignment, we incur a cost δ .
- (a) [Mismatch cost] For each pair **p** and **q** that have been matched in **M**, we incur cost α_{pq} ; typically $\alpha_{pp} = 0$.

Edit distance is special case when $\delta = \alpha_{pq} = 1$.

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An Example

Example

Alternative:

Or a really stupid solution (delete string, insert other string):

$$\mathbf{o} \mid \mathbf{c} \mid \mathbf{u} \mid \mathbf{r} \mid \mathbf{r} \mid \mathbf{a} \mid \mathbf{n} \mid \mathbf{c} \mid \mathbf{e} \mid \mathbf{o} \mid \mathbf{c} \mid \mathbf{c} \mid \mathbf{u} \mid \mathbf{r} \mid \mathbf{r} \mid \mathbf{e} \mid \mathbf{n} \mid \mathbf{c} \mid \mathbf{e}$$
$$\mathsf{Cost} = \mathbf{19}\delta.$$

 $= \delta + \alpha_{ae}$

What is the edit distance between...

What is the minimum edit distance for the following two strings, if insertion/deletion/change of a single character cost 1 unit?



(A) 1
(B) 2
(C) 3
(D) 4
(E) 5

Sequence Alignment

- Input Given two words **X** and **Y**, and gap penalty δ and mismatch costs α_{pq}
- Goal Find alignment of minimum cost

Let $X = \alpha x$ and $Y = \beta y$

 $\alpha, oldsymbol{eta}$: strings.

x and y single characters.

Think about optimal edit distance between X and Y as alignment, and consider last column of alignment of the two strings:

$\boldsymbol{\alpha}$	x	or	α	x	or	αχ	
$\boldsymbol{\beta}$	У	01	βу		0i	β	У

Observation

Prefixes must have optimal alignment!

Problem Structure

Observation

Let $X = x_1 x_2 \cdots x_m$ and $Y = y_1 y_2 \cdots y_n$. If (m, n) are not matched then either the mth position of X remains unmatched or the nth position of Y remains unmatched.

1 Case $\mathbf{x}_{\mathbf{m}}$ and $\mathbf{y}_{\mathbf{n}}$ are matched.

- Pay mismatch cost \$\alpha_{x_my_n}\$ plus cost of aligning strings \$\$x_1 \cdots x_{m-1}\$ and \$\$y_1 \cdots y_{n-1}\$\$
- Case x_m is unmatched.

 $\textbf{0} \text{ Pay gap penalty plus cost of aligning } \textbf{x}_1 \cdots \textbf{x}_{m-1} \text{ and } \textbf{y}_1 \cdots \textbf{y}_n$

- **3** Case y_n is unmatched.
 - $\textbf{0} \text{ Pay gap penalty plus cost of aligning } \textbf{x}_1 \cdots \textbf{x}_m \text{ and } \textbf{y}_1 \cdots \textbf{y}_{n-1}$

Subproblems and Recurrence

Optimal Costs

Let Opt(i, j) be optimal cost of aligning $x_1 \cdots x_i$ and $y_1 \cdots y_j$. Then

$$Opt(\mathbf{i}, \mathbf{j}) = \min \begin{cases} \alpha_{x_i y_j} + Opt(\mathbf{i} - 1, \mathbf{j} - 1), \\ \delta + Opt(\mathbf{i} - 1, \mathbf{j}), \\ \delta + Opt(\mathbf{i}, \mathbf{j} - 1) \end{cases}$$

Base Cases: $Opt(i, 0) = \delta \cdot i$ and $Opt(0, j) = \delta \cdot j$

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Dynamic Programming Solution

```
\label{eq:constraint} \begin{array}{l} \mbox{for all } i \mbox{ do } M[i,0] = i\delta \\ \mbox{for all } j \mbox{ do } M[0,j] = j\delta \\ \end{array} \\ \mbox{for } i = 1 \mbox{ to } m \mbox{ do } \\ \mbox{ for } j = 1 \mbox{ to } n \mbox{ do } \\ \mbox{ } M[i,j] = \min \begin{cases} \alpha_{x_iy_j} + M[i-1,j-1], \\ \delta + M[i-1,j], \\ \delta + M[i,j-1] \end{cases} \end{array}
```

Analysis

Running time is **O(mn)**.

Dynamic Programming Solution

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Analysis

Running time is O(mn).

Dynamic Programming Solution

```
\label{eq:constraint} \begin{array}{l} \mbox{for all } i \mbox{ do } M[i,0] = i\delta \\ \mbox{for all } j \mbox{ do } M[0,j] = j\delta \\ \end{array} \\ \mbox{for } i = 1 \mbox{ to } m \mbox{ do } \\ \mbox{ for } j = 1 \mbox{ to } n \mbox{ do } \\ \mbox{ } M[i,j] = \min \begin{cases} \alpha_{x_iy_j} + M[i-1,j-1], \\ \delta + M[i-1,j], \\ \delta + M[i,j-1] \end{cases} \end{array}
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Analysis

Running time is O(mn).

Space used is O(mn).

Matrix and DAG of Computation

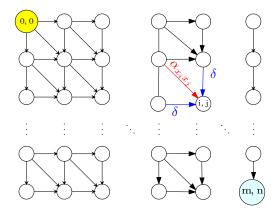


Figure : Iterative algorithm in previous slide computes values in row order. Optimal value is a shortest path from (0,0) to (m,n) in

Sequence Alignment in Practice

- Typically the DNA sequences that are aligned are about 10⁵ letters long!
- So about 10¹⁰ operations and 10¹⁰ bytes needed
- The killer is the 10GB storage
- On we reduce space requirements?

Optimizing Space

Recall

$$\mathsf{M}(\mathsf{i},\mathsf{j}) = \min \begin{cases} \alpha_{\mathsf{x}_{\mathsf{i}}\mathsf{y}_{\mathsf{j}}} + \mathsf{M}(\mathsf{i}-1,\mathsf{j}-1), \\ \delta + \mathsf{M}(\mathsf{i}-1,\mathsf{j}), \\ \delta + \mathsf{M}(\mathsf{i},\mathsf{j}-1) \end{cases}$$

- Entries in jth column only depend on (j 1)st column and earlier entries in jth column
- Only store the current column and the previous column reusing space; N(i, 0) stores M(i, j 1) and N(i, 1) stores M(i, j)

Computing in column order to save space

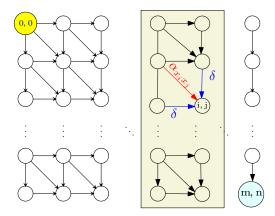


Figure : M(i, j) only depends on previous column values. Keep only two columns and compute in column order.

Space Efficient Algorithm

$$\begin{array}{l} \mbox{for all } i \mbox{ do } N[i,0] = i\delta \\ \mbox{for } j = 1 \mbox{ to } n \mbox{ do } \\ N[0,1] = j\delta \ (* \mbox{ corresponds to } M(0,j) \ *) \\ \mbox{ for } i = 1 \mbox{ to } m \mbox{ do } \\ N[i,1] = \min \begin{cases} \alpha_{x_iy_j} + N[i-1,0] \\ \delta + N[i-1,1] \\ \delta + N[i,0] \end{cases} \\ \mbox{for } i = 1 \mbox{ to } m \mbox{ do } \\ \mbox{ Copy } N[i,0] = N[i,1] \end{cases}$$

Analysis

Running time is O(mn) and space used is O(2m) = O(m)

Analyzing Space Efficiency

- From the m × n matrix M we can construct the actual alignment (exercise)
- Matrix N computes cost of optimal alignment but no way to construct the actual alignment
- Space efficient computation of alignment? More complicated algorithm see text book.

Takeaway Points

- Oynamic programming is based on finding a recursive way to solve the problem. Need a recursion that generates a small number of subproblems.
- Given a recursive algorithm there is a natural DAG associated with the subproblems that are generated for given instance; this is the dependency graph. An iterative algorithm simply evaluates the subproblems in some topological sort of this DAG.
- The space required to evaluate the answer can be reduced in some cases by a careful examination of that dependency DAG of the subproblems and keeping only a subset of the DAG at any time.