

DP in DAGs and Strongly Connected Components

Lecture 17

March 27, 2025

Part I

Dynamic Programming and DAGs

Recall LIS

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Consider the *subproblem dependency graph*:

- Vertex i corresponds to subproblem $LIS(i)$
- Include edge (i, j) if computing $LIS(i)$ uses the value of $LIS(j)$
("Subproblem i depends on subproblem j ")

Subproblem Dependency Graph Example

Suppose $A = [3, 1, 4, 1, 5]$.

(Recall $LIS(i) = 1 + \max\{LIS(j) \mid j > i \text{ and } A[j] > A[i]\}$)

DP is DAGs

For every DP algorithm, the subproblem dependency graph is a DAG.

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An evaluation order is valid *if and only if* it is a reverse topological order of the dependency graph.

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General outline:

- For each vertex v , define some subproblem corresponding to v .
- Write a recurrence for your subproblems. (Most often v will refer to the subproblems of either its parents or its children.)
- Evaluate the subproblems in (reverse) topological order.

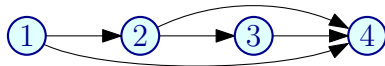
Example of DAG DP

Given an (unweighted) DAG G in topological order, what is the length of the longest path in G ?



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Given an (unweighted) DAG G in topological order, what is the length of the longest path in G ?



Subproblem definition?

Recurrence?

Evaluation order?

Longest Path in a DAG

DAG-LongestPath(G):

Initialize array LLP

for vertices v in reverse topological order:

if v is a sink:

$LLP[v] = 0$

else

$LLP[v] = 1 + \max\{LLP(u) \mid (v, u) \in E\}$

return $\max_v LLP(v)$

Efficiency?

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Efficiency? $O(V + E)$

Exercise: generalize this algorithm to

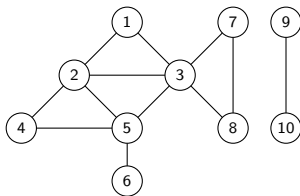
- Weighted edges
- Paths from s to t
- *Shortest* path from s to t
- ...

Part II

Strongly Connected Components

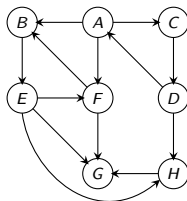
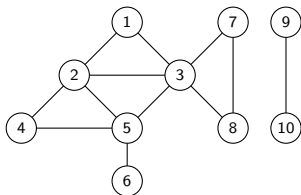
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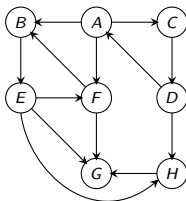


In a *directed* graph this relation isn't symmetric, so we can't talk about the "connected components of **G**".

Strongly Connected Components

Definition

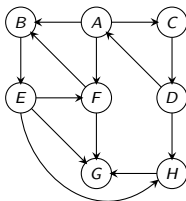
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Strongly Connected Components

Definition

The **strongly connected component** (SCC) of a vertex v is the set of all vertices u such that v can reach u and u can reach v .



This definition doesn't depend on what vertex we choose within the SCC, so we can talk about the SCCs of G !

The Meta-Graph

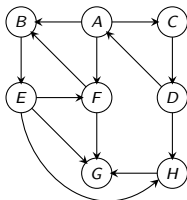
Once we have the SCCs of G , we can construct a “meta graph”:

- A vertex for each SCC.
- An edge (C_1, C_2) iff there is an edge in G between *some* vertex in C_1 and *some* vertex in C_2 .

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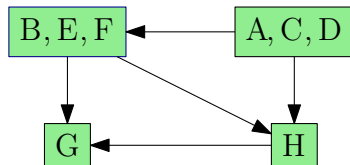
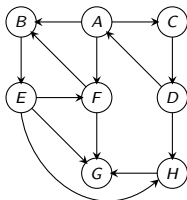
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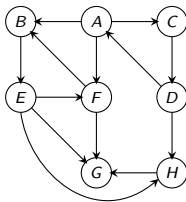
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Meta graph will always be a DAG! (Also called the “DAG of SCCs”.)

Warm-Up: Compute One SCC

How would we compute the SCC of a particular vertex? (Say **B**)



Naïve SCC Algorithm

FindSCC(G , v):

Construct ‘‘reverse graph’’ G^R (reverse all edges)

Compute $\text{reach}(v) = \text{WFS}(G, v)$

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Efficiency? $O(V + E)$ for FindSCC, $O(V \cdot (V + E))$ for NaïveSCC

Can we do better?

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Efficiency? $O(V + E)$

How do we find a vertex in a sink SCC though?

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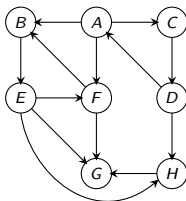
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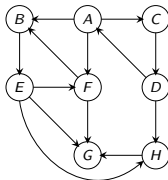


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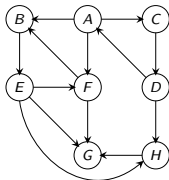
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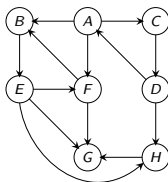


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But *everything* is reachable from **A**, **C**, and **D**, so that DFS run finds all remaining vertices, making it the last one.

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Claim

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So the *last* run of DFS must start from a source SCC!

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KosarajuSharirSCC(G):

Construct G^R by reversing all edges

Run DFSAll(G^R)

for vertices v in decreasing order of post:

if v is still in G :

 Find all vertices reachable from v with WFS

 Mark these as v 's SCC and remove them from G

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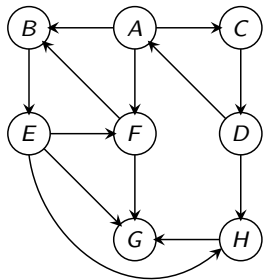
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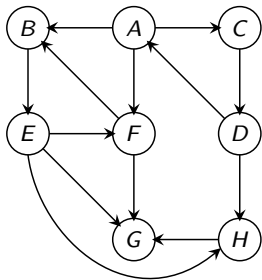
Efficiency?

Kosaraju-Sharir Example

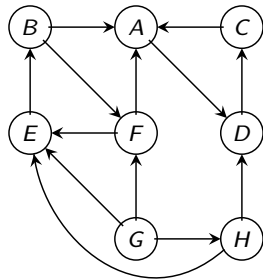


Graph **G**

Kosaraju-Sharir Example

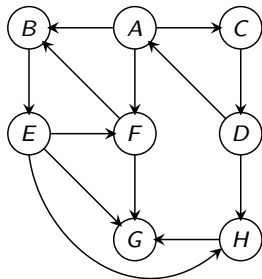


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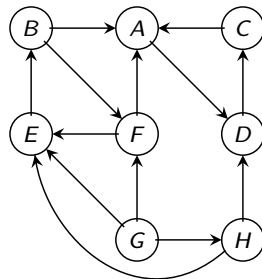


Graph G^R

Kosaraju-Sharir Example



Graph G



Graph G^R

Vertex	A	B	C	D	E	F	G	H
pre	1	7	3	2	9	8	13	14
post	6	12	4	5	10	11	16	15

Problems and Algorithms From Today

- Longest path in a DAG (weighted or unweighted)
 - Use DP, $O(V + E)$ time
 - Can also find shortest $s - t$ path
- Find the SCC of a single vertex
 - WFS on G and G^R , $O(V + E)$
- Find *all* SCCs of G
 - Kosaraju-Sharir, $O(V + E)$
 - Can also output the DAG of SCCs