CS 473: Fundamental Algorithms, Fall 2014

More Dynamic Programming

Lecture 9 September 30, 2014

What is the running time of the following?

Consider computing $f(x, y)$ by recursive function + memoization.

$$
f(x,y) = \sum_{i=1}^{x+y-1} x * f(x + y - i, i - 1),
$$

$$
f(0,y) = y \qquad f(x,0) = x.
$$

The resulting algorithm when computing $f(n, n)$ would take: (A) O(n) (B) O(n log n) $(C) O(n^2)$ $(D) O(n^3)$ (E) The function is ill defined - it can not be computed.

Part I

[Maximum Weighted Independent Set](#page-2-0) [in Trees](#page-2-0)

Maximum Weight Independent Set Problem

- Input Graph $G = (V, E)$ and weights $w(v) > 0$ for each v ∈ V
- Goal Find maximum weight independent set in G

Maximum weight independent set in above graph: ${B, D}$

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Maximum Weight Independent Set in a Tree

Input Tree $\mathsf{T} = (\mathsf{V}, \mathsf{E})$ and weights $\mathsf{w}(\mathsf{v}) \geq 0$ for each $\mathsf{v} \in \mathsf{V}$ Goal Find maximum weight independent set in T

Maximum weight independent set in above tree: ??

In a tree with \bf{n} nodes, there is always an independent set of size (bigger is better [this is America!])

```
(A) \Omega(1)(B) Ω(log n)
(C) Ω(√
n)
(D) n/2
(E) n – 5
```
For an arbitrary graph G:

- **1** Number vertices as v_1, v_2, \ldots, v_n
- **2** Find recursively optimum solutions without v_n (recurse on $G - v_n$) and with v_n (recurse on $G - v_n - N(v_n)$ & include v_n).
- Saw that if graph **G** is arbitrary there was no good ordering that resulted in a small number of subproblems.

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Natural candidate for v_n is root r of T? Let $\mathcal O$ be an optimum solution to the whole problem.

- Case $r \notin \mathcal{O}$: Then $\mathcal O$ contains an optimum solution for each subtree of T hanging at a child of r .
- Case $\mathbf{r} \in \mathcal{O}$: None of the children of \mathbf{r} can be in \mathcal{O} . $\mathcal{O} \{ \mathbf{r} \}$ contains an optimum solution for each subtree of T hanging at a grandchild of r.

Subproblems? Subtrees of T hanging at nodes in T .

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A Recursive Solution

 $T(u)$: subtree of T hanging at node u $OPT(u)$: max weighted independent set value in $T(u)$

> **OPT(u)** = max $\left\{\sum_{v \text{ child of } u} \text{OPT}(v),\right\}$ $\mathsf{w}(\mathsf{u}) + \sum_{\mathsf{v} \text{ grandchild of } \mathsf{u}} \mathsf{OPT}(\mathsf{v})$

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- \bullet Compute $\mathsf{OPT}(u)$ bottom up. To evaluate $\mathsf{OPT}(u)$ need to have computed values of all children and grandchildren of $\mathbf u$
- 2 What is an ordering of nodes of a tree **T** to achieve above? Post-order traversal of a tree.

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- \bullet Naive bound: $\mathsf{O}(\mathsf{n}^2)$ since each $\mathsf{M}[\mathsf{v}_\mathsf{i}]$ evaluation may take O(n) time and there are **n** evaluations.
- **2** Better bound: $O(n)$. A value $M[v_i]$ is accessed only by its parent and grand parent.

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\begin{array}{ll}\n\text{MIS-Tree}(T): \\
\text{Let } v_1, v_2, \ldots, v_n \text{ be a post-order traversal of nodes of T} \\
\text{for } i = 1 \text{ to } n \text{ do} \\
M[v_i] = \max \left(\sum_{v_j \text{ child of } v_i} M[v_j], \right. \\
\text{return } M[v_n] \quad (* \text{ Note: } v_n \text{ is the root of } T*)\n\end{array}
$$

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Dominating set

Definition

 $G = (V, E)$. The set $X \subseteq V$ is a **dominating set**, if any vertex $v \in V$ is either in **X** or is adjacent to a vertex in **X**.

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Dominating Set is NP-Hard!

Minimum weight dominating set in a tree can be computed using the recursive formula...

(A)
$$
\mathcal{O}(u) = \min \left\{ \sum_{v \text{ child of } u} \mathcal{O}(v), \right\}
$$

\n(B)
$$
\mathcal{O}(u) = w(u) + \min \left\{ \sum_{v \text{ grandchild of } u} \mathcal{O}(v), \right\}
$$

\n(C)
$$
\mathcal{O}(u) = w(u) + \max \left\{ \sum_{v \text{ grandchild of } u} \mathcal{O}(v), \right\}
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\n(D)
$$
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$$

\n(E) None of the above.

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Part II

[DAGs and Dynamic Programming](#page-28-0)

Recursion and DAGs

Observation

Let **A** be a recursive algorithm for problem Π . For each instance \Box of Π there is an associated DAG $G(I)$.

- \bullet Create directed graph $G(1)$ as follows...
- **2** For each sub-problem in the execution of **A** on **I** create a node.
- **3** If sub-problem **v** depends on or *recursively calls* sub-problem **u** add *directed* edge (u, v) to graph.
- \bigcirc G(I) is a DAG. Why? If G(I) has a cycle then A will not terminate on I.

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Iterative Algorithm for... Dynamic Programming and DAGs

Observation

An iterative algorithm \bf{B} obtained from a recursive algorithm \bf{A} for a problem Π does the following: For each instance $\mathsf I$ of $\mathsf \Pi$, it computes a topological sort

of $G(1)$ and evaluates sub-problems according to the topological ordering.

- \bullet Sometimes the DAG $G(I)$ can be obtained directly without thinking about the recursive algorithm $\mathbf A$
- **2** In some cases (not all) the computation of an optimal solution reduces to a shortest/longest path in $\rm DAG$ G(1)
- **3** Topological sort based shortest/longest path computation is dynamic programming!

A quick reminder...

A Recursive Algorithm for weighted interval scheduling

Let O_i be value of an optimal schedule for the first *i* jobs.

```
Schedule(n):
          if n = 0 then return 0
          if n = 1 then return w(v_1)O_{p(n)} \leftarrowSchedule(p(n))
          O_{n-1} \leftarrowSchedule(n – 1)
          if (O_{p(n)} + w(v_n) < O_{n-1}) then
                O_n = O_{n-1}else
                O_n = O_{p(n)} + w(v_n)return O<sub>n</sub>
```
Given intervals, create a DAG as follows:

- **4** Create one node for each interval, plus a dummy sink node **0** for interval $\mathbf{0}$, plus a dummy source node s.
- $\bullet\,$ For each interval $\mathsf i$ add edge $(\mathsf i, \mathsf p(\mathsf i))$ of the length/weight of $\mathsf v_\mathsf i.$
- **3** Add an edge from **s** to **n** of length **0**.
- \bullet For each interval i add edge $(i, i 1)$ of length 0.

Example

Relating Optimum Solution

Given interval problem instance \blacksquare let $\mathsf{G}(\mathsf{I})$ denote the DAG constructed as described.

Claim

Optimum solution to weighted interval scheduling instance **I** is given by longest path from s to 0 in $G(I)$.

Assuming claim is true,

- \bigcirc If I has n intervals, DAG G(I) has $n + 2$ nodes and $O(n)$ edges. Creating $G(I)$ takes $O(n \log n)$ time: to find $p(i)$ for each i. How?
- **2** Longest path can be computed in $O(n)$ time recall $O(m + n)$ algorithm for shortest/longest paths in DAGs.
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DAG for Longest Increasing Sequence

Given sequence a_1, a_2, \ldots, a_n create DAG as follows:

- **1** add sentinel a_0 to sequence where a_0 is less than smallest element in sequence
- \bullet for each i there is a node v_i
- **3** if $i < j$ and $a_i < a_j$ add an edge (v_i, v_j)
- \bullet find longest path from v_0

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Part III

[Edit Distance and Sequence Alignment](#page-39-0)

Spell Checking Problem

Given a string "exponen" that is not in the dictionary, how should a spell checker suggest a *nearby* string?

What does nearness mean?

Question: Given two strings $x_1x_2 \ldots x_n$ and $y_1y_2 \ldots y_m$ what is a distance between them?

Edit Distance: minimum number of "edits" to transform x into y.

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Edit Distance

Definition

Edit distance between two words X and Y is the number of letter insertions, letter deletions and letter substitutions required to obtain Y from **X**.

Example

The edit distance between FOOD and MONEY is at most 4:

 $FOOD \rightarrow MOOD \rightarrow MONOD \rightarrow MONED \rightarrow MONEY$

Alignment

Place words one on top of the other, with gaps in the first word indicating insertions, and gaps in the second word indicating deletions.

F O O D M O N E Y

Formally, an alignment is a set M of pairs (i, j) such that each index appears at most once, and there is no "crossing": $\mathbf{i} < \mathbf{i}'$ and \mathbf{i} is matched to **j** implies i' is matched to $j' > j$. In the above example, this is $M = \{(1, 1), (2, 2), (3, 3), (4, 5)\}\)$. Cost of an alignment is the number of mismatched columns plus number of unmatched indices in both strings.

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Edit Distance Problem

Problem

Given two words, find the edit distance between them, i.e., an alignment of smallest cost.

Applications

- **1** Spell-checkers and Dictionaries
- 2 Unix diff
- **3** DNA sequence alignment . . . but, we need a new metric

Similarity Metric

Definition

For two strings X and Y , the cost of alignment M is

- **1** [Gap penalty] For each gap in the alignment, we incur a cost δ .
- **2** [Mismatch cost] For each pair **p** and **q** that have been matched in M, we incur cost α_{pq} ; typically $\alpha_{pp} = 0$.

Edit distance is special case when $\delta = \alpha_{\text{no}} = 1$.

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An Example

Example

o c u r r a n c e o c c u r r e n c e Cost = δ + αae

Alternative:

o c u r r a n c e o c c u r r e n c e Cost = 3δ

Or a really stupid solution (delete string, insert other string):

o c u r r a n c e o c c u r r e n c e Cost = 19δ.

What is the edit distance between...

What is the minimum edit distance for the following two strings, if insertion/deletion/change of a single character cost 1 unit?

(A) 1 (B) 2 (C) 3 (D) 4 (E) 5

Sequence Alignment

- Input Given two words **X** and **Y**, and gap penalty δ and mismatch costs α_{pa}
	- Goal Find alignment of minimum cost

Let $X = \alpha x$ and $Y = \beta y$

 α, β : strings.

x and **y** single characters.

Think about optimal edit distance between X and Y as alignment.

and consider last column of alignment of the two strings:

Observation

Prefixes must have optimal alignment!

Problem Structure

Observation

Let $X = x_1x_2 \cdots x_m$ and $Y = y_1y_2 \cdots y_n$. If (m, n) are not matched then either the m th position of X remains unmatched or the nth position of Y remains unmatched.

 \bullet Case x_m and y_n are matched.

- **1** Pay mismatch cost $\alpha_{x_m y_n}$ plus cost of aligning strings $x_1 \cdots x_{m-1}$ and $y_1 \cdots y_{n-1}$
- \bullet Case x_m is unmatched.

1 Pay gap penalty plus cost of aligning $x_1 \cdots x_{m-1}$ and $y_1 \cdots y_n$

- \bullet Case y_n is unmatched.
	- \bullet Pay gap penalty plus cost of aligning $x_1 \cdots x_m$ and $y_1 \cdots y_{n-1}$

Subproblems and Recurrence

Optimal Costs

Let $\mathrm{Opt}(\mathbf{i},\mathbf{j})$ be optimal cost of aligning $\mathsf{x}_1\cdots \mathsf{x}_\mathsf{i}$ and $\mathsf{y}_1\cdots \mathsf{y}_\mathsf{j}$. Then

$$
Opt(i, j) = min \begin{cases} \alpha_{x_i y_j} + Opt(i - 1, j - 1), \\ \delta + Opt(i - 1, j), \\ \delta + Opt(i, j - 1) \end{cases}
$$

Base Cases: $Opt(i, 0) = \delta \cdot i$ and $Opt(0, j) = \delta \cdot j$

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Base Cases: $\text{Opt}(i, 0) = \delta \cdot i$ and $\text{Opt}(0, j) = \delta \cdot j$

Dynamic Programming Solution

```
for all i do M[i, 0] = i\deltafor all j do M[0, j] = i\deltafor i = 1 to m do
for i = 1 to n do
       M[i, j] = min\sqrt{ }\int\mathcal{L}\alpha_{x_iy_j} + M[i – 1, j – 1],
                             \delta + M[i - 1, j],
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```
Analysis

 \bullet Running time is $O(mn)$.

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```
Analysis

 \bullet Running time is $O(mn)$.

2 Space used is **O(mn)**.

Matrix and DAG of Computation

Figure : Iterative algorithm in previous slide computes values in row order. Optimal value is a shortest path from $(0, 0)$ to (m, n) in

Sequence Alignment in Practice

- **1** Typically the DNA sequences that are aligned are about $10⁵$ letters long!
- 2 So about 10^{10} operations and 10^{10} bytes needed
- **3** The killer is the 10GB storage
- 4 Can we reduce space requirements?

Optimizing Space

$$
M(i,j) = min \begin{cases} \alpha_{x_iy_j} + M(i-1,j-1), \\ \delta + M(i-1,j), \\ \delta + M(i,j-1) \end{cases}
$$

- 2 Entries in jth column only depend on $(i 1)$ st column and earlier entries in *i*th column
- **3** Only store the current column and the previous column reusing space; $N(i, 0)$ stores $M(i, j - 1)$ and $N(i, 1)$ stores $M(i, j)$

Computing in column order to save space

Figure : $M(i, j)$ only depends on previous column values. Keep only two columns and compute in column order.

Space Efficient Algorithm

$$
\begin{array}{l} \text { for all i do } \mathsf{N[i, 0]} = \mathrm{i} \delta \\ \text { for } j = 1 \text { to n do } \\ \mathsf{N[0, 1]} = \mathrm{j} \delta \text { (* corresponds to } \mathsf{M(0, j)} \text { *)} \\ \text { for } i = 1 \text { to m do } \\ \mathsf{N[i, 1]} = \min \begin{cases} \alpha_{x_i y_j} + \mathsf{N[i - 1, 0]} \\ \delta + \mathsf{N[i - 1, 1]} \\ \delta + \mathsf{N[i, 0]} \\ \text { for } i = 1 \text { to m do } \\ \text { Copy } \mathsf{N[i, 0]} = \mathsf{N[i, 1]} \end{cases} \end{array}
$$

Analysis

Running time is $O(mn)$ and space used is $O(2m) = O(m)$

Analyzing Space Efficiency

- **O** From the $m \times n$ matrix **M** we can construct the actual alignment (exercise)
- **2** Matrix **N** computes cost of optimal alignment but no way to construct the actual alignment
- Space efficient computation of alignment? More complicated algorithm — see text book.

Takeaway Points

- **1** Dynamic programming is based on finding a recursive way to solve the problem. Need a recursion that generates a small number of subproblems.
- \bullet Given a recursive algorithm there is a natural $\rm DAG$ associated with the subproblems that are generated for given instance; this is the dependency graph. An iterative algorithm simply evaluates the subproblems in some topological sort of this DAG.
- **3** The space required to evaluate the answer can be reduced in some cases by a careful examination of that dependency $\rm DAG$ of the subproblems and keeping only a subset of the DAG at any time.