

CS/ECE 374 A: Algorithms & Models of Computation

Reductions

Lecture 22

April 17, 2025

Course Outline

- Part I: models of computation (reg exps, DFA/NFA, CFGs, TMs)
- Part II: (efficient) algorithm design
- Part III: limits of (efficient) computation
 - Undecidability: problems that have *no* algorithms
 - NP-Completeness: problems that (we think) have no *efficient* algorithms

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 - NP-Completeness: problems that (we think) have no *efficient* algorithms

Key tool for proving intractability: reductions!

Part I

Reductions for Algorithms

Recall: Longest Sequences

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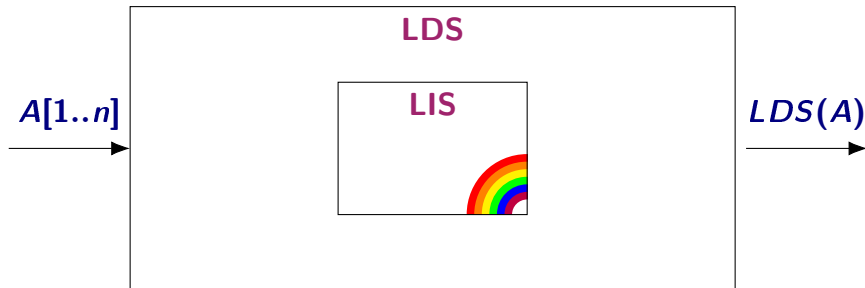
Longest *Decreasing* Subsequence: Find the longest subsequence of $A[1..n]$ such that each term is *smaller* than the last.

LDS Reduction

```
from magic import LIS
LDS(A[1..n]):
    Negate every element of A
    Compute seq = LIS(A)
    Negate every element of seq
    Return seq
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Vertex Weights

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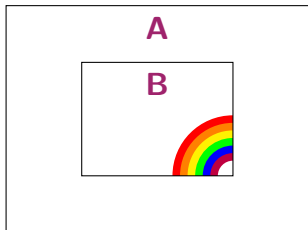
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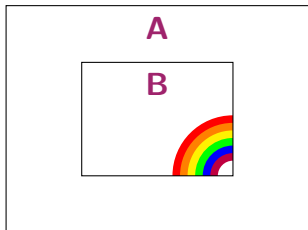
A is “no harder than” **B**: any algorithm for **B** gives one for **A**.

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A is “no harder than” **B**: any algorithm for **B** gives one for **A**.

B is “no easier than” **A**: if **A** has no “good” algorithm, neither does **B**!

Part II

Practice with Reductions

Autograding CS 124

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Autograding CS 124

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```
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Can we (algorithmically) check if a student's code works?

Intuitively simpler question: can we check if a student's code at least doesn't run forever?

Reducing “Hello World!” to Halting

We want to reduce checking if a student’s code prints “Hello World!” and halts to just checking if it (eventually) halts.

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from magic import TestHalt
TestHW(StudentCode):
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Note: P halts if and only if StudentCode is correct!

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This tells us that checking if a student’s code is correct is “no harder than” just checking if it runs forever.

Reducing Halting to “Hello World”

We can use these same ideas to reduce in the opposite direction!

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from magic import TestHW
TestHalt(StudentCode):
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This means that checking if a student’s code halts is “no harder than” checking if it’s correct—so the two tasks are the same “level of difficulty”!

Independent Set and Clique

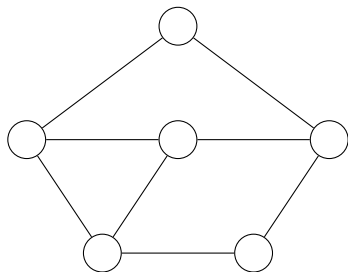
Given a graph $G = (V, E)$, we define

- A **clique** as $C \subseteq V$ such that each vertex in C has an edge to every other vertex in C .
- A **independent set** as $S \subseteq V$ such that no two vertices in S have an edge between them.

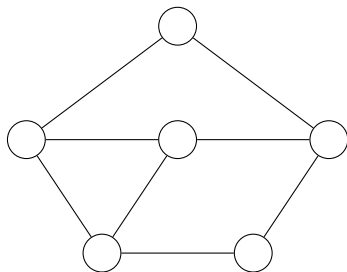
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Cliques



Independent Sets

Independent Set and Clique

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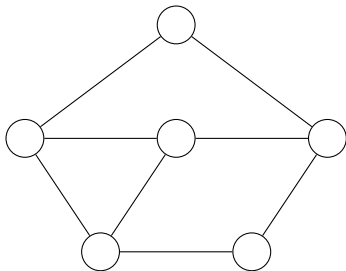
- A **clique** as $C \subseteq V$ such that each vertex in C has an edge to every other vertex in C .
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Problems of interest: given a graph G and an integer $1 \leq k \leq |V|$,

- Does G have a clique of size k ?
- Does G have an independent set of size k ?

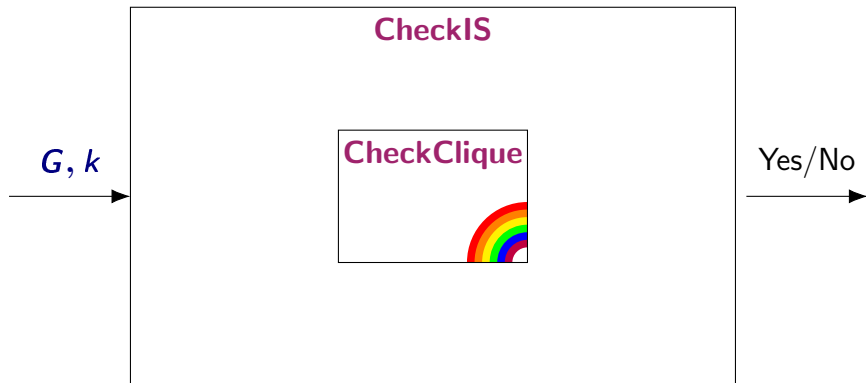
Reducing Independent Set to Clique I

Say we wanted to check if there is an independent set of size 3 in this graph. How can we use `CheckClique` to help?



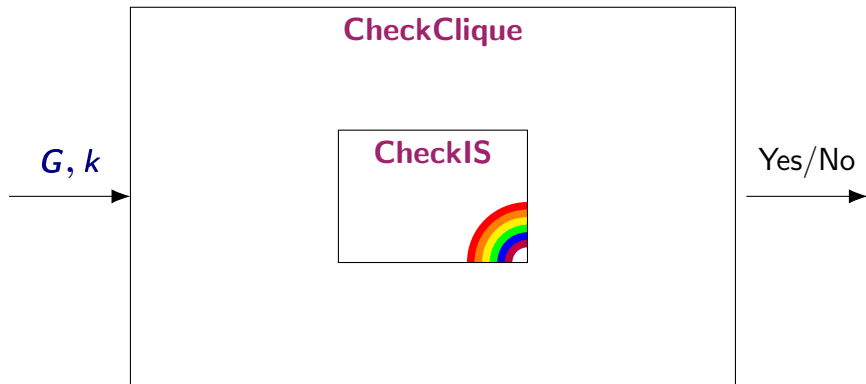
Reducing Independent Set to Clique II

We want to check if G has an independent set of size k , given the ability to check if a graph has a clique of some size.



Reducing Clique to Independent Set

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So Independent Set and Clique are “as easy / difficult” as each other!

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Both reductions we've seen so far can work in either direction—but this isn't always the case!

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Can we reduce checking for a clique to checking if a program halts?

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from magic import TestHalt
CheckClique( $G, k$ ):
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It turns out this is impossible! (We'll see why in the next lecture.)

Takeaway: It matters which direction your reduction goes—some problems really are “strictly harder” than others!

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Concretely, how do the following problems compare?

- **CheckClique(G, k)**: check if G has a clique of size k .
- **FindClique(G, k)**: output a clique of size k if one exists, or say “Not possible”.

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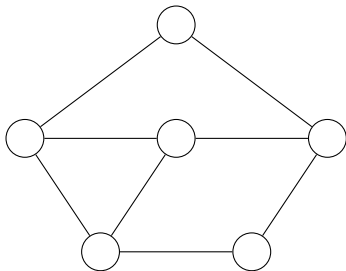
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Immediate: if we can solve FindClique , we can solve CheckClique .

Clique Search to Decision Intuition

Say we wanted to find a clique of size 3 in this graph. How can we use `CheckClique` to help?



Clique Search to Decision Reduction

```
from magic import CheckClique
FindClique( $G, k$ ):
    if CheckClique( $G, k$ ) is false:
        Return ‘‘Not possible’’
    for each vertex  $v \in G$ :
        Construct  $G'$  by removing  $v$  (and its edges) from  $G$ 
        if CheckClique( $G', k$ ) is true:
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Correctness?

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Correctness?

This means that checking if a clique exists and actually finding one
“as easy / difficult” as each other!

Part III

Reductions for Decision Problems

Decision Problems

Similar to the first third of the class, we will be mostly interested in *decision* problems: our answer is either “Yes” or “No”.

Decision Problems

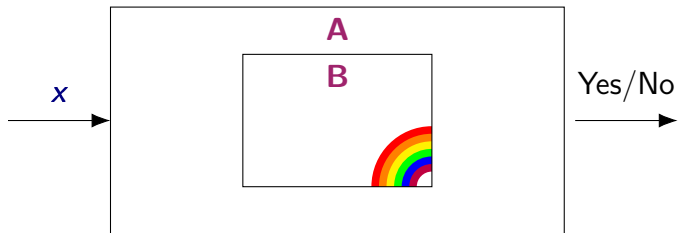
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Recall that we often refer to such problems as a “language”

$L \subseteq \{0, 1\}^*$ —strings in L are exactly those that we want to output “Yes” on (ie, accept).

Reducing Decision Problems

Say we have two decision problems A and B . We can reduce A to B by giving a function f such that $x \in L_A$ if and only if $f(x) \in L_B$.



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Examples from before:

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When using this type of reduction, you just have to define f and prove that $x \in L_A$ iff $f(x) \in L_B$!

- This will be the most common type of reduction we use because it is the most simple.

Takeaway Points

Reductions are a powerful tool in CS

- Reducing A to a problem with a known algorithm gives us an algorithm for A .
- Reducing a “hard” problem to B tells us that B must also be “hard”.

To reduce A to B , write an algorithm for A where we can use a subroutine that solves B .

- *Don't* worry about how the subroutine for B is implemented—just use that it solves B !
- For decision problems, it suffices to give a function f such that $x \in L_A$ if and only if $f(x) \in L_B$.