

Even More on Dynamic Programming

Lecture 15

Thursday, March 7, 2019

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Part I

Longest Common Subsequence Problem

The LCS Problem

Definition

LCS between two strings X and Y is the length of longest common subsequence between X and Y .

Example

LCS between ABAZDC and BACBAD is 4 via ABAD

Derive a dynamic programming algorithm for the problem.

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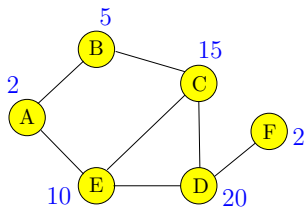
Part II

Maximum Weighted Independent Set in Trees

Maximum Weight Independent Set Problem

Input Graph $G = (V, E)$ and weights $w(v) \geq 0$ for each $v \in V$

Goal Find maximum weight independent set in G

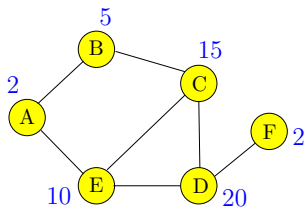


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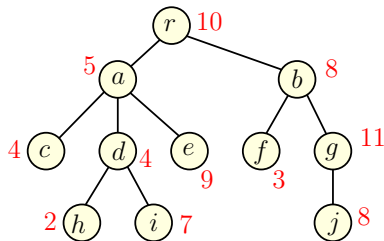


Maximum weight independent set in above graph: $\{B, D\}$

Maximum Weight Independent Set in a Tree

Input Tree $T = (V, E)$ and weights $w(v) \geq 0$ for each $v \in V$

Goal Find maximum weight independent set in T



Maximum weight independent set in above tree: ??

Towards a Recursive Solution

For an arbitrary graph G :

- 1 Number vertices as v_1, v_2, \dots, v_n
- 2 Find recursively optimum solutions without v_n (recurse on $G - v_n$) and with v_n (recurse on $G - v_n - N(v_n)$ & include v_n).
- 3 Saw that if graph G is arbitrary there was no good ordering that resulted in a small number of subproblems.

What about a tree? Natural candidate for v_n is root r of T ?

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Towards a Recursive Solution

Natural candidate for v_n is root r of T ? Let \mathcal{O} be an optimum solution to the whole problem.

Case $r \notin \mathcal{O}$: Then \mathcal{O} contains an optimum solution for each subtree of T hanging at a child of r .

Case $r \in \mathcal{O}$: None of the children of r can be in \mathcal{O} . $\mathcal{O} - \{r\}$ contains an optimum solution for each subtree of T hanging at a grandchild of r .

Subproblems? Subtrees of T rooted at nodes in T .

How many of them? $O(n)$

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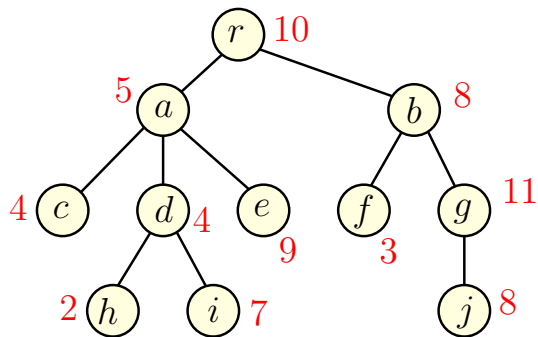
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Example



A Recursive Solution

$T(u)$: subtree of T hanging at node u

$OPT(u)$: max weighted independent set value in $T(u)$

$$OPT(u) = \max \left\{ \begin{array}{l} \sum_{v \text{ child of } u} OPT(v), \\ w(u) + \sum_{v \text{ grandchild of } u} OPT(v) \end{array} \right.$$

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Iterative Algorithm

- 1 Compute $OPT(u)$ bottom up. To evaluate $OPT(u)$ need to have computed values of all children and grandchildren of u
- 2 What is an ordering of nodes of a tree T to achieve above?
Post-order traversal of a tree.

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Iterative Algorithm

MIS-Tree(T):

Let v_1, v_2, \dots, v_n be a post-order traversal of nodes of T
for $i = 1$ **to** n **do**

$$M[v_i] = \max \left(\begin{array}{l} \sum_{v_j \text{ child of } v_i} M[v_j], \\ w(v_i) + \sum_{v_j \text{ grandchild of } v_i} M[v_j] \end{array} \right)$$

return $M[v_n]$ (* Note: v_n is the root of T *)

Space: $O(n)$ to store the value at each node of T

Running time:

- 1 Naive bound: $O(n^2)$ since each $M[v_i]$ evaluation may take $O(n)$ time and there are n evaluations.
- 2 Better bound: $O(n)$. A value $M[v_j]$ is accessed only by its parent and grand parent.

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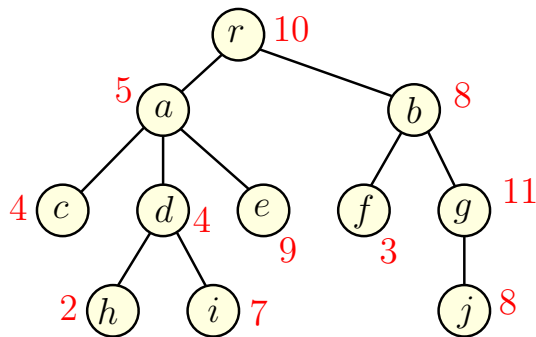
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Example



Part III

Context free grammars: The CYK Algorithm

Parsing

We saw **regular** languages and **context free** languages.

Most programming languages are specified via context-free grammars. Why?

- **CFLs** are sufficiently expressive to support what is needed.
- At the same time one can “efficiently” solve the **parsing** problem: given a string/program **w**, is it a valid program according to the CFG specification of the programming language?

CFG specification for C

```
<relational-expression> ::= <shift-expression>
    | <relational-expression> < <shift-expression>
    | <relational-expression> > <shift-expression>
    | <relational-expression> <= <shift-expression>
    | <relational-expression> >= <shift-expression>

<shift-expression> ::= <additive-expression>
    | <shift-expression> << <additive-expression>
    | <shift-expression> >> <additive-expression>

<additive-expression> ::= <multiplicative-expression>
    | <additive-expression> + <multiplicative-expression>
    | <additive-expression> - <multiplicative-expression>

<multiplicative-expression> ::= <cast-expression>
    | <multiplicative-expression> * <cast-expression>
    | <multiplicative-expression> / <cast-expression>
    | <multiplicative-expression> % <cast-expression>

<cast-expression> ::= <unary-expression>
    | ( <type-name> ) <cast-expression>

<unary-expression> ::= <postfix-expression>
    | ++ <unary-expression>
    | -- <unary-expression>
    | <unary-operator> <cast-expression>
    | sizeof <unary-expression>
    | sizeof <type-name>
```

Algorithmic Problem

Given a CFG $G = (V, T, P, S)$ and a string $w \in T^*$, is $w \in L(G)$?

- That is, does S derive w ?
- Equivalently, is there a parse tree for w ?

Simplifying assumption: G is in Chomsky Normal Form (CNF)

- Productions are all of the form $A \rightarrow BC$ or $A \rightarrow a$.
If $\epsilon \in L$ then $S \rightarrow \epsilon$ is also allowed.
(This is the only place in the grammar that has an ϵ .)
- Every CFG G can be converted into CNF form via an efficient algorithm
- Advantage: parse tree of constant degree.

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CYK Algorithm

CYK Algorithm = Cocke-Younger-Kasami algorithm

Example

$S \rightarrow \epsilon \mid AB \mid XB$

$Y \rightarrow AB \mid XB$

$X \rightarrow AY$

$A \rightarrow 0$

$B \rightarrow 1$

Question:

- Is **000111** in $L(G)$?
- Is **00011** in $L(G)$?

Towards Recursive Algorithm

Assume G is a CNF grammar.

S derives w iff one of the following holds:

- $|w| = 1$ and $S \rightarrow w$ is a rule in P
- $|w| > 1$ and there is a rule $S \rightarrow AB$ and a split $w = uv$ with $|u|, |v| \geq 1$ such that A derives u and B derives v

Observation: Subproblems generated require us to know if some non-terminal A will derive a substring of w .

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Recursive solution

- 1 Input: $w = w_1 w_2 \dots w_n$
- 2 Assume r non-terminals in G : R_1, \dots, R_r .
- 3 R_1 : Start symbol.
- 4 $f(\ell, s, b)$: **TRUE** $\iff w_s w_{s+1} \dots, w_{s+\ell-1} \in L(R_b)$.
= Substring w starting at pos ℓ of length s is deriveable by R_b .
- 5 Recursive formula: $f(\ell, s, a)$ is 1 iff $(R_a \rightarrow w_s) \in G$.
- 6 For $\ell > 1$:

$$f(\ell, s, a) = \bigvee_{p=1}^{\ell-1} \bigvee_{(R_a \rightarrow R_b R_c) \in G} (f(p, s, b) \wedge f(\ell - p, s + p, c))$$

- 7 Output: $w \in L(G) \iff f(n, 1, 1) = 1$.

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- 6 For $\ell > 1$:

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- 7 **Output**: $w \in L(G) \iff f(n, 1, 1) = 1$.

Analysis

Assume $\mathbf{G} = \{R_1, R_2, \dots, R_r\}$ with start symbol R_1

- Number of subproblems: $O(rn^2)$
- Space: $O(rn^2)$
- Time to evaluate a subproblem from previous ones: $O(|P|n)$ where P is set of rules
- Total time: $O(|P|rn^3)$ which is polynomial in both $|w|$ and $|\mathbf{G}|$. For fixed \mathbf{G} the run time is cubic in input string length.
- Running time can be improved to $O(n^3|P|)$.
- Not practical for most programming languages. Most languages assume restricted forms of CFGs that enable more efficient parsing algorithms.

CYK Algorithm

Input string: $X = x_1 \dots x_n$.

Input grammar G : r nonterminal symbols $R_1 \dots R_r$, R_1 start symbol.

$P[n][n][r]$: Array of booleans. Initialize all to **FALSE**

for $s = 1$ to n do

 for each unit production $R_v \rightarrow x_s$ do

$P[1][s][v] \leftarrow \text{TRUE}$

for $\ell = 2$ to n do // Length of span

 for $s = 1$ to $n - \ell + 1$ do // Start of span

 for $p = 1$ to $\ell - 1$ do // Partition of span

 for all $(R_a \rightarrow R_b R_c) \in G$ do

 if $P[p][s][b]$ and $P[\ell - p][s + p][c]$ then

$P[\ell][s][a] \leftarrow \text{TRUE}$

if $P[n][1][1]$ is **TRUE** then

 return `` X is member of language''

else

 return `` X is not member of language''

Example

$S \rightarrow \epsilon \mid AB \mid XB$

$Y \rightarrow AB \mid XB$

$X \rightarrow AY$

$A \rightarrow 0$

$B \rightarrow 1$

Question:

- Is **000111** in $L(G)$?
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Order of evaluation for iterative algorithm: increasing order of substring length.

Example

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Takeaway Points

- 1 Dynamic programming is based on finding a recursive way to solve the problem. Need a recursion that generates a small number of subproblems.
- 2 Given a recursive algorithm there is a natural **DAG** associated with the subproblems that are generated for given instance; this is the dependency graph. An iterative algorithm simply evaluates the subproblems in some topological sort of this **DAG**.
- 3 The space required to evaluate the answer can be reduced in some cases by a careful examination of that dependency **DAG** of the subproblems and keeping only a subset of the **DAG** at any time.