

NFAs continued, Closure Properties of Regular Languages

Lecture 5

January 31, 2023

Regular Languages, DFAs, NFAs

Theorem

Languages accepted by DFAs, NFAs, and regular expressions are the same.

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Languages accepted by DFAs, NFAs, and regular expressions are the same.

- DFAs are special cases of NFAs (trivial)
- NFAs accept regular expressions (we saw already)
- DFAs accept languages accepted by NFAs (today)
- Regular expressions for languages accepted by DFAs (today, informally)

Part I

Equivalence of NFAs and DFAs

Equivalence of NFAs and DFAs

Theorem

For every NFA N there is a DFA M such that $L(M) = L(N)$.

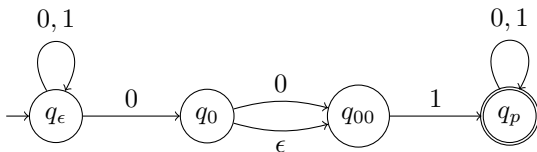
Equivalence of NFAs and DFAs

Theorem

For every NFA N there is a DFA M such that $L(M) = L(N)$.

- The number of states in N can be exponential in number of states of M
- Examples show that it is necessary in some cases. That is, there are regular languages for which the best/smallest DFA has exponentially more states than the best/smallest NFA.

NFAs and acceptance



A NFA N accepts a string w iff some accepting state is reached by N from the start state on input w .

The language accepted (or recognized) by a NFA N is denoted by $L(N)$ and defined as: $L(N) = \{w \mid N \text{ accepts } w\}$.

Formal Tuple Notation for NFA

Definition

A **non-deterministic finite automata (NFA)** $N = (Q, \Sigma, \delta, s, A)$ is a five tuple where

- Q is a finite set whose elements are called **states**,
- Σ is a finite set called the **input alphabet**,
- $\delta : Q \times \Sigma \cup \{\epsilon\} \rightarrow \mathcal{P}(Q)$ is the **transition function** (here $\mathcal{P}(Q)$ is the power set of Q),
- $s \in Q$ is the **start state**,
- $A \subseteq Q$ is the set of **accepting/final** states.

$\delta(q, a)$ for $a \in \Sigma \cup \{\epsilon\}$ is a subset of Q — a set of states.

Extending the transition function to strings

Definition

For NFA $N = (Q, \Sigma, \delta, s, A)$ and $q \in Q$ the $\epsilon\text{reach}(q)$ is the set of all states that q can reach using only ϵ -transitions.

Definition

Inductive definition of $\delta^* : Q \times \Sigma^* \rightarrow \mathcal{P}(Q)$:

- if $w = \epsilon$, $\delta^*(q, w) = \epsilon\text{reach}(q)$
- if $w = a$ where $a \in \Sigma$
$$\delta^*(q, a) = \cup_{p \in \epsilon\text{reach}(q)} (\cup_{r \in \delta(p, a)} \epsilon\text{reach}(r))$$
- if $w = ax$,
$$\delta^*(q, w) = \cup_{p \in \delta^*(q, a)} \delta^*(p, x)$$
- if $w = xa$, alternate definition based on string suffixes
$$\delta^*(q, w) = \cup_{p \in \delta^*(q, r)} \delta^*(p, a)$$

Definition of language accepted by N

Definition

A string w is accepted by NFA N if $\delta_N^*(s, w) \cap A \neq \emptyset$.

Definition

The language $L(N)$ accepted by a NFA $N = (Q, \Sigma, \delta, s, A)$ is

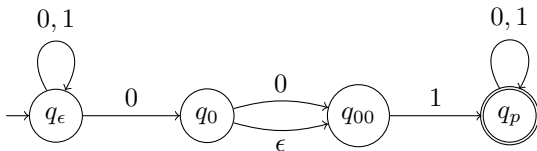
$$\{w \in \Sigma^* \mid \delta^*(s, w) \cap A \neq \emptyset\}.$$

Simulating an NFA by a DFA

- Think of a program with fixed memory that needs to simulate NFA N on input w .
- What does it need to store after seeing a prefix x of w ?
- **Easier question:** Can we write a program that decides whether N accepts a string?

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Does N accept $000101010010001000010000010000001000000111110001$?

Simulating an NFA by a DFA

- Think of a program with fixed memory that needs to simulate NFA N on input w .
- What does it need to store after seeing a prefix x of w ?
- It needs to know at least $\delta^*(s, x)$, the set of states that N could be in after reading x
- Is it sufficient?

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- It needs to know at least $\delta^*(s, x)$, the set of states that N could be in after reading x
- Is it sufficient? Yes, if it can compute $\delta^*(s, xa)$ after seeing another symbol a in the input.
- When should the program accept a string w ?

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- Is it sufficient? Yes, if it can compute $\delta^*(s, xa)$ after seeing another symbol a in the input.
- When should the program accept a string w ? If $\delta^*(s, w) \cap A \neq \emptyset$.

Key Observation: A DFA M that simulates N should keep in its memory/state the **set of states of N**

Thus the state space of the DFA should be $\mathcal{P}(Q)$.

Subset Construction

NFA $N = (Q, \Sigma, s, \delta, A)$. We create a DFA $M = (Q', \Sigma, \delta', s', A')$ as follows:

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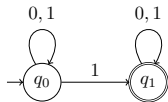
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- $Q' = \mathcal{P}(Q)$
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- $A' = \{X \subseteq Q \mid X \cap A \neq \emptyset\}$
- $\delta'(X, a) = \cup_{q \in X} \delta^*(q, a)$ for each $X \subseteq Q, a \in \Sigma$.

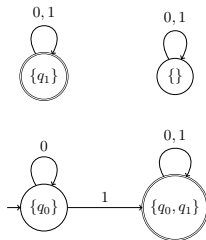
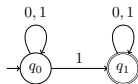
Example

No ϵ -transitions



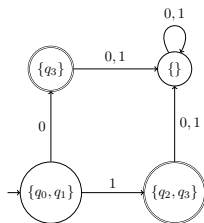
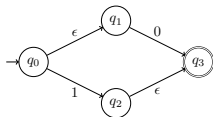
Example

No ϵ -transitions



Incremental construction

Only build states reachable from $s' = \epsilon\text{reach}(s)$ the start state of M



$$\delta'(X, a) = \cup_{q \in X} \delta^*(q, a)$$

Incremental algorithm

- Build M beginning with start state $s' == \epsilon\text{reach}(s)$
- For each existing state $X \subseteq Q$ consider each $a \in \Sigma$ and calculate the state $Y = \delta'(X, a) = \cup_{q \in X} \delta^*(q, a)$ and add a transition.
- If Y is a new state add it to reachable states that need to be explored.

To compute $\delta^*(q, a)$ - set of all states reached from q on string a

- Compute $X = \epsilon\text{reach}(q)$
- Compute $Y = \cup_{p \in X} \delta(p, a)$
- Compute $Z = \epsilon\text{reach}(Y) = \cup_{r \in Y} \epsilon\text{reach}(r)$

Proof of Correctness

Theorem

Let $N = (Q, \Sigma, s, \delta, A)$ be a NFA and let $M = (Q', \Sigma, \delta', s', A')$ be a DFA constructed from N via the subset construction. Then $L(N) = L(M)$.

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Stronger claim:

Lemma

For every string w , $\delta_N^*(s, w) = \delta_M^*(s', w)$.

Proof by induction on $|w|$.

Base case: $w = \epsilon$.

$$\delta_N^*(s, \epsilon) = \epsilon\text{reach}(s).$$

$$\delta_M^*(s', \epsilon) = s' = \epsilon\text{reach}(s) \text{ by definition of } s'.$$

Proof continued

Lemma

For every string w , $\delta_N^*(s, w) = \delta_M^*(s', w)$.

Inductive step: $w = xa$ (Note: suffix definition of strings)

$\delta_N^*(s, xa) = \cup_{p \in \delta_N^*(s, x)} \delta_N^*(p, a)$ by inductive defn of δ_N^*

Proof continued

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By inductive hypothesis: $Y = \delta_N^*(s, x) = \delta_M^*(s', x)$ since $|x| < |w|$

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Thus $\delta_N^*(s, xa) = \cup_{p \in Y} \delta_N^*(p, a) = \delta_M(Y, a)$ by definition of δ_M .

Proof continued

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Therefore,

$\delta_N^*(s, xa) = \delta_M(Y, a) = \delta_M(\delta_M^*(s, x), a) = \delta_M^*(s', xa)$

which is what we need.

Part II

DFA/NFA to Regular Expressions

DFA to Regular Expressions

Theorem

Given a DFA $M = (Q, \Sigma, \delta, s, A)$ there is a regular expression r such that $L(r) = L(M)$. That is, regular expressions are as powerful as DFAs (and hence also NFAs).

- Simple algorithm but formal proof is involved. See notes.
- An easier proof via a more involved algorithm (maybe later in the course)

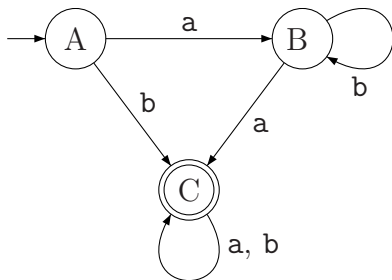
NFA to Regular Expressions

In fact the algorithm transforms an NFA $N = (Q, \Sigma, \delta, s, A)$ to a regular expression via GNFA's which are generalized NFAs.

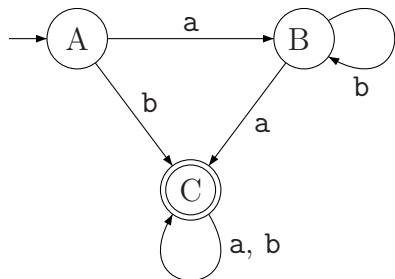
Informal Definition: A generalized NFA or a GNFA is specified like an NFA but each arc is labeled with a regular expression. One can transition an arc (p, q) from state p to state q labeled with a regular expression r by reading any string $w \in L(r)$.

One can show that GNFA's are equivalent to NFAs by simply replacing each arc with reg exp r via a NFA for r via algorithm from last semester.

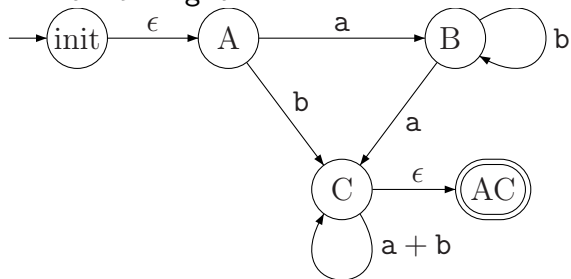
Stage 0: Input



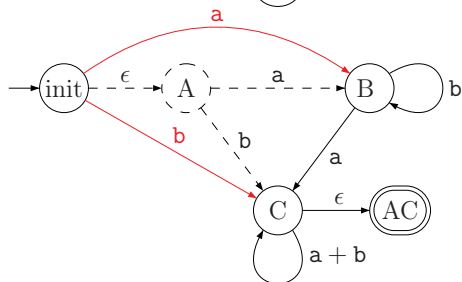
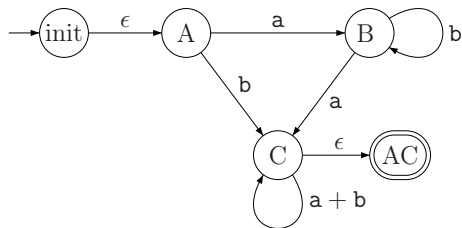
Stage 1: Normalizing



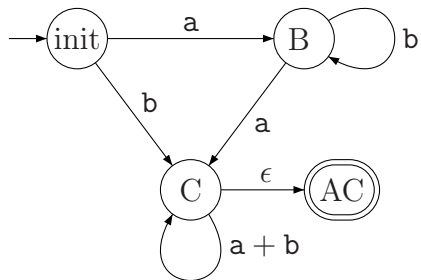
2: Normalizing it.



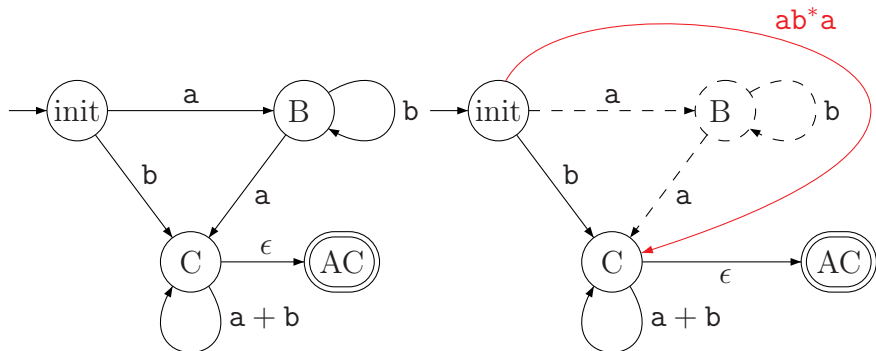
Stage 2: Remove state A



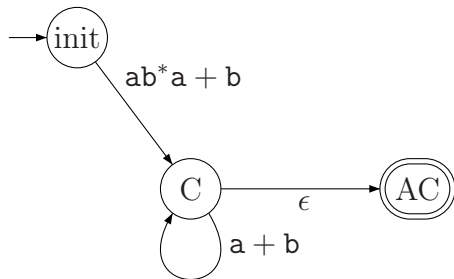
Stage 4: Redrawn without old edges



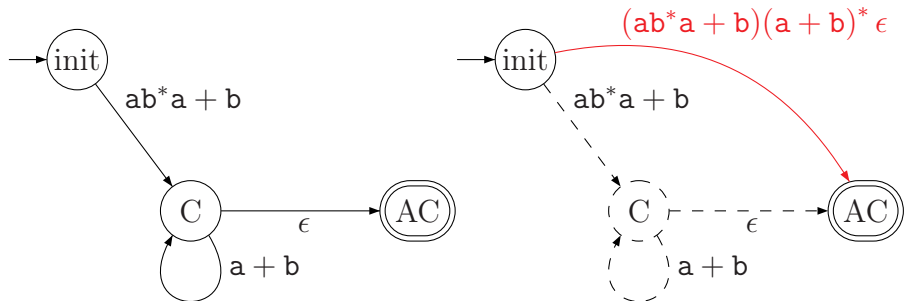
Stage 4: Removing B



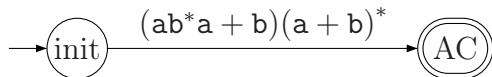
Stage 5: Redraw



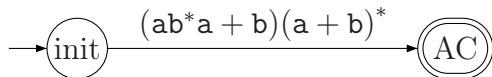
Stage 6: Removing C



Stage 7: Redraw



Stage 8: Extract regular expression



Thus, this automata is equivalent to the regular expression $(ab^*a + b)(a + b)^*$.

Part III

Closure Properties of Regular Languages

Regular Languages

Regular languages have three different characterizations

- Inductive definition via base cases and closure under union, concatenation and Kleene star
- Languages accepted by DFAs
- Languages accepted by NFAs

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Regular language closed under many operations:

- union, concatenation, Kleene star via inductive definition or NFAs
- complement, union, intersection via DFAs
- homomorphism, inverse homomorphism, reverse, . . .

Different representations allow for flexibility in proofs

Examples: PREFIX and SUFFIX

Let L be a language over Σ .

Definition

$$\text{PREFIX}(L) = \{w \mid wx \in L, x \in \Sigma^*\}$$

Definition

$$\text{SUFFIX}(L) = \{w \mid xw \in L, x \in \Sigma^*\}$$

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Theorem

If L is regular then $\text{PREFIX}(L)$ is regular.

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If L is regular then $\text{SUFFIX}(L)$ is regular.

PREFIX

Let $M = (Q, \Sigma, \delta, s, A)$ be a DFA that recognizes L

Create new DFA/NFA to accept $\text{PREFIX}(L)$ (or $\text{SUFFIX}(L)$).

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$$X = \{q \in Q \mid s \text{ can reach } q \text{ in } M\}$$

$$Y = \{q \in Q \mid q \text{ can reach some state in } A\}$$

$$Z = X \cap Y$$

Theorem

Consider DFA $M' = (Q, \Sigma, \delta, s, Z)$. $L(M') = \text{PREFIX}(L)$.

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Claim: $L(N) = \text{SUFFIX}(L)$.