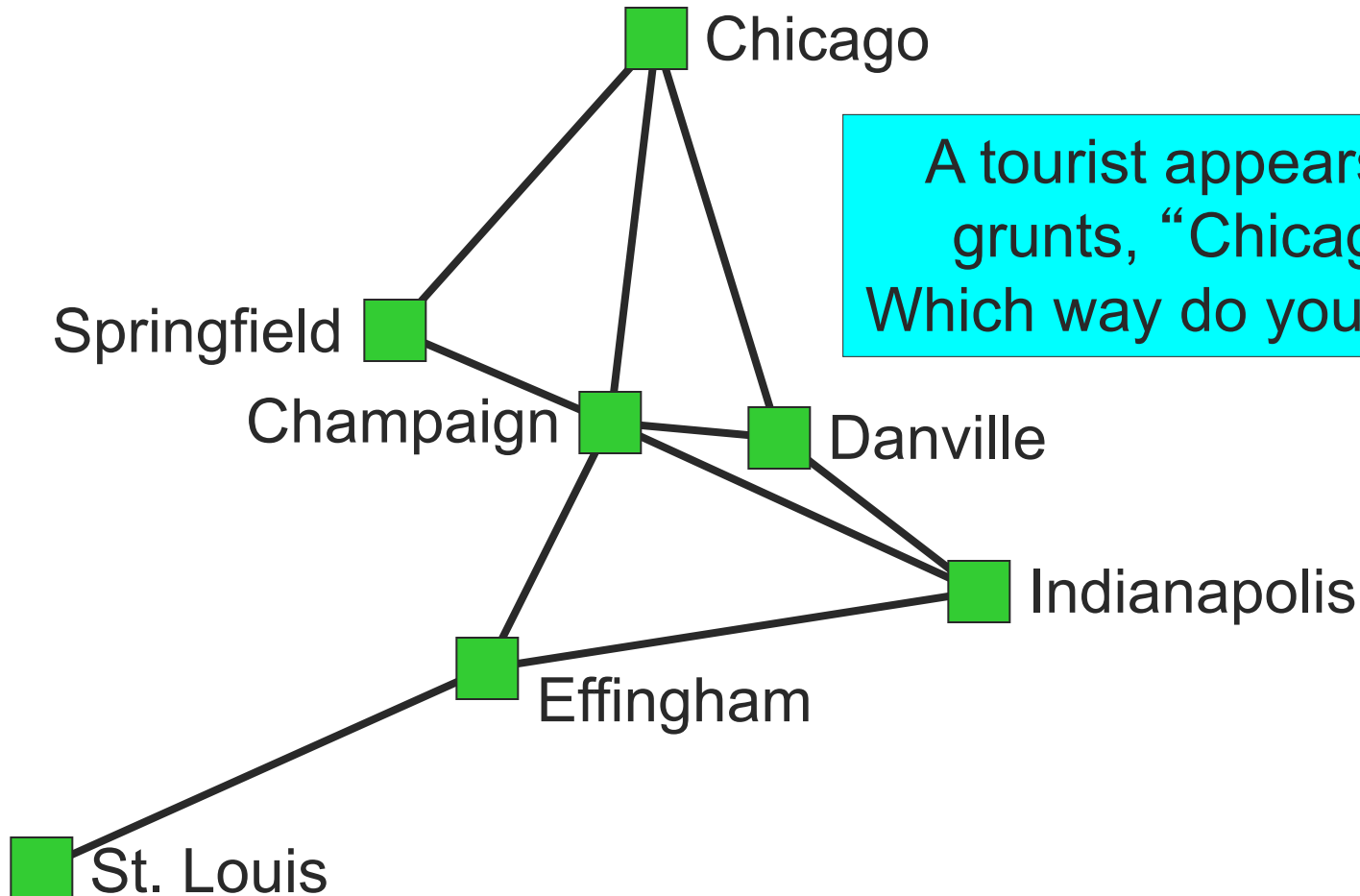




Routing

[Routing]

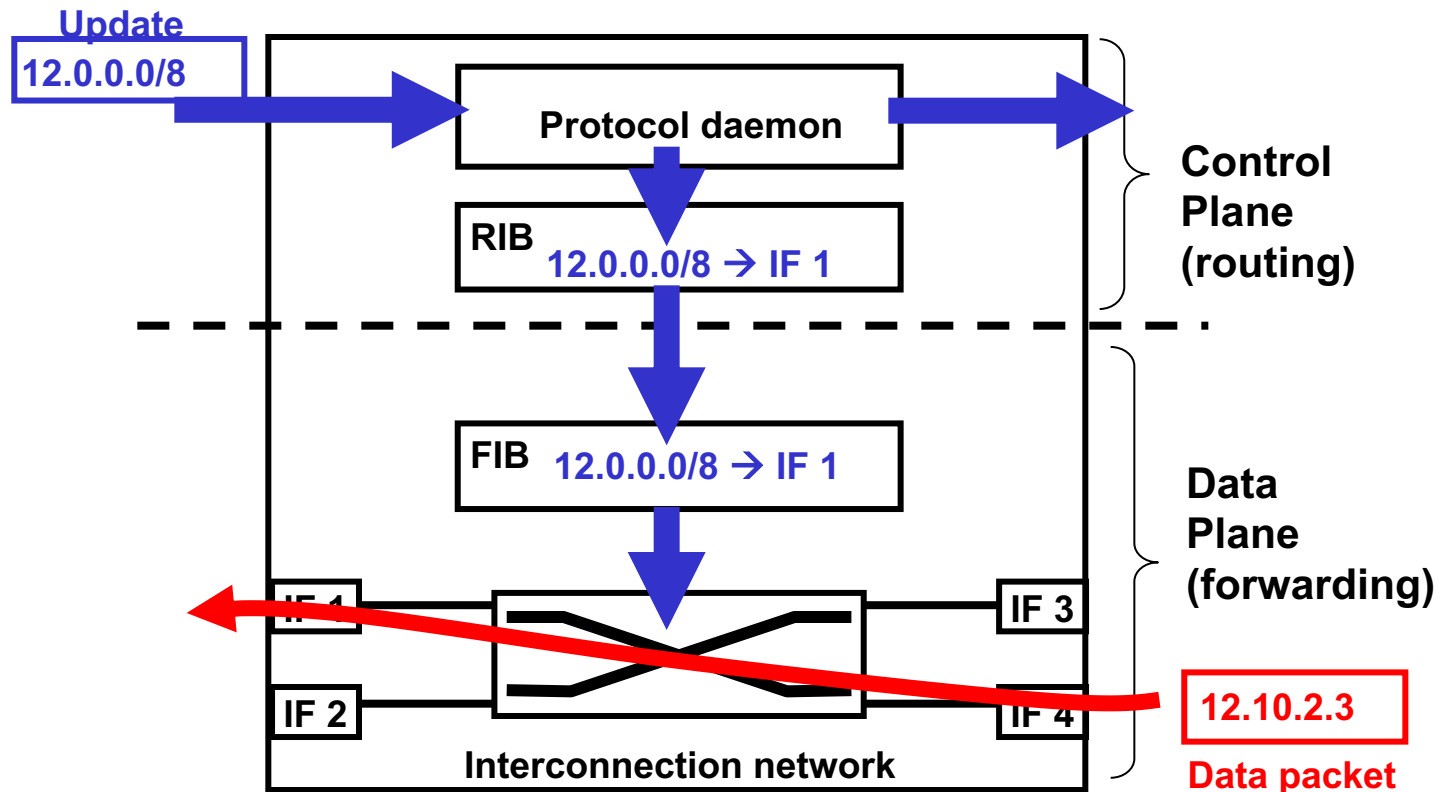


A tourist appears and grunts, “Chicago?”
Which way do you point?



Network Routing

Constructing and maintaining forwarding information in hosts or routers



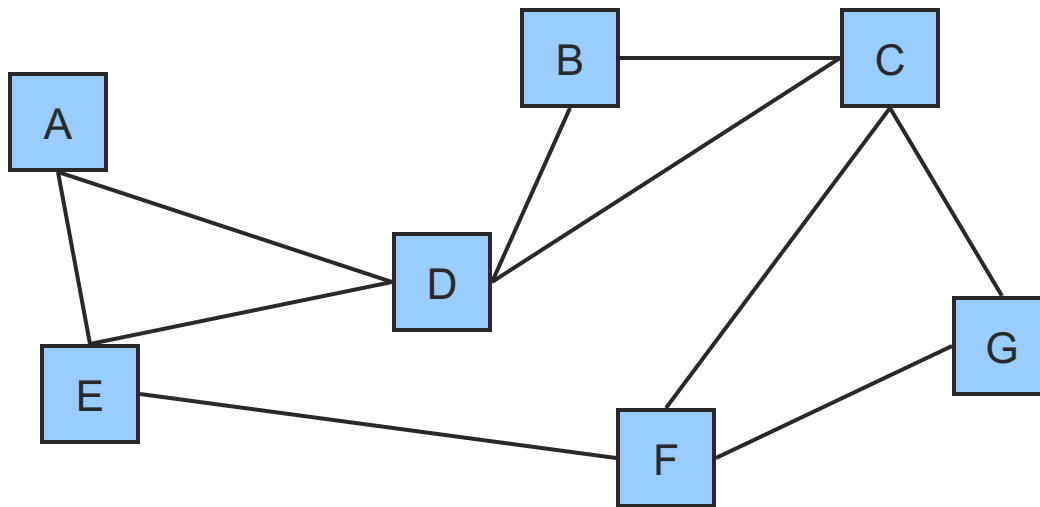
[Routing]

- Goals
 - Capture the notion of “best” routes
 - Propagate changes effectively
 - Require limited information exchange
- Conceptually
 - A network can be represented as a graph where each host/router is a node and each physical connection is a link



Routing: Ideal Approach

- Maintain information about each link
- Calculate fastest path between each directed pair



For each direction, maintain:

- Bandwidth
- Latency
- Queueing delay



[Routing: Ideal Approach]

- Problems
 - Unbounded amount of information
 - Queueing delay can change rapidly
 - Graph connectivity can change rapidly
- Solution
 - Dynamic
 - Periodically recalculate routes
 - Distributed
 - No single point of failure
 - Reduced computation per node
 - Abstract Metric
 - “Distance” may combine many factors
 - Use heuristics



[Routing Overview]

- Algorithms
 - Static shortest path algorithms
 - Bellman-Ford
 - Based on local iterations
 - Dijkstra's algorithm
 - Build tree from source
 - Distributed, dynamic routing algorithms
 - Distance vector routing
 - Distributed Bellman-Ford
 - Link state routing
 - Implement Dijkstra's algorithm at each node



[Bellman-Ford Algorithm]

- Concept
 - Static centralized algorithm
- Given
 - Directed graph with edge costs and destination node
- Finds
 - Least cost path from each node to destination
- Multiple nodes
 - To find shortest paths for multiple destination nodes, run entire Bellman-Ford algorithm once per destination

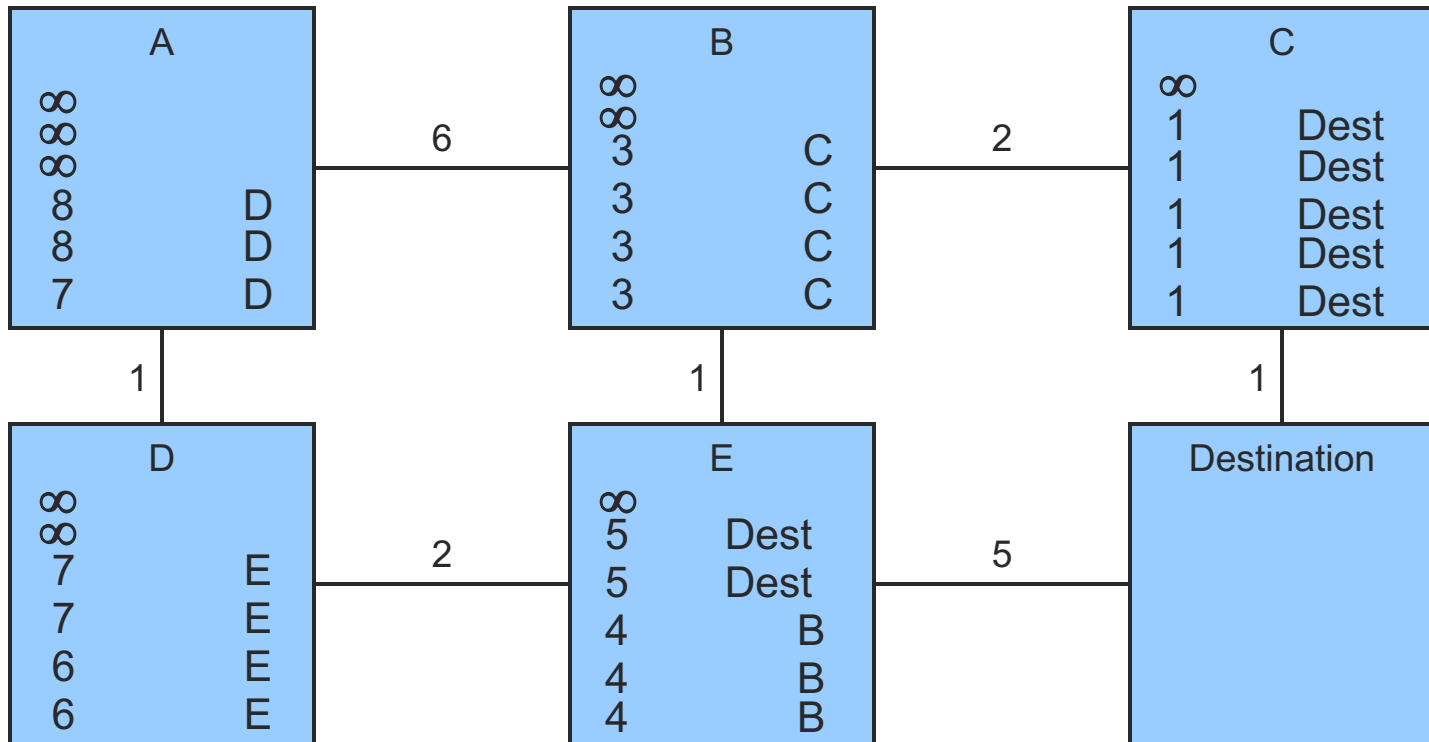


[Bellman-Ford Algorithm]

- Based on repetition of iterations
 - For every node A and every neighbor B of A
 - Is the cost of the path (A → B → → → destination) smaller than the currently known cost from A to destination?
 - If YES
 - Make B the successor node for A
 - Update cost from A to destination
 - Can run iterations synchronously or all at once



Bellman-Ford Algorithm



Distance Vector Routing

- Distributed dynamic version of Bellman-Ford
- Each node maintains a table of
 - *<destination, distance, successor>*
- Information acquisition
 - Assume nodes initially know cost to immediate neighbor
 - Nodes send *<destination, distance>* vectors to all immediate neighbors
 - Periodically – seconds, minutes
 - Whenever vector changes – triggered update



Distance Vector Routing

- When a route changes
 - Local failure detection
 - Control message not acknowledged
 - Timeout on periodic route update
 - Current route disappears
 - Newly advertised route is shorter than previous route
- Used in
 - Original ARPANET (until 1979)
 - Early Internet: Routing Information Protocol (RIP)
 - Early versions of DECnet and Novell IPX



Distance vector: update propagation

D tells B: I am D, and I can reach F via 1 hop

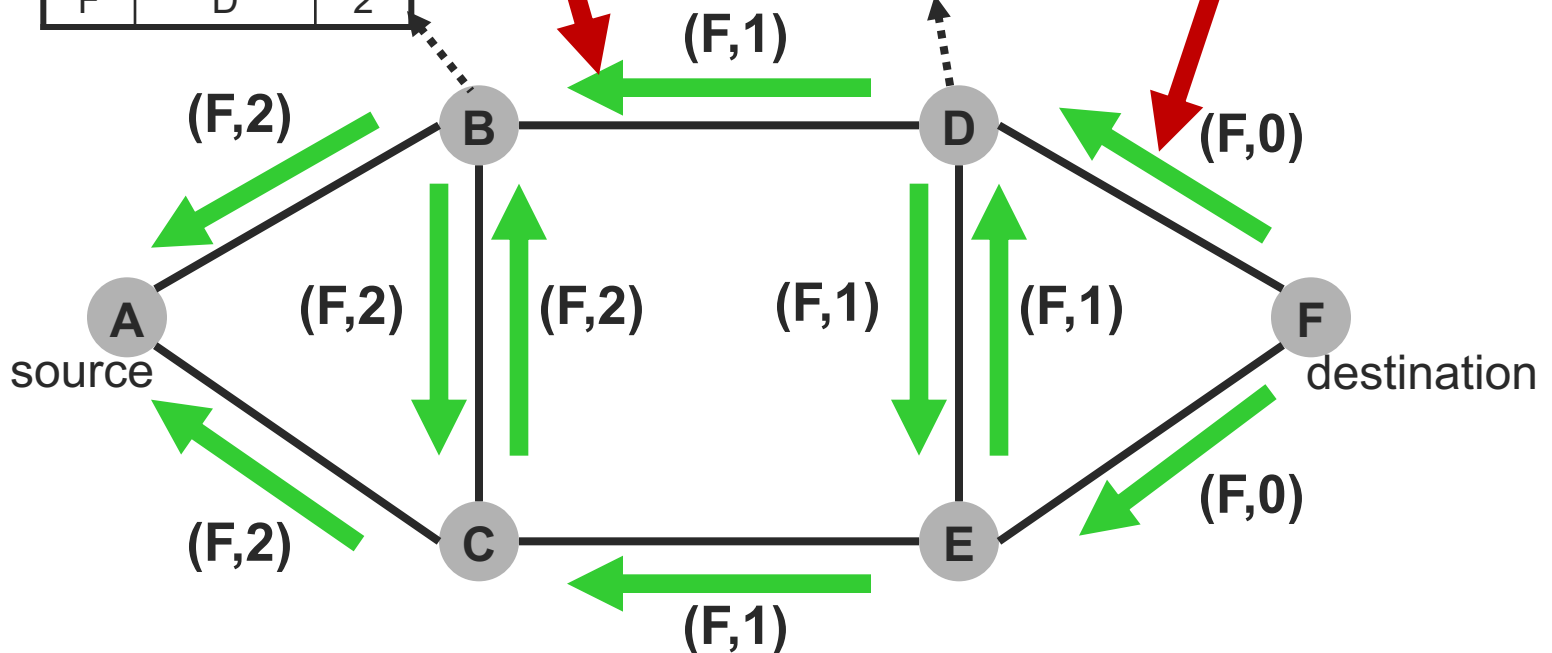
B's forwarding table

Dest	NextHop	Dist
F	D	2

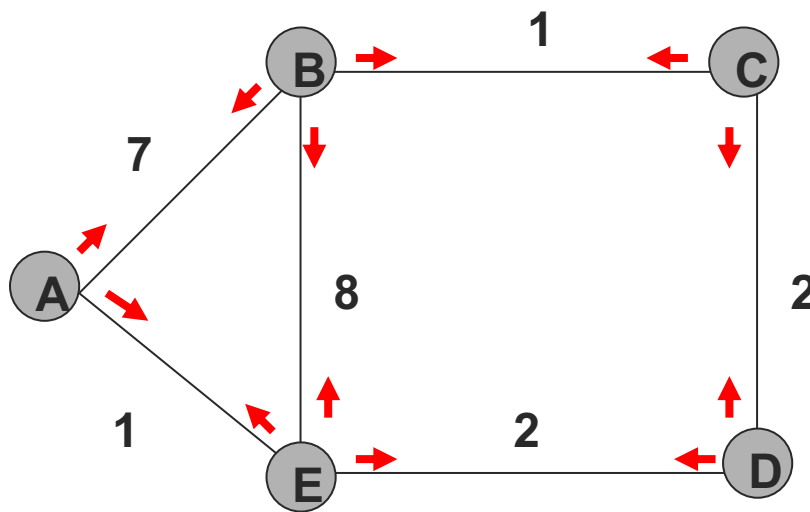
D's forwarding table

Dest	NextHop	Dist
F	F	1

F tells D: I am F, and I can reach F via 0 hops



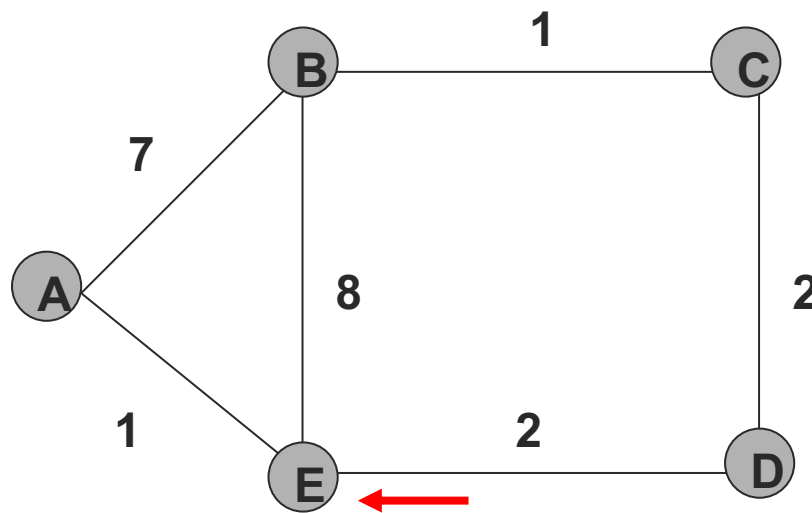
Example - Initial Distances



Info at node	Distance to node				
	A	B	C	D	E
A	0	7	~	~	1
B	7	0	1	~	8
C	~	1	0	2	~
D	~	~	2	0	2
E	1	8	~	2	0



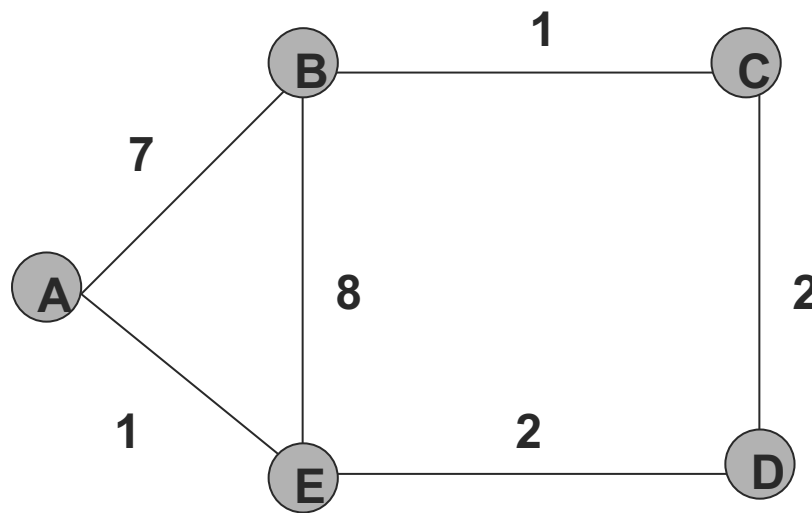
[E Receives D's Routes]



Info at node	Distance to node				
	A	B	C	D	E
A	0	7	~	~	1
B	7	0	1	~	8
C	~	1	0	2	~
D	~	~	2	0	2
E	1	8	~	2	0



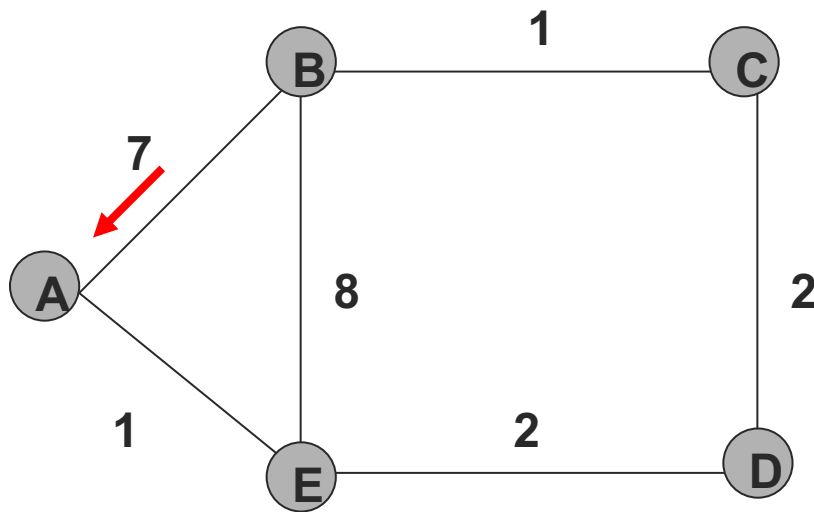
[E Updates Cost to C]



Info at node	Distance to node				
	A	B	C	D	E
A	0	7	~	~	1
B	7	0	1	~	8
C	~	1	0	2	~
D	~	~	2	0	2
E	1	8	4	2	0



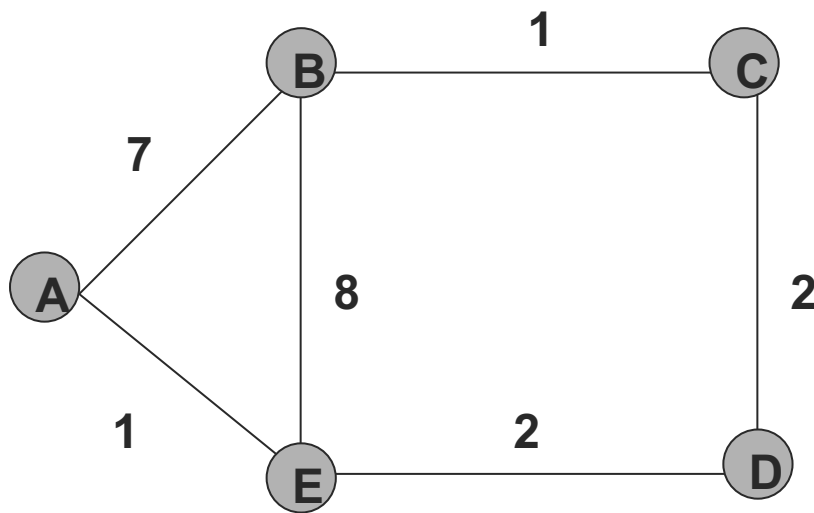
[A Receives B's Routes]



Info at node	Distance to node				
	A	B	C	D	E
A	0	7	~	~	1
B	7	0	1	~	8
C	~	1	0	2	~
D	~	~	2	0	2
E	1	8	4	2	0



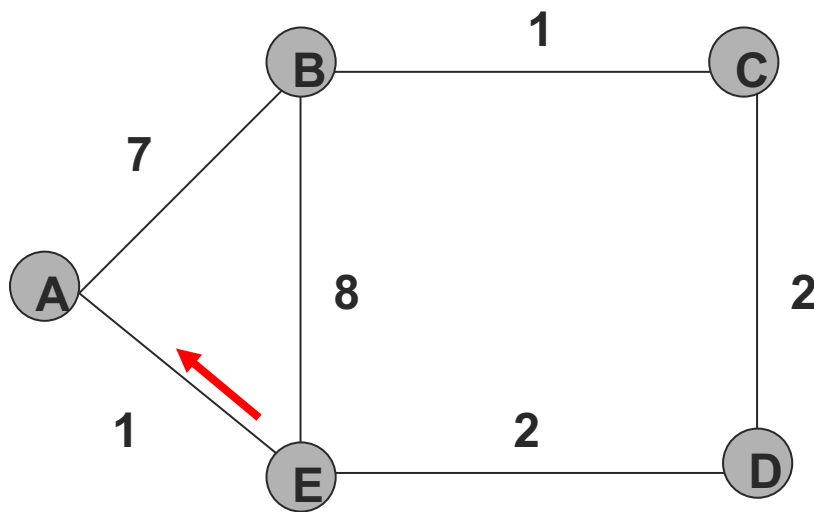
[A Updates Cost to C]



Info at node	Distance to node				
	A	B	C	D	E
A	0	7	8	~	1
B	7	0	1	~	8
C	~	1	0	2	~
D	~	~	2	0	2
E	1	8	4	2	0



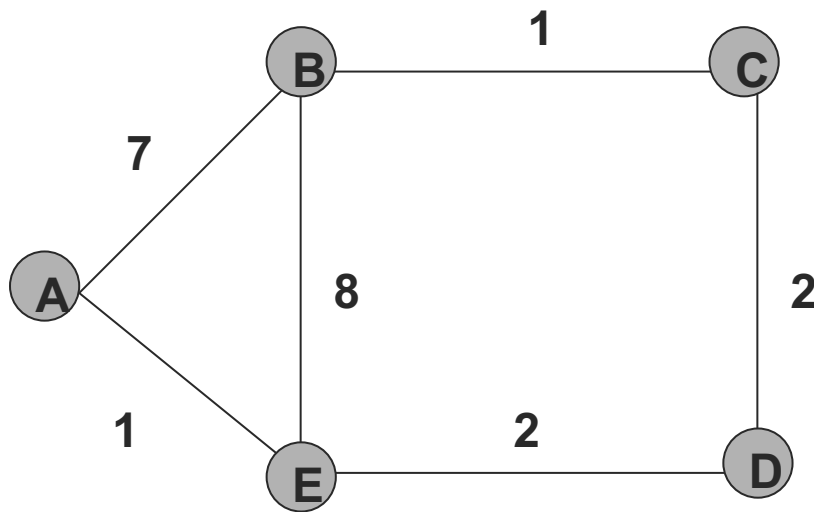
[A Receives E's Routes]



Info at node	Distance to node				
	A	B	C	D	E
A	0	7	8	~	1
B	7	0	1	~	8
C	~	1	0	2	~
D	~	~	2	0	2
E	1	8	4	2	0



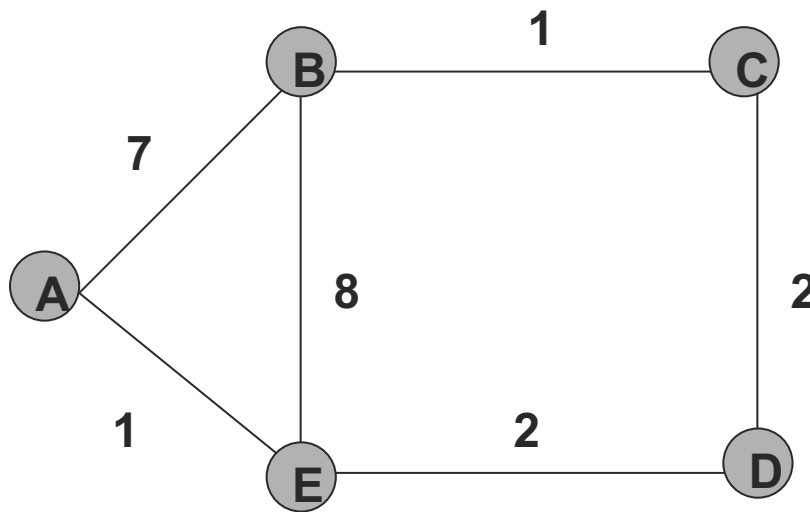
[A Updates Cost to C and D]



Info at node	Distance to node				
	A	B	C	D	E
A	0	7	5	3	1
B	7	0	1	~	8
C	~	1	0	2	~
D	~	~	2	0	2
E	1	8	4	2	0



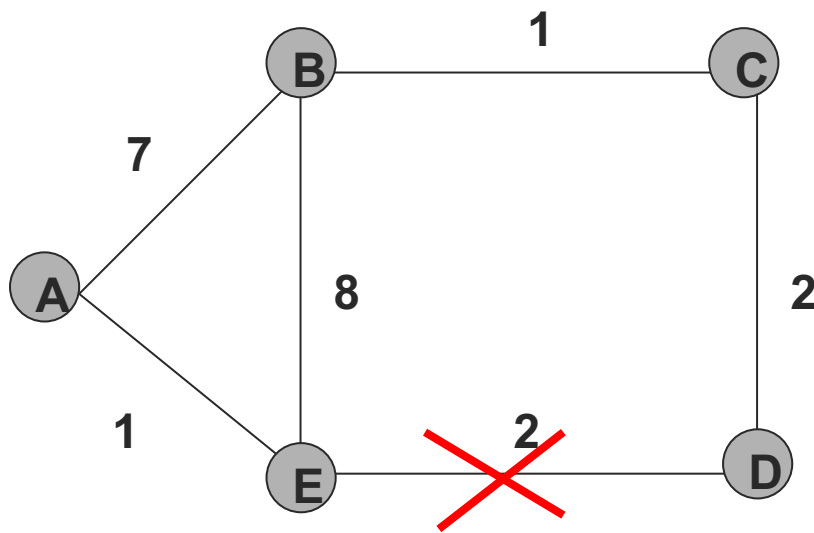
[Final Distances]



Info at node	Distance to node				
	A	B	C	D	E
A	0	6	5	3	1
B	6	0	1	3	5
C	5	1	0	2	4
D	3	3	2	0	2
E	1	5	4	2	0



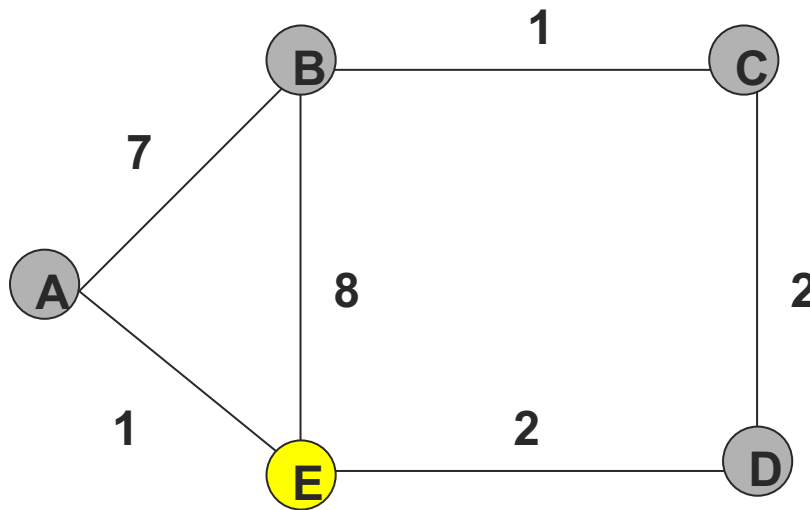
Final Distances After Link Failure



Info at node	Distance to node				
	A	B	C	D	E
A	0	7	8	10	1
B	7	0	1	3	8
C	8	1	0	2	9
D	10	3	2	0	11
E	1	8	9	11	0



View From a Node



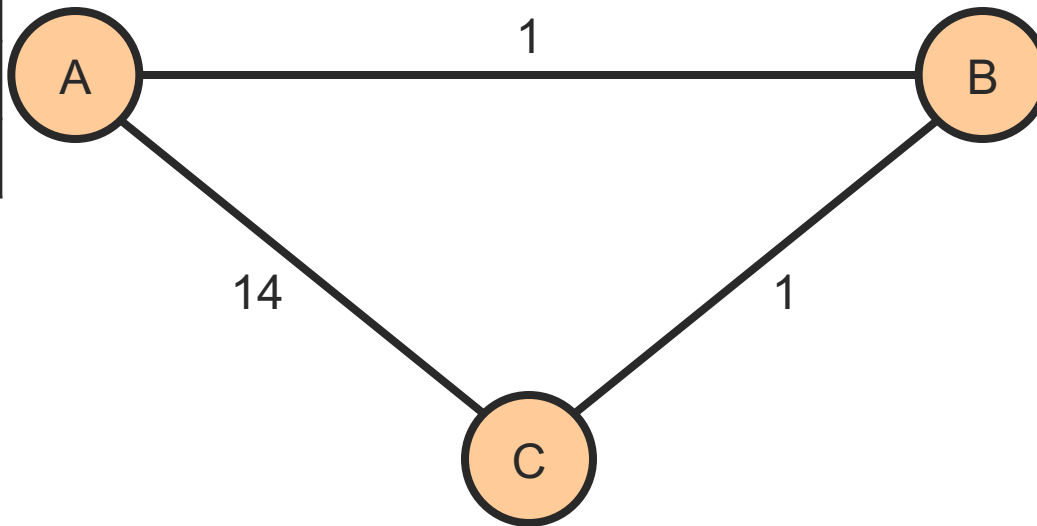
E's routing table

dest	Next hop		
	A	B	D
A	1	14	5
B	7	8	5
C	6	9	4
D	4	11	2



What happens after a failure?

dest	cost
B	1
C	2



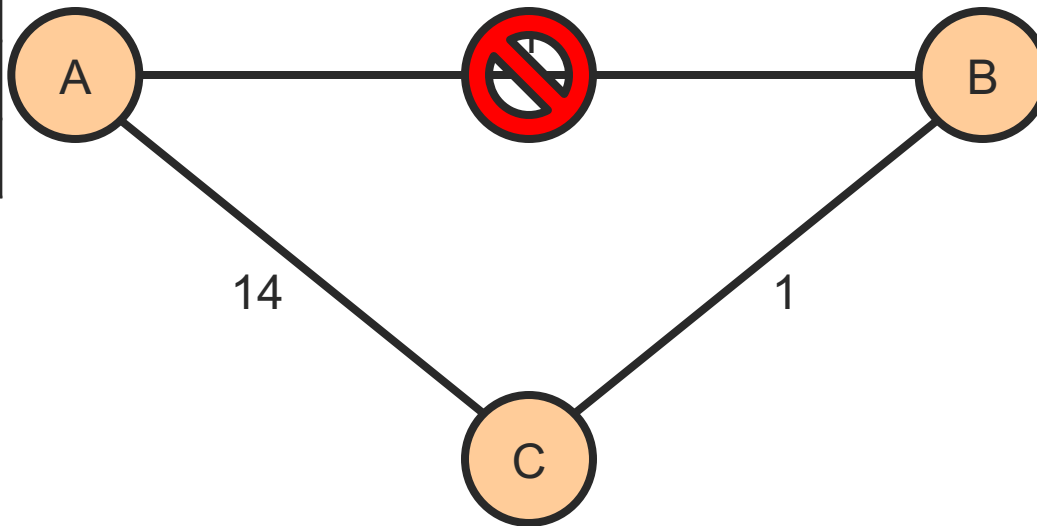
dest	cost
A	1
C	1

dest	cost
A	2
B	1



Count-to-Infinity Problem

dest	cost
B	1
C	2



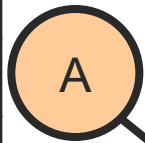
dest	cost
A	1
C	1

dest	cost
A	2
B	1

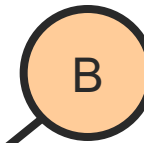
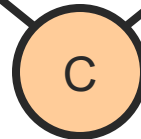


Count-to-Infinity Problem

dest	cost
B	1
C	2



14



dest	cost
A	1
C	1

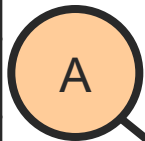
1

dest	cost
A	2
B	1

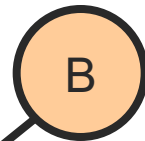
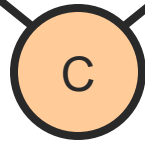


Count-to-Infinity Problem

dest	cost
B	1
C	2



14



dest	cost
A	1 ~
C	1

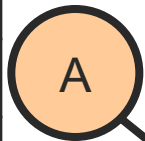
1

dest	cost
A	2
B	1

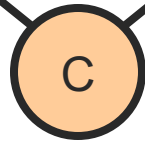


Count-to-Infinity Problem

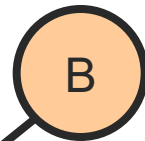
dest	cost
B	1
C	2



14



A	2
---	---

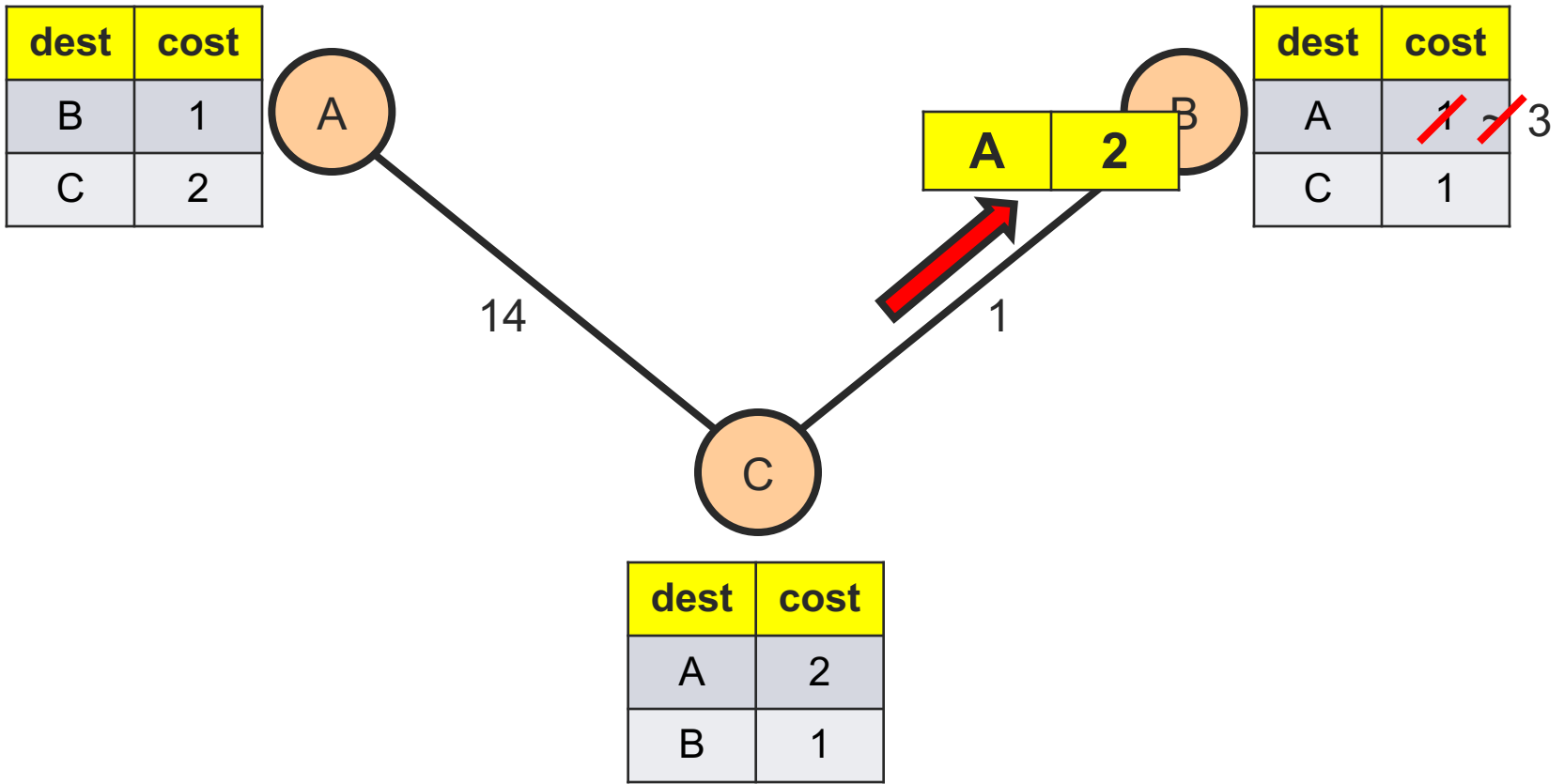


dest	cost
A	1 ~
C	1

dest	cost
A	2
B	1

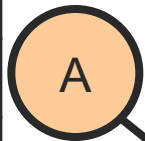


Count-to-Infinity Problem

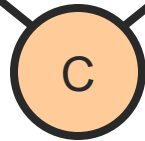


Count-to-Infinity Problem

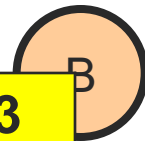
dest	cost
B	1
C	2



14



A	3
---	---



dest	cost
A	1 3
C	1

1

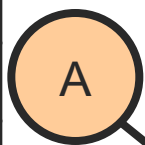
dest	cost
A	2
B	1



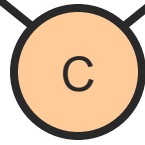
Count-to-Infinity Problem

Really through B

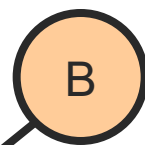
dest	cost
B	1
C	2



14



dest	cost
A	3



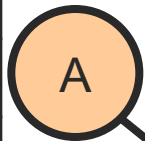
dest	cost
A	1 3
C	1

dest	cost
A	2 4
B	1

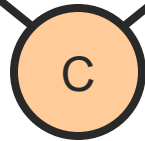


Count-to-Infinity Problem

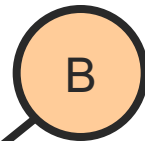
dest	cost
B	1
C	2



14



A	4
---	---



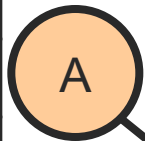
dest	cost
A	1 3
C	1

dest	cost
A	2 4
B	1

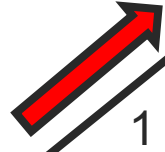
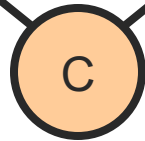


Count-to-Infinity Problem

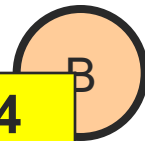
dest	cost
B	1
C	2



14



1



A	4
---	---

dest	cost
A	1 2 3 5
C	1

Also called the bouncing effect

dest	cost
A	2 4
B	1



[Distance Vector Routing]

■ Problem

- Node **X** notices that its link to **Y** is broken
- Other nodes believe that the route through **X** is still good
- Mutual deception!



How Are These Loops Caused?

- Observation 1:
 - B's metric **increases**
- Observation 2:
 - C picks B as next hop to A
 - But, the **implicit path** from C to A includes itself!



[Solution 1: Holddowns]

- If metric increases, delay propagating information
 - in our example, B delays advertising route
 - C eventually thinks B's route is gone, picks its own route
 - B then selects C as next hop
- Adversely affects convergence



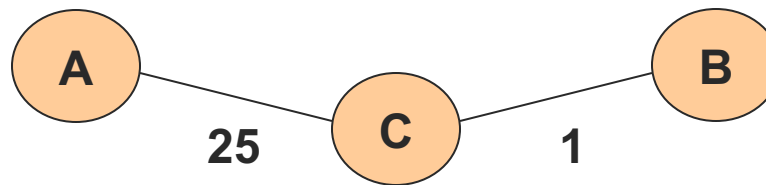
Heuristics for breaking loops

- Set infinity to 16
 - Small limit allows fast completion of “counting to infinity”
 - Limits the size of the network
- Split horizon
 - Avoid counting to infinity by solving “mutual deception” problem
- Split horizon with poisoned reverse
 - “Poison” the routes sent to you by your neighbors
- Sequence numbers on delay estimates



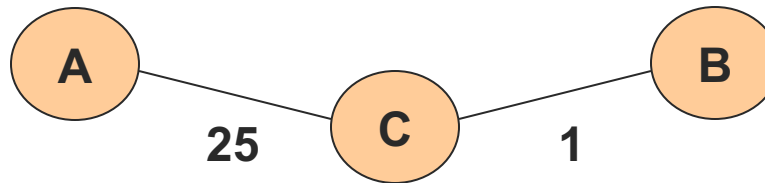
[Split Horizon]

- Avoid counting to infinity by solving “mutual deception” problem
- Distance Vector with split horizon:
 - when sending an update to node **X**, do not include destinations that you would route through **X**
 - If **X** thinks route is not through you, no effect
 - If **X** thinks route is through you, **X** will timeout route



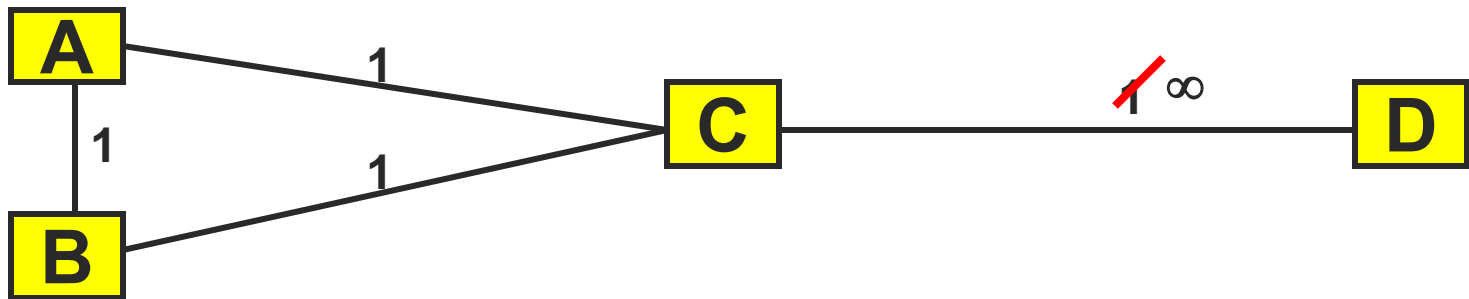
Split Horizon and Poisoned Reverse

- Distance Vector with Split Horizon and Poisoned Reverse:
 - When sending update to node **X**, include destinations that you would route through **X** with distance set to infinity
 - Don't need to wait for **X** to timeout
- Problem:
 - still doesn't fix loops of 3+ hops!



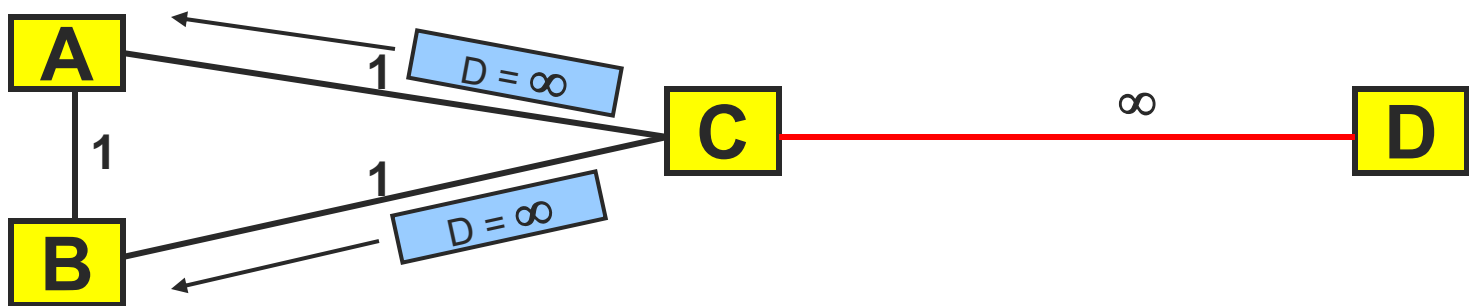
[Split Horizon]

- Split Horizon (with or without poisoned reverse) may still allow some routing loops and counting to infinity
 - guarantees no 2-node loops
 - can still be fooled by 3-node (or larger) loops
- Consider link failure from **C** to **D**



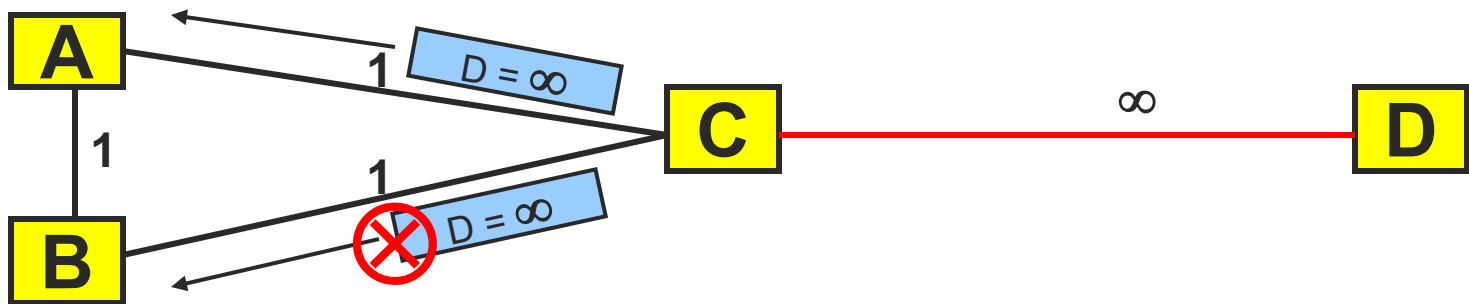
[Split Horizon]

- Initial routing table entries for route to **D**:
 - A** 2 via **C**
 - B** 2 via **C**
 - C** 1
- **C** notices link failure and changes to infinity
- Now **C** sends updates to **A** and **B**:
 - to **A**: infinity
 - to **B**: infinity



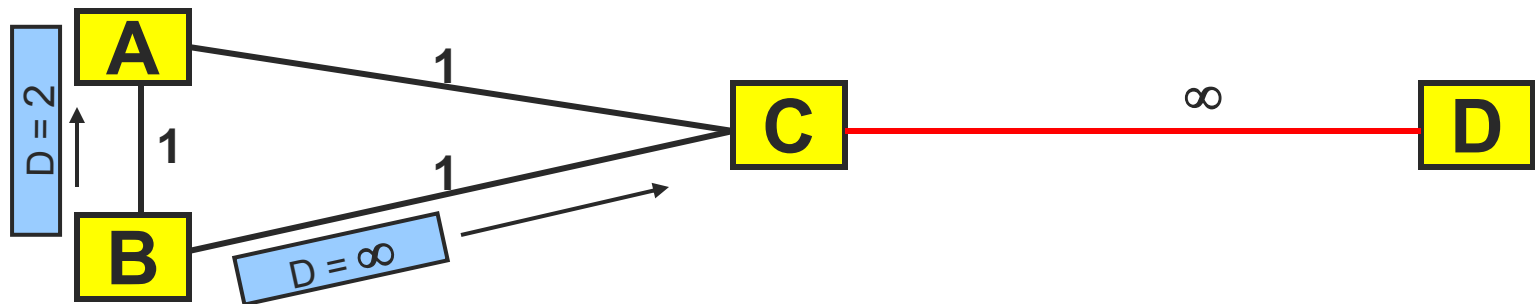
[Split Horizon]

- Suppose update to **B** is lost
- New tables:
A unreachable
B 2 via C
C unreachable



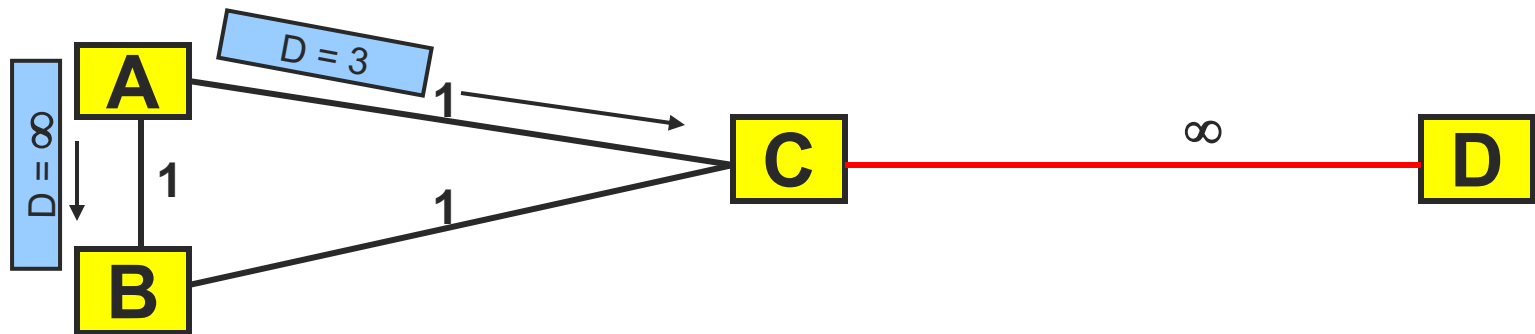
[Split Horizon]

- Suppose update to **B** is lost
- New tables:
 - A** unreachable
 - B** 2 via **C**
 - C** unreachable
- Now **B** sends its periodic routing update:
 - to **C**: infinity (poisoned reverse)
 - to **A**: 2



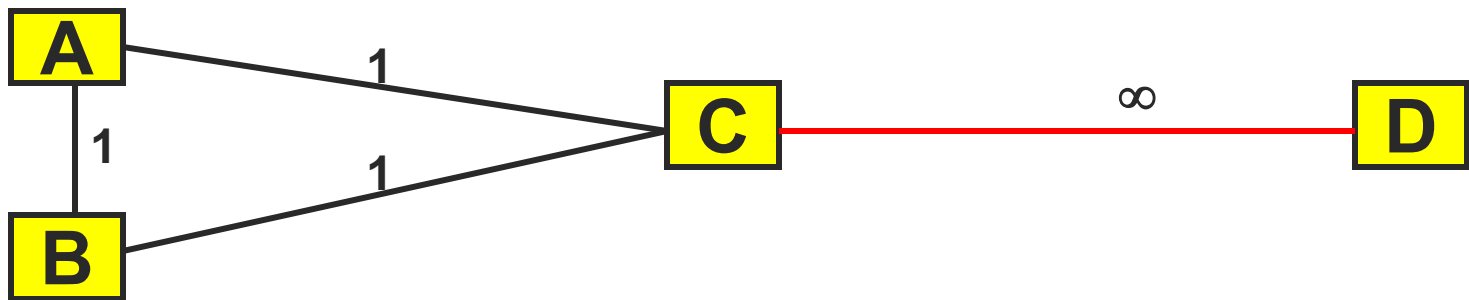
[Split Horizon]

- New tables for route to **D**:
 - A** 3 via **B**
 - B** 2 via **C**
 - C** unreachable
- Finally **A** sends its periodic routing update:
 - to **B**: infinity (poisoned reverse)
 - to **C**: 3



[Split Horizon]

- New tables for route to **D**:
 - A 3 via B
 - B 2 via C
 - C 4 via A
- A, B and C will still continue to count to infinity



Avoiding the Counting to Infinity Problem

- Select loop-free **paths**
- One way of doing this:
 - Each route advertisement carries entire path instead of just distance
 - If router sees itself in path, reject route
 - \Rightarrow called Path-Vector routing
- BGP does it this way
- Space proportional to diameter



Loop Freedom at Every Instant

- Have we now avoided all loops?
 - No! **Transient** loops are still possible
 - Why? Implicit path information may be stale
- Many approaches to fix this
 - Maintain backup paths in case you get stuck
 - Use multiple paths
 - Source routing
 - Keep packets flowing or queued during convergence
 - ...and much more current research



Distance Vector in Practice

- RIP and RIP2
 - uses split-horizon/poison reverse
- BGP/IDRP
 - propagates entire path
 - path also used for affecting policies
- AODV
 - “on-demand” protocol for wireless networks
 - Only maintain distance vectors along paths to destinations that you need to reach



[Routing So Far ...]

- Problem
 - Information propagates slowly
 - One period per hop for new routes
 - Count to infinity to detect lost routes



[Dijkstra's Algorithm]

- Given
 - Directed graph with edge weights (distances)
- Calculate
 - Shortest paths from one node to all others

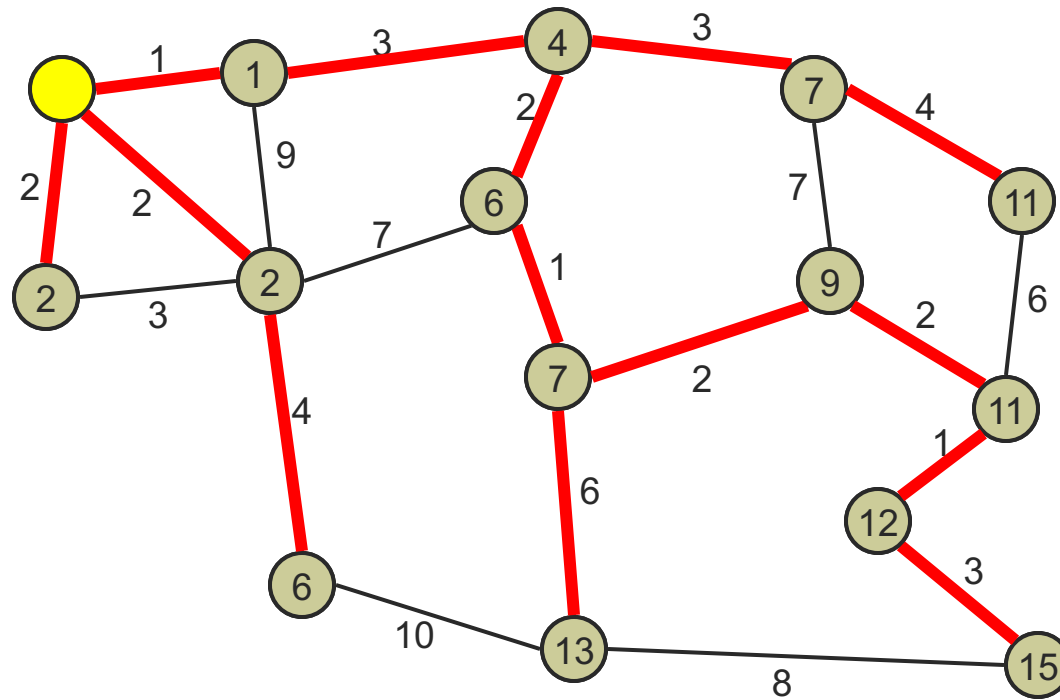


[Dijkstra's Algorithm]

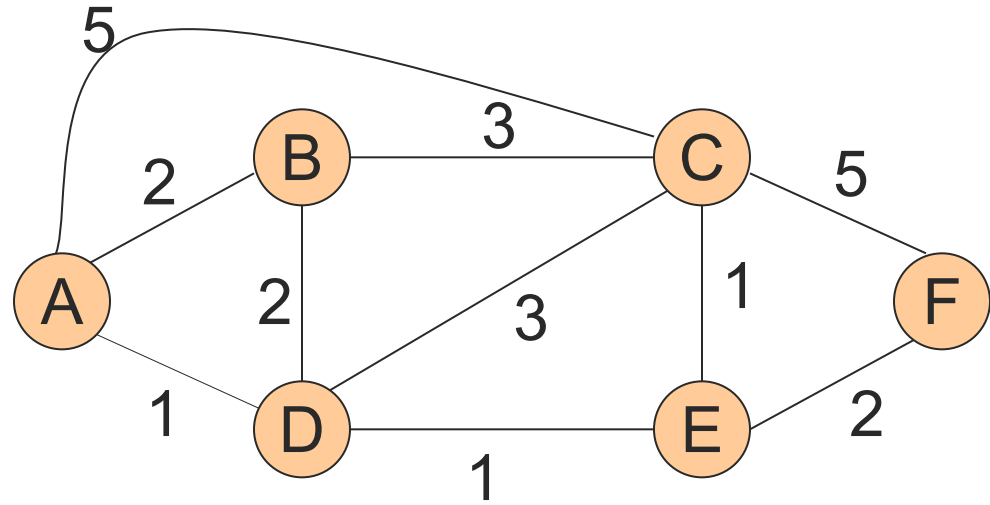
- Greedily grow set C of confirmed least cost paths
- Initially $C = \{\text{source}\}$
- Loop N-1 times
 - Determine the node M outside C that is closest to the source
 - Add M to C and update costs for each node P outside C
 - Is the path (source $\rightarrow \dots \rightarrow M \rightarrow P$) better than the previously known path for (source $\rightarrow P$)?
 - If YES
 - Update cost to reach P



[Dijkstra's Algorithm]



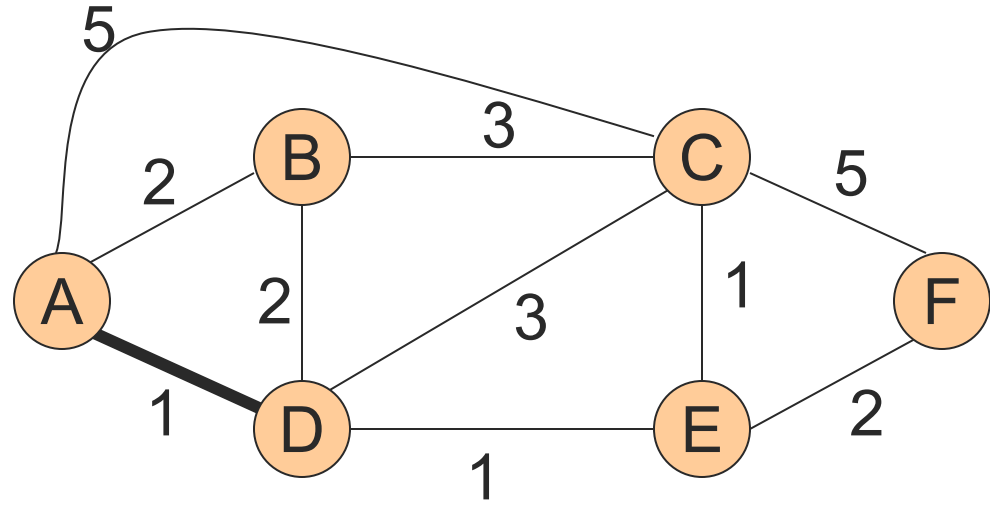
[Example]



		B	C	D	E	F
step	SPT	D(b), P(b)	D(c), P(c)	D(d), P(d)	D(e), P(e)	D(f), P(f)
0	A	2, A	5, A	1, A	~	~



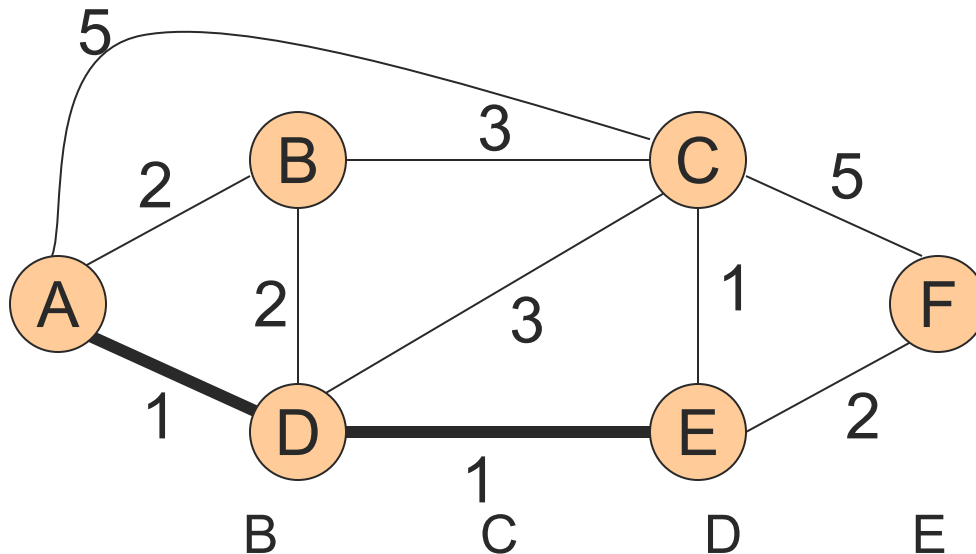
[Example]



		B	C	D	E	F
step	SPT	D(b), P(b)	D(c), P(c)	D(d), P(d)	D(e), P(e)	D(f), P(f)
0	A	2, A	5, A	1, A	~	~
1	AD	2, A	4, D		2, D	~



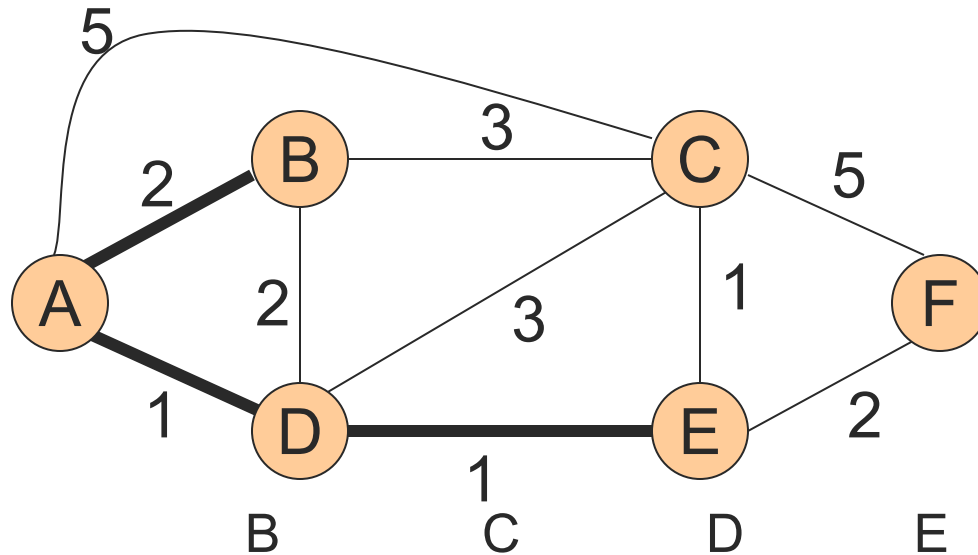
Example



step	SPT	B	C	D	E	F
	SPT	D(b), P(b)	D(c), P(c)	D(d), P(d)	D(e), P(e)	D(f), P(f)
0	A	2, A	5, A	1, A	~	~
1	AD	2, A	4, D		2, D	~
2	ADE	2, A	3, E			4, E



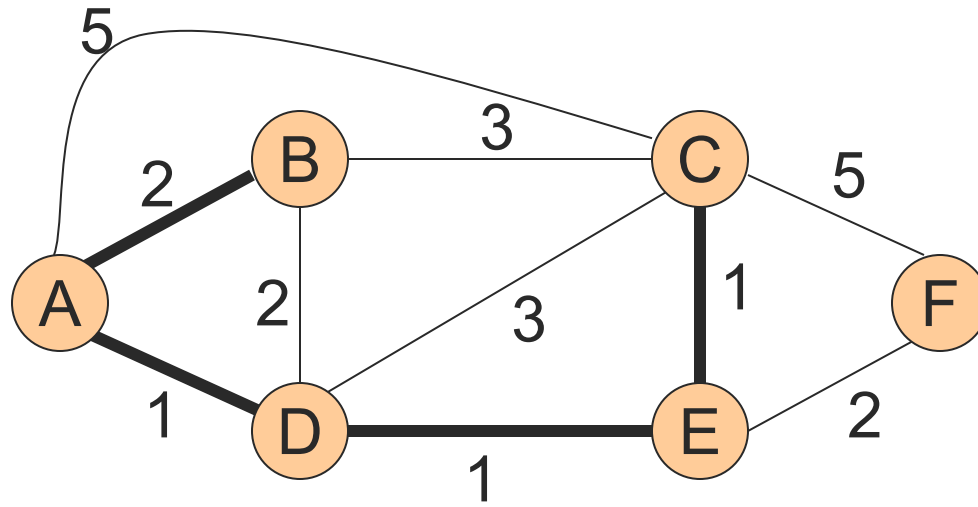
Example



step	SPT	D(b), P(b)	D(c), P(c)	D(d), P(d)	D(e), P(e)	D(f), P(f)
0	A	2, A	5, A	1, A	~	~
1	AD	2, A	4, D		2, D	~
2	ADE	2, A	3, E			4, E
3	ADEB		3, E			4, E



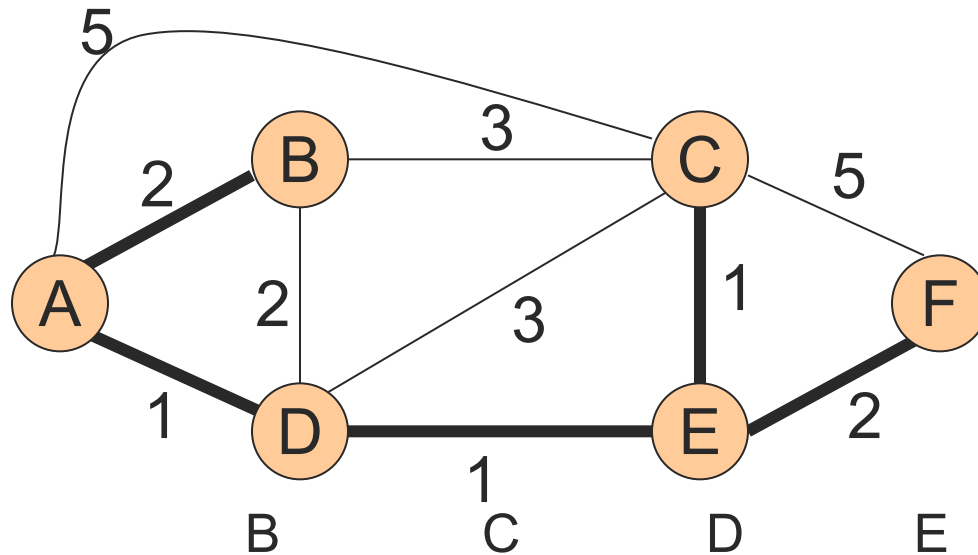
[Example]



		B	C	D	E	F
step	SPT	D(b), P(b)	D(c), P(c)	D(d), P(d)	D(e), P(e)	D(f), P(f)
0	A	2, A	5, A	1, A	~	~
1	AD	2, A	4, D		2, D	~
2	ADE	2, A	3, E			4, E
3	ADEB		3, E			4, E
4	ADEBC					4, E



Example



step	SPT	B	C	D	E	F
	SPT	D(b), P(b)	D(c), P(c)	D(d), P(d)	D(e), P(e)	D(f), P(f)
0	A	2, A	5, A	1, A	~	~
1	AD	2, A	4, D		2, D	~
2	ADE	2, A	3, E			4, E
3	ADEB		3, E			4, E
4	ADEBC					4, E

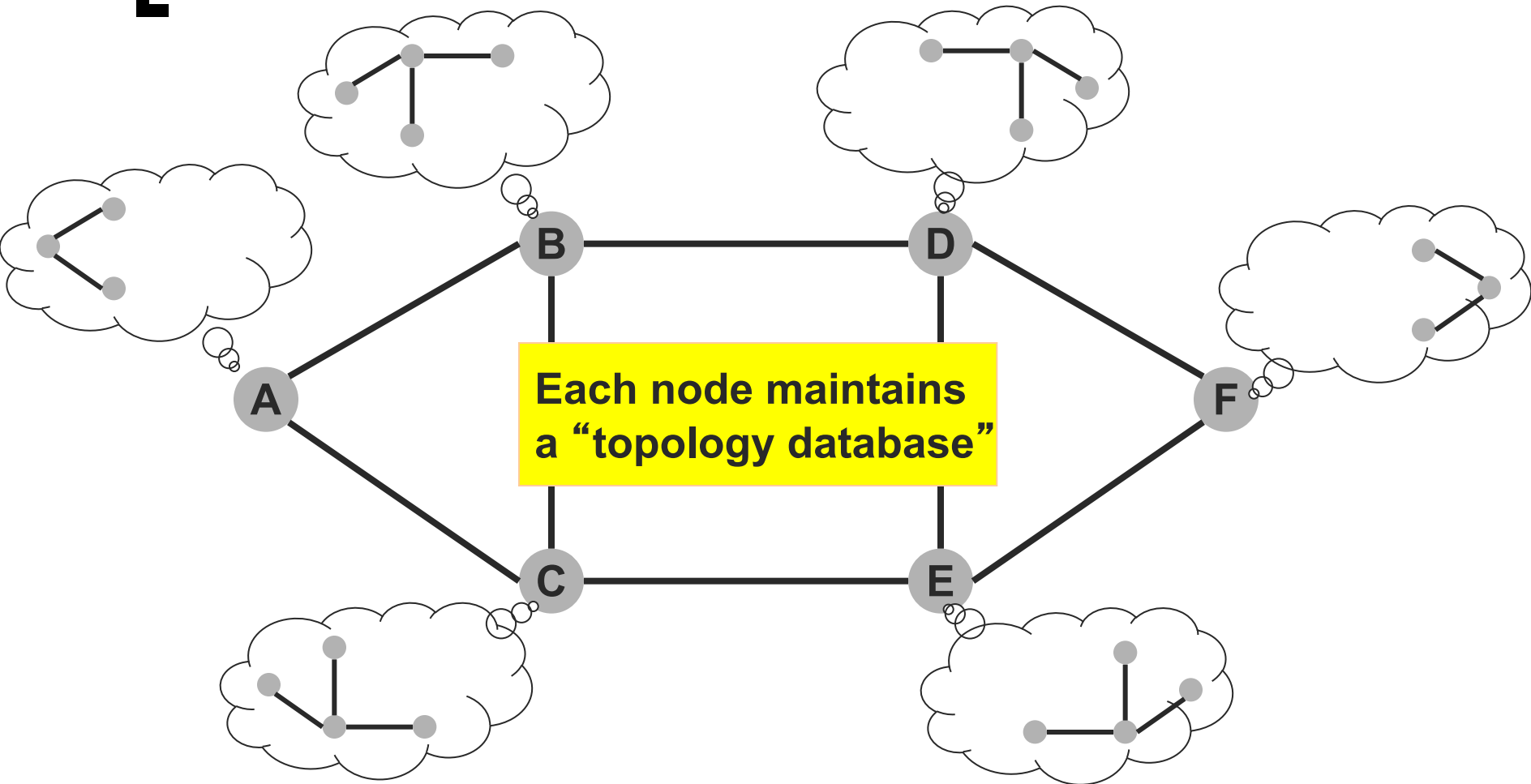


Link State Routing

- Strategy
 - Send all nodes information about directly connected links
 - Status of links is flooded in link state packets (LSPs)
- Each LSP carries
 - ID of node that created the LSP
 - Vector of <neighbor, cost of link to neighbor> pairs for the node that created the LSP
 - Sequence number
 - Time-to-live (TTL)
- Each node maintains a list of (ideally all) LSP's and runs Dijkstra's algorithm on the list

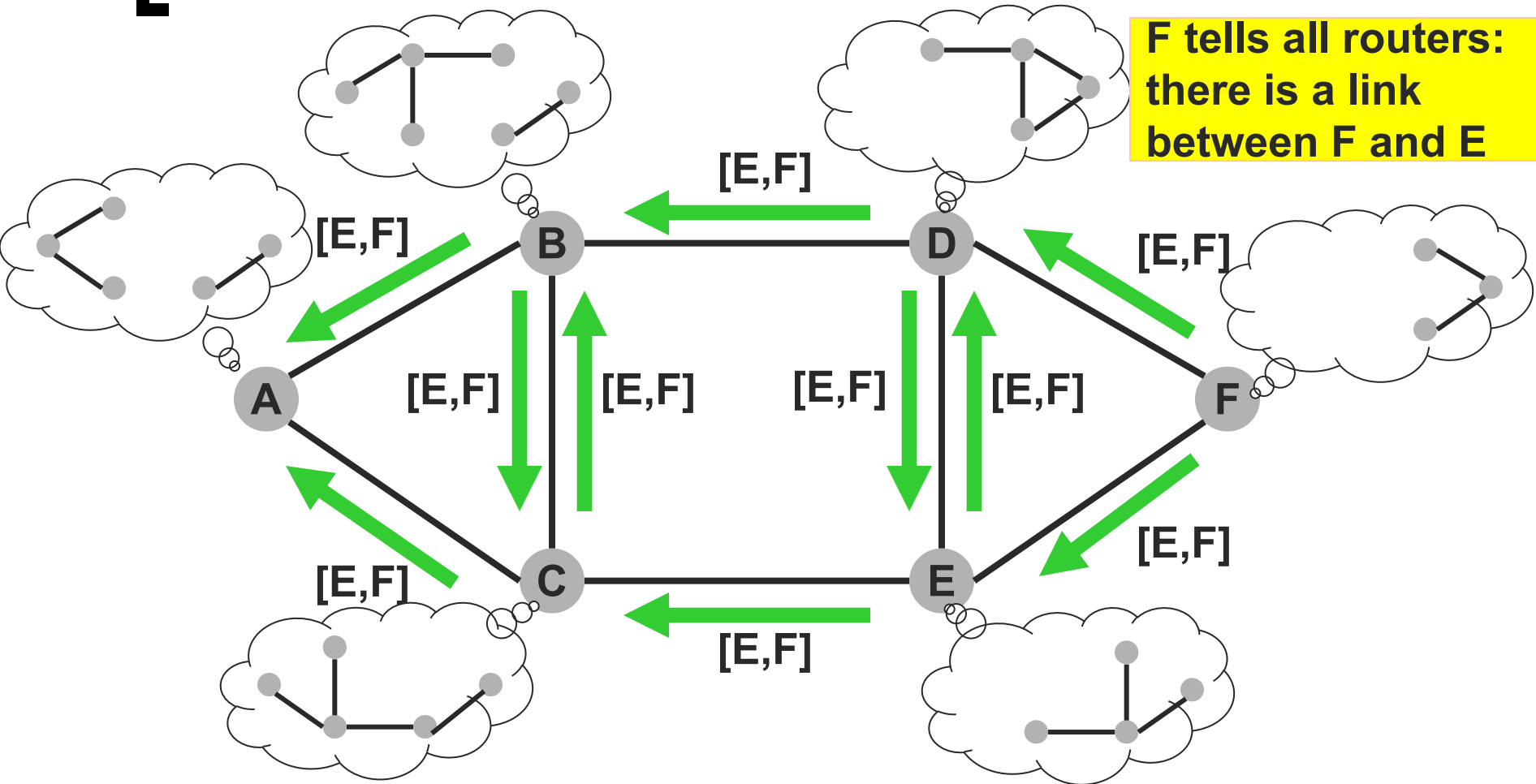


[Link state: update propagation]

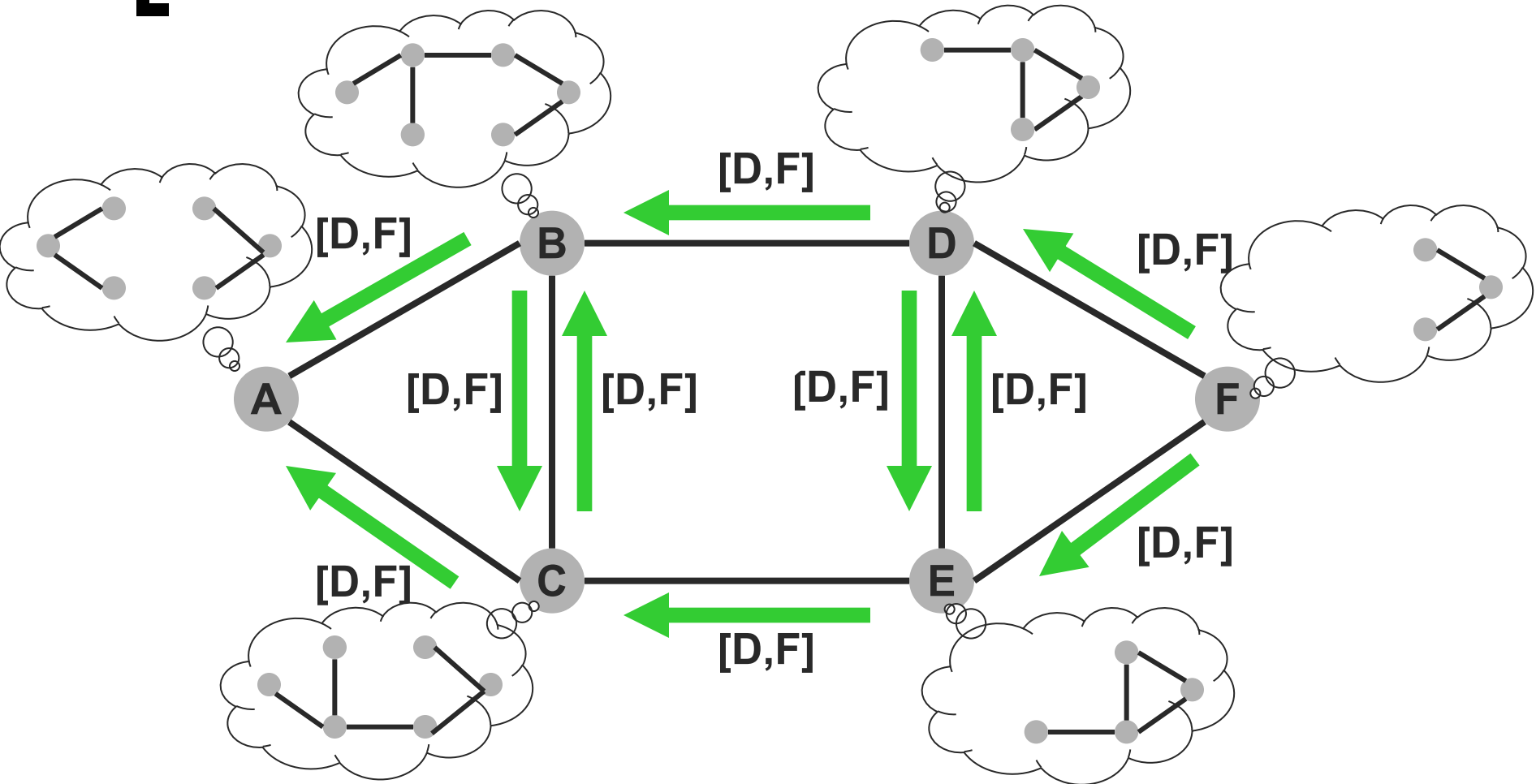


Link state: update propagation

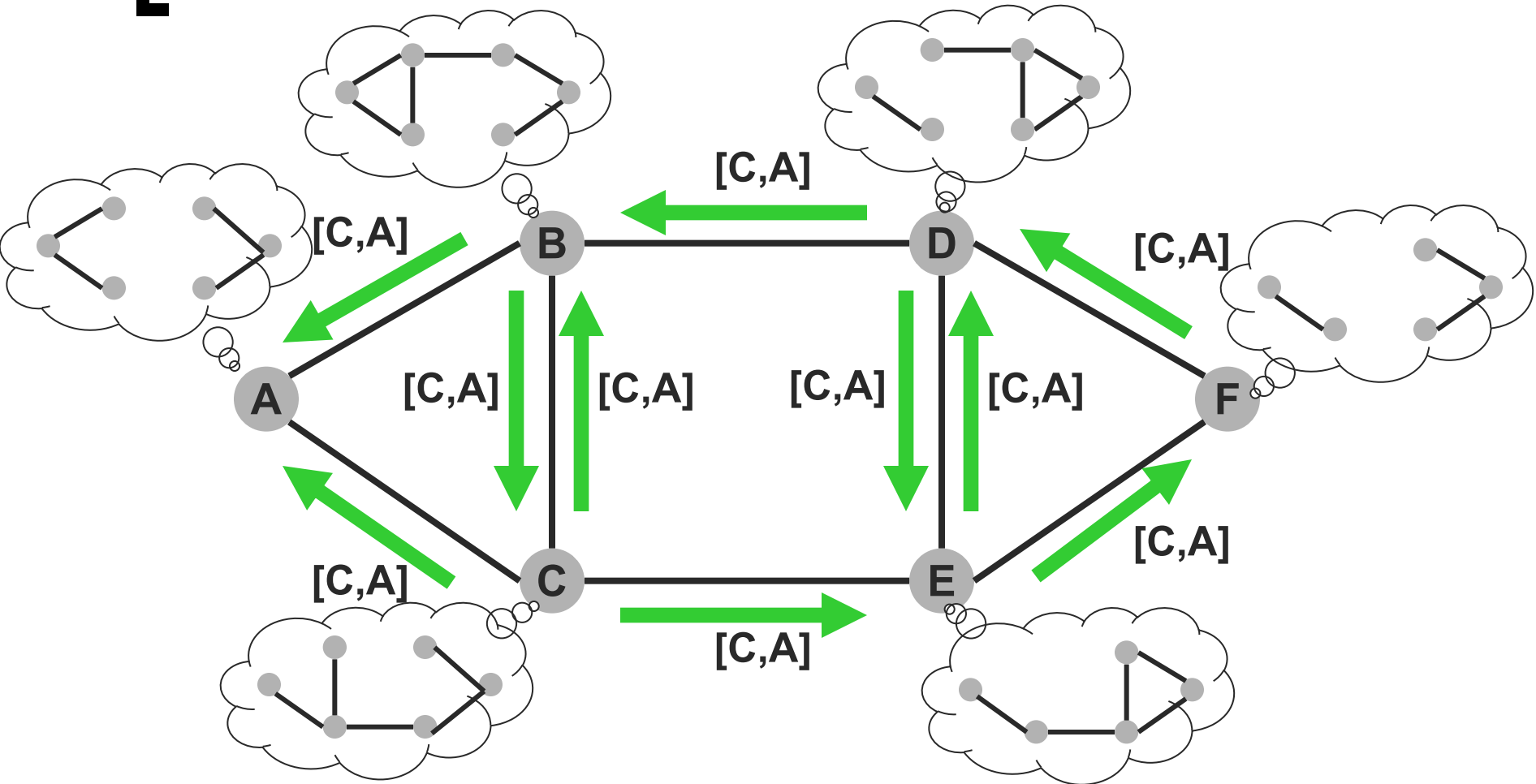
F tells all routers: there is a link between F and E



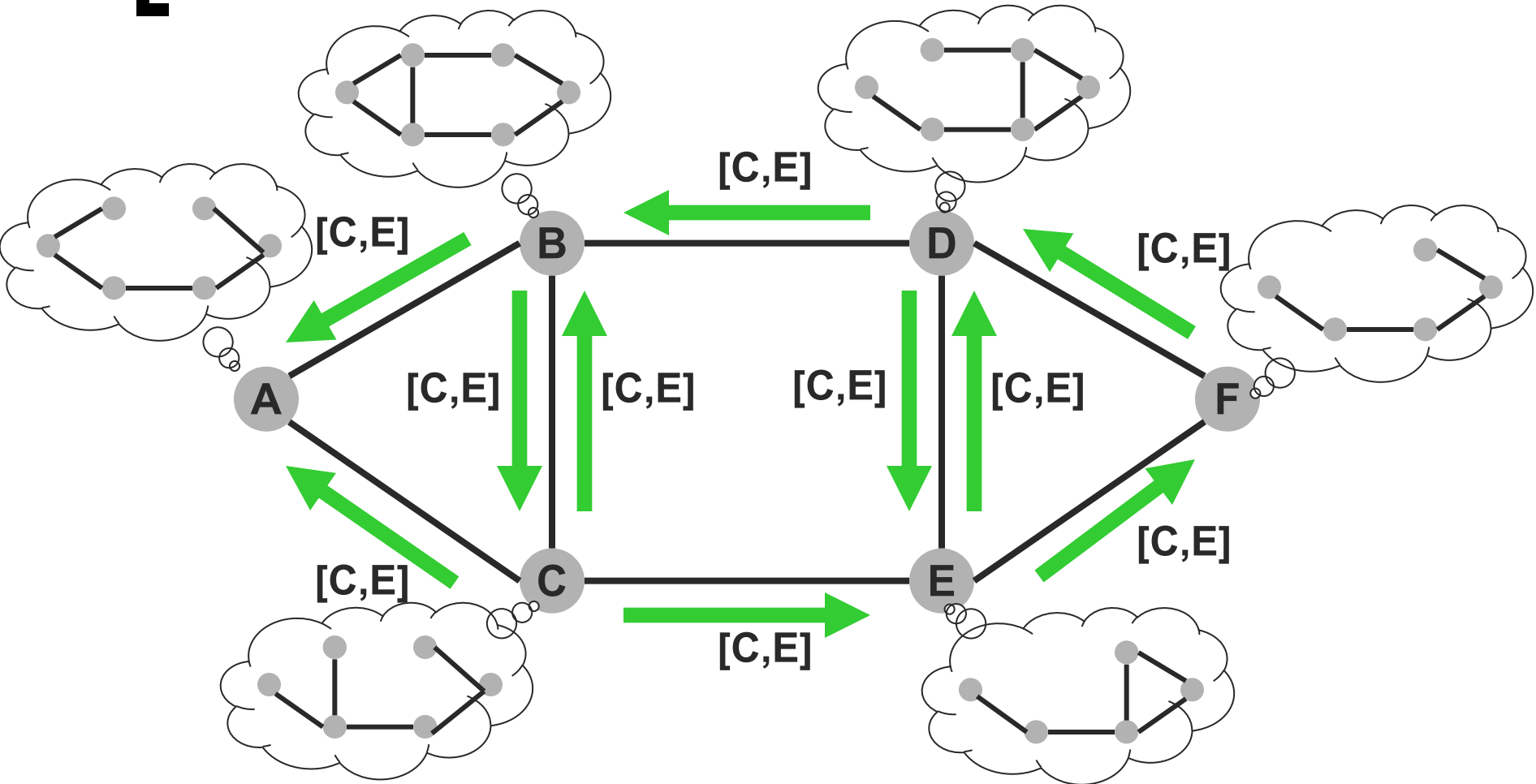
Link state: update propagation



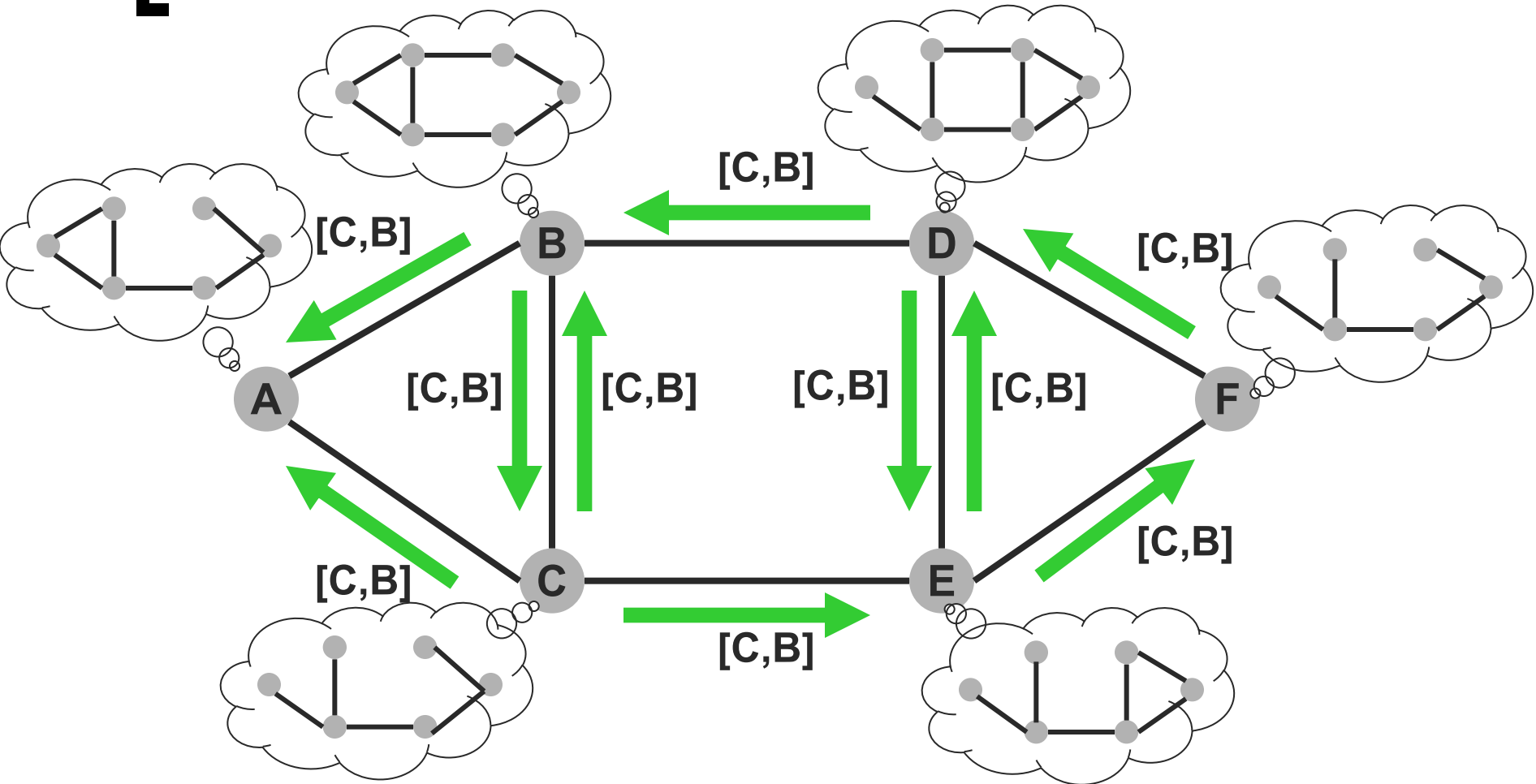
[Link state: update propagation]



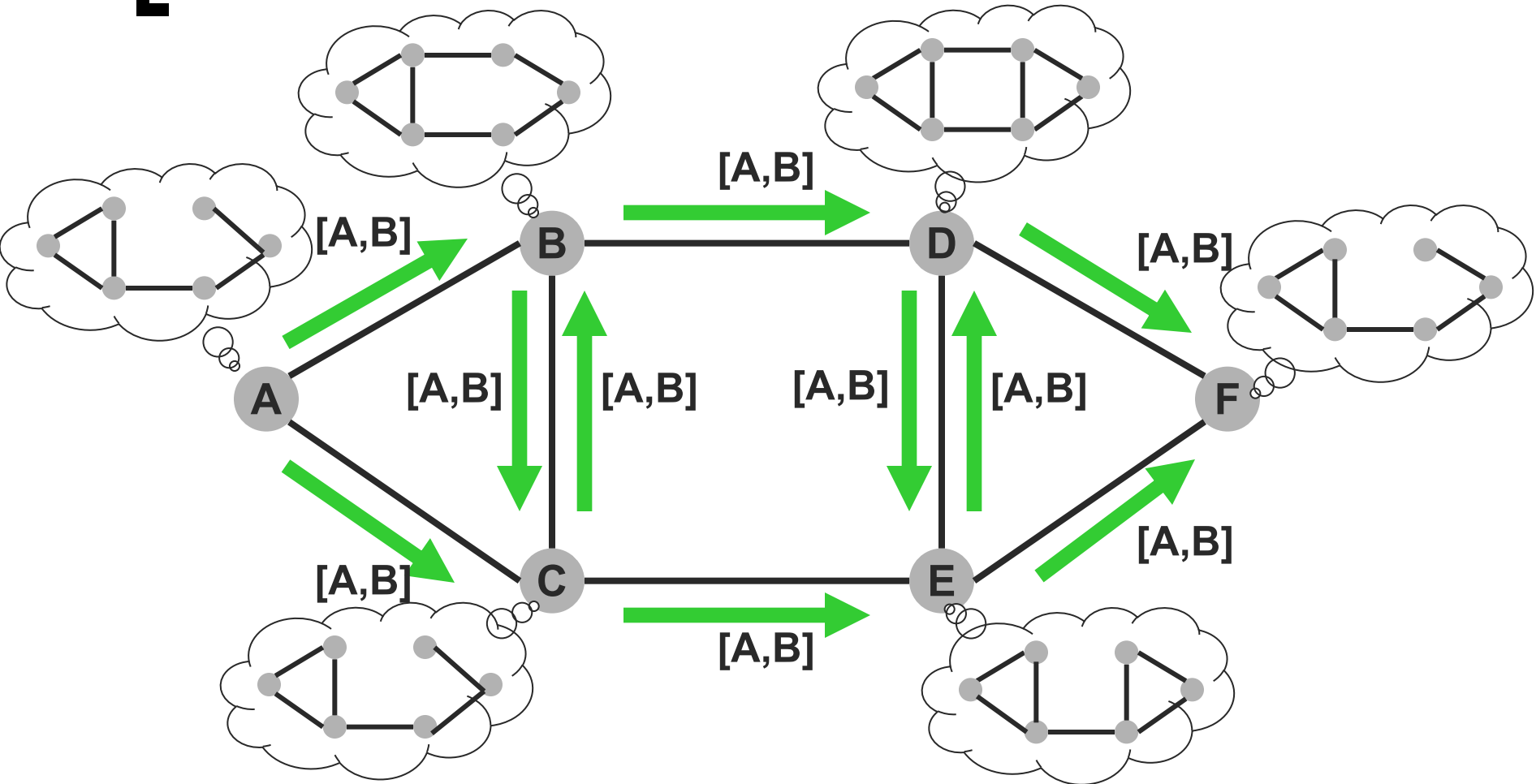
Link state: update propagation



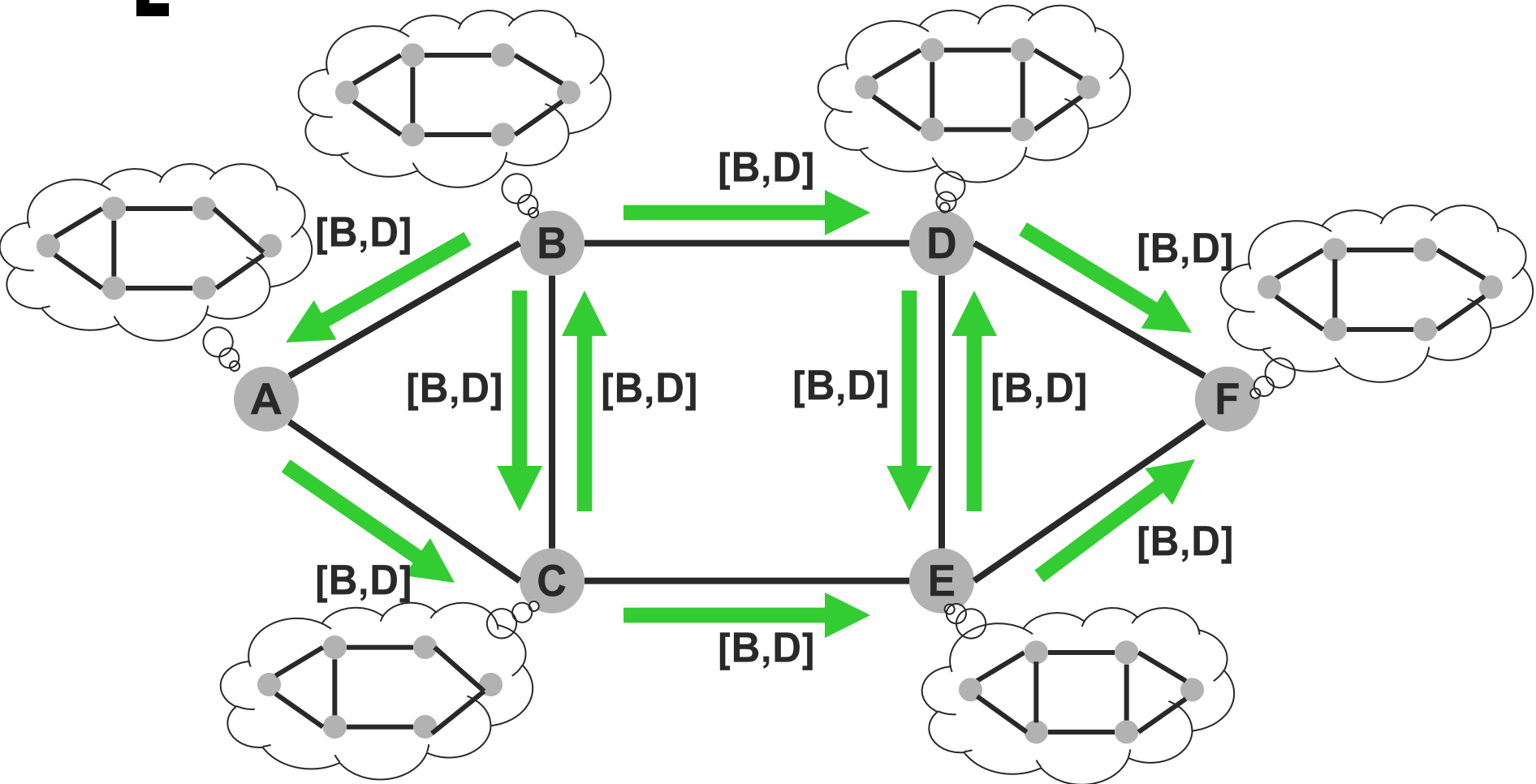
[Link state: update propagation]



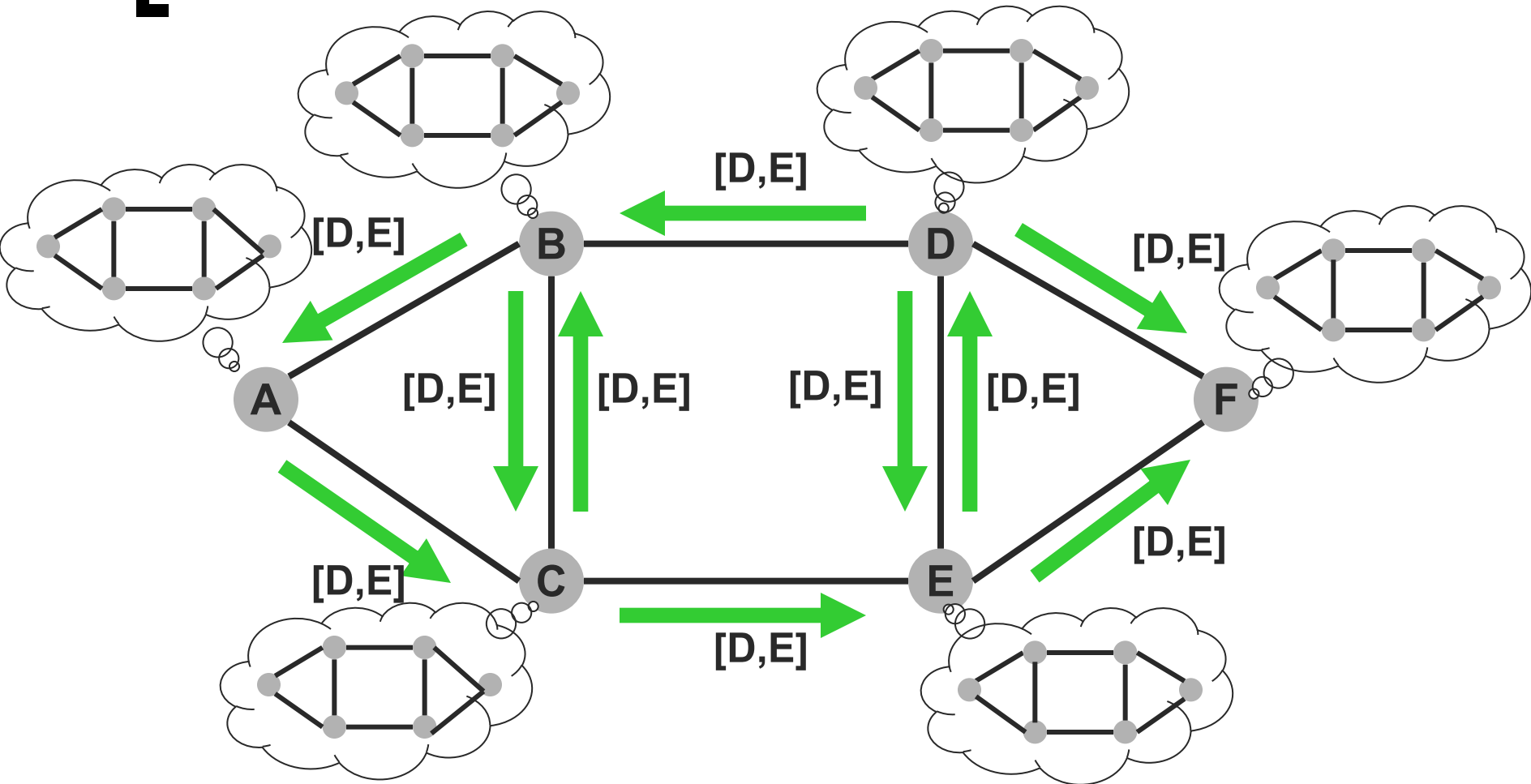
Link state: update propagation



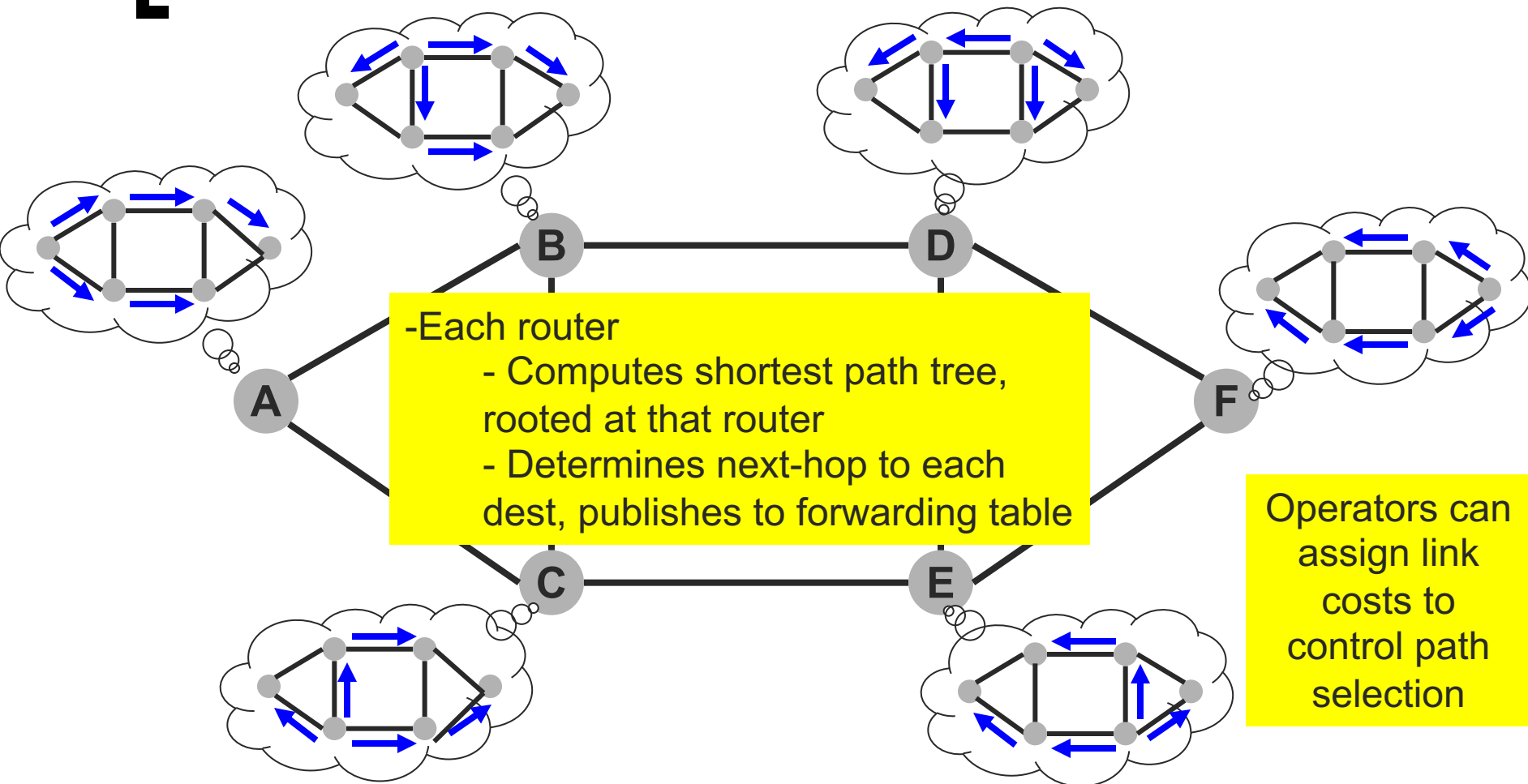
[Link state: update propagation]



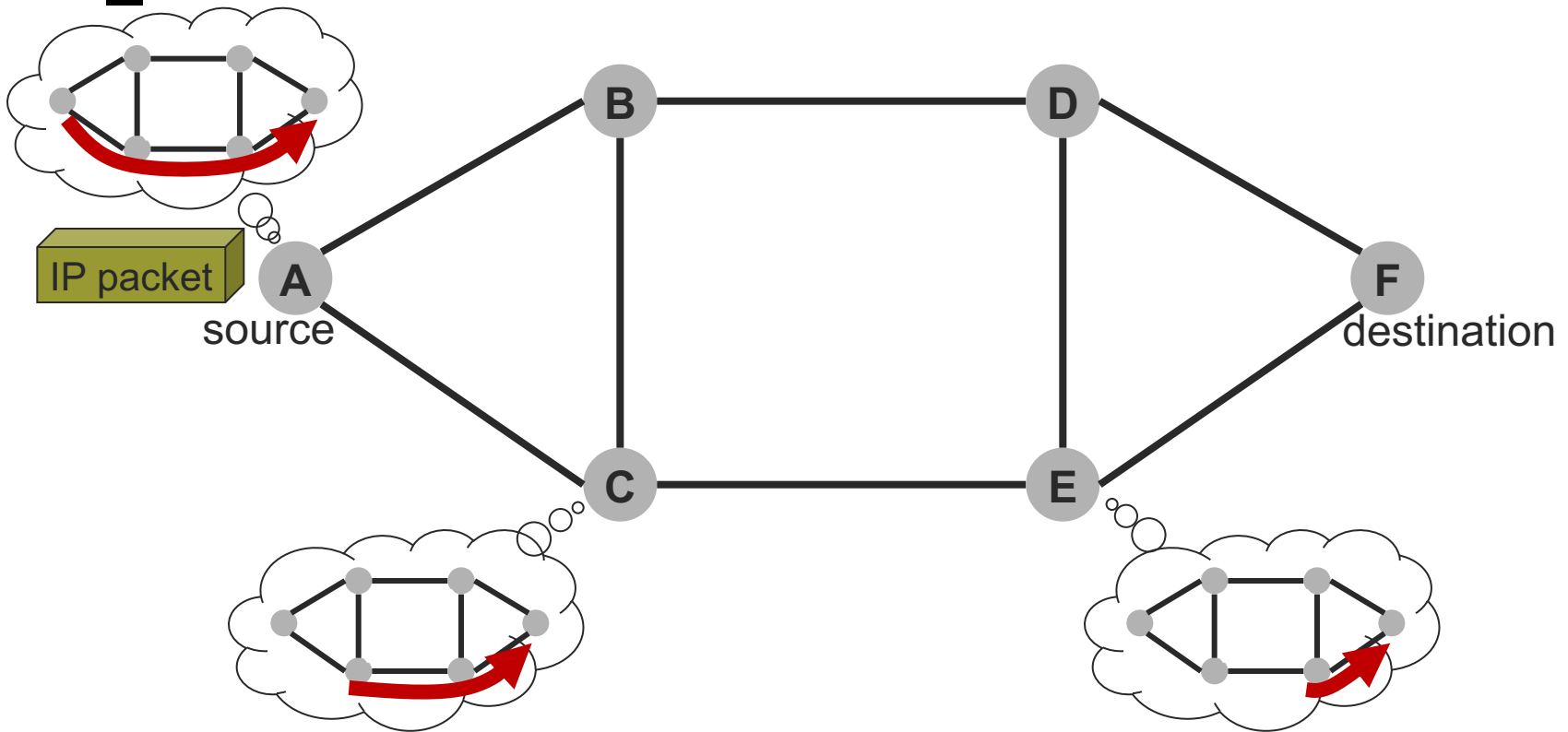
Link state: update propagation



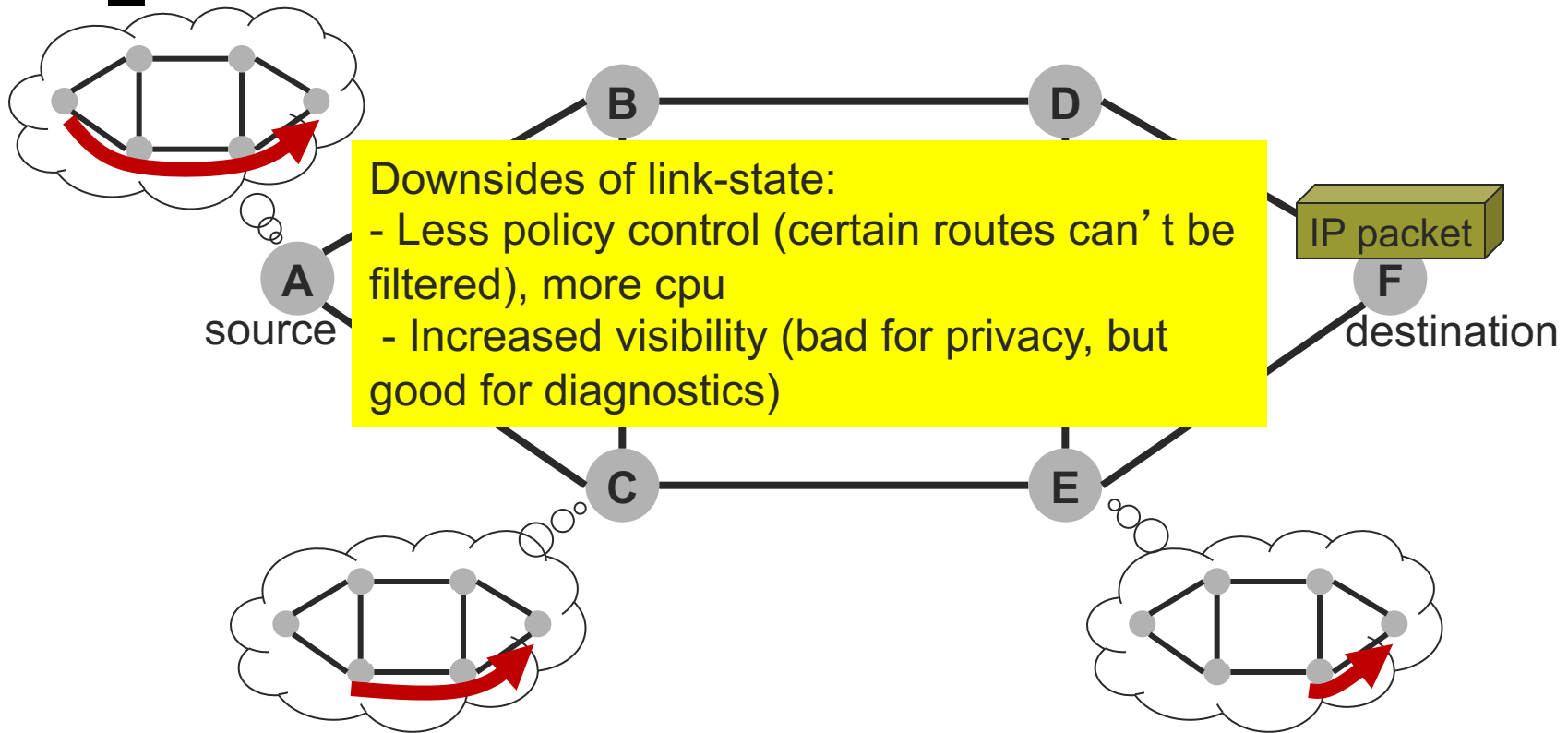
Link state: route computation



Link-state: packet forwarding



Link-state: packet forwarding



[Link State Routing]

- LSP must be delivered to all nodes
- Information acquisition via reliable flooding
 - Create local LSP periodically with increasing sequence number
 - Send local LSP to all immediate neighbors
 - Forward new LSP out on all other links
- What does “new” mean?
 - New sequence number
 - TTL accounts for wrapped sequence numbers
 - Decrement TTL for stored nodes



[Basic Steps]

- Each node assumed to know state of links to its neighbors
- **Step 1:** Each node broadcasts its state to all other nodes
- **Step 2:** Each node locally computes shortest paths to all other nodes from global state



[Reliable Flooding]

- When i receives LSP from j:
 - If LSP is the most recent LSP from j that i has seen so far
 - i saves it in database and forwards a copy on all links except link LSP was received on
 - Otherwise, discard LSP

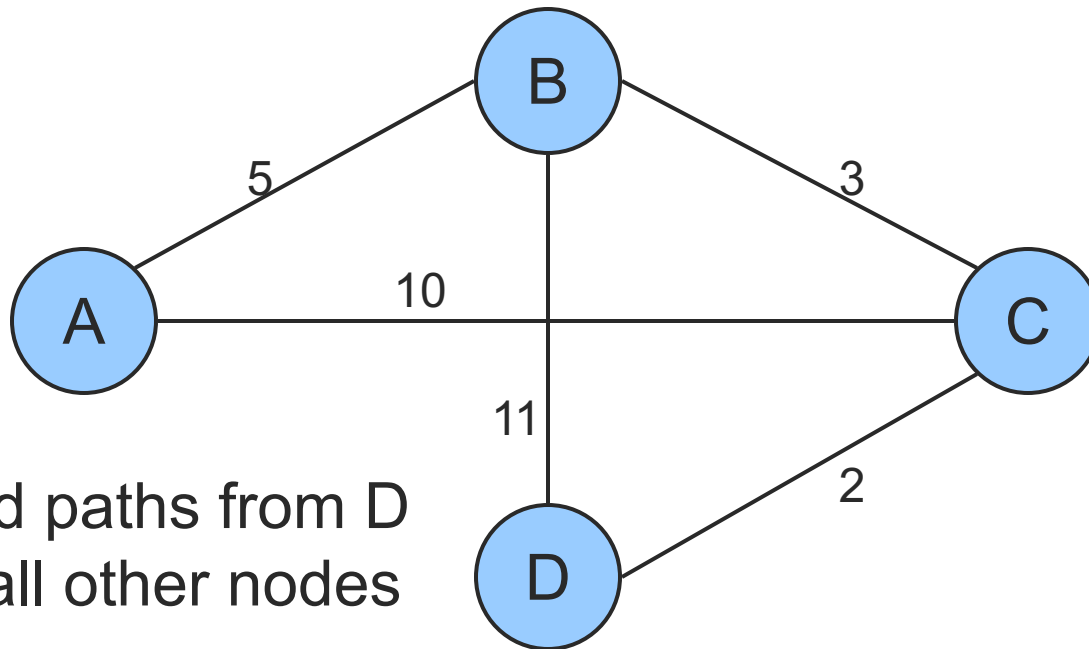


[Link State Routing]

- At each router, perform a forward search algorithm
 - Variation of Dijkstra's
 - Variants to improve performance
 - e.g., incremental Dijkstra's
- Router maintains two lists
 - Tentative
 - Confirmed
- Each list contains triplets
 - <destination, cost, nexthop>



[Link State Routing]

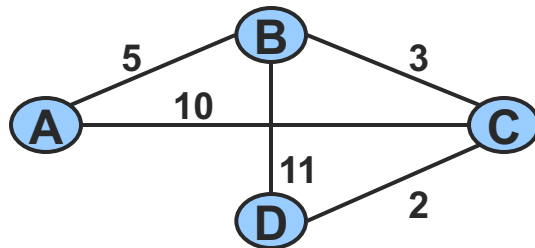


Find paths from D
to all other nodes



[Link State Routing]

Step	Confirmed	Tentative
1.		
2.		
3.		
4.		

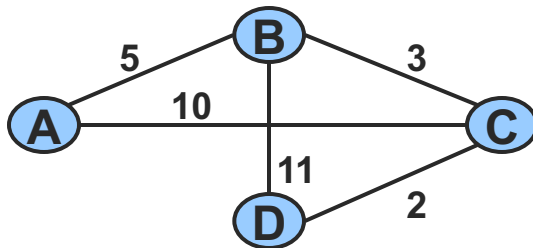


Step	Confirmed	Tentative
5		
6		
7		



Link State Routing

Step	Confirmed	Tentative
1.	(D,0,-)	
2.	(D,0,-)	(B,11,B) (C,2,C)
3.	(D,0,-) (C,2,C)	(B,11,B)
4.	(D,0,-) (C,2,C)	(B,5,C) (A,12,C)

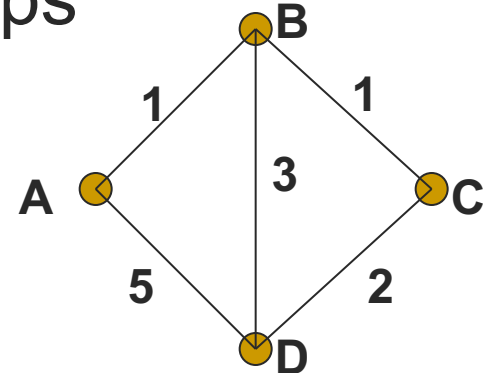


Step	Confirmed	Tentative
5	(D,0,-) (C,2,C) (B,5,C)	(A,12,C)
6	(D,0,-) (C,2,C) (B,5,C)	(A,10,C)
7	(D,0,-) (C,2,C) (B,5,C) (A,10,C)	



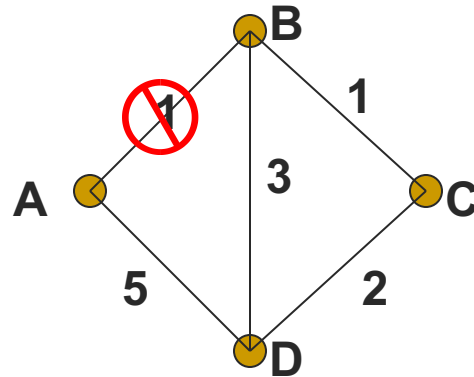
Link State Characteristics

- With consistent LSDBs, all nodes compute consistent loop-free paths
- Limited by Dijkstra computation overhead, space requirements
- Can still have transient loops



[Link State Characteristics]

- How could this cause loops?



Packet from C→A
may loop around BDC



[Source Routing]

- Variant of link state routing
 - Like link state, distribute network topology and compute shortest paths at source
 - ...but only at source, not every hop!



[Link State Routing]

- Pros

- Stabilizes quickly, does not generate much traffic, responds to topology changes or node failures

- Cons

- Amount of information stored at each node is large



Link State Routing in the Wild

- Intermediate System-Intermediate System (IS-IS)
 - Designed for DECnet
 - Adopted by ISO for connectionless network layer protocol (CNLP)
 - Used in NSFNET backbone
 - Used in some digital cellular systems
- ARPANET
 - Bad heuristics brought down the network in 1981
- Internet
 - Open shortest path first (OSPF)
 - Defined in RFC 5340
 - Used in some ISPs

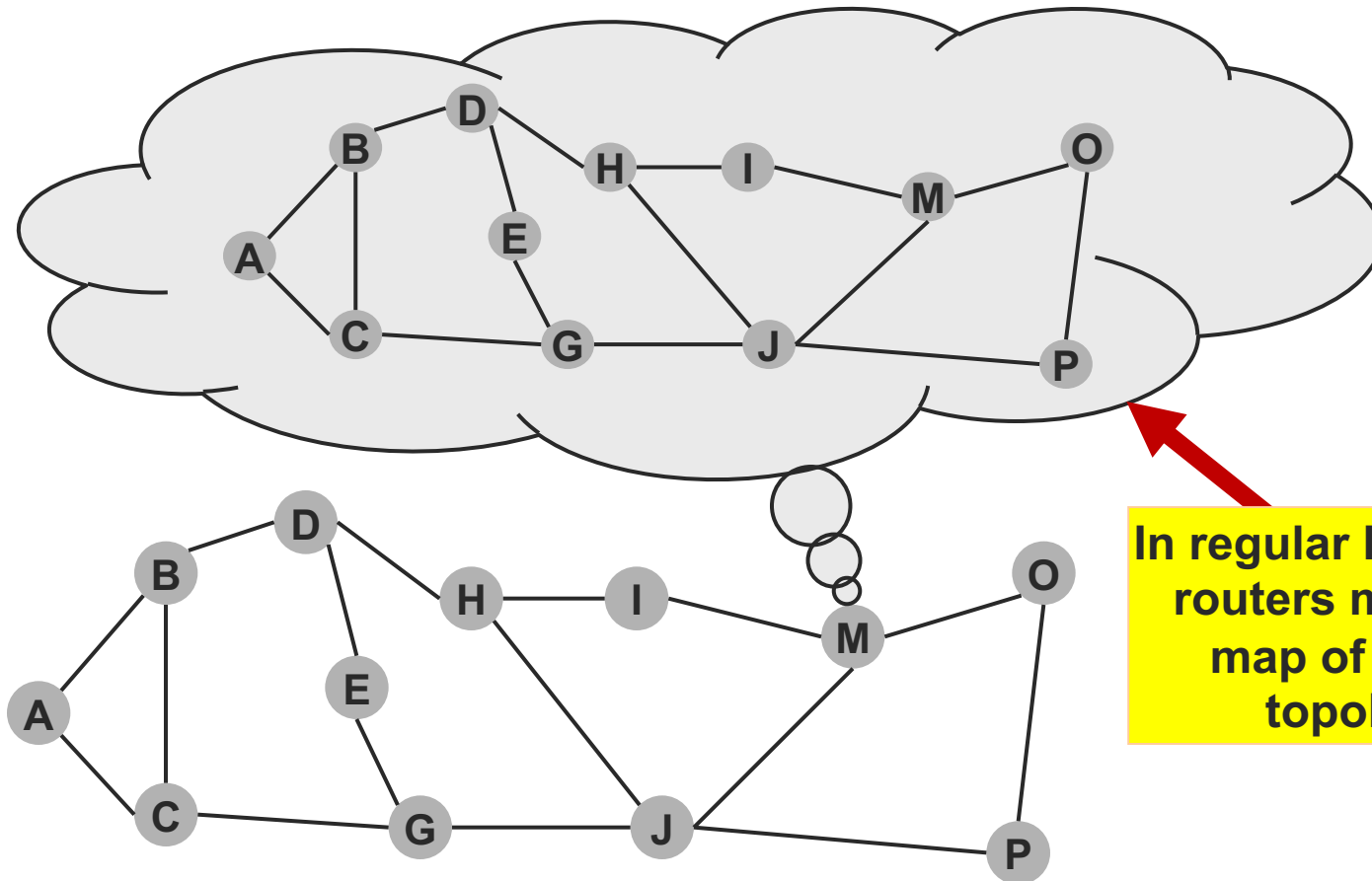


[OSPF]

- Authentication of routing messages
 - Encrypted communication between routers
- Additional hierarchy
 - Domains are split into areas
 - Routers only need to know how to reach every node in a domain
 - Routers need to know how to get to the right area
 - Load balancing
 - Allows traffic to be distributed over multiple routes



OSPF - Hierarchical routing



In regular link-state, routers maintain map of entire topology

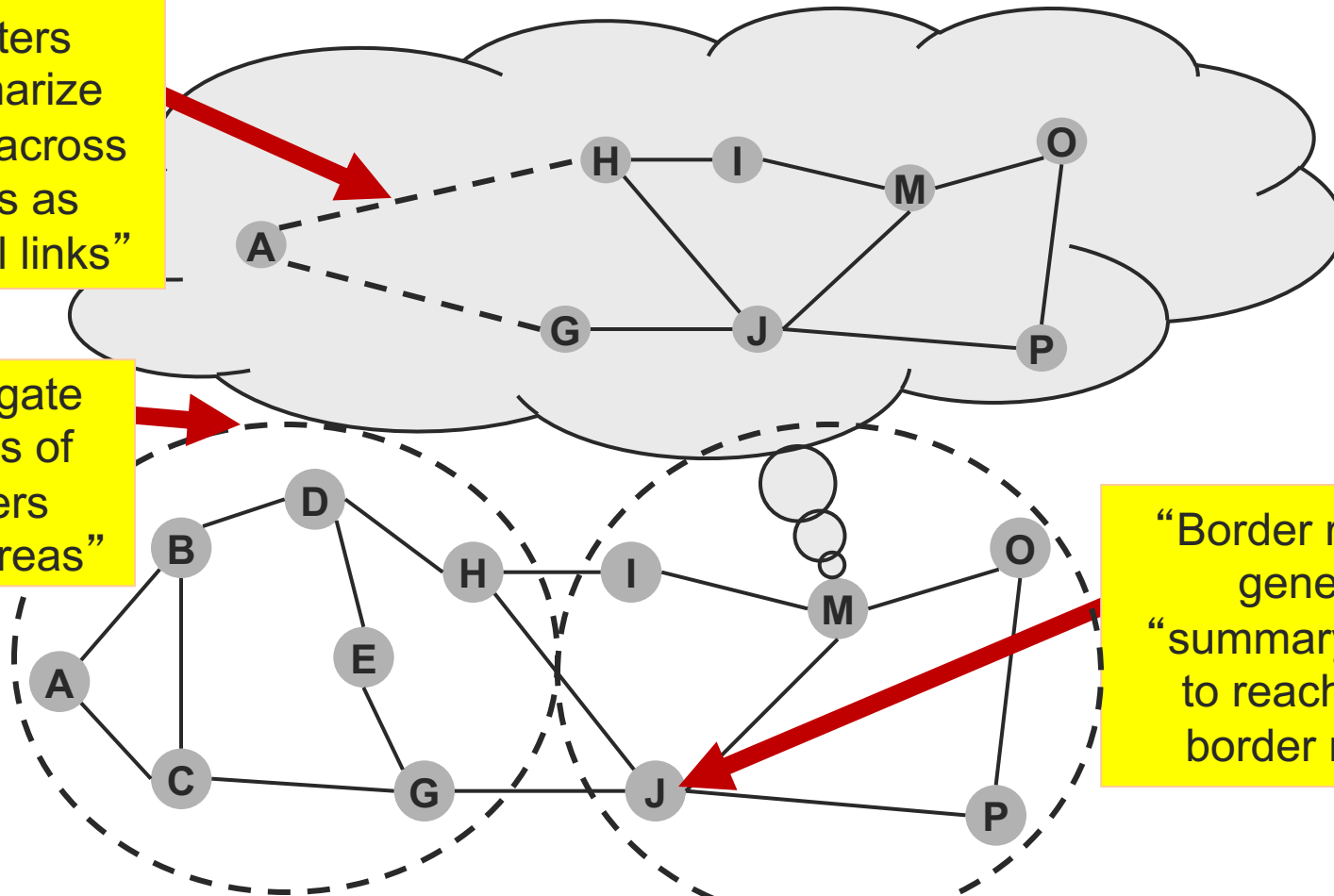


OSPF - Hierarchical routing

Routers summarize paths across areas as “virtual links”

Aggregate groups of routers into “areas”

“Border routers” generate “summary LSPs” to reach other border routers



Tradeoffs of hierarchical routing

- Advantages: scalability
 - Reduce size of link-state database
 - Isolate rest of network from changes/faults
- Disadvantages
 - Complexity
 - Extra configuration effort
 - Requires tight coupling with address assignment
 - Inefficiency
 - One link change may affect multiple path costs
 - Summarization hides shorter paths



[LS vs. DV]

- DV
 - Send everything you know to your neighbors
- LS
 - Send info about your neighbors to everyone
- Message size
 - Small with LS
 - Potentially large with DV
- Message exchange
 - LS: $O(nE)$
 - DV: only to neighbors



[LS vs. DV]

- Convergence speed
 - LS: fast
 - DV: fast with triggered updates
- Space requirements
 - LS maintains entire topology
 - DV maintains only neighbor state



[LS vs. DV: Robustness]

- LS can broadcast incorrect/corrupted LSP
 - localized problem
- DV can advertise incorrect paths to all destinations
 - incorrect calculation can spread to entire network
- Soft-state vs. Hard-state approaches
 - Should we periodically refresh? Or rely on routers to locally maintain their state correctly?



[LS vs. DV]

■ LS

- Nodes must compute consistent routes independently
- Must protect against LSDB corruption

■ DV

- Routes are computed relative to other nodes

■ Bottom line

- No clear winner, but we see more frequent use of LS in the Internet



[LS vs. DV]

- LS typically used *within* ISPs because
 - Faster convergence (usually)
 - Simpler troubleshooting
- DV typically used *between* ISPs because
 - Can support more flexible policies
 - Can avoid exporting routes
 - Can hide private regions of topology



A decorative graphic consisting of a thin gold circle on the left. A horizontal bar with a gold-to-white gradient extends from the circle across the top of the slide. A large black left bracket is on the left side of the bar, and a large gold right bracket is on the right side.

Metrics

Traffic engineering with routing protocols

- Load balancing
 - Some hosts/networks/paths are more popular than others
 - Need to shift traffic to avoid overrunning capacity
- Avoiding oscillations
 - What if metrics are a function of offered load?
 - Causes dependencies across paths



Importance of Cost Metric

- Choice of link cost defines traffic load
 - Low cost = high probability link belongs to SPT
 - Will attract traffic, which increases cost
- Main problem: convergence
 - Avoid oscillations
 - Achieve good network utilization



[Metrics]

- Capture a general notion of distance
- A heuristic combination of
 - Distance
 - Bandwidth
 - Average traffic
 - Queue length
 - Measured delay



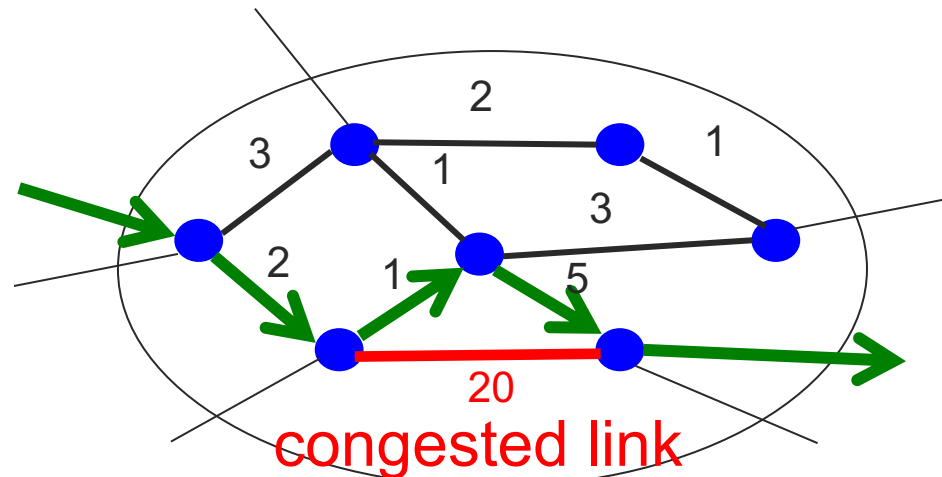
[Metric Choices]

- Static metrics (e.g., hop count)
 - Good only if links are homogeneous
 - Definitely not the case in the Internet
- Static metrics do not take into account
 - Link delay
 - Link capacity
 - Link load (hard to measure)
- But, can improve stability



[Original ARPANET (1969)]

- Distance vector routing
 - Routing tables exchanged every $2/3$ seconds
- Use queue length as distance
 - Number of packets waiting to use a link
 - Instantaneous queue length as delay estimator



Original ARPANET Algorithm

- Light load
 - Delay dominated by the constant part (transmission and propagation delay)
- Medium load
 - Queuing delay no longer negligible
 - Moderate traffic shifts to avoid congestion
- Heavy load
 - Very high metrics on congested links
 - Busy links look bad to all of the routers
 - All routers avoid the busy links
 - Routers may send packets on longer paths



[Original ARPANET]

- Uniform 56 Kbps lines
 - Bandwidth equal on every line
 - Latency relatively unimportant
- Problems
 - Uniform bandwidth became an invalid assumption
 - Latency comparable to 1 KB transmission delay on 1.544 Mbps link



[New ARPANET(1979)]

- Switch to link-state routing
- Routing updates only contain link cost information
- Link metric is measured delay
- Max time between updates = 50 sec



[New ARPANET(1979)]

- Averaging of link metric over time
 - Old: Instantaneous delay fluctuates a lot
 - New: Averaging reduces the fluctuations
- Link-state protocol instead of DV
 - Old: DV led to loops
 - New: Flood metrics and let each router compute shortest paths
- Reduce frequency of updates
 - Old: Sending updates on each change is too much
 - New: Send updates if change passes a threshold



[Problem #2: Load balancing]

- Conventional static metrics:
 - Proportional to physical distance
 - Inversely proportional to link capacity
- Conventional dynamic metrics:
 - Tune weights based on the offered traffic
 - Network-wide optimization of link-weights
 - Directly minimizes metrics like maximum link utilization



Metrics: New Arpanet

- Captured delay, bandwidth and latency
- Queue delay
 - Timestamp packet arrival time (AT)
 - Also timestamp packet departure time (DT)
 - Only calculate when ACK received
 - Average DT- AT over packets and time
- Used fixed (per-link) measurements
 - Transmission time (bandwidth)
 - Latency
- Add three terms to find “distance” metric



Metrics: New ARPANET

- Assumption
 - Measured delay = expected delay
- Worked well under light load
 - Static factors dominated cost
- Oscillated under heavy load
 - Heavily loaded link advertises high price
 - All traffic moves off
 - Then link advertises light load
 - All traffic returns
 - Repeat cycle

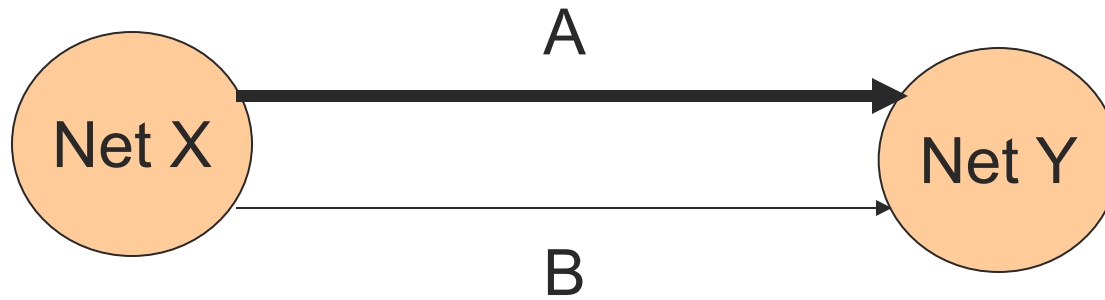


[Specific problems]

- Range is too wide
 - 9.6 Kbps highly loaded link can appear 127 times costlier than 56 Kbps lightly loaded link.
 - Can make a 127-hop path look better than 1-hop.
- No limit in reported delay variation
- All nodes calculate routes simultaneously
 - Triggered by link update

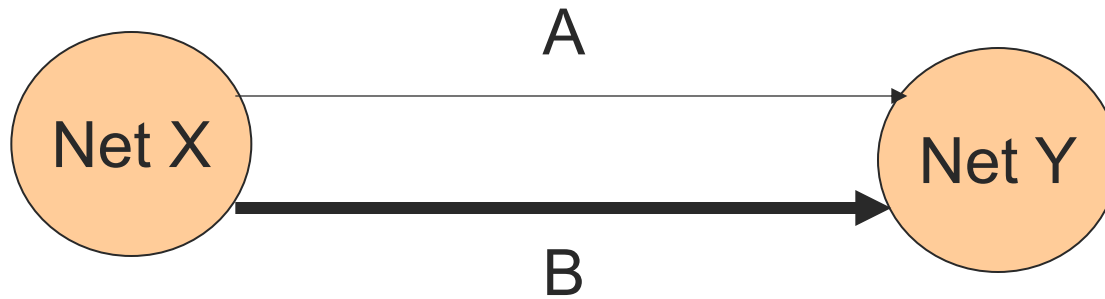


[Example]



[Example]

After everyone re-calculates routes:



.. Oscillations!



[Consequences]

- Low network utilization (50% in example)
- Congestion can spread elsewhere
- Routes could oscillate between short and long paths
- Large swings lead to frequent route updates
 - More messages
 - Frequent SPF re-calculation



[Some Considerations]

- Delay as absolute measure of path length
- Greedy approach to route selection
 - Each node chooses shortest path without regards for how it affects others
- Instead, routing should provide good path to average node
 - Some nodes get longer routes



Metrics: Revised ARPANET

- Measure link utilization
- Feed measurement through function to restrict dynamic range
- Specific function chosen carefully based on bandwidth and latency
- Aspects of class of functions
 - Cost is constant at low to moderate utilization
 - Link cost is no more than 3 times idle link cost
 - Maximum cost (over all links) is no more than 7 times minimum cost (over all links)



[Reality of the Modern Internet]

- Hierarchical routing used
 - Between different Autonomous Systems (e.g., a provider network), a standard protocol
 - Within each AS
 - Up to AS administrator
 - Usually a variant of link-state or distance-vector
- What metrics are really used?
 - Nothing involving load
 - Just too unstable



Application to AT&T's backbone network

- Performance of the optimized weights
 - Search finds a good (approximate) solution within a few minutes
 - Much better than link capacity or physical distance
- How AT&T changes the link weights
 - Maintenance from Midnight to 6am ET
 - Predict effects of removing links from network
 - Reoptimize links to avoid congestion
 - Configure new weights before disabling equipment (costing-out)

