

Distributed Hash Tables

CS425 /ECE428 – DISTRIBUTED SYSTEMS – FALL 2021

Material derived from slides by I. Gupta, M. Harandi,
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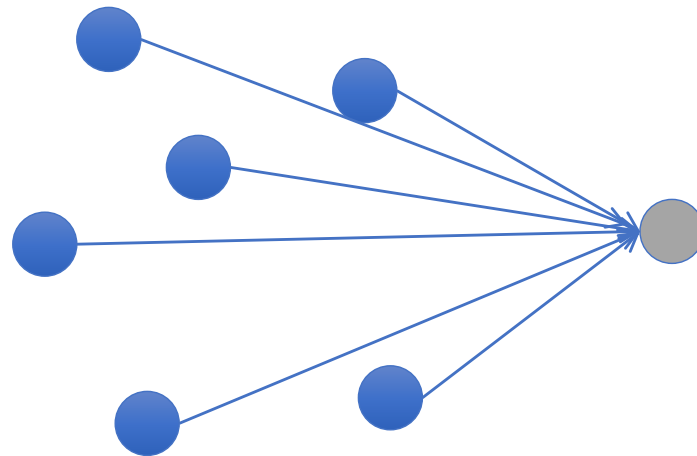


Distributed System Organization

- Centralized
- Ring
- Clique
- How well do these work with 1M+ nodes?

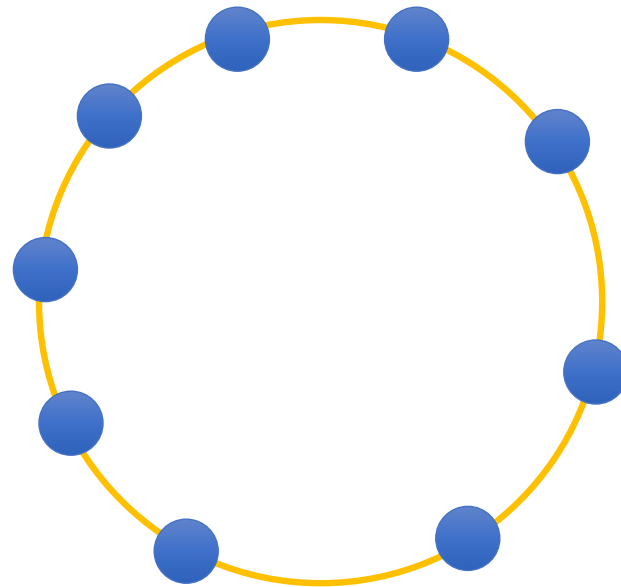
Centralized

- Problems?
- Leader a bottleneck
 - $O(N)$ load on leader
- Leader election expensive



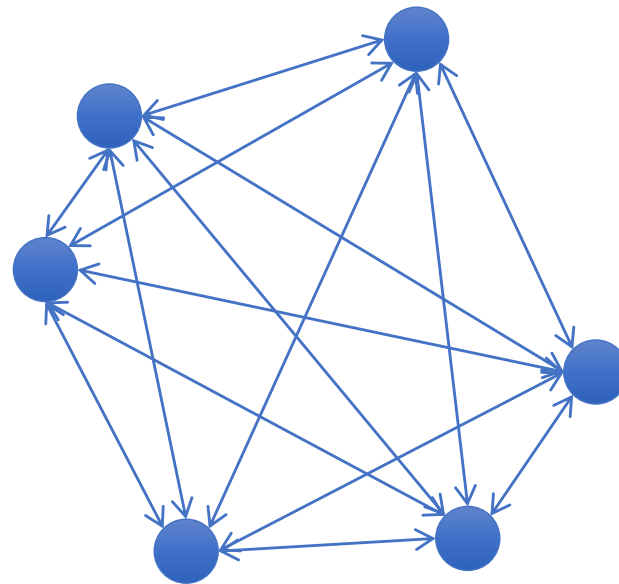
Ring

- Problems?
- Fragile
 - $O(1)$ failures tolerated
- Slow communication
 - $O(N)$ messages



Clique

- Problems?
- High overhead
 - $O(N)$ state at each node
 - $O(N^2)$ messages for failure detection



Distributed Hash Tables

- Middle point between ring and clique
- Scalable *and* fault-tolerant
 - Maintain $O(\log N)$ state
 - Routing complexity $O(\log N)$
 - Tolerate $O(N)$ failures
- Other possibilities:
 - State: $O(1)$, routing: $O(\log N)$
 - State: $O(\log N)$, routing: $O(\log N / \log \log N)$
 - State: $O(\sqrt{N})$, routing: $O(1)$

Distributed Hash Table



- A hash table allows you to insert, lookup and delete objects with keys
- A *distributed* hash table allows you to do the same in a distributed setting (objects=files)
- DHT also sometimes called a **key-value store** when used within a cloud
- Performance Concerns:
 - Load balancing
 - Fault-tolerance
 - Efficiency of lookups and inserts

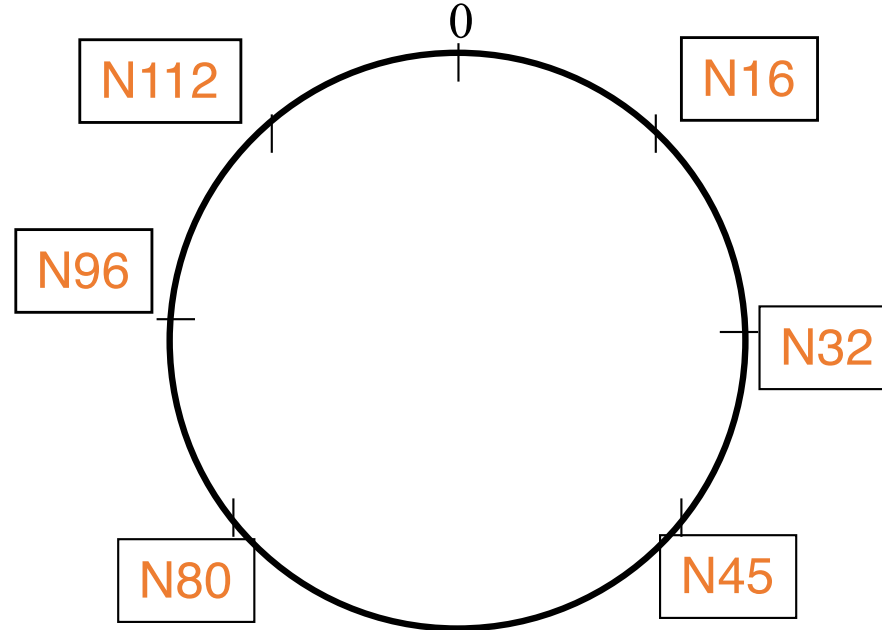
Chord

- Intelligent choice of neighbors to reduce latency and message cost of routing (lookups/inserts)
- Uses *Consistent Hashing* on node' s (peer' s) address
 - (ip_address,port) \rightarrow hashed id (m bits)
 - Called peer *id* (number between 0 and $2^m - 1$)
 - Not unique but id conflicts very unlikely
 - Can then map peers to one of 2^m logical points on a circle

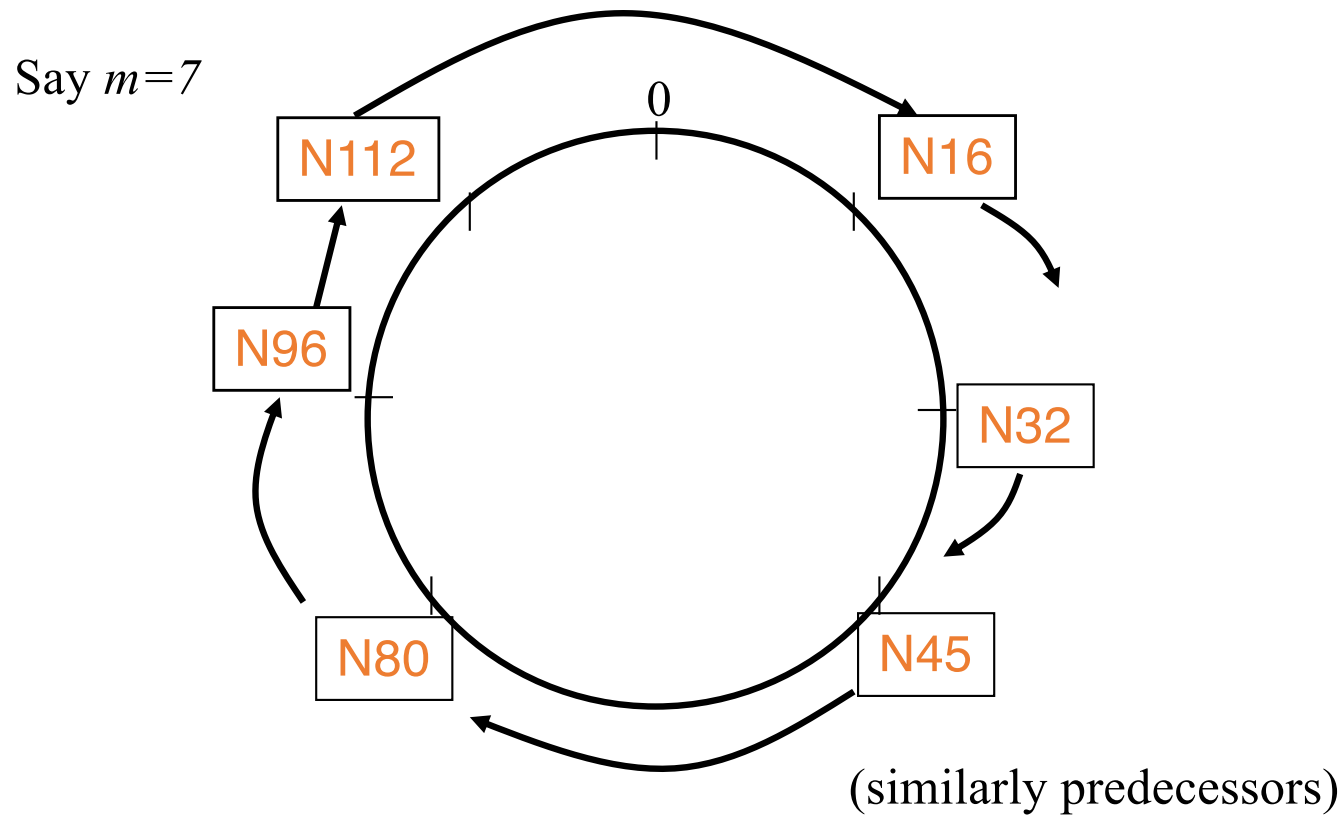
Ring of peers

Say $m=7$

6 nodes



Peer pointers (1): *successors*

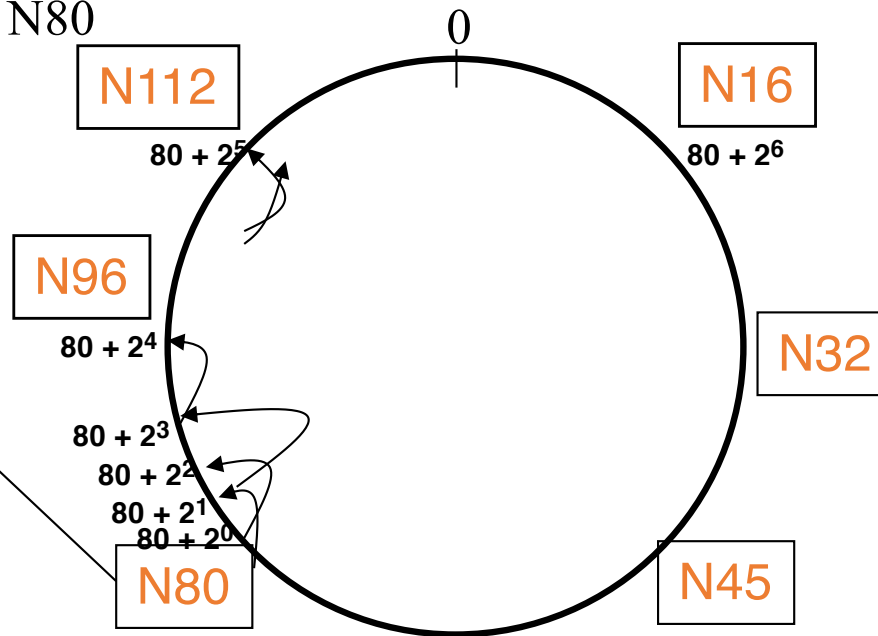


Peer pointers (2): *finger tables*

Say $m=7$

Finger Table at N80

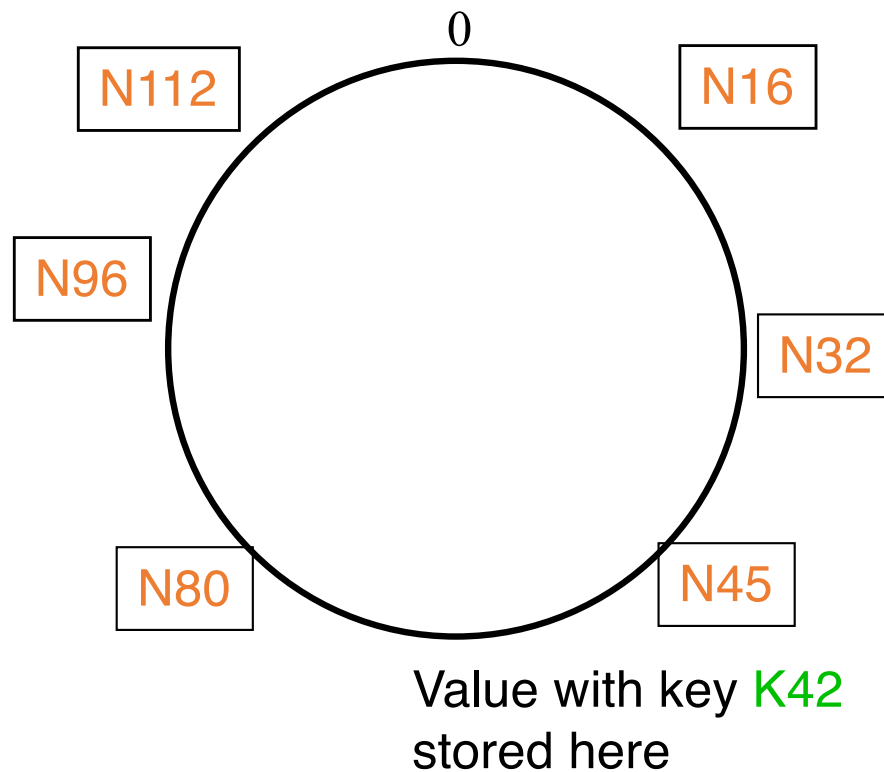
i	$ft[i]$
0	96
1	96
2	96
3	96
4	96
5	112
6	16



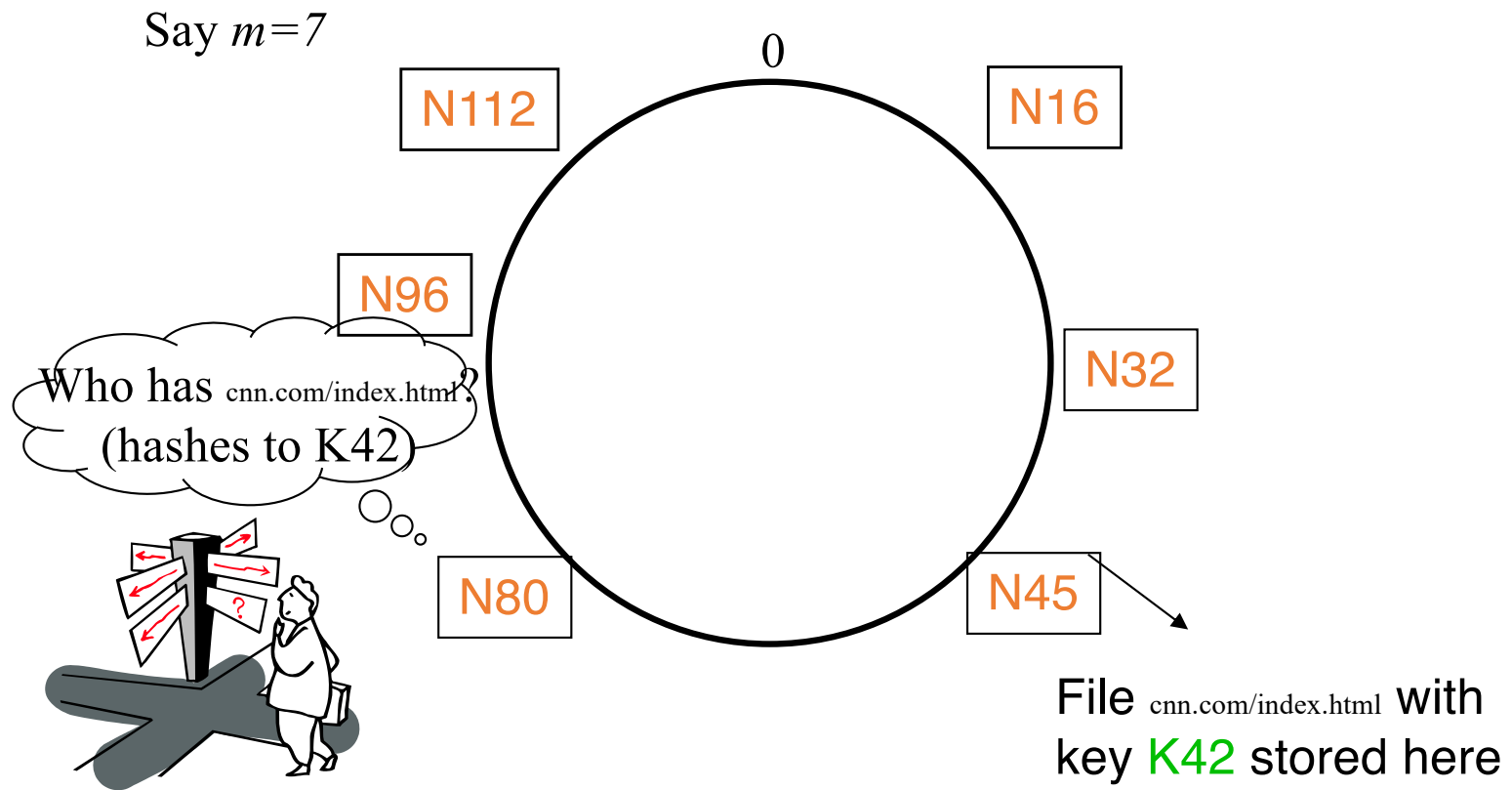
i th entry at peer with id n is first peer with id $\geq n + 2^i \pmod{2^m}$

Mapping Values

- Key =
hash(ident)
 - m bit string
- Value is stored at **first peer with id greater than its key (mod 2^m)**



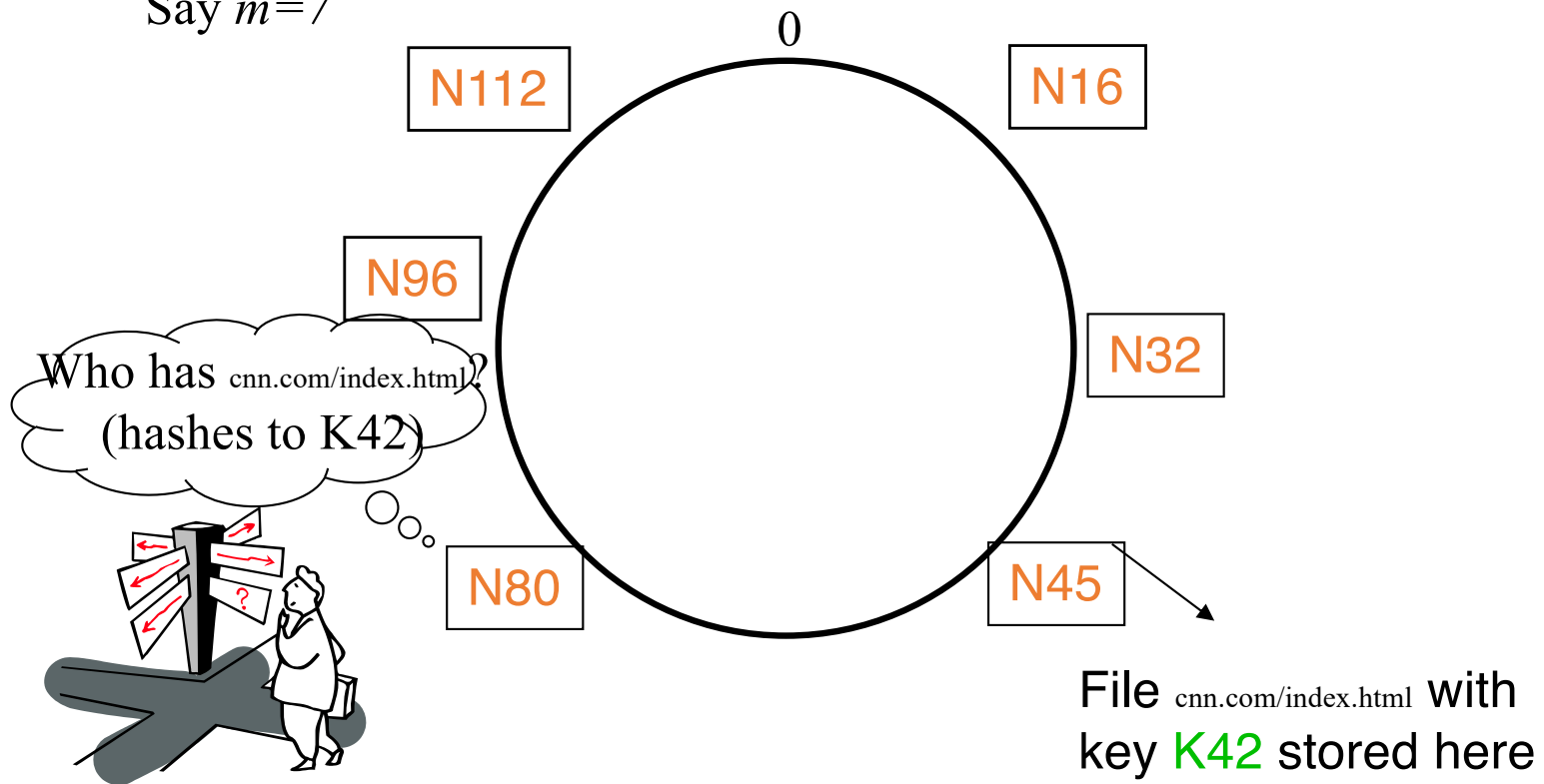
Search



Search

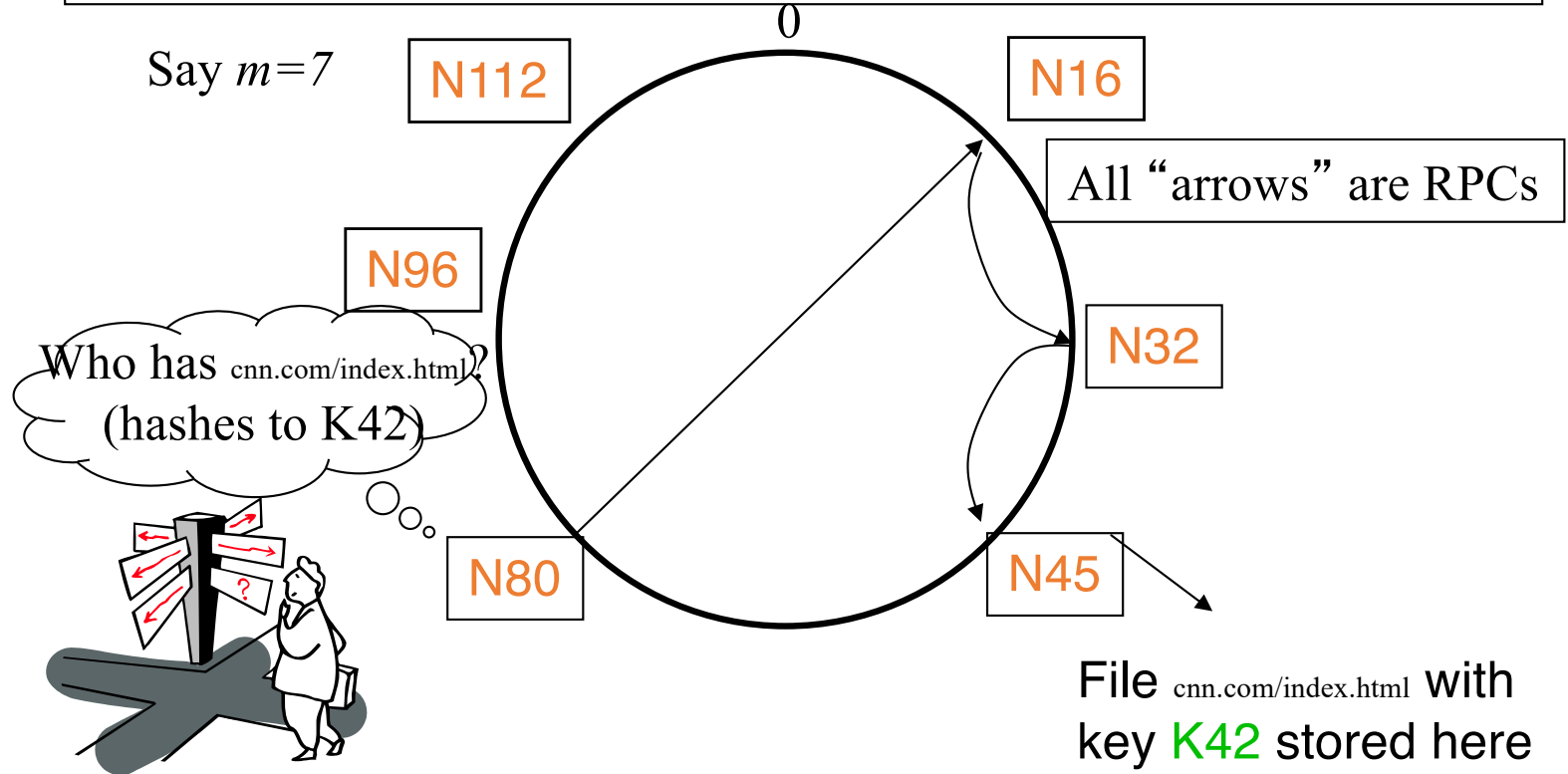
At node n , send query for key k to largest successor/finger entry $\leq k$
if none exist, send query to $successor(n)$

Say $m=7$



Search

At node n , send query for key k to largest successor/finger entry $\leq k$
if none exist, send query to $successor(n)$



Analysis

Search takes $O(\log(N))$ time

Proof

- (intuition): *at each step, distance between query and peer-with-file reduces by a factor of at least 2* (why?)

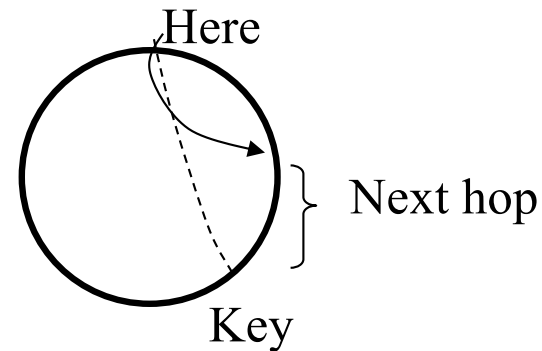
Takes at most m steps: 2^m is at most a constant multiplicative factor above N , lookup is $O(\log(N))$

- (intuition): after $\log(N)$ forwardings, distance to key is at most $2^m / N$ (why?)

Number of node identifiers in a range of $2^m / N$

is $O(\log(N))$ with high probability (why?)

So using *successors* in that range will be ok

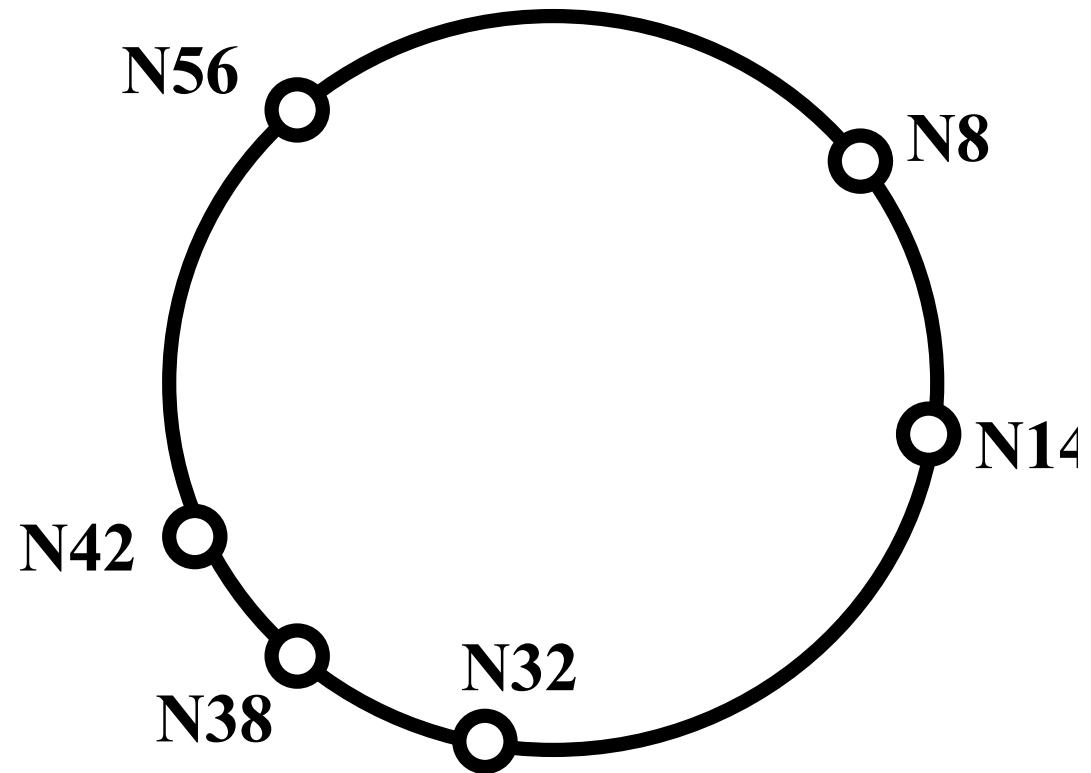


Analysis (contd.)

- $O(\log(N))$ search time holds for file insertions too (in general for *routing to any key*)
 - “Routing” can thus be used as a **building block** for
 - All operations: insert, lookup, delete
- $O(\log(N))$ time true only if finger and successor entries correct
- When might these entries be wrong?
 - When you have failures

Chord Recap

Each node has an identifier
 $id = H(\text{address})$ in the range $[0, 2^m)$



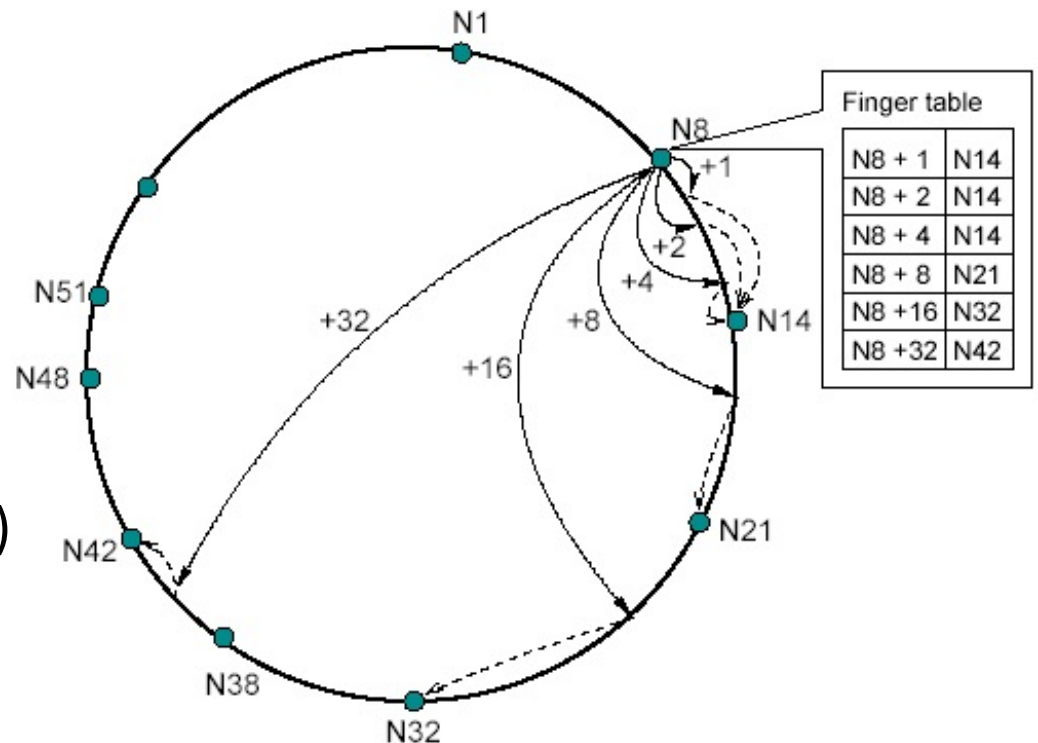
Chord Recap

Each node has an identifier $id = H(\text{address})$ in the range $[0, 2^m)$

$\text{succ}(n)$ = node with next largest ID $> n$, wrapping around mod 2^m

Node with id connects to:

- $\text{succ}(id)$ (successor)
- $\text{succ}((id + 2^i) \bmod 2^m)$ (fingers)



Chord Recap

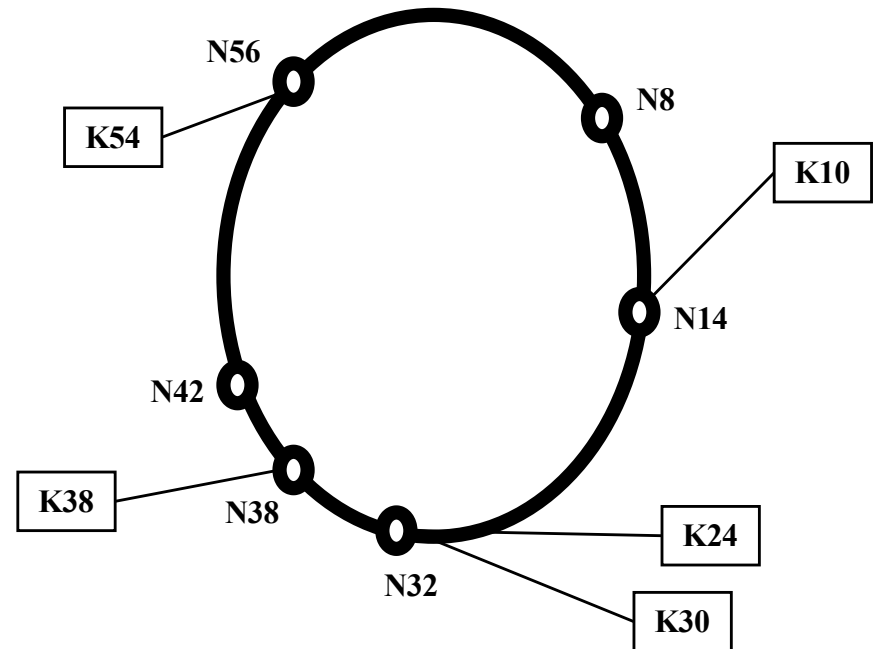
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Chord Recap

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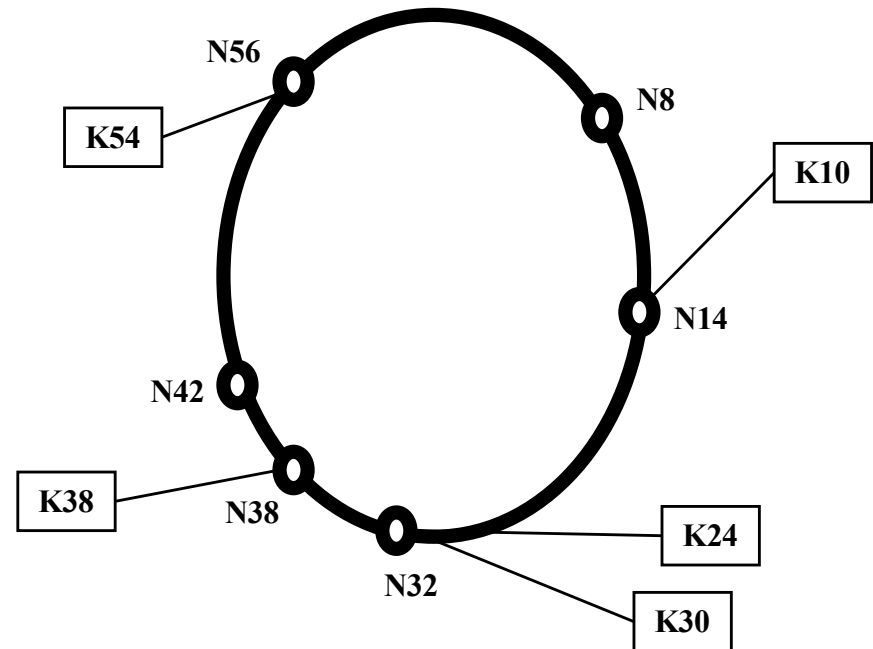
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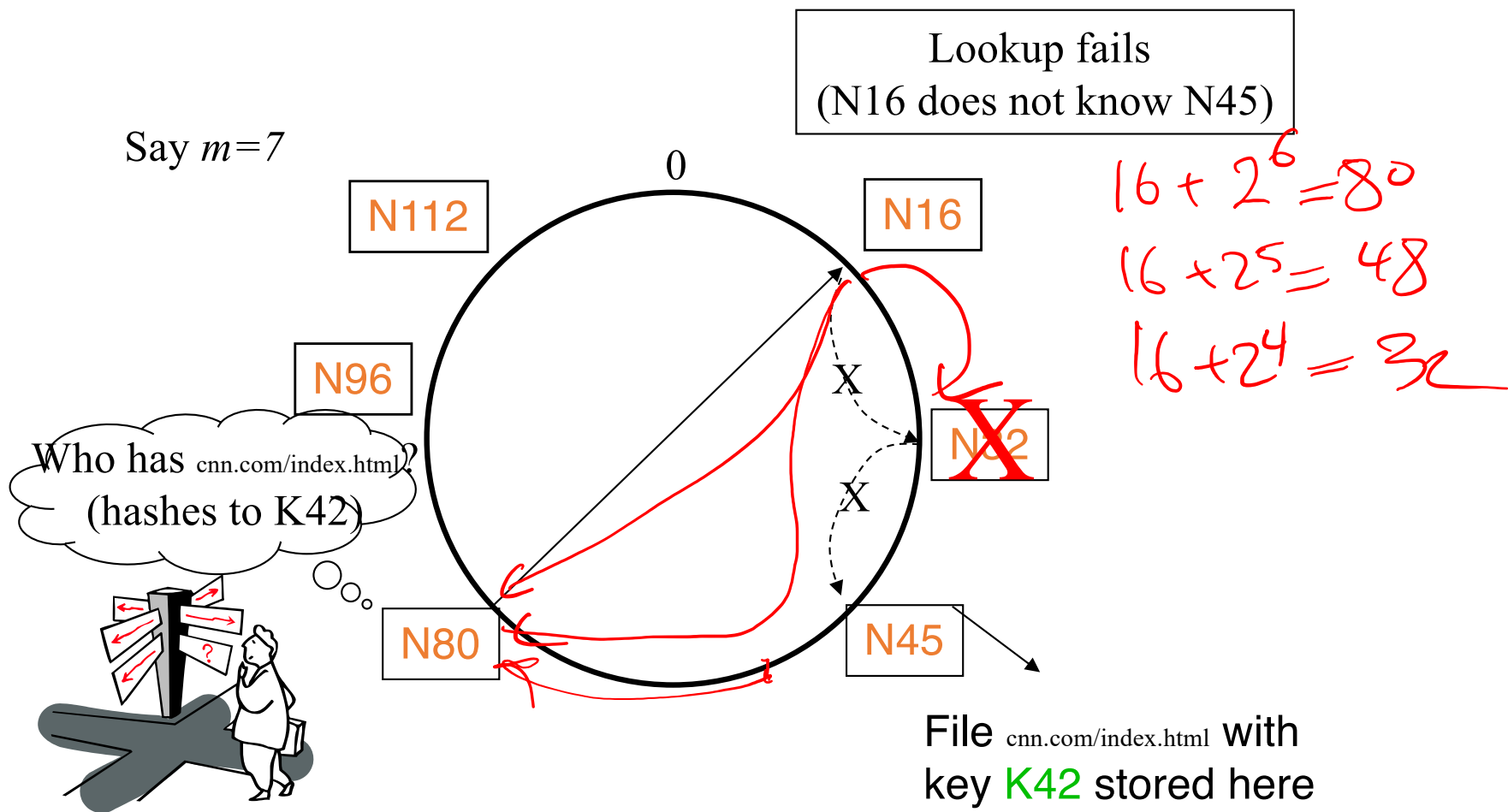
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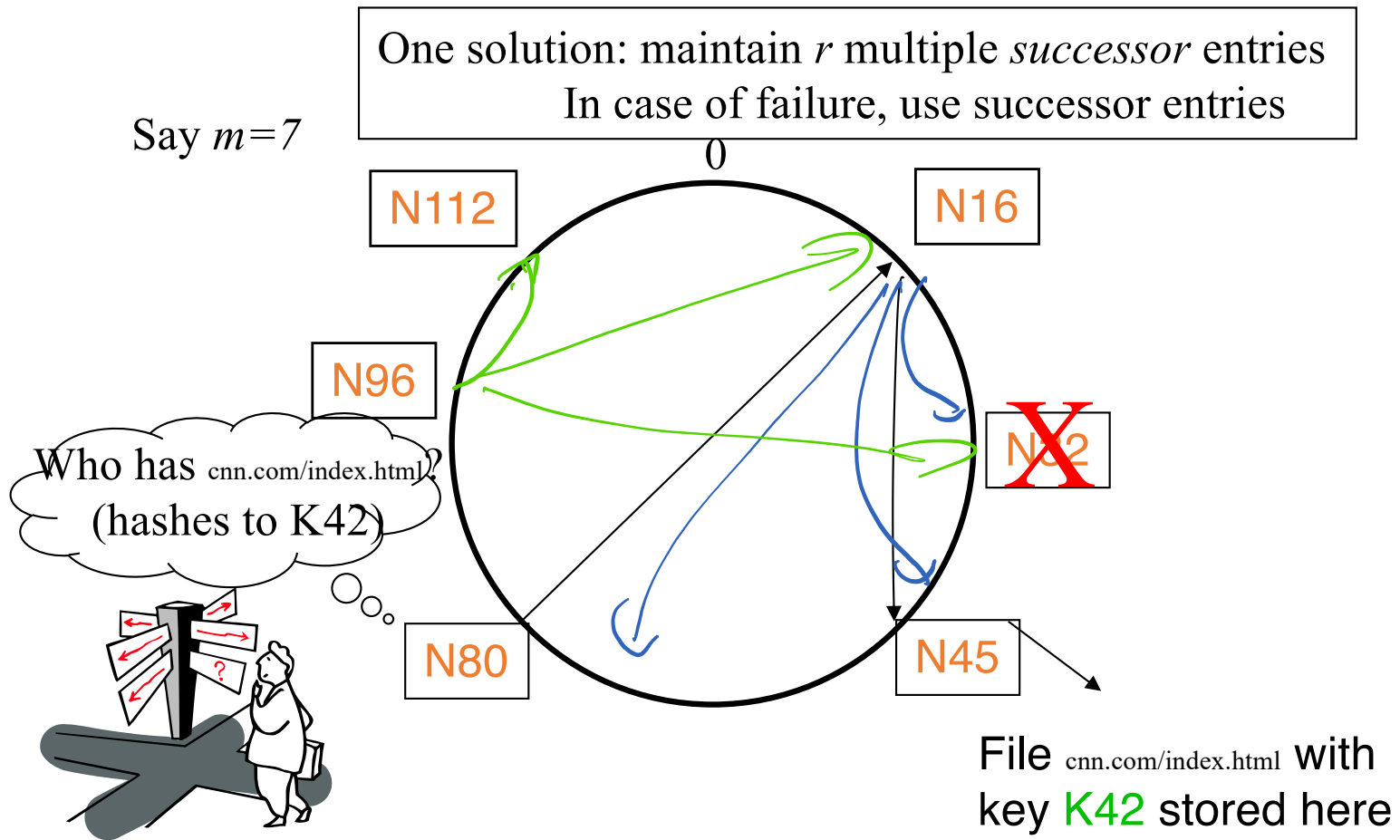
To find key k , recursively follow the finger that gets you closest to k



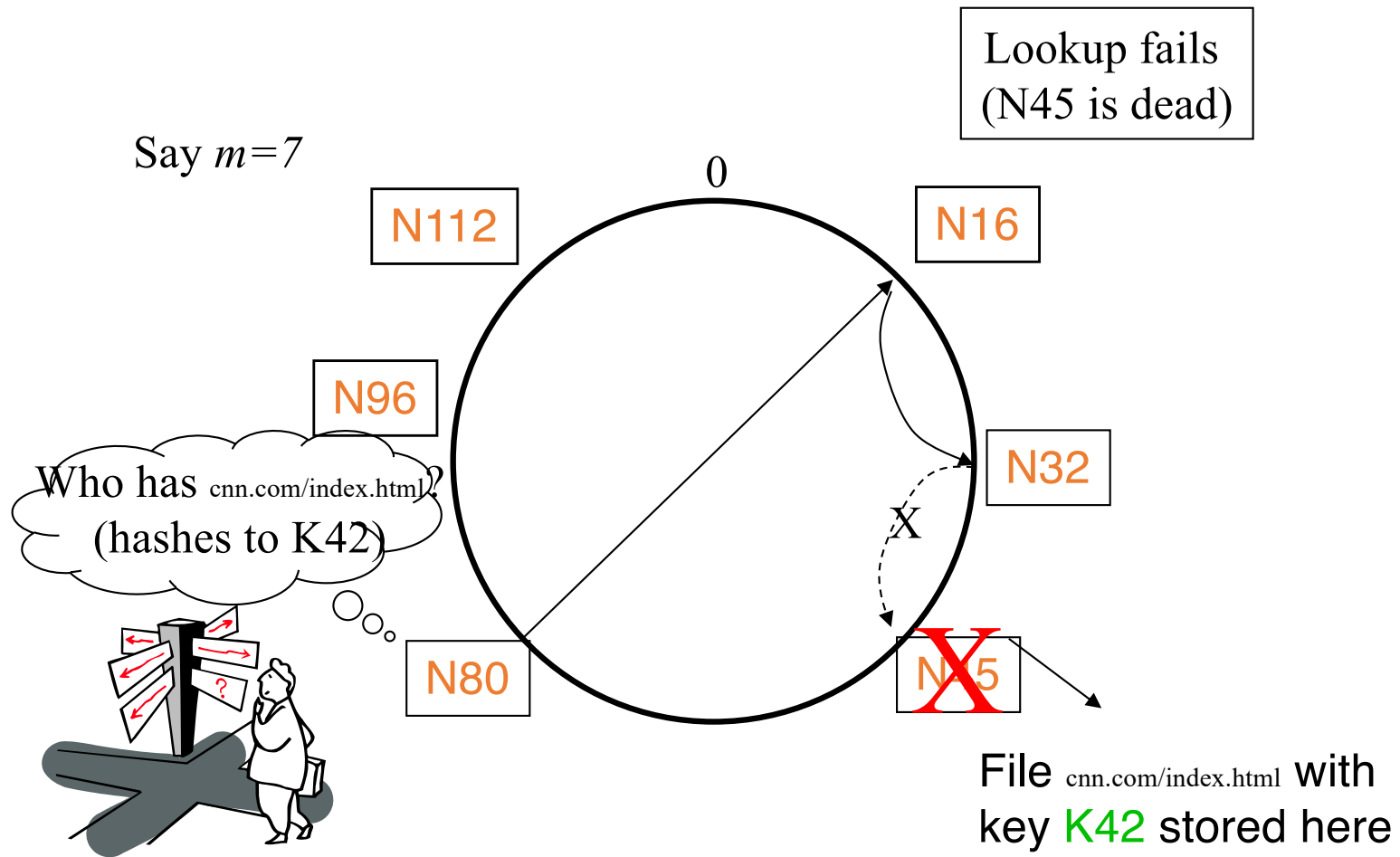
Search under peer failures



Search under peer failures



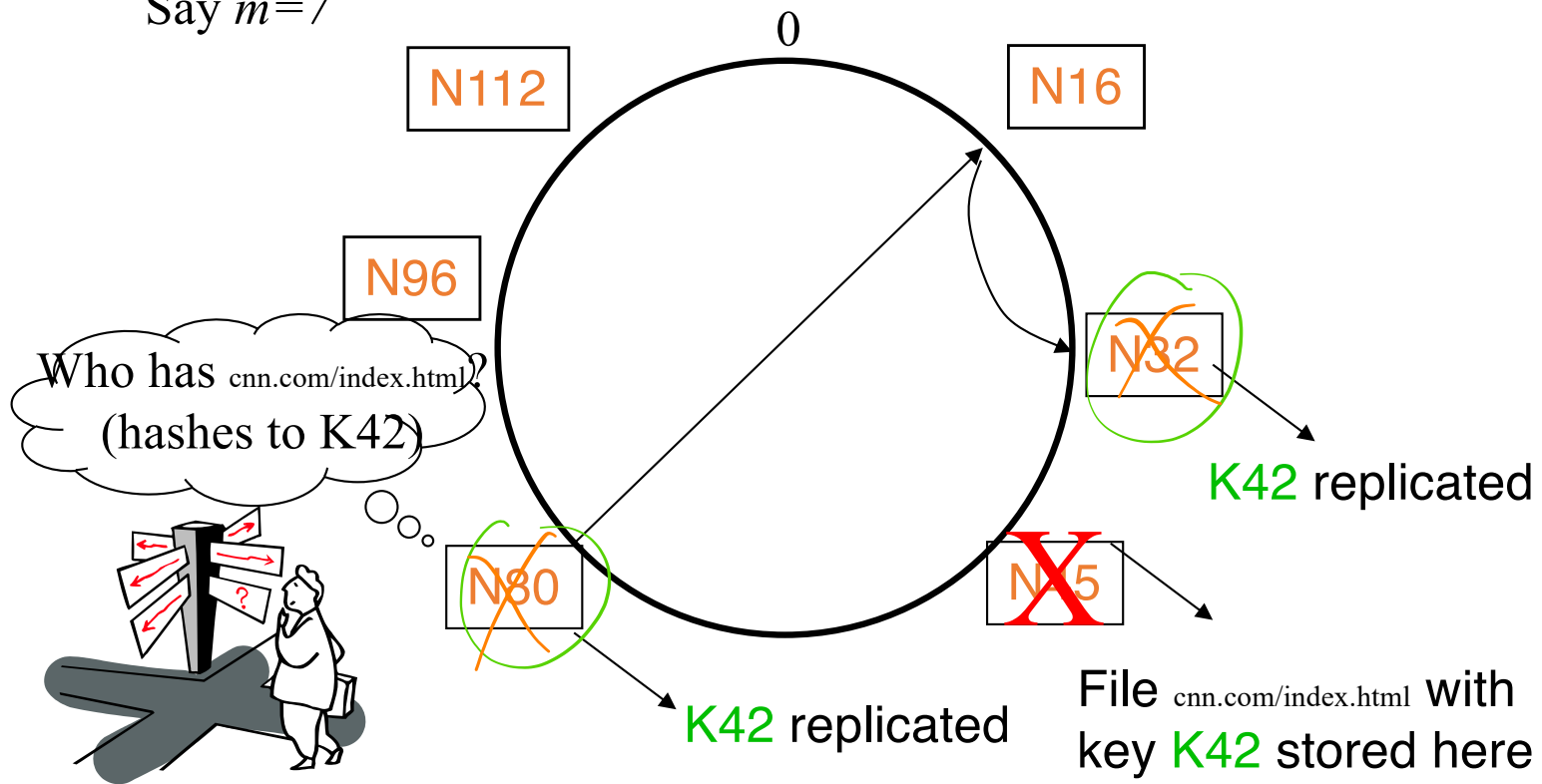
Search under peer failures (2)



Search under peer failures (2)

One solution: replicate file/key at r successors and predecessors

Say $m=7$



Need to deal with dynamic changes

✓ Peers fail

- New peers join
- Peers leave
 - P2P systems have a high rate of *churn* (node join, leave and failure)

→ Need to update *successors* and *fingers*, and copy keys

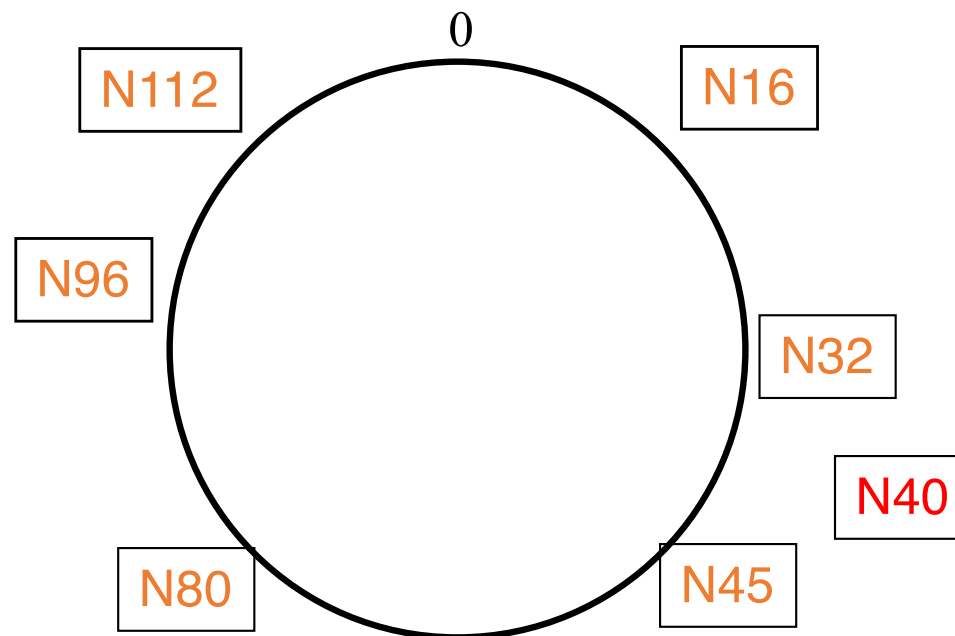
New peers joining

Introducer directs N40 to N45 (and N32)

N32 updates successor to N40

N40 initializes successor to N45, and inits fingers from it

Say $m=7$



New peers joining

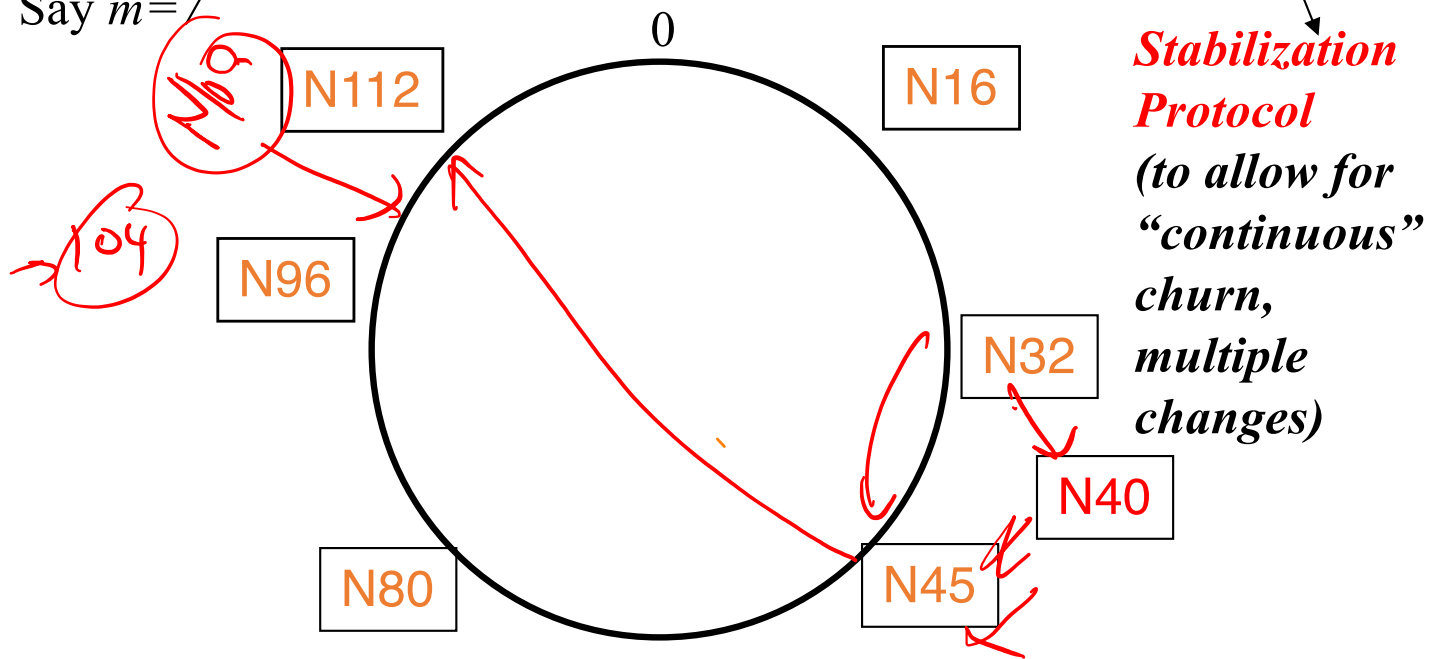
Introducer directs N40 to N45 (and N32)

N32 updates successor to N40

N40 initializes successor to N45, and inits fingers from it

N40 periodically talks to its neighbors to update finger table

Say $m=7$



Stabilization Protocol

(to allow for “continuous” churn, multiple changes)

$$40 + 2^6 \rightarrow$$

$$40 + 2^5$$

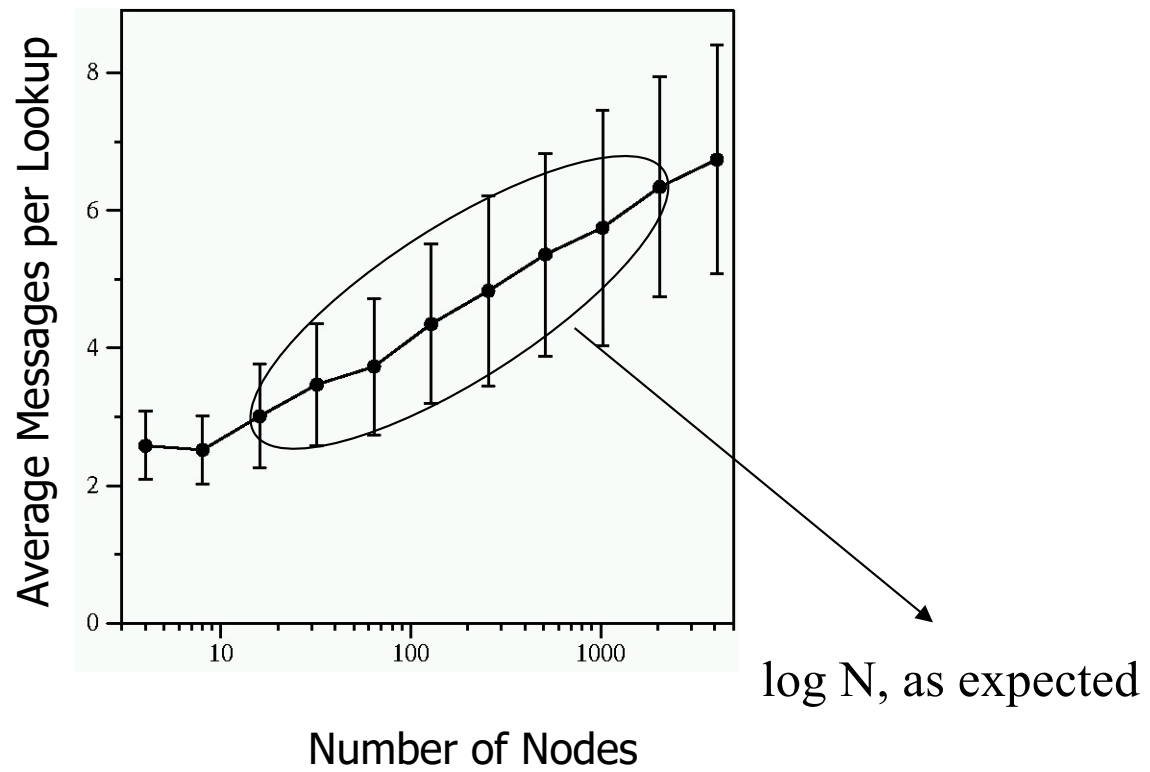
$$40 + 2^4$$

⋮

$$40 + 2^0$$



Lookups



Chord Protocol: Summary

- $O(\log(N))$ memory and lookup costs
- Hashing to distribute filenames uniformly across key/address space
- Allows dynamic addition/deletion of nodes

DHT Deployment

- Many DHT designs
 - Chord, Pastry, Tapestry, Koorde, CAN, Viceroy, Kelips, Kademlia, ...
- Slow adoption in real world
 - Most real-world P2P systems unstructured
 - No guarantees
 - Controlled flooding for routing
 - Kademlia slowly made inroads, now used in many file sharing networks
- Distributed key-value stores adopt some of the ideas of DHTs
 - Dynamo, Cassandra, etc.