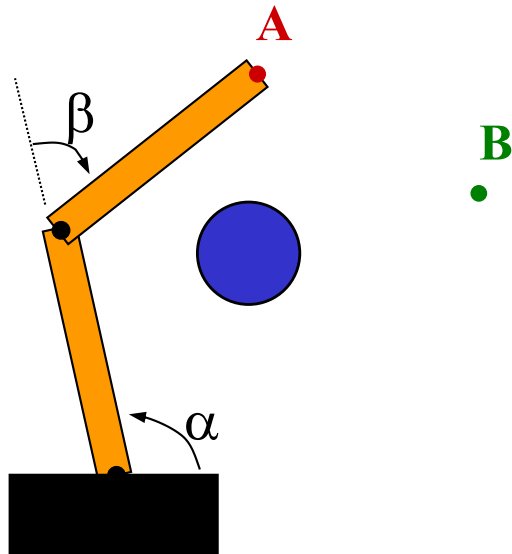
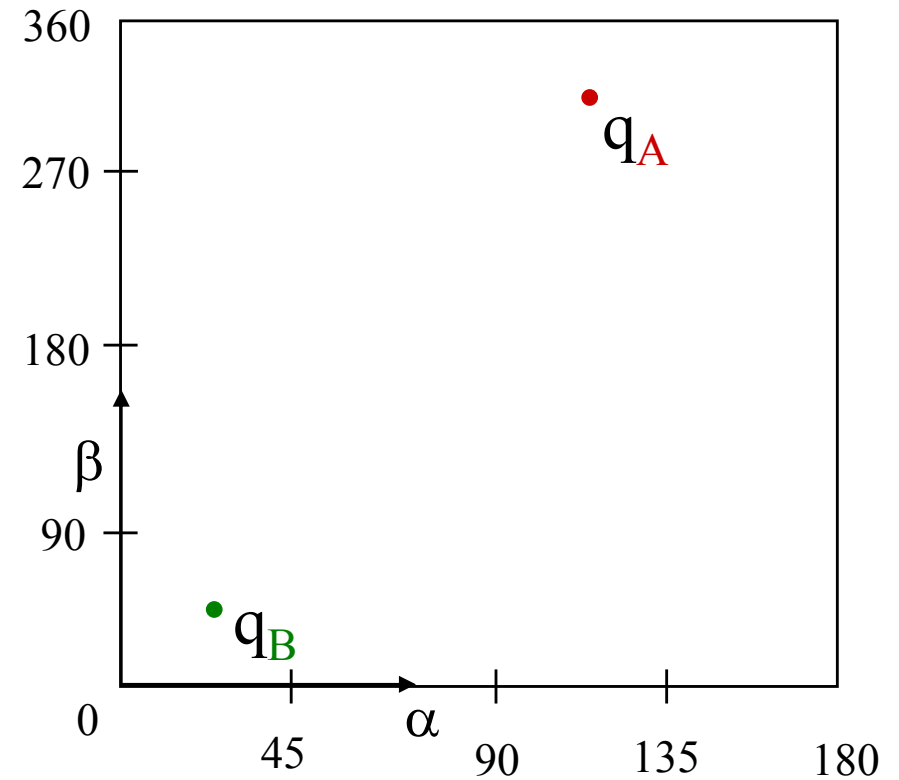


Configuration Space “Quiz”

Where do we put  ?



An obstacle in the robot's workspace

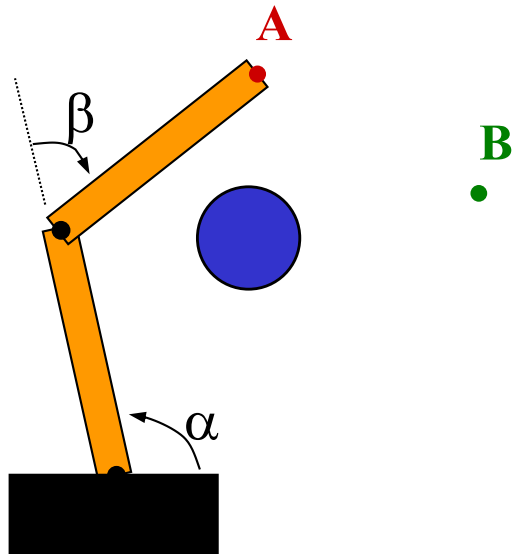


Torus
(wraps vertically)

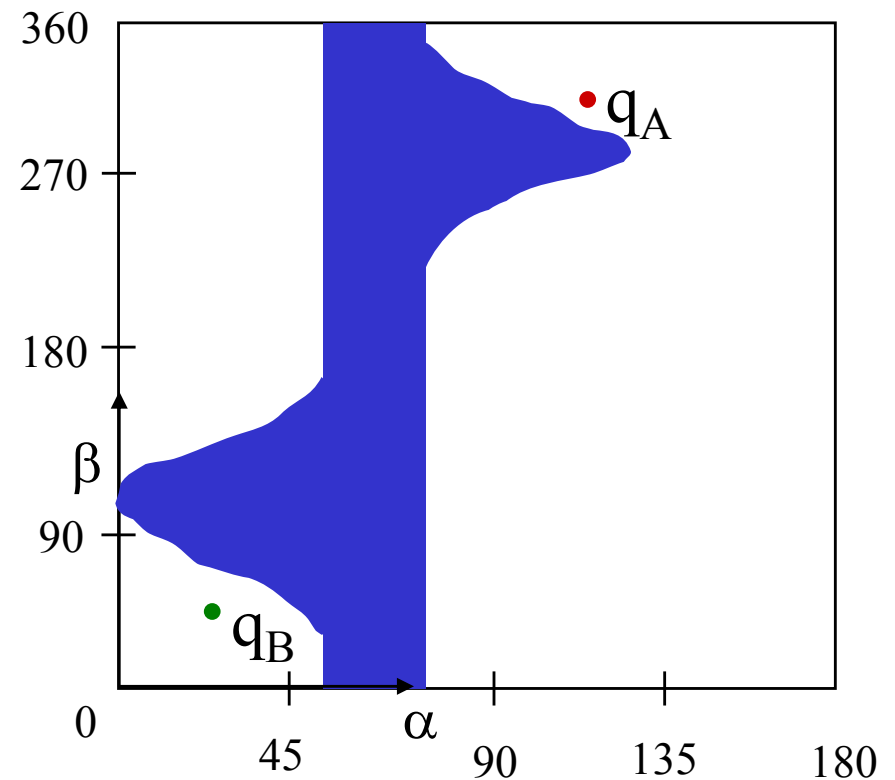
Configuration Space Obstacle

How do we get from **A** to **B** ?

Reference *configuration*

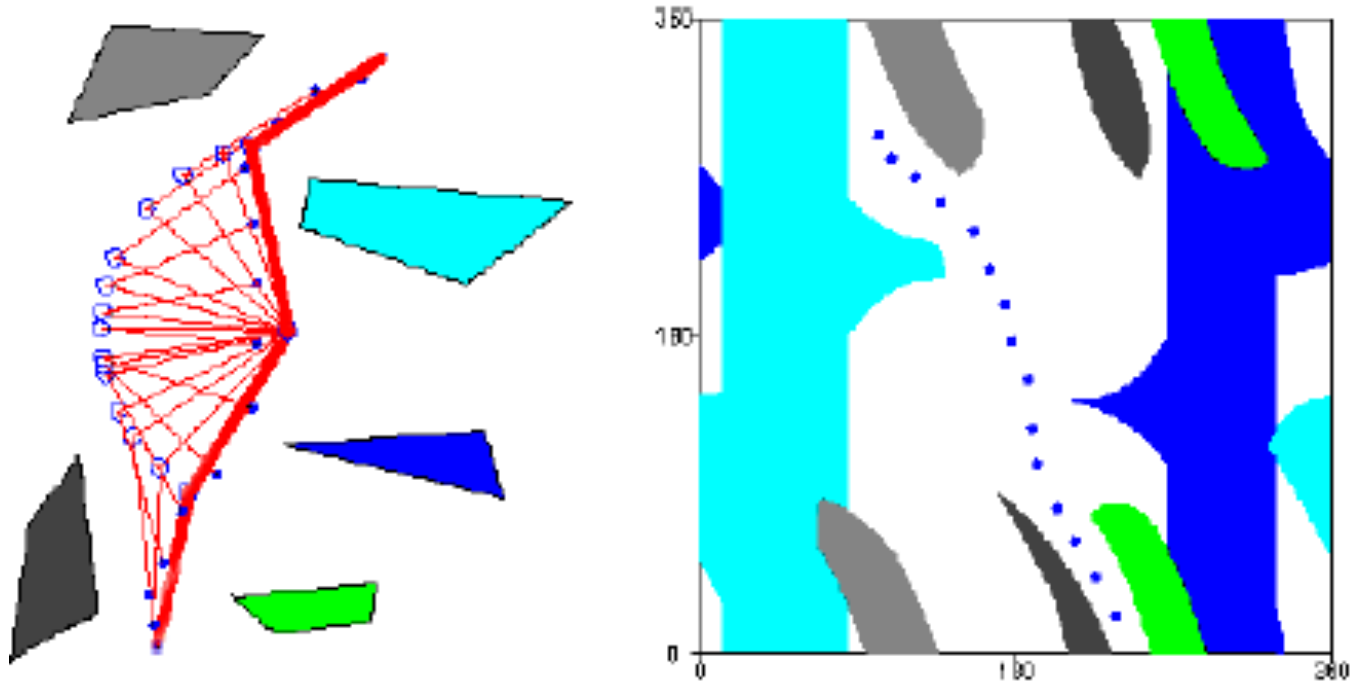


An obstacle in the robot's workspace



The C-space representation
of this obstacle...

Two Link Path



Thanks to Ken Goldberg

Two Link Path

