# NP Completeness and Cook-Levin Theorem

Lecture 22 April 19, 2011

# P and NP and Turing Machines

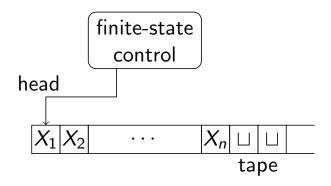
- P: set of decision problems that have polynomial time algorithms.
- NP: set of decision problems that have polynomial time non-deterministic algorithms.

Question: What is an algorithm? Depends on the model of computation!

What is our model of computation?

Formally speaking our model of computation is Turing Machines.

# Turing Machines: Recap



- Infinite tape.
- Finite state control.
- Input at beginning of tape.
- Special tape letter "blank" □.
- Head can move only one cell to left or right.

# Turing Machines: Formally

A TM  $M = (Q, \Sigma, \Gamma, \delta, q_0, q_{accept}, q_{reject})$ :

- Q is set of states in finite control
- ullet  $oldsymbol{q}_0$  start state,  $oldsymbol{q}_{accept}$  is accept state,  $oldsymbol{q}_{reject}$  is reject state
- $\Sigma$  is input alphabet,  $\Gamma$  is tape alphabet (includes  $\sqcup$ )
- $\delta: \mathbf{Q} \times \Gamma \to \{\mathbf{L}, \mathbf{R}\} \times \Gamma \times \mathbf{Q}$  is transition function
  - $\delta(q, a) = (q', b, L)$  means that M in state q and head seeing a on tape will move to state q' while replacing a on tape with b and head moves left.

L(M): language accepted by M is set of all input strings s on which M accepts; that is:

- TM is started in state  $q_0$ .
- Initially, the tape head is located at the first cell.
- The tape contain **s** on the tape followed by blanks.
- The TM halts in the state  $q_{accept}$ .

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## P via TMs

#### **Definition**

M is a polynomial time TM if there is some polynomial  $p(\cdot)$  such that on all inputs w, M halts in p(|w|) steps.

#### **Definition**

 $m{L}$  is a language in  $m{P}$  iff there is a polynomial time  $m{TM}$   $m{M}$  such that  $m{L} = m{L}(m{M})$ .

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## NP via TMs

#### Definition

 $\boldsymbol{L}$  is an  $\overline{NP}$  language iff there is a *non-deterministic* polynomial time  $\overline{TM}$   $\boldsymbol{M}$  such that  $\boldsymbol{L} = \boldsymbol{L}(\boldsymbol{M})$ .

Non-deterministic TM: each step has a choice of moves

- $\delta: \mathbf{Q} \times \Gamma \to \mathcal{P}(\mathbf{Q} \times \Gamma \times \{\mathbf{L}, \mathbf{R}\})$ .
  - Example:  $\delta(q, a) = \{(q_1, b, L), (q_2, c, R), (q_3, a, R)\}$  means that M can non-deterministically choose one of the three possible moves from (q, a).
- L(M): set of all strings s on which there exists some sequence of valid choices at each step that lead from  $q_0$  to  $q_{accept}$

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## Non-deterministic TMs vs certifiers

#### NP

Two definition of NP:

- **L** is in NP iff **L** has a polynomial time certifier  $C(\cdot, \cdot)$ .
- **L** is in NP iff **L** is decided by a non-deterministic polynomial time TM **M**.

#### Claim

Two definitions are equivalent.

#### Why?

Informal proof idea: the certificate t for C corresponds to non-deterministic choices of M and vice-versa. In other words L is in NP iff L is accepted by a NTM which first guesses a proof t of length poly in input |s| and then acts as a deterministic TM.

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# Non-determinism, guessing and verification

- A non-deterministic machine has choices at each step and accepts a string if there exists a set of choices which lead to a final state.
- Equivalently the choices can be thought of as *guessing* a solution and then *verifying* that solution. In this view all the choices are made a priori and hence the verification can be deterministic. The "guess" is the "proof" and the "verifier" is the "certifier".
- We reemphasize the asymmetry inherent in the definition of non-determinism. Strings in the language can be easily verified.
   No easy way to verify that a string is not in the language.

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# Algorithms: TMs vs RAM Model

Why do we use TMs some times and RAM Model other times?

- TMs are very simple: no complicated instruction set, no jumps/pointers, no explicit loops etc.
  - Simplicity is useful in proofs.
  - The "right" formal bare-bones model when dealing with subtleties.
- RAM model is a closer approximation to the running time/space usage of realistic computers for reasonable problem sizes
  - Not appropriate for certain kinds of formal proofs when algorithms can take super-polynomial time and space

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## "Hardest" Problems

#### Question

What is the hardest problem in NP? How do we define it?

#### Towards a definition

- Hardest problem must be in NP.
- Hardest problem must be at least as "difficult" as every other problem in NP.

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# **NP-Complete** Problems

#### **Definition**

A problem **X** is said to be **NP-Complete** if

- $X \in NP$ , and
- (Hardness) For any  $Y \in NP$ ,  $Y \leq_P X$ .

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# Solving NP-Complete Problems

#### **Proposition**

Suppose X is NP-Complete. Then X can be solved in polynomial time if and only if P = NP.

#### Proof.

- $\Rightarrow$  Suppose **X** can be solved in polynomial time
  - Let  $Y \in NP$ . We know  $Y \leq_P X$ .
  - We showed that if  $Y \leq_P X$  and X can be solved in polynomial time, then Y can be solved in polynomial time.
  - Thus, every problem  $Y \in \mathbb{NP}$  is such that  $Y \in P$ ;  $\mathbb{NP} \subseteq P$ .
  - Since  $P \subseteq NP$ , we have P = NP.
- $\Leftarrow$  Since P = NP, and  $X \in NP$ , we have a polynomial time algorithm for X.

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# NP-Hard Problems

## Definition

A problem X is said to be NP-HARD if

• (Hardness) For any  $Y \in NP$ ,  $Y \leq_P X$ 

An NP-HARD problem need not be in NP!

Example: Halting problem is NP-HARD (why?) but not NP-COMPLETE.

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# Consequences of proving NP-Completeness

#### If X is NP-COMPLETE

- Since we believe  $P \neq NP$ ,
- and solving X implies P = NP.
- **X** is unlikely to be efficiently solvable.

At the very least, many smart people before you have failed to find an efficient algorithm for X.

(This is proof by mob opinion — take with a grain of salt.)

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# **NP-Complete** Problems

## Question

Are there any problems that are NP-COMPLETE?

#### Answer

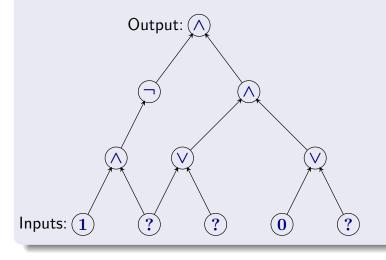
Yes! Many, many problems are NP-COMPLETE.

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## Circuits

#### **Definition**

A circuit is a directed acyclic graph with



- Input vertices (without incoming edges) labelled with
  0, 1 or a distinct variable
- Every other vertex is labelled
  ∨, ∧ or ¬
- Single node output vertex with no outgoing edges

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## Cook-Levin Theorem

## Definition (Circuit Satisfaction (CSAT).)

Given a circuit as input, is there an assignment to the input variables that causes the output to get value 1?

# Theorem (Cook-Levin)

**CSAT** is NP-COMPLETE.

Need to show

- **CSAT** is in NP
- every NP problem X reduces to CSAT.

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## **CSAT**: Circuit Satisfaction

#### Claim

**CSAT** is in NP.

- Certificate: Assignment to input variables.
- Certifier: Evaluate the value of each gate in a topological sort of DAG and check the output gate value.

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## **CSAT** is **NP**-hard: Idea

Need to show that every NP problem X reduces to CSAT.

What does it mean that  $X \in NP$ ?

 $X \in \mathbb{NP}$  implies that there are polynomials p() and q() and certifier/verifier program C such that for every string s the following is true:

- If s is a YES instance  $(s \in X)$  then there is a *proof* t of length p(|s|) such that C(s, t) says YES.
- If s is a NO instance  $(s \not\in X)$  then for every string t of length at p(|s|), C(s,t) says NO.
- C(s, t) runs in time q(|s| + |t|) time (hence polynomial time).

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# Reducing X to CSAT

X is in NP means we have access to  $p(), q(), C(\cdot, \cdot)$ . What is  $C(\cdot, \cdot)$ ? It is a program or equivalently a Turing Machine! How are p() and q() given? As numbers.

Example: if 3 is given then  $p(n) = n^3$ .

Thus an NP problem is essentially a three tuple  $\langle p, q, C \rangle$  where C is either a program or a TM.

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# Reducing X to CSAT

Thus an NP problem is essentially a three tuple  $\langle p, q, C \rangle$  where C is either a program or TM.

Problem X: Given string s, is  $s \in X$ ?

Same as the following: is there a proof t of length p(|s|) such that C(s, t) says YES.

How do we reduce X to CSAT? Need an algorithm A that

- takes s (and < p, q, C >) and creates a circuit G in polynomial time in |s| (note that < p, q, C > are fixed).
- G is satisfiable if and only if there is a proof t such that C(s, t) says YES.

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# Reducing X to CSAT

How do we reduce  $\boldsymbol{X}$  to CSAT? Need an algorithm  $\boldsymbol{\mathcal{A}}$  that

- takes s (and  $\langle p, q, C \rangle$ ) and creates a circuit G in polynomial time in |s| (note that  $\langle p, q, C \rangle$  are fixed).
- G is satisfiable if and only if there is a proof t such that C(s,t) says YES

Simple but Big Idea: Programs are essentially the same as Circuits!

- Convert C(s, t) into a circuit G with t as unknown inputs (rest is known including s)
- We know that |t| = p(|s|) so express boolean string t as p(|s|) variables  $t_1, t_2, \ldots, t_k$  where k = p(|s|).
- Asking if there is a proof t that makes C(s, t) say YES is same as whether there is an assignment of values to "unknown" variables  $t_1, t_2, \ldots, t_k$  that will make G evaluate to true/YES.

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# Example: Independent Set

- Problem: Does G = (V, E) have an **Independent Set** of size  $\geq k$ ?
  - Certificate: Set  $S \subseteq V$
  - Certifier: Check  $|S| \ge k$  and no pair of vertices in S is connected by an edge

Formally, why is **Independent Set** in NP?

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# Example: Independent Set

Formally why is **Independent Set** in NP?

- Input:
  - <  $n, y_{1,1}, y_{1,2}, \dots, y_{1,n}, y_{2,1}, \dots, y_{2,n}, \dots, y_{n,1}, \dots, y_{n,n}, k >$  encodes < G, k >.
    - *n* is number of vertices in *G*
    - $y_{i,j}$  is a bit which is 1 if edge (i,j) is in G and 0 otherwise (adjacency matrix representation)
    - **k** is size of independent set.
- Certificate:  $t = t_1 t_2 \dots t_n$ . Interpretation is that  $t_i$  is 1 if vertex i is in the independent set, 0 otherwise.

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# Certifier for Independent Set

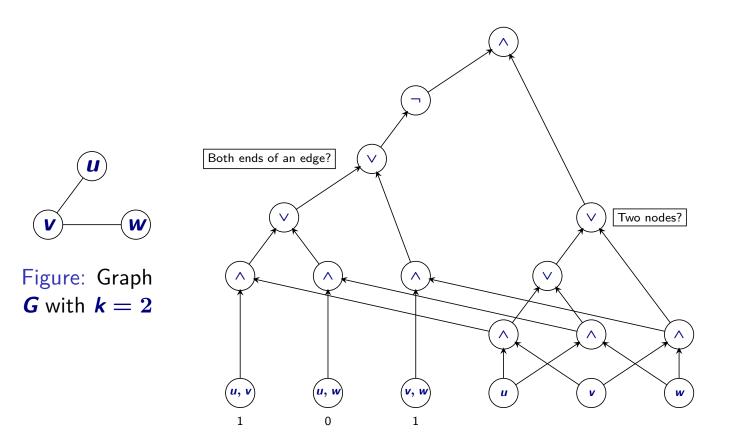
```
Certifier C(s, t) for Independent Set:
```

```
if (t_1+t_2+\ldots+t_n< k) then return NO else for each (i,j) do if (t_i \wedge t_j \wedge y_{i,j}) then return NO
```

return YES

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# Example: Independent Set



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## Circuit from Certifier

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# Programs, Turing Machines and Circuits

Consider "program" **A** that takes f(|s|) steps on input string **s**.

Question: What computer is the program running on and what does step mean?

Real computers difficult to reason with mathematically because

- instruction set is too rich
- pointers and control flow jumps in one step
- assumption that pointer to code fits in one word

#### **Turing Machines**

- simpler model of computation to reason with
- can simulate real computers with polynomial slow down
- all moves are local (head moves only one cell)

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## Certifiers that at TMs

Assume  $C(\cdot, \cdot)$  is a (deterministic) Turing Machine M

Problem: Given M, input s, p, q decide if there is a proof t of length p(|s|) such that M on s, t will halt in q(|s|) time and say YES.

There is an algorithm  $\mathcal{A}$  that can reduce above problem to **CSAT** mechanically as follows.

- $\mathcal{A}$  first computes p(|s|) and q(|s|).
- Knows that **M** can use at most q(|s|) memory/tape cells
- Knows that M can run for at most q(|s|) time
- Simulates the evolution of the state of M and memory over time using a big circuit.

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# Simulation of Computation via Circuit

- Think of M's state at time  $\ell$  as a string  $x^{\ell} = x_1 x_2 \dots x_k$  where each  $x_i \in \{0, 1, B\} \times Q \cup \{q_{-1}\}$ .
- At time 0 the state of M consists of input string s a guess t (unknown variables) of length p(|s|) and rest q(|s|) blank symbols.
- At time q(|s|) we wish to know if M stops in  $q_{accept}$  with say all blanks on the tape.
- We write a circuit  $\emph{\textbf{C}}_{\ell}$  which captures the transition of  $\emph{\textbf{M}}$  from time  $\ell$  to time  $\ell+1$ .
- ullet Composition of the circuits for all times 0 to  $m{q}(|m{s}|)$  gives a big (still poly) sized circuit  $m{\mathcal{C}}$
- The final output of  $\mathcal C$  should be true if and only if the entire state of M at the end leads to an accept state.

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## NP-Hardness of Circuit Satisfaction

Key Ideas in reduction:

- Use TMs as the code for certifier for simplicity
- Since p() and q() are known to A, it can set up all required memory and time steps in advance
- ullet Simulate computation of the TM from one time to the next as a circuit that only looks at three adjacent cells at a time

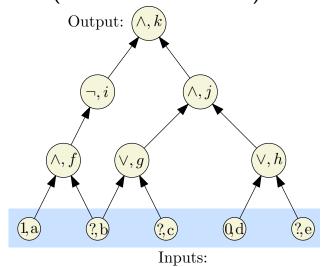
Note: Above reduction can be done to **SAT** as well. Reduction to **SAT** was the original proof of Steve Cook.

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# **SAT** is NP-Complete

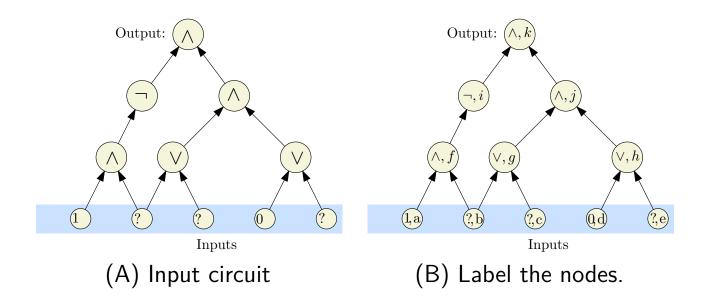
- We have seen that  $SAT \in NP$
- To show NP-HARDNESS, we will reduce Circuit Satisfiability (CSAT) to SAT

Instance of **CSAT** (we label each node):



# Converting a circuit into a CNF formula

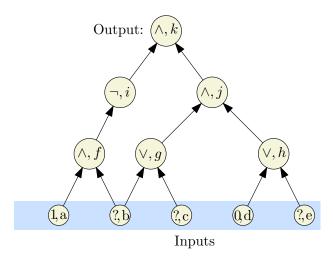
Label the nodes



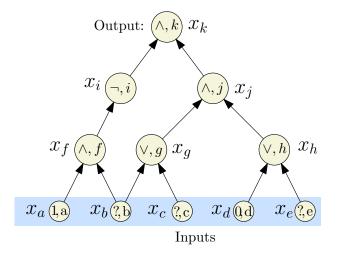
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# Converting a circuit into a CNF formula

Introduce a variable for each node



(B) Label the nodes.

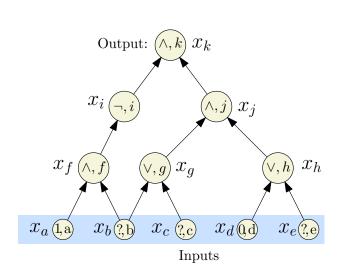


(C) Introduce var for each node.

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# Converting a circuit into a CNF formula

Write a sub-formula for each variable that is true if the var is computed correctly.



(C) Introduce var for each node.

 $egin{aligned} x_k & ext{ (Demand a sat' assignment!)} \ x_k &= x_i \wedge x_k \ x_j &= x_g \wedge x_h \ x_i &= \neg x_f \ x_h &= x_d \vee x_e \ x_g &= x_b \vee x_c \ x_f &= x_a \wedge x_b \ x_d &= 0 \ x_a &= 1 \end{aligned}$ 

(D) Write a sub-formula for each variable that is true if the var is computed correctly.

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# Converting a circuit into a CNF formula

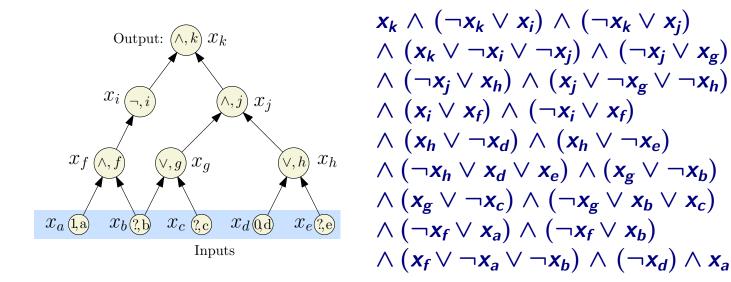
Convert each sub-formula to an equivalent CNF formula

$\boldsymbol{x_k}$	$\boldsymbol{x_k}$
$x_k = x_i \wedge x_j$	$(\neg x_k \lor x_i) \land (\neg x_k \lor x_j) \land (x_k \lor \neg x_i \lor \neg x_j)$
$x_j = x_g \wedge x_h$	$   (\neg x_j \lor x_g) \land (\neg x_j \lor x_h) \land (x_j \lor \neg x_g \lor \neg x_h) \land   $
$x_i = \neg x_f$	$(x_i \vee x_f) \wedge (\neg x_i \vee x_f) \wedge$
$x_h = x_d \lor x_e$	$(x_h \vee \neg x_d) \wedge (x_h \vee \neg x_e) \wedge (\neg x_h \vee x_d \vee x_e)$
$x_g = x_b \vee x_c$	$(x_g \vee \neg x_b) \wedge (x_g \vee \neg x_c) \wedge (\neg x_g \vee x_b \vee x_c)$
$x_f = x_a \wedge x_b$	$(\neg x_f \lor x_a) \land (\neg x_f \lor x_b) \land (x_f \lor \neg x_a \lor \neg x_b)$
$x_d = 0$	$\neg x_d$
$x_a = 1$	X <sub>a</sub>

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# Converting a circuit into a CNF formula

Take the conjunction of all the CNF sub-formulas



We got a CNF formula that is satisfiable if and only if the original circuit is satisfiable.

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# Reduction: $CSAT \leq_P SAT$

- ullet For each gate (vertex)  $oldsymbol{v}$  in the circuit, create a variable  $oldsymbol{x}_{oldsymbol{v}}$
- Case  $\neg$ :  $\mathbf{v}$  is labeled  $\neg$  and has one incoming edge from  $\mathbf{u}$  (so  $\mathbf{x}_{\mathbf{v}} = \neg \mathbf{x}_{\mathbf{u}}$ ). In SAT formula generate, add clauses  $(\mathbf{x}_{\mathbf{u}} \vee \mathbf{x}_{\mathbf{v}})$ ,  $(\neg \mathbf{x}_{\mathbf{u}} \vee \neg \mathbf{x}_{\mathbf{v}})$ . Observe that

$$x_v = \neg x_u$$
 is true  $\iff \frac{(x_u \lor x_v)}{(\neg x_u \lor \neg x_v)}$  both true.

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# Reduction: $CSAT \leq_P SAT$

Continued...

• Case  $\vee$ : So  $x_v = x_u \vee x_w$ . In **SAT** formula generated, add clauses  $(x_v \vee \neg x_u)$ ,  $(x_v \vee \neg x_w)$ , and  $(\neg x_v \vee x_u \vee x_w)$ . Again, observe that

$$x_v = x_u \lor x_w$$
 is true  $\iff (x_v \lor \neg x_u), (x_v \lor \neg x_w),$  all true.  $(\neg x_v \lor x_u \lor x_w)$ 

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# Reduction: $CSAT \leq_P SAT$

Continued...

• Case  $\wedge$ : So  $x_v = x_u \wedge x_w$ . In **SAT** formula generated, add clauses  $(\neg x_v \vee x_u)$ ,  $(\neg x_v \vee x_w)$ , and  $(x_v \vee \neg x_u \vee \neg x_w)$ . Again observe that

$$x_v = x_u \wedge x_w$$
 is true  $\iff (\neg x_v \vee x_u), (\neg x_v \vee x_w), (x_v \vee \neg x_u \vee \neg x_w)$  all true.

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# Reduction: $CSAT \leq_P SAT$

Continued...

- If v is an input gate with a fixed value then we do the following. If  $x_v = 1$  add clause  $x_v$ . If  $x_v = 0$  add clause  $\neg x_v$
- Add the clause  $x_v$  where v is the variable for the output gate

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## Correctness of Reduction

Need to show circuit C is satisfiable iff  $\varphi_C$  is satisfiable

- $\Rightarrow$  Consider a satisfying assignment **a** for **C** 
  - Find values of all gates in C under a
  - Give value of gate  $\mathbf{v}$  to variable  $\mathbf{x}_{\mathbf{v}}$ ; call this assignment  $\mathbf{a}'$
  - a' satisfies  $\varphi_{C}$  (exercise)
- $\leftarrow$  Consider a satisfying assignment **a** for  $\varphi_{\mathcal{C}}$ 
  - Let a' be the restriction of a to only the input variables
  - Value of gate  $\mathbf{v}$  under  $\mathbf{a'}$  is the same as value of  $\mathbf{x}_{\mathbf{v}}$  in  $\mathbf{a}$
  - Thus, a' satisfies C

#### **Theorem**

**SAT** is NP-Complete.

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# Proving that a problem X is NP-Complete

To prove **X** is NP-COMPLETE, show

- Show **X** is in NP.
  - certificate/proof of polynomial size in input
  - polynomial time certifier C(s, t)
- Reduction from a known NP-COMPLETE problem such as CSAT or SAT to X

SAT  $\leq_P X$  implies that every NP problem  $Y \leq_P X$ . Why? Transitivity of reductions:

 $Y \leq_P SAT$  and  $SAT \leq_P X$  and hence  $Y \leq_P X$ .

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# NP-Completeness via Reductions

- **CSAT** is NP-Complete.
- CSAT  $\leq_P$  SAT and SAT is in NP and hence SAT is NP-COMPLETE.
- SAT  $\leq_P$  3-SAT and hence 3-SAT is NP-COMPLETE.
- 3-SAT ≤<sub>P</sub> Independent Set (which is in NP) and hence Independent Set is NP-Complete.
- **Vertex Cover** is NP-Complete.
- Clique is NP-COMPLETE.

Hundreds and thousands of different problems from many areas of science and engineering have been shown to be NP-COMPLETE.

A surprisingly frequent phenomenon!

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