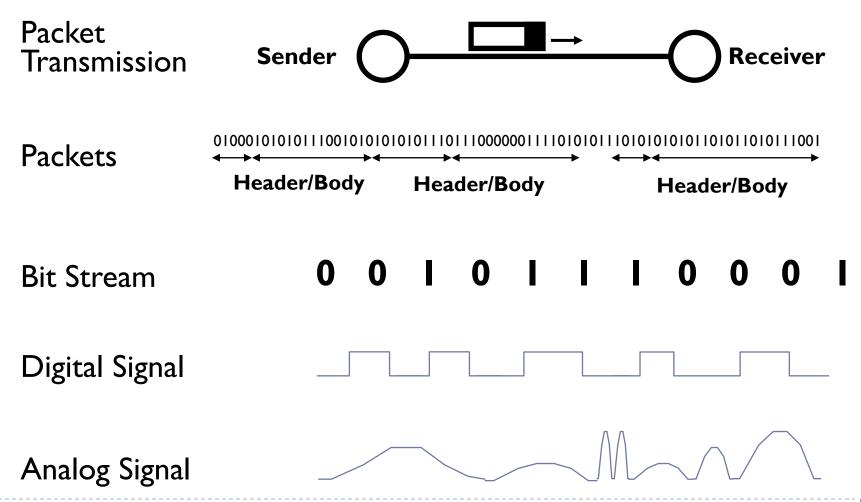
CS/ECE 439: Wireless Networking

Physical Layer – Coding and Modulation

From Signals to Packets



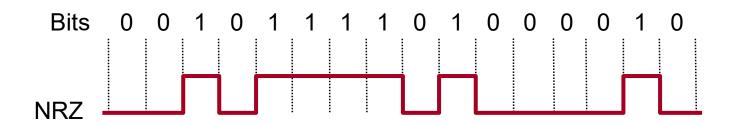
Binary Voltage Encoding

- Common binary voltage encodings
 - Non-return to zero (NRZ)
 - NRZ inverted (NRZI)
 - Manchester (used by IEEE 802.3—10 Mbps Ethernet)
 - ▶ 4B/5B



Non-Return to Zero (NRZ)

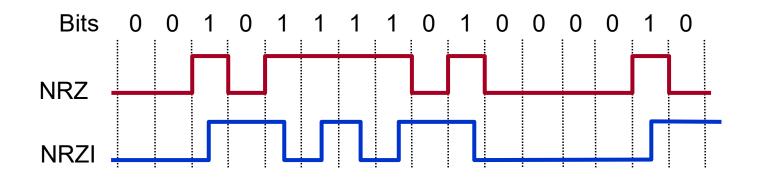
- Signal to Data
 - ▶ High
 - ► Low ⇒ 0
- Comments
 - Transitions maintain clock synchronization
 - Long strings of 0s confused with no signal
 - Long strings of Is causes baseline wander
 - Both inhibit clock recovery





Non-Return to Zero Inverted (NRZI)

- Signal to Data
 - ▶ Transition
 - Maintain ⇒ 0
- Comments
 - Solves series of Is, but not 0s





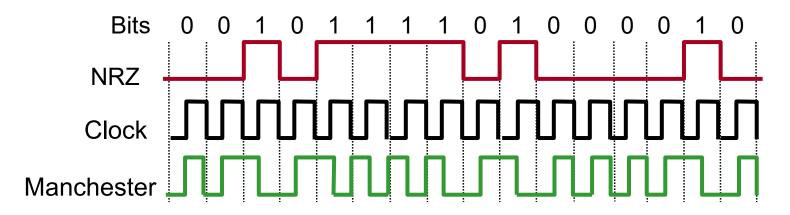
Manchester Encoding

Signal to Data

- XOR NRZ data with clock
- ▶ High to low transition
- ▶ Low to high transition

Comments

- (used by IEEE 802.3—10 Mbps Ethernet)
- Solves clock recovery problem
- ▶ Only 50% efficient (½ bit per transition)





4B/5B

Signal to Data

▶ Encode every 4 consecutive bits as a 5 bit symbol

Symbols

- At most I leading 0
- At most 2 trailing 0s
- Never more than 3 consecutive 0s
- Transmit with NRZI

Comments

- ▶ 16 of 32 possible codes used for data
- At least two transitions for each code
- ▶ 80% efficient



4B/5B – Data Symbols

At most 1 leading 0

At most 2 trailing 0s

▶ 0000 ⇒	11110		1000 =
▶ 0001 ⇒	01001		1001 =
> 0010 ⇒	10 <mark>100</mark>	-	1010 =
> 0011 ⇒	10 <mark>101</mark>		1011 =
▶ 0100 ⇒	01010		1100 =
▶ 0101 ⇒	01011		1101 =
▶ 0110 ⇒	01 <mark>110</mark>		1110 =
▶ 0111 ⇒	01 <mark>111</mark>		1111 =



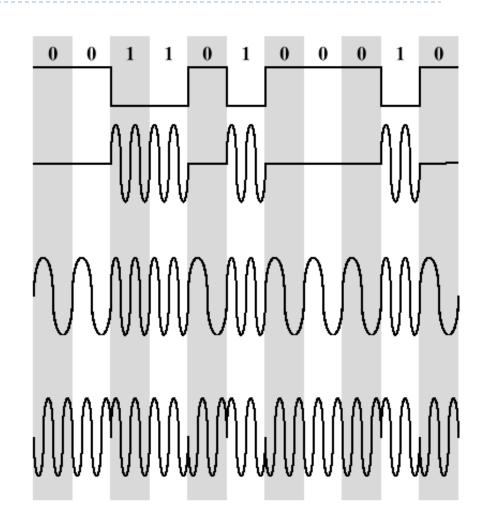
4B/5B – Control Symbols

```
\blacktriangleright | | | | | \Rightarrow
                     idle
▶ 11000 ⇒
                     start of stream I
▶ 10001 ⇒
                     start of stream 2
▶ 01101 ⇒
                     end of stream I
▶ 00111 ⇒
                     end of stream 2
> 00100 ⇒
                     transmit error
\triangleright Other \Rightarrow
                            invalid
```



Basic Modulation Techniques

- Encode digital data in an analog signal
- Amplitude-shift keying (ASK)
 - Amplitude difference of carrier frequency
- Frequency-shift keying (FSK)
 - Frequency difference near carrier frequency
- Phase-shift keying (PSK)
 - Phase of carrier signal shifted



Amplitude-Shift Keying

- Binary digit (I)
 - Represented by presence of carrier, at constant amplitude
- Binary digit (0)
 - Represented by absence of carrier

$$s(t) = \begin{cases} A\cos(2\pi f_c t) & \text{binary 1} \\ 0 & \text{binary 0} \end{cases}$$

- where the carrier signal is $A\cos(2\pi f_c t)$
- Inefficiencies
 - Sudden gain changes
 - Only used when bandwidth is not a concern, e.g. on voice lines (< 1200 bps) or on digital fiber



Binary Frequency-Shift Keying (BFSK)

- Binary digits (0 and 1)
 - Represented by two different frequencies near the carrier frequency

$$s(t) = \begin{cases} A\cos(2\pi f_1 t) & \text{binary 1} \\ A\cos(2\pi f_2 t) & \text{binary 0} \end{cases}$$

- where f_1 and f_2 are offset from carrier frequency f_c by equal but opposite amounts
- Less susceptible to error than ASK
- Sometimes used for radio (3 to 30 MHz) or coax
- Demodulator looks for power around f₁ and f₂



Multiple Frequency-Shift Keying (MFSK)

- More than two frequencies are used
 - More bandwidth efficient but more susceptible to error

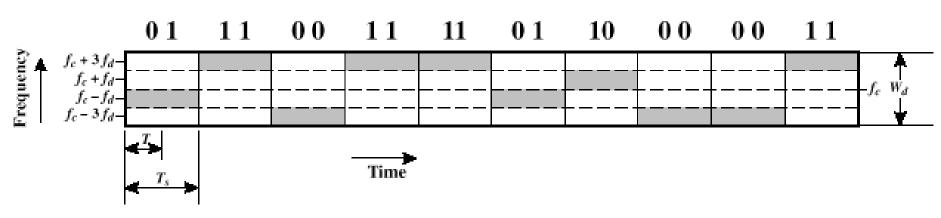
$$s_i(t) = A\cos 2\pi f_i t \quad 1 \le i \le M$$

- $f_i = f_c + (2i I M)f_d$
- f_c = the carrier frequency
- f_d = the difference frequency
- $M = \text{number of different signal elements} = 2^{L}$
- L = number of bits per signal element



Multiple Frequency-Shift Keying (MFSK)

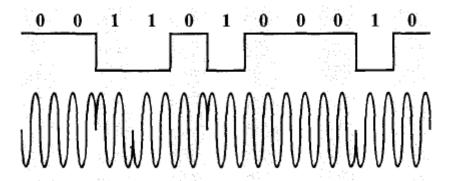
- More than two frequencies are used
 - More bandwidth efficient but more susceptible to error
- Each symbol represents L bits
 - Symbol length is T_s =LT seconds, where T is the bit period



- Two-level PSK (BPSK)
 - Uses two phases to represent binary digits

$$s(t) = \begin{cases} A\cos(2\pi f_c t) & \text{binary 1} \\ A\cos(2\pi f_c t + \pi) & \text{binary 0} \end{cases}$$
$$= \begin{cases} A\cos(2\pi f_c t) & \text{binary 1} \\ -A\cos(2\pi f_c t) & \text{binary 0} \end{cases}$$

- Differential PSK (DPSK)
 - Phase shift with reference to previous bit
 - ▶ Binary 0
 - ☐ Signal of same phase as previous signal burst
 - Binary I
 - ☐ Signal of opposite phase to previous signal burst



Four-level PSK (QPSK)

- Each element represents more than one bit
- \triangleright Ex. Phase shift of multiples of 2π (90°)

$$S(t) = \begin{cases} A\cos\left(2\pi f_c t + \frac{\pi}{4}\right) & 11\\ A\cos\left(2\pi f_c t + \frac{3\pi}{4}\right) & 01\\ A\cos\left(2\pi f_c t - \frac{3\pi}{4}\right) & 00\\ A\cos\left(2\pi f_c t - \frac{\pi}{4}\right) & 10 \end{cases}$$

Multilevel PSK

- Each angle has more than one amplitude
- Multiple signals elements

$$D = \frac{R}{L} = \frac{R}{\log_2 M}$$

- D = modulation rate, baud
- R = data rate, bps
- ▶ $M = number of different signal elements = 2^{L}$
- L = number of bits per signal element



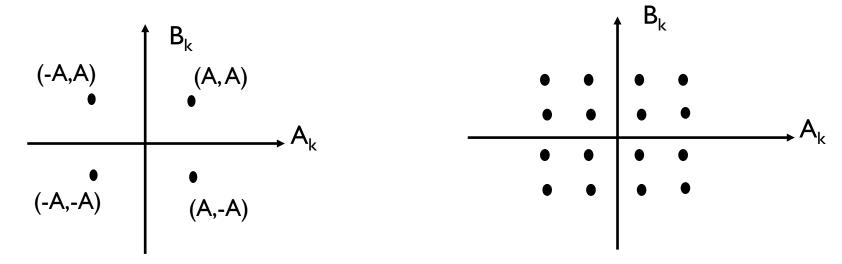
Quadrature Amplitude Modulation (QAM)

- QAM uses two-dimensional signaling
 - ASK and PSK
 - A_k modulates in-phase $\cos(2\pi f_c t)$
 - ▶ B_k modulates quadrature phase $sin(2\pi f_c t)$

$$s(t) = A_k(t)\cos 2\pi f_c t + B_k(t)\sin 2\pi f_c t$$

Signal Constellations

- Each pair (A_k, B_k) defines a point in the plane
- Signal constellation set of signaling points

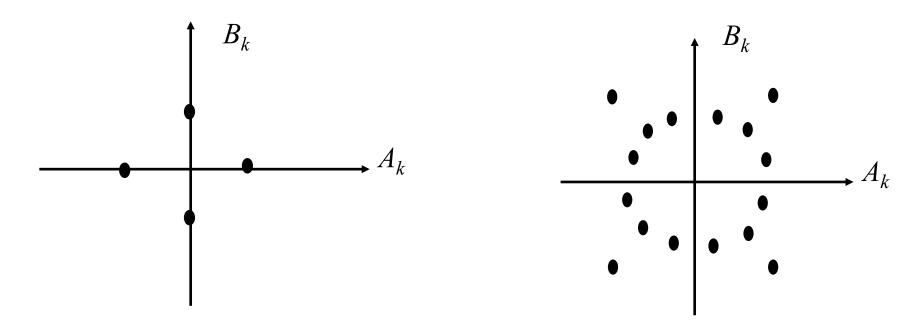


4 possible points per *T* sec. 2 bits / pulse

16 possible points per *T* sec.4 bits / pulse

Other Signal Constellations

Point selected by amplitude & phase



4 possible points per T sec.

16 possible points per T sec.



Adapting to Channel Conditions

- Channel conditions vary
 - Physical environment of the channel
 - Changes over time (slow and fast fading)
- Fixed coding/modulation scheme will often be inefficient
 - Too conservative for good channels
 - Too aggressive for bad channels
- Adjust coding/modulation based on channel conditions – "rate" adaptation
 - Controlled by the MAC protocol
 - E.g. 802. I Ia: BPSK QPSK 16-QAM 64 QAM Good



Some Examples

Gaussian Frequency Shift Keying

- ► I/-I is a positive/negative frequency shift from base
- Gaussian filter is used to smooth pulses— reduces the spectral bandwidth — "pulse shaping"
- Used in Bluetooth

Differential quadrature phase shift keying

- Variant of "regular" frequency shift keying
- Symbols are encoded as changes in phase
- Requires decoding on $\pi/4$ phase shift
- Used in 802.11b networks

Quadrature Amplitude modulation

- Combines amplitude and phase modulation
- Uses two amplitudes and 4 phases to represent the value of a 3 bit sequence

