

Looking Back, Moving Forward



Computational Photography

Derek Hoiem, University of Illinois

Photo Credit
Lee Cullivan

Today

- Beyond this class...
- ICES forms
- Reminder: final project
 - Reports due Dec 14 11:59pm
 - Poster presentations on Dec 15 at 1:30pm on the first floor of Siebel
 - Half of class will present at one time, then switch
 - Everyone is assigned to review two posters (and should also look at the others that are of interest)

Project 5

- Incomplete list of excellent projects
 - <http://tliang7.web.engr.illinois.edu/cs445/proj5/> -- Good smooth blend results (cut-car is removed)
 - <http://geellis2.web.engr.illinois.edu/cs445/proj5/> -- Good additional video result
 - http://xwu68.web.engr.illinois.edu/cs445/proj5 -- Good additional video result
 - <http://jmakdah2.web.engr.illinois.edu/cs445/proj5/> -- Good additional video result
 - <http://kurtovc2.web.engr.illinois.edu/cs445/proj5/> -- Good explanation
 - <http://dsun18.web.engr.illinois.edu/cs445/proj5/> -- Good results for background/foreground movie

This course has provided fundamentals

- How photographs are captured from and relate to the 3D scene
- How to think of an image as: a signal to be processed, a graph to be searched, an equation to be solved
- How to manipulate photographs: cutting, growing, compositing, morphing, stitching
- Basic principles of computer vision: filtering, correspondence, alignment

What else is out there?

Lots!

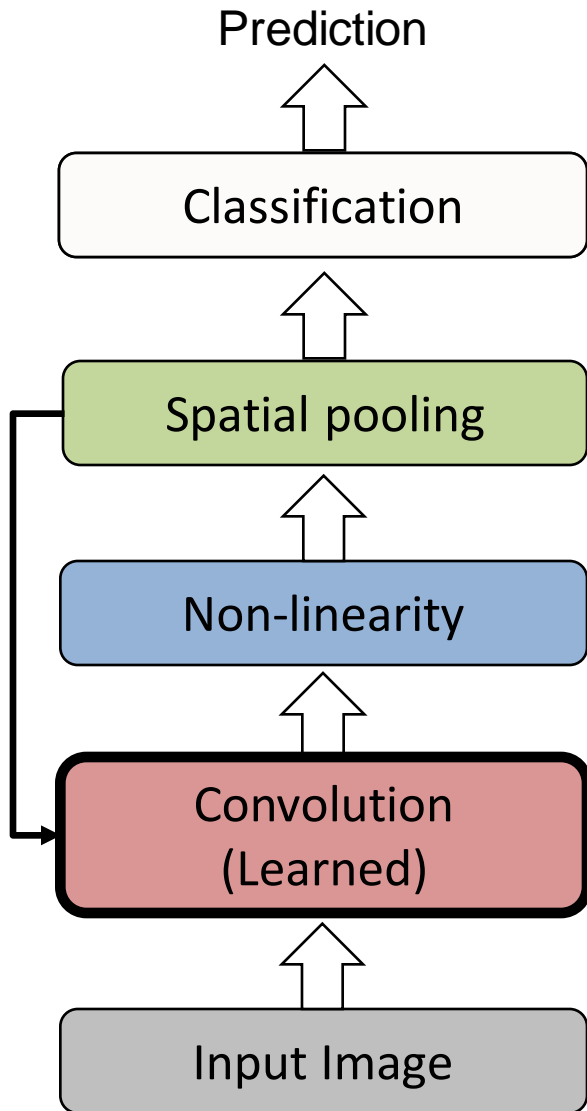
- Machine learning
- Videos and motion
- Scene understanding
- Modeling humans
- Better/cheaper devices
- ...

SIGGRAPH 2017 highlights

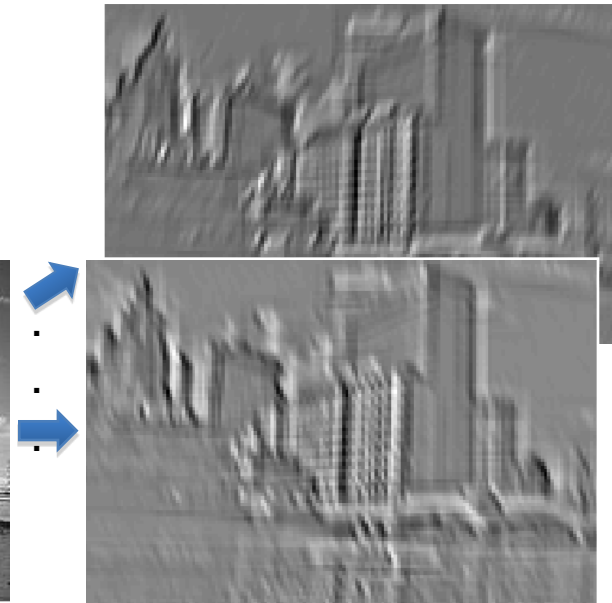
<http://s2017.siggraph.org/technical-papers>

Deep networks: new major influence

Key operations in a CNN

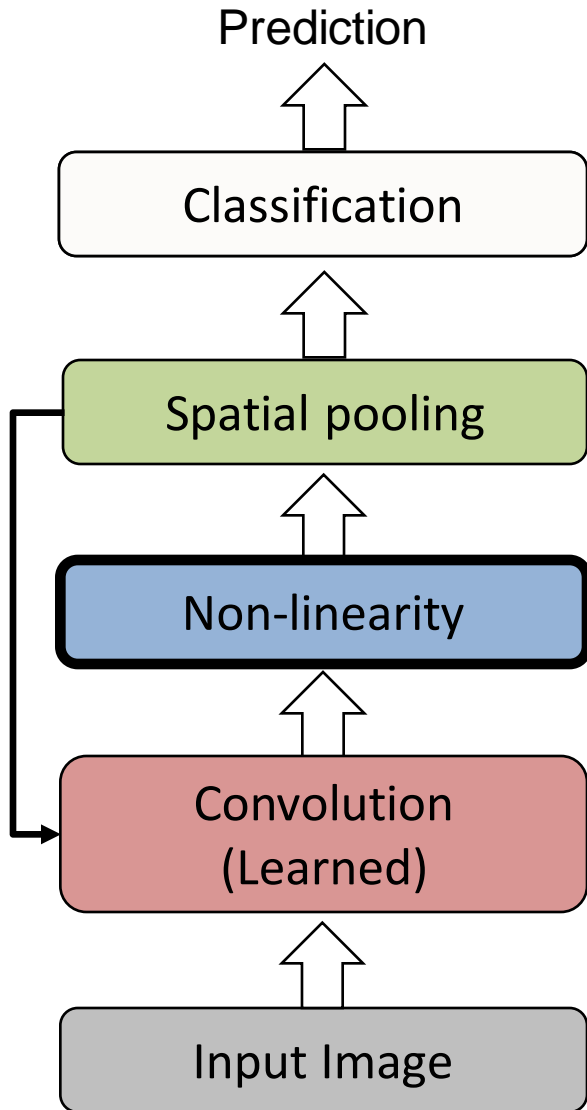


Input

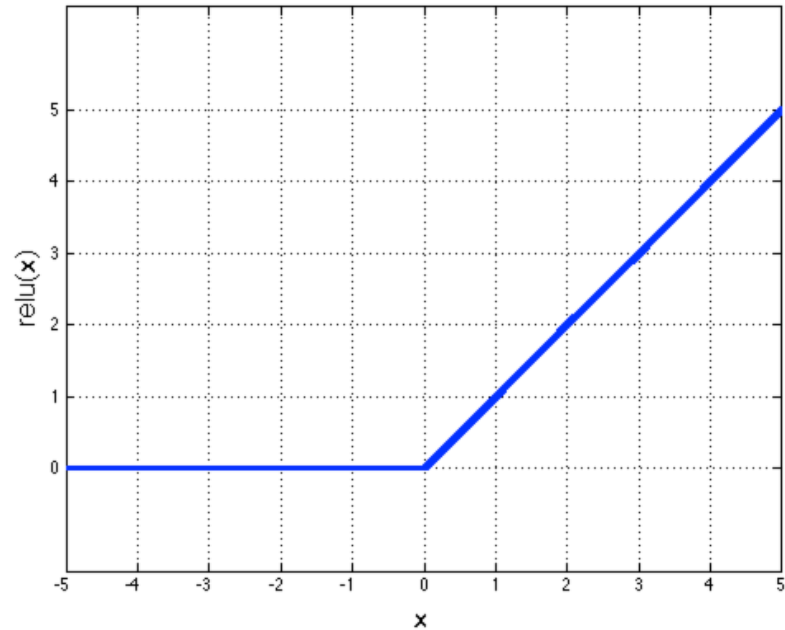


Feature Map

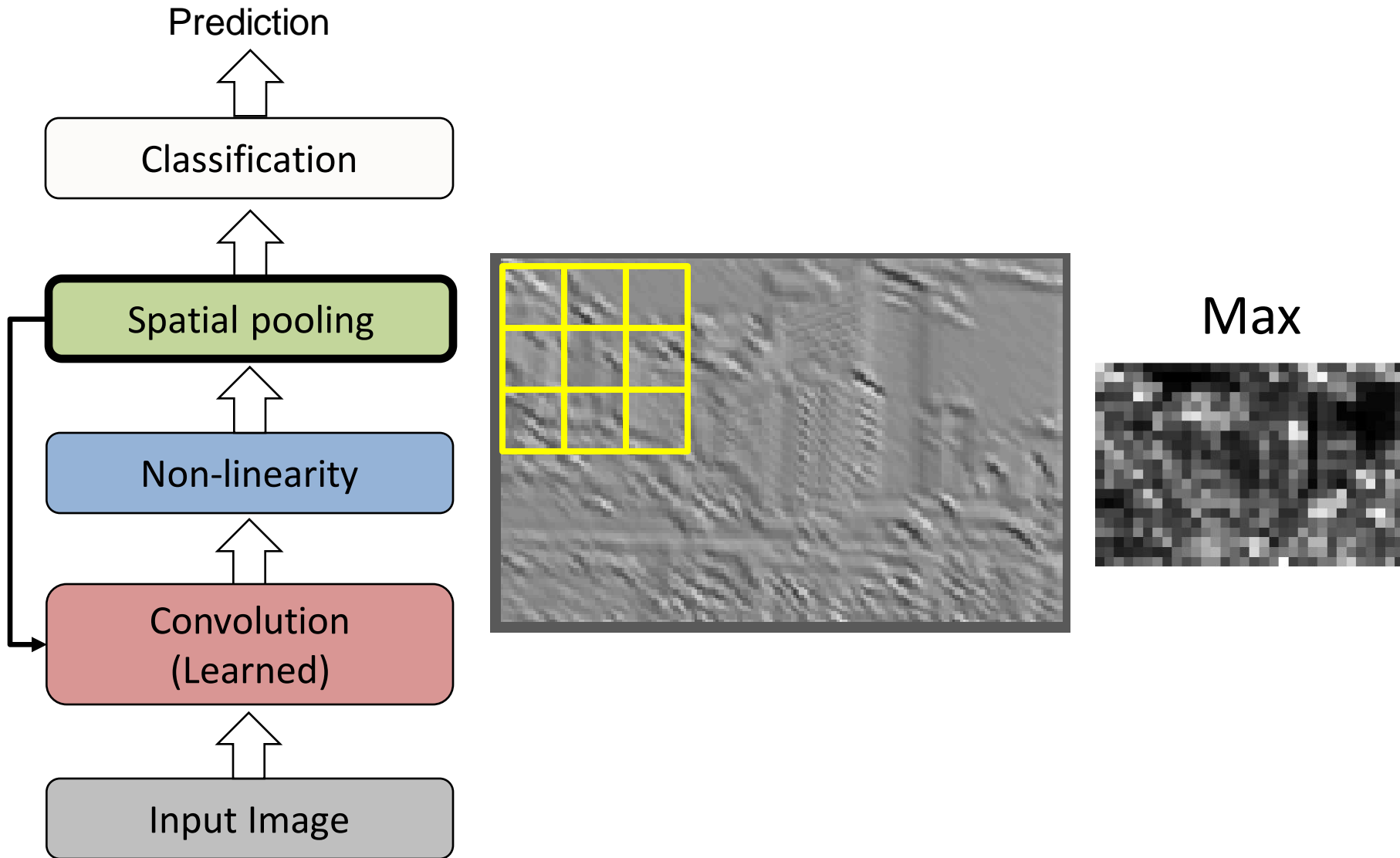
Key operations



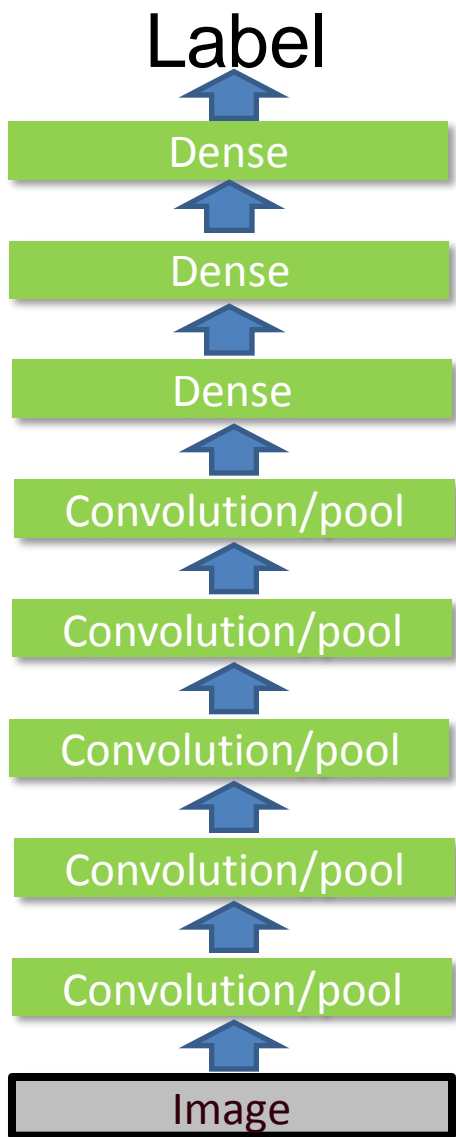
Rectified Linear Unit (ReLU)



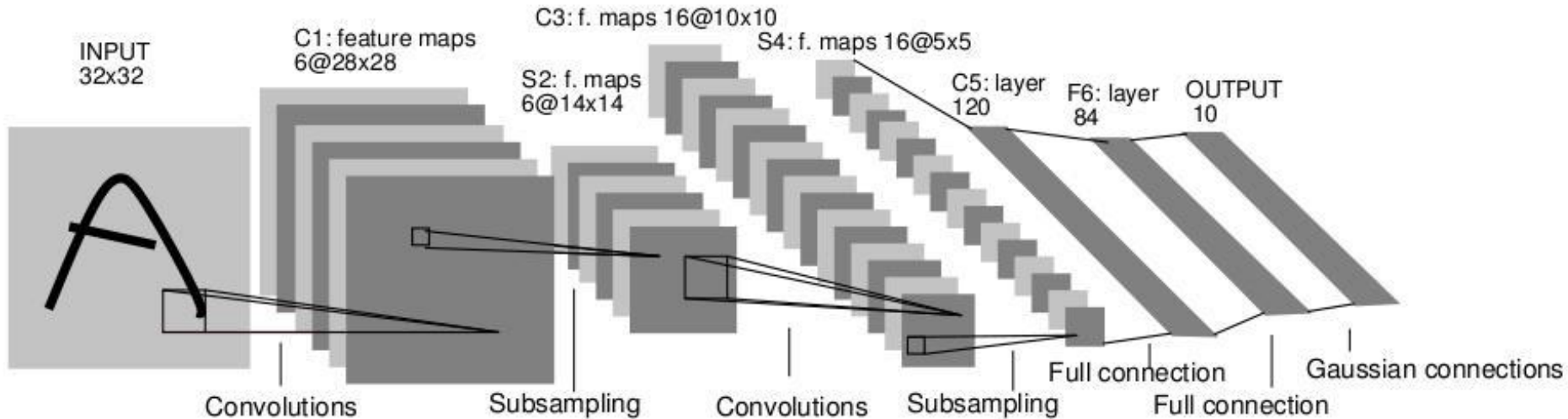
Key operations



Key idea: learn features and classifier that work well together (“end-to-end training”)



LeNet-5



- Average pooling
- Sigmoid or tanh nonlinearity
- Fully connected layers at the end
- Trained on MNIST digit dataset with 60K training examples

Y. LeCun, L. Bottou, Y. Bengio, and P. Haffner, Gradient-based learning applied to document recognition, Proc. IEEE 86(11): 2278–2324, 1998.

Image-to-Image Translation with Conditional Adversarial Networks

<https://phillipi.github.io/pix2pix/>

Phillip Isola

Jun-Yan Zhu

Tinghui Zhou

Alexei A. Efros

Berkeley AI Research (BAIR) Laboratory
University of California, Berkeley

`{isola, junyanz, tinghuiz, efros}@eecs.berkeley.edu`

Learn to map from one image representation to another

- Trained from input/output pairs
- Patch memorization is implicit through learned representation

Labels to Street Scene



input

output

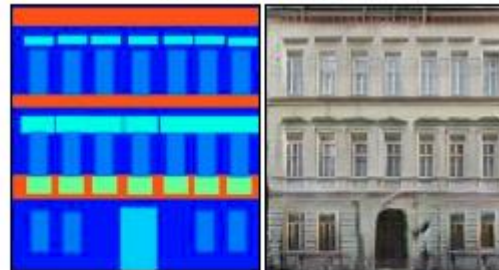
Aerial to Map



input

output

Labels to Facade



input

output

Day to Night



input

output

BW to Color



input

output

Edges to Photo



input

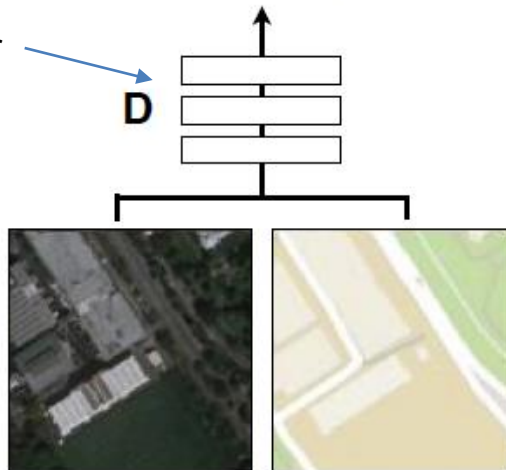
output

Learning to synthesize

Positive examples

Real or fake pair?

Scores NxN patches for realism

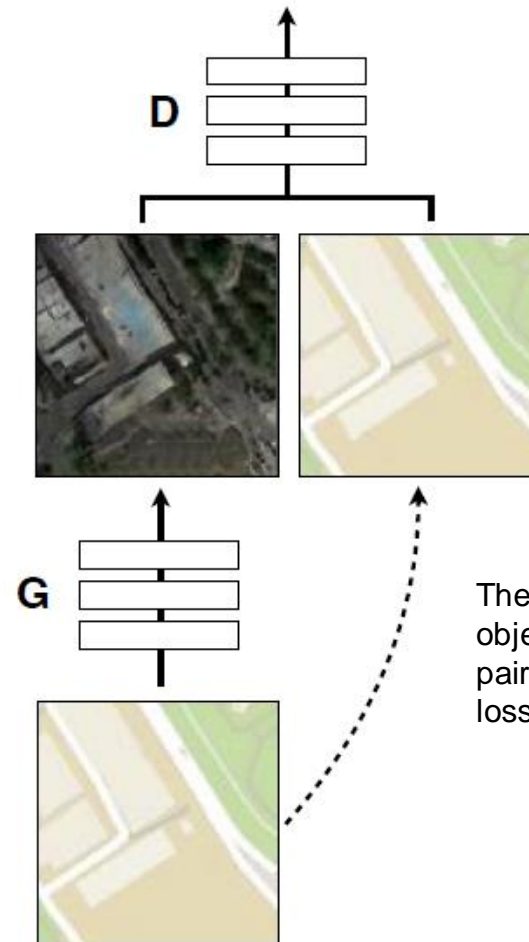


G tries to synthesize fake images that fool **D**

D tries to identify the fakes

Negative examples

Real or fake pair?

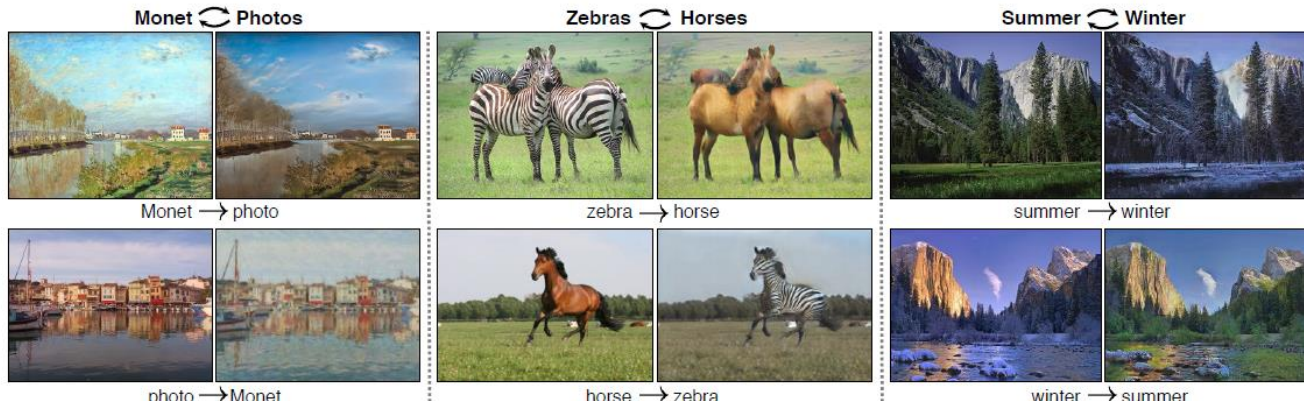


There is also an objective to produce the paired image with a L1 loss

CycleGAN

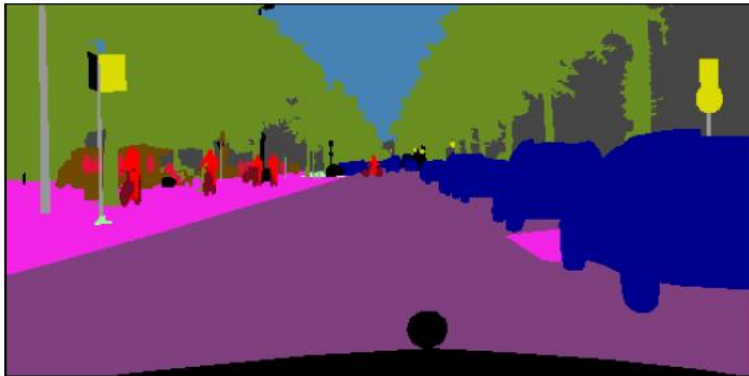
Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks

Jun-Yan Zhu* Taesung Park* Phillip Isola Alexei A. Efros
Berkeley AI Research (BAIR) laboratory, UC Berkeley



[https://www.youtube.com/watch?v=yL
CvWoQLnms](https://www.youtube.com/watch?v=yL
CvWoQLnms)

Image Synthesis

Qifeng Chen^{†‡}Vladlen Koltun[†]

(a) Input semantic layouts

(b) Synthesized images

Cascaded Refinement Network (iteratively upsample features and refine, no GAN)
+ L1 loss on VGG features

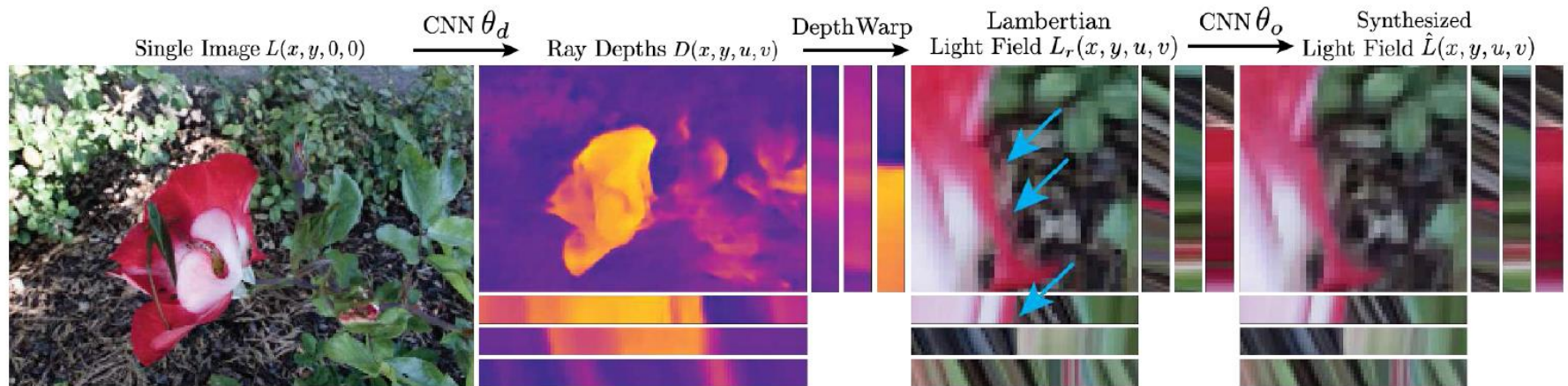
Image \rightarrow Light Field

Learning to Synthesize a 4D RGBD Light Field from a Single Image

Pratul P. Srinivasan¹, Tongzhou Wang¹, Ashwin Sreelal¹, Ravi Ramamoorthi², Ren Ng¹

¹University of California, Berkeley

²University of California, San Diego



<https://www.youtube.com/watch?v=yLCvWoQLnms>

Superresolution

EnhanceNet: Single Image Super-Resolution Through Automated Texture Synthesis

Mehdi S. M. Sajjadi Bernhard Schölkopf Michael Hirsch



Bicubic

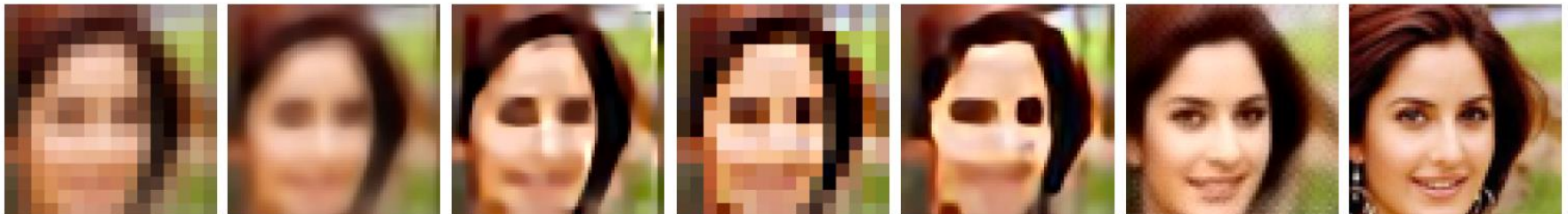
ENet-E

ENet-PAT

Ground Truth

E: Optimize least squares objective with upsampling network

PAT: Optimize “perceptual” (VGG features) loss, adversarial loss, texture corr loss



(a) Input

(b) SR [18]

(c) SR [18]+Deblur [33]

(d) Deblur [33]

(e) Deblur [33]+SR [18]

(f) Ours

(g) GT

Learning to Super-Resolve Blurry Face and Text Images

Pretty similar to above, more limited domain

Xiangyu Xu^{1,2,3} Deqing Sun^{3,4} Jinshan Pan⁵ Yujin Zhang¹

Hanspeter Pfister³ Ming-Hsuan Yang²

¹Tsinghua University ²University of California, Merced ³Harvard University

⁴Nvidia ⁵Nanjing University of Science & Technology

De-beautification

Makeup-Go: Blind Reversion of Portrait Edit*

Ying-Cong Chen¹ Xiaoyong Shen² Jiaya Jia^{1,2}

¹The Chinese University of Hong Kong ²Tencent Youtu Lab

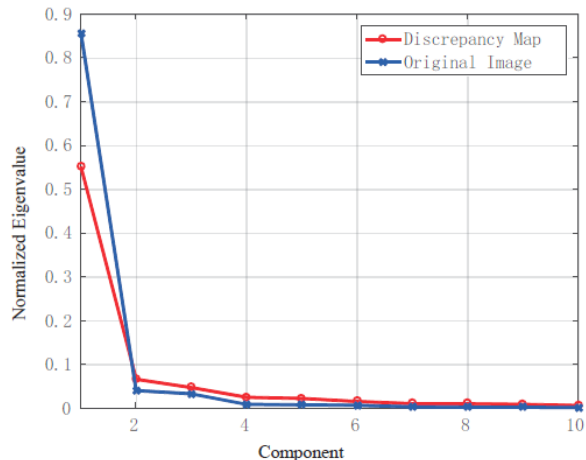
ycchen@cse.cuhk.edu.hk dylanshen@tencent.com leojia9@gmail.com



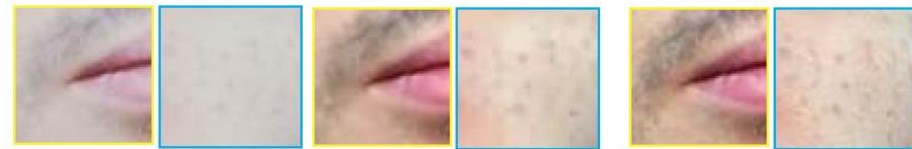
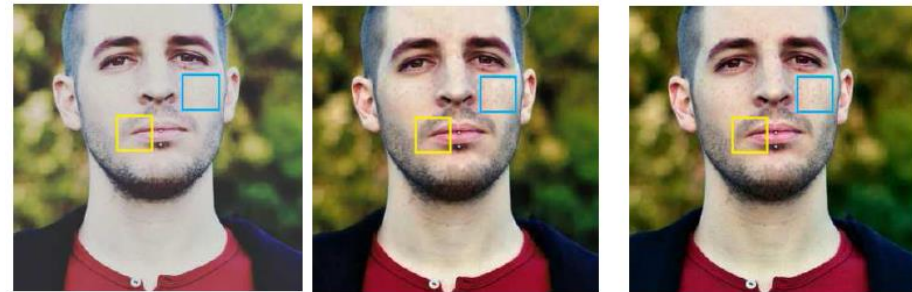
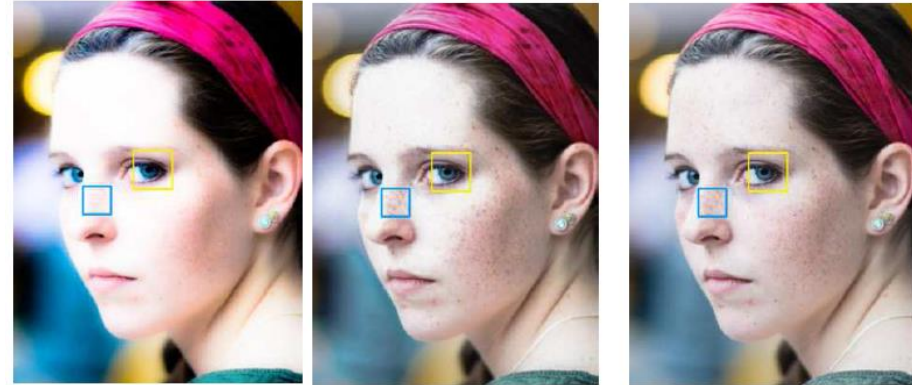
(a) Original Image



(b) Discrepancy Map



(c) Normalized Eigenvalue Distribution



(a) Edited Image

(d) Ours

(e) Ground truth

Network regresses principal components of discrepancy map

LDR --> HDR

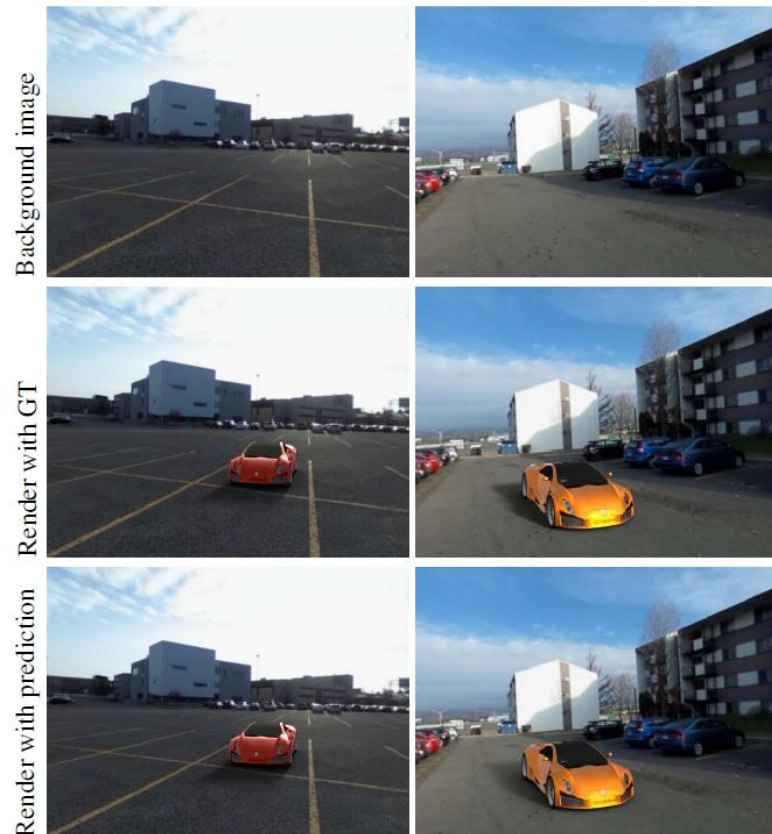
Learning High Dynamic Range from Outdoor Panoramas

Jinsong Zhang Jean-François Lalonde
Université Laval, Québec, Canada

jinsong.zhang.1@ulaval.ca, jflalonde@gel.ulaval.ca

<http://www.jflalonde.ca/projects/learningHDR>

- Regress HDR from one LDR image
- Train on synthetic data
- Limited to outdoor scenes, rotated so that sun is on top



Smarter user assistance

- Handwriting beautification (Zitnick SG'13)
- 3D object modeling (Chen et al. SGA'13)
- 3D object modeling (Kholgade et al. SG'14)

Video and motion

- Video = sequence of images
 - Track points → optical flow, tracked objects, 3D reconstruction
 - Find coherent space-time regions → segmentation
 - Recognizing actions and events
- Examples:
 - Point tracking for structure-from-motion
 - Boujou 1
 - Facial transfer: Xu et al. SG2014

Scene understanding

Interpret image in terms of scene categories, objects, surfaces, interactions, goals, etc.



- Remove the guy lying down (Alyosha)
- Make the woman dance or the guy get up
- Fill in the window with bricks
- Find me images with only Alyosha and Pietro

Scene understanding

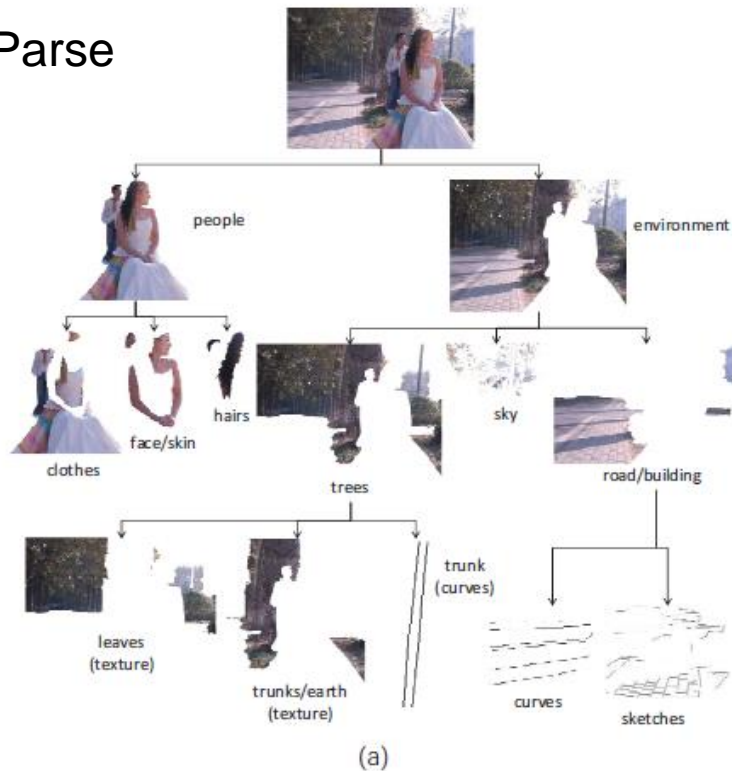
- Mostly unsolved, but we're getting there (especially for graphics purposes)
- Examples
 - “From Image Parsing to Painterly Rendering” (Zeng et al. 2010)
 - “Sketch2Photo: Internet Image Montage” (Chen et al. 2009)
 - Editing via scene attributes (Laffont et al. 2014)

Image Parsing to Painterly Rendering



Image Parsing to Painterly Rendering

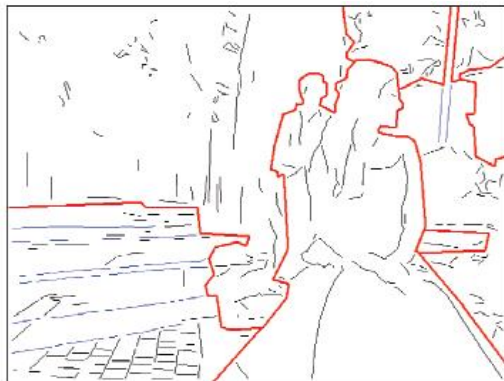
Parse



Brush Strokes



Sketch



Brush Orientations



Image Parsing to Painterly Rendering



Image Parsing to Painterly Rendering



More examples

- Sketch2photo:

<http://www.youtube.com/watch?v=dW1Epl2LdFM>

- Animating still photographs



**Animating Pictures
with Stochastic
Motion Textures**

Modeling humans

- Estimating pose and shape
 - <http://clothingparsing.com/>
 - Parselets (Dong et al., ICCV 2013)



- Motion capture
- 3D face from image (Kemelmacher ICCV'13)

Better and simpler 3D reconstruction

MobileFusion (2015): https://youtu.be/8M_-lSYqACo

Questions, Looking Forward

- How can we get computers to understand scenes (make predictions, describe them, etc.)?
- How can we design programs where semi-smart computers and people collaborate?
- What if we just capture and store the whole visual world (think StreetView)?
- How will photography change when depth cameras become standard?

How can you learn more?

- Relevant courses
 - Production graphics (CS 419)
 - Machine learning (CS 446 and others)
 - Computer vision (CS 543)
 - Optimization methods (w/ David Forsyth)
 - Parallel processing / GPU
 - HCI, data mining, NLP, robotics

Computer vision (with Prof Lazebnik Spring 2018)

Similar stuff to CP

- Camera models, filtering, single-view geometry, light and capture

New stuff

- Mid-level vision
 - Edge detection, clustering, segmentation
- Recognition
 - Image features and classifiers
 - Object category recognition
 - Action/activity recognition
- Videos
 - Tracking, optical flow
 - Structure from motion
- Multi-view geometry

How do you learn more?

Explore!

Thank you!

ICES forms and Feedback