CS 425 / ECE 428 Distributed Systems Fall 2014

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Lecture 4: Failure Detection and Membership

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A CHALLENGE

• You've been put in charge of a datacenter, and your manager has told you, "Oh no! We don't have any failures in our datacenter!"

• Do you believe him/her?

- What would be your first responsibility?
- Build a failure detector
- What are some things that could go wrong if you didn't do this?

FAILURES ARE THE NORM

... not the exception, in datacenters.

Say, the rate of failure of one machine (OS/disk/motherboard/network, etc.) is once every 10 years (120 months) on average.

When you have 120 servers in the DC, the mean time to failure (MTTF) of the next machine is 1 month.

When you have 12,000 servers in the DC, the MTTF is about once every 7.2 hours!

Soft crashes and failures are even more frequent!

TO BUILD A FAILURE DETECTOR

You have a few options

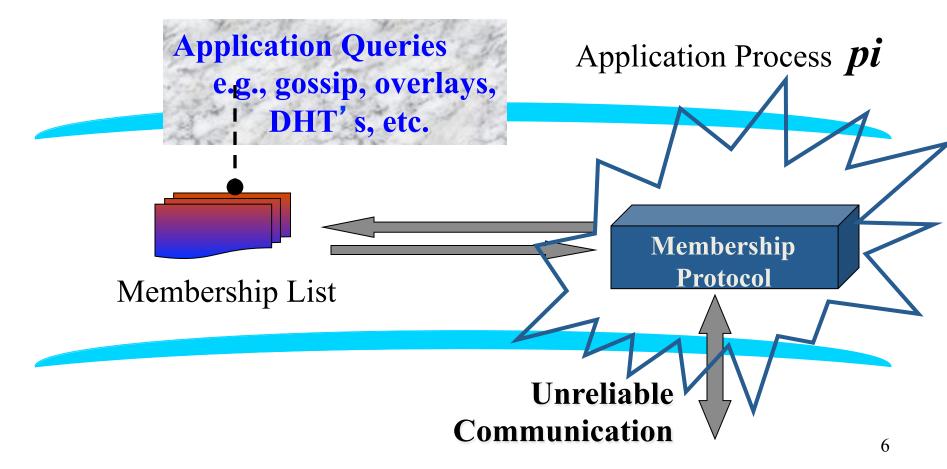
- 1. Hire 1000 people, each to monitor one machine in the datacenter and report to you when it fails.
- 2. Write a failure detector program (distributed) that automatically detects failures and reports to your workstation.

TARGET SETTINGS

- Process 'group' -based systems
 - Clouds/Datacenters
 - Replicated servers
 - Distributed databases

Crash-stop/Fail-stop process failures

GROUP MEMBERSHIP SERVICE

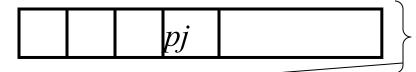


TWO SUB-PROTOCOLS

Application Process *pi*

Group

Membership List



- Complete list all the time (Strongly consistent)
 - Virtual synchrony
- Almost-Complete list (Weakly consistent)
 - •Gossip-style, SWIM, ...
- •Or *Partial-random* list (other systems)
 - •SCAMP, T-MAN, Cyclon,...

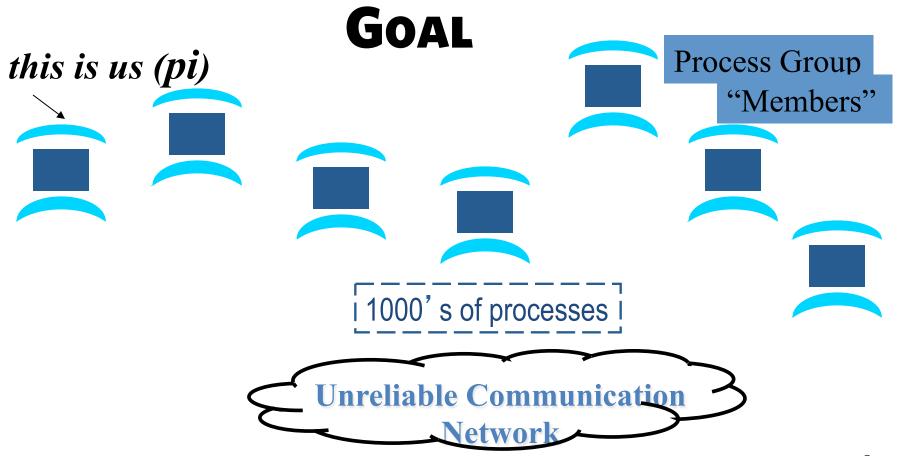
Unreliable Communication

Dissemination

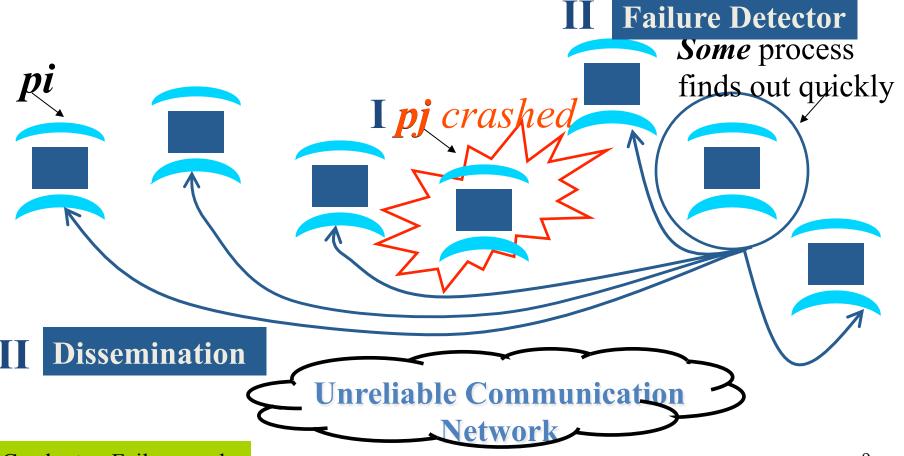
Failure Detector

Focus of this series of lecture

LARGE GROUP: SCALABILITY A



GROUP MEMBERSHIP PROTOCOL



Crash-stop Failures only

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NEXT

• How do you design a group membership protocol?

I. pj crashes

- Nothing we can do about it!
- A frequent occurrence
- Common case rather than exception
- Frequency goes up linearly with size of datacenter

II. DISTRIBUTED FAILURE DETECTORS: DESIRABLE PROPERTIES

- Completeness = each failure is detected
- Accuracy = there is no mistaken detection
- Speed
 - Time to first detection of a failure
- Scale
 - Equal Load on each member
 - Network Message Load

DISTRIBUTED FAILURE DETECTORS: PROPERTIES

- Completeness
- ` Accuracy
 - Speed
 - Time to first detection of a failur
 - Scale
 - Equal Load on each member
 - Network Message Load

Impossible together in lossy networks [Chandra and Toueg]

If possible, then can solve consensus!

WHAT REAL FAILURE DETECTORS PREFER

- Completeness : Guaranteed

 Partial/Probabilistic guarantee
 - Speed
 - Time to first detection of a failure
 - Scale
 - Equal Load on each member
 - Network Message Load

WHAT REAL FAILURE DETECTORS **PREFER**

- Guaranteed **Completeness** Partial/Probabilistic ----Accuracy guarantee
 - Speed
 - Time to first detection of a failure
 - Scale
 - Equal Load on each member

process detects the failure

Time until some

Network Message Load

WHAT REAL FAILURE DETECTORS PREFER

- Completeness

 -Accuracy

 Speed

 Guaranteed

 Partial/Probabilistic
 guarantee
 - Time to first detection of a failure
 - Scale _____ Time until some process detects the failure
 - Equal Load on each member
 - Network Message Load

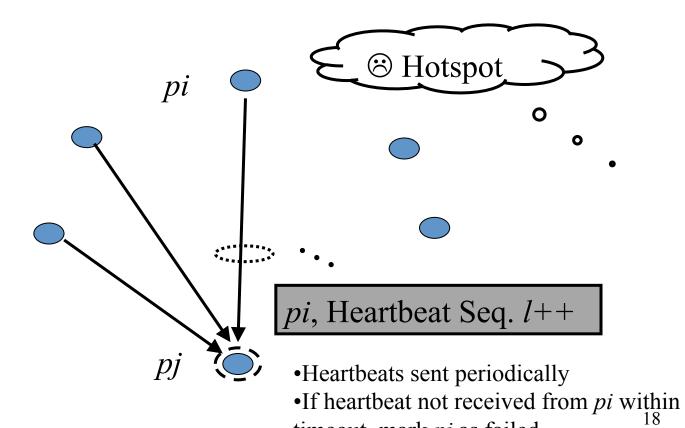
No bottlenecks/single failure point

FAILURE DETECTOR PROPERTIES

- Completeness
- Accuracy
- Speed
 - Time to first detection of a failure
- Scale
 - Equal Load on each member
 - Network Message Load

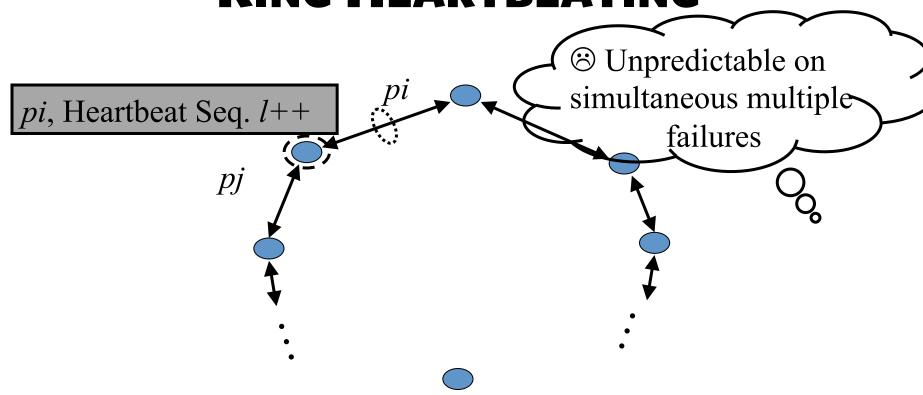
In spite of arbitrary simultaneous process failures

CENTRALIZED HEARTBEATING

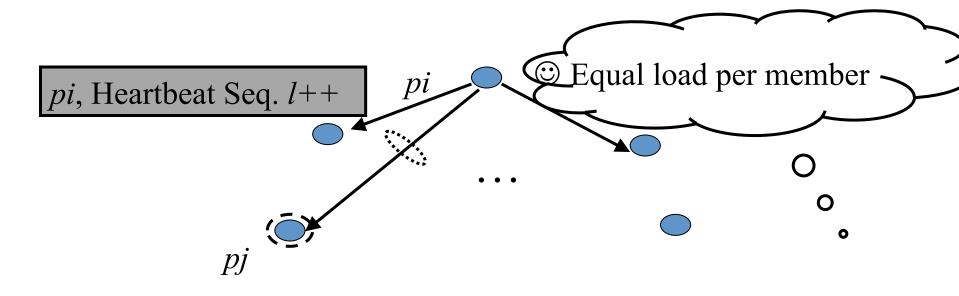


timeout, mark pi as failed

RING HEARTBEATING



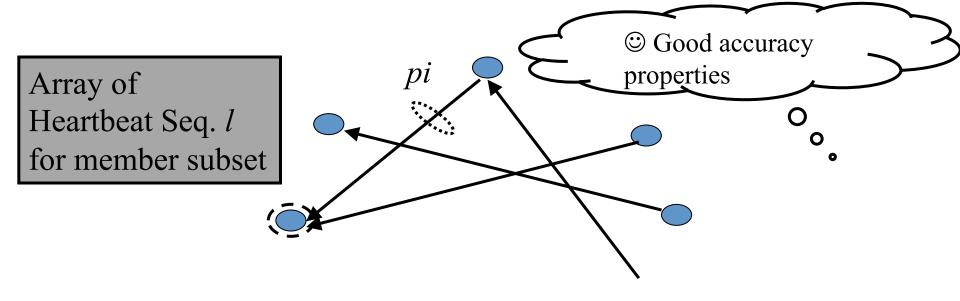
ALL-TO-ALL HEARTBEATING



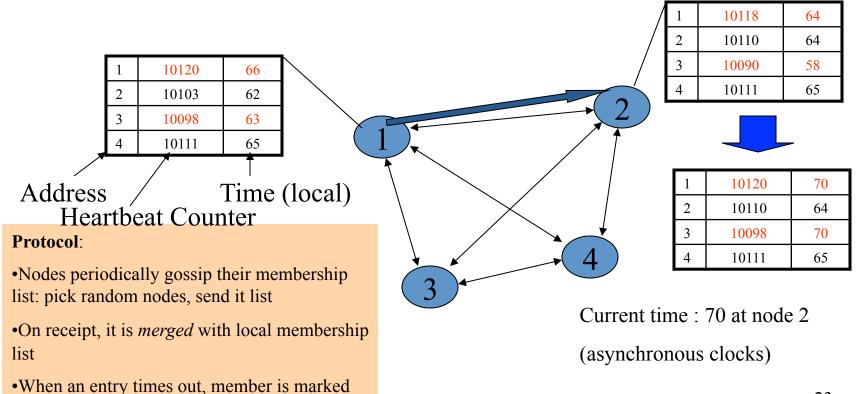
NEXT

• How do we increase the robustness of all-to-all heartbeating?

GOSSIP-STYLE HEARTBEATING



GOSSIP-STYLE FAILURE DETECTION



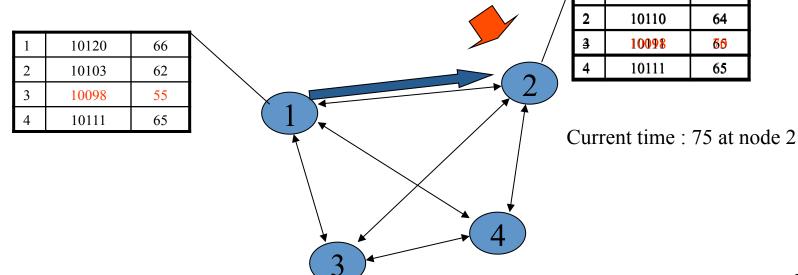
as failed

GOSSIP-STYLE FAILURE DETECTION

- If the heartbeat has not increased for more than T_{fail} seconds, the member is considered failed
- And after T_{cleanup} seconds, it will delete the member from the list
- Why two different timeouts?

GOSSIP-STYLE FAILURE DETECTION

• What if an entry pointing to a failed node is deleted right after T_{fail} (=24) seconds?



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MULTI-LEVEL GOSSIPING •Network topology is hierarchical

- •Random gossip target selection => core routers face O(N) load (Why?)

- •Fix: In subnet i, which contains n_i nodes, pick gossip target in your subnet with probability (1-1/ n_i
- •Router load=O(1)
- •Dissemination time=O(log(N))
- •What about latency for multilevel topologies?

N/2 nodes in a subnet (Slide corrected after lecture) Router N/2 nodes in a subnet

[Gupta et al, TPDS 06]

ANALYSIS/DISCUSSION

- What happens if gossip period T_{gossip} is decreased?
- A single heartbeat takes O(log(N)) time to propagate. So: N heartbeats take:
 - O(log(N)) time to propagate, if bandwidth allowed per node is allowed to be
 O(N)
 - O(N.log(N)) time to propagate, if bandwidth allowed per node is only O(1)
 - What about O(k) bandwidth?
- What happens to P_{mistake} (false positive rate) as T_{fail} , T_{cleanup} is increased?
- Tradeoff: False positive rate vs. detection time vs. bandwidth

NEXT

• So, is this the best we can do? What is the best we can do?

FAILURE DETECTOR PROPERTIES ...

- Completeness
- Accuracy
- Speed
 - Time to first detection of a failure
- Scale
 - Equal Load on each member
 - Network Message Load

...ARE APPLICATION-DEFINED REQUIREMENTS

- Completeness Guarantee always

 Accuracy

 T time units
 - Time to first detection of a failure
 - Scale
 - Equal Load on each member
 - Network Message Load

...ARE APPLICATION-DEFINED

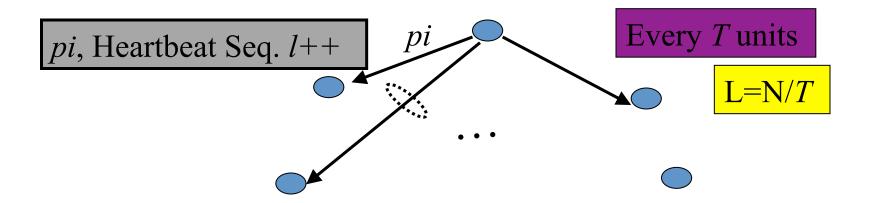
- REQUIREMENTS Guarantee always <: Completeness: Probability PM(T)- Accuracy *T* time units Speed

- Time to first detection of a failure

N*L: Compare this across protocols

- Scale
 - Equal Load on each member
 - Network Message Load

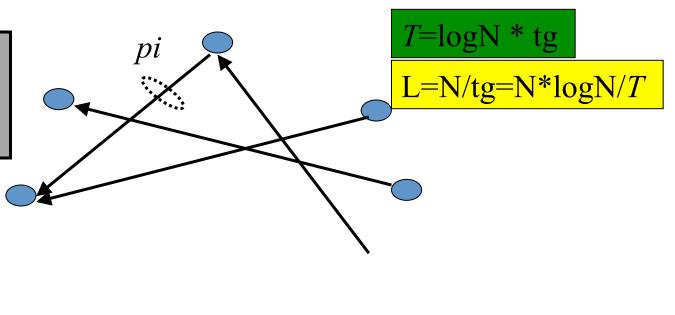
ALL-TO-ALL HEARTBEATING



GOSSIP-STYLE HEARTBEATING

Array of Heartbeat Seq. *l* for member subset

Every tg units
=gossip period,
send O(N) gossip
message



WHAT'S THE BEST/OPTIMAL WE CAN DO? Slide changed after lecture

- Worst case load L* per member in the group (messages per second)
 - as a function of T, PM(T), N
 - Independent Message Loss probability p_{ml}

•
$$L^* = \frac{\log(PM(T))}{\log(p_{ml})} \cdot \frac{1}{T}$$

HEARTBEATING

- Optimal L is independent of N (!)
- All-to-all and gossip-based: sub-optimal
 - L=O(N/T)
 - try to achieve simultaneous detection at *all* processes
 - fail to distinguish *Failure Detection* and *Dissemination* components

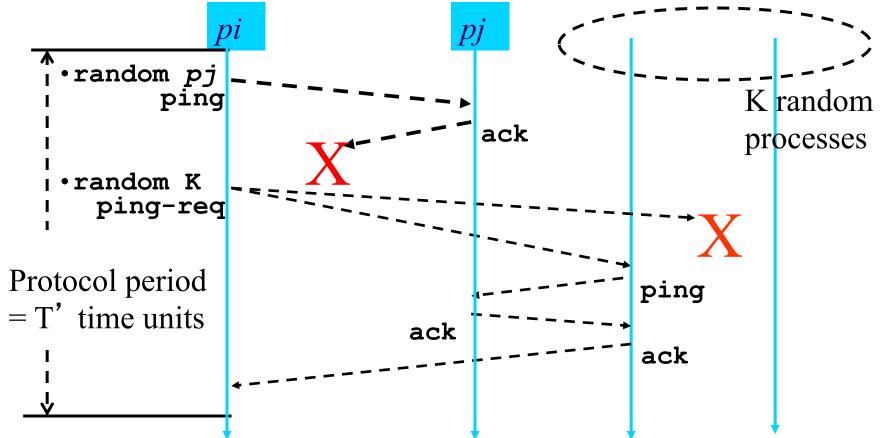
⇒Key:

- Separate the two components
- □ Use a non heartbeat-based Failure Detection Component

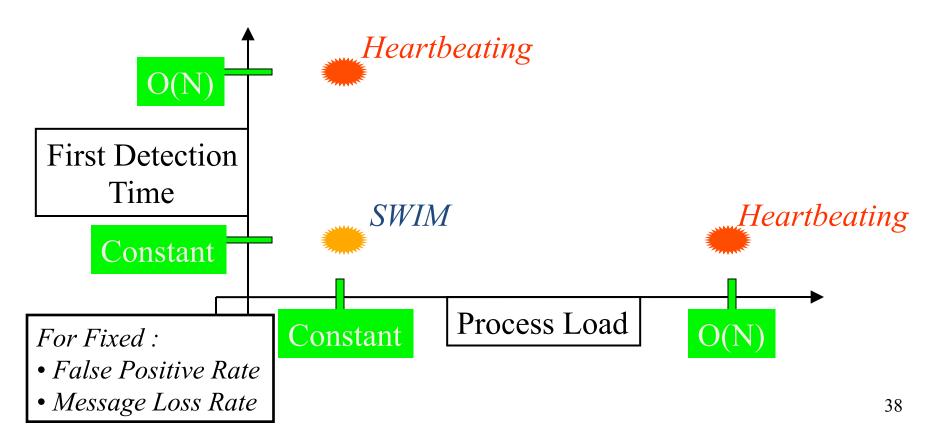
NEXT

• Is there a better failure detector?

SWIM FAILURE DETECTOR PROTOCOL



SWIM VERSUS HEARTBEATING



SWIM FAILURE DETECTOR

Parameter	SWIM
First Detection Time	• Expected $\left[\frac{e}{e-1}\right]$ periods • Constant (independent of group size)
Process Load	• Constant per period • < 8 L* for 15% loss
False Positive Rate	Tunable (via K)Falls exponentially as load is scaled
Completeness	 Deterministic time-bounded Within O(log(N)) periods w.h.p.

Accuracy, Load

- PM(T) is exponential in -K. Also depends on pml (and pf)
 - See paper

$$\frac{L}{L^*} < 28$$

$$\frac{E[L]}{L^*} < 8$$

for up to 15 % loss rates

DETECTION TIME

• Prob. of being pinged in T'=
$$1 - (1 - \frac{1}{N})^{N-1} = 1 - e^{-1}$$

•
$$E[T] = T' \cdot \frac{e}{e-1}$$

- Completeness: Any alive member detects failure
 - Eventually
 - By using a trick: within worst case O(N) protocol periods

This slide not covered (not in syllabus)

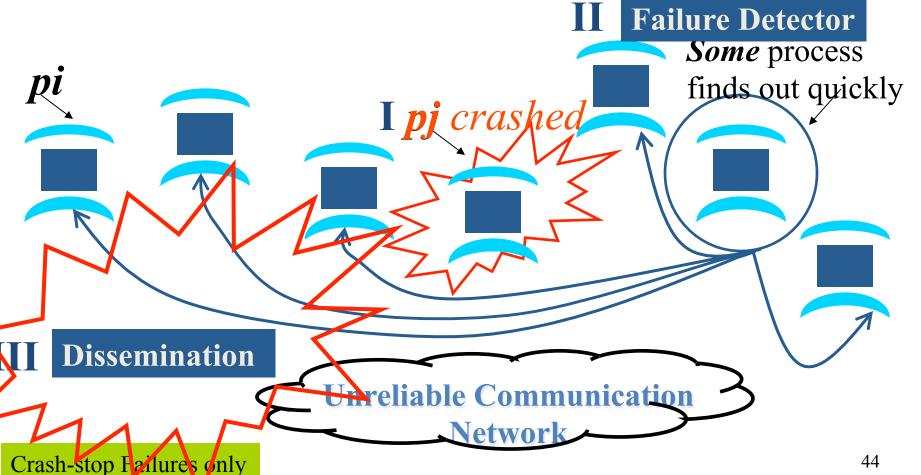
TIME-BOUNDED COMPLETENESS

- Key: select each membership element once as a ping target in a traversal
 - Round-robin pinging
 - Random permutation of list after each traversal
- Each failure is detected in worst case 2N-1 (local) protocol periods
- Preserves FD properties

NEXT

- How do failure detectors fit into the big picture of a group membership protocol?
- What are the missing blocks?

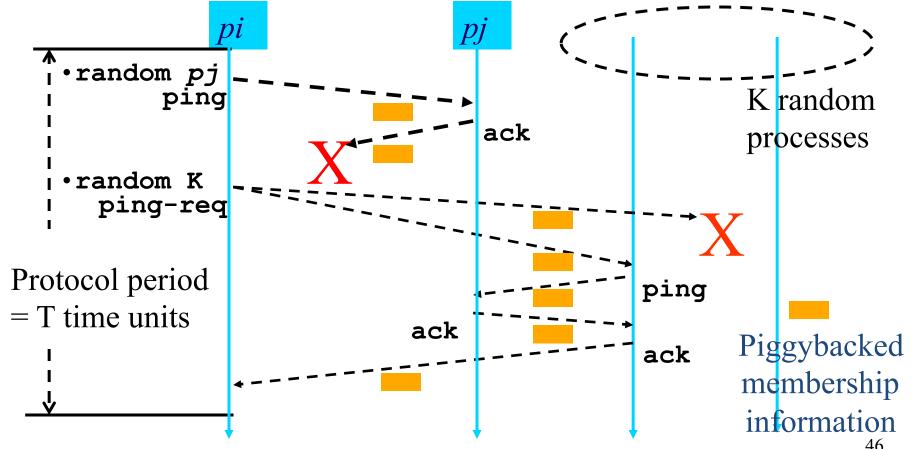
GROUP MEMBERSHIP PROTOCOL



DISSEMINATION OPTIONS

- Multicast (Hardware / IP)
 - unreliable
 - multiple simultaneous multicasts
- Point-to-point (TCP / UDP)
 - expensive
- Zero extra messages: Piggyback on Failure Detector messages
 - Infection-style Dissemination

INFECTION-STYLE DISSEMINATION



This slide not covered (not in syllabus)

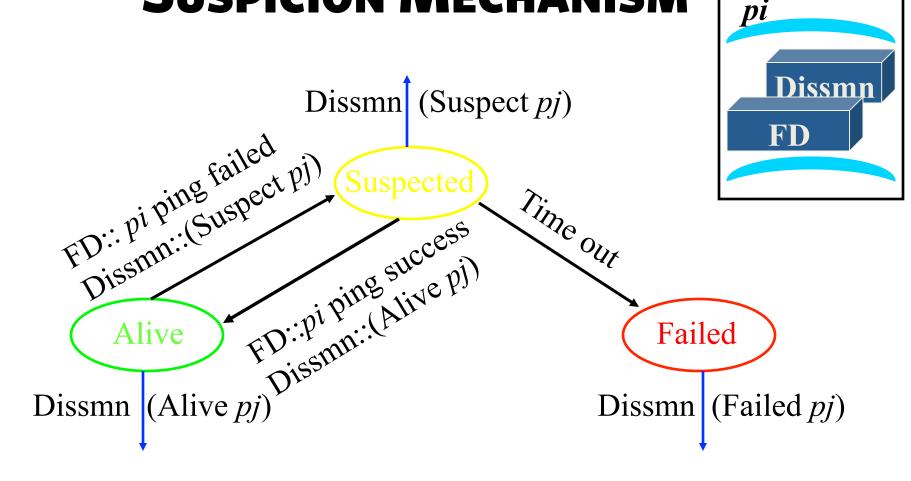
INFECTION-STYLE DISSEMINATION

- Epidemic/Gossip style dissemination
 - After $\lambda . \log(N)$ protocol periods, $N^{-(2\lambda-2)}$ processes would not have heard about an update
- Maintain a buffer of recently joined/evicted processes
 - Piggyback from this buffer
 - Prefer recent updates
- Buffer elements are garbage collected after a while
 - After $\lambda_{.\log(N)}$ protocol periods, i.e., once they've propagated through the system; this defines weak consistency

SUSPICION MECHANISM

- False detections, due to
 - Perturbed processes
 - Packet losses, e.g., from congestion
- Indirect pinging may not solve the problem
- Key: *suspect* a process before *declaring* it as failed in the group

SUSPICION MECHANISM



SUSPICION MECHANISM

- Distinguish multiple suspicions of a process
 - Per-process incarnation number
 - Inc # for pi can be incremented only by pi
 - e.g., when it receives a (Suspect, pi) message
 - Somewhat similar to DSDV
- Higher inc# notifications over-ride lower inc#'s
- Within an inc#: (Suspect inc #) > (Alive, inc #)
- (Failed, inc #) overrides everything else

WRAP UP

- Failures the norm, not the exception in datacenters
- Every distributed system uses a failure detector
- Many distributed systems use a membership service

- Ring failure detection underlies
 - IBM SP2 and many other similar clusters/machines
- Gossip-style failure detection underlies
 - Amazon EC2/S3 (rumored!)

IMPORTANT ANNOUNCEMENT

- Next week Tue and Thu: We'll have a flipped classroom! (like Khan Academy)
- Homework **before** Next week
 - Please see video lectures for two topics
 - Timestamps and Ordering before Tue
 - Global Snapshots before Thu
- When you come to class on Sep 9th (Tue) and Sep 11th (Thu) the TAs will be helping you do exercises in class (not HW problems, but other exercise problems we will give you)
- We will not replay videos in class, i.e., there will be no lecturing.
- If you don't see the videos **before** class, you will flounder in class. So make sure you see them before class.
- Exercises *may* count for grades.
- Please bring a pen/pencil and paper to both classes.