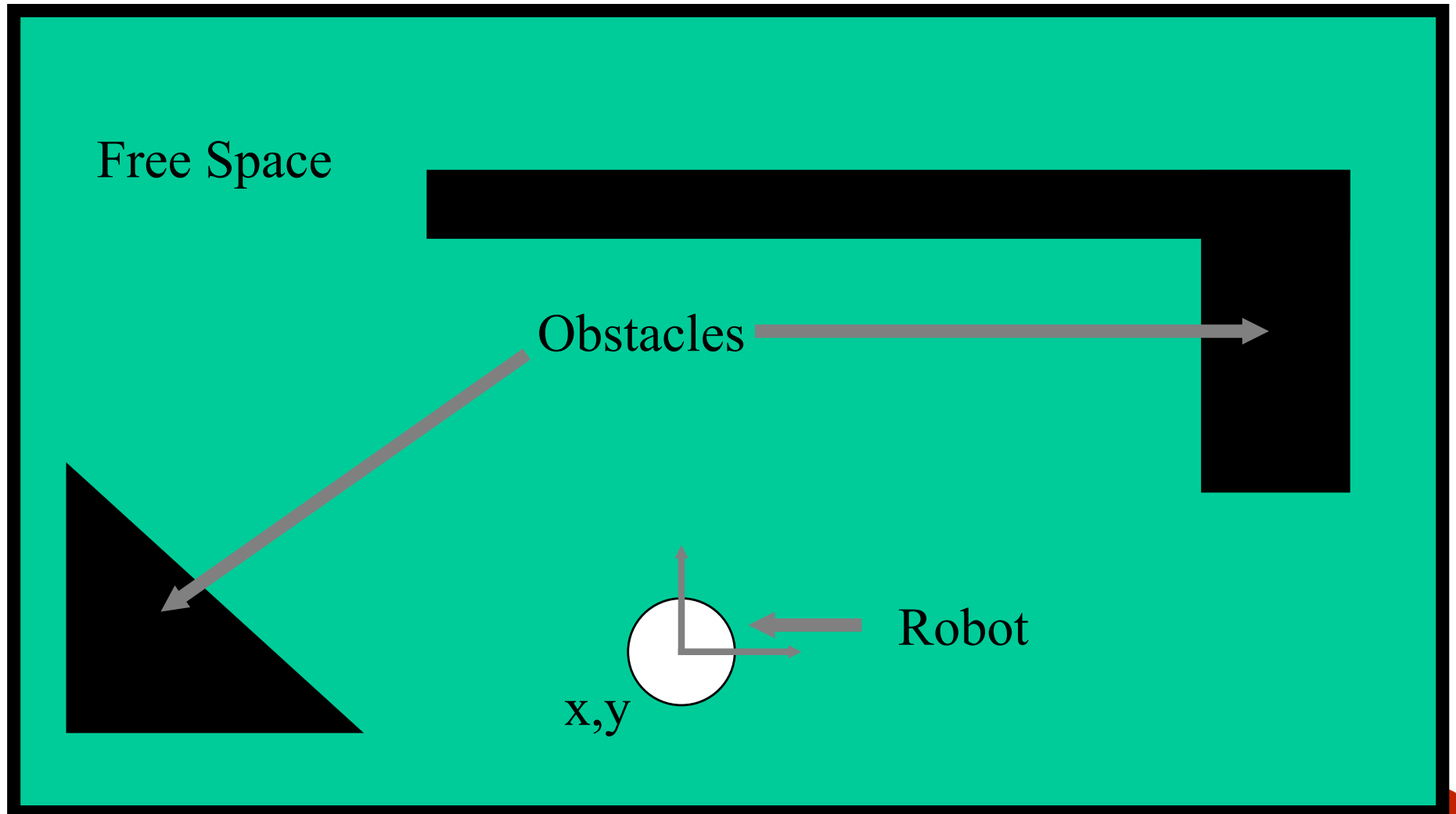


# Example of a World (and Robot)



# Configuration Space: Accommodate Robot Size

