

Turing Machines, contd.

Lecture 9

Turing Machine



Finite alphabet

Read

Write

Move +1 or -1

Halt condition

Internal state (finite number)



TM for Decision Problems

$M = (Q, \Sigma, \Gamma, B, \delta, q_{\text{start}}, q_{\text{accept}}, q_{\text{reject}})$:

Γ is a finite tape alphabet.

- B or \square is the blank symbol (special symbol)

- Σ is a finite input alphabet $\Sigma \subseteq \Gamma \setminus B$

Q is a finite set of states

$q_{\text{start}} \in Q$ is the initial state

$q_{\text{accept}}, q_{\text{reject}} \in Q$ accept/reject states

Or maybe run forever

Transition function: $\delta : Q \times \Gamma \text{ (read)} \rightarrow Q \times \Gamma \text{ (write)} \times \{ L, R \}$



TMs: what we saw and will see

- They are quite tedious to program, but possible! (it's the assembly language version)
- They can do anything a computer can do (copy, shift, add...)
- e.g. RAM



TMs: what we saw and will see



- Will see that a TM can simulate itself. Write a TM interpreter in TM!
- Universal TM.

TMs: what we saw and will see



- **Church-Turing Thesis:**

“Any physically realizable model of computation is equivalent to a TM”

- More of a physical law than a math theorem.
- e.g. Python doesn't have additional power over TM.
- sounds fancy but it says no more than “a Python interpreter can compute anything you can compute in Python”

TMs: what we saw and will see



- **Church-Turing Thesis:**

“Any physically realizable model of computation is equivalent to a TM”

- There are models of computation not equivalent to TM, we won't see them this semester.

Variants/Extensions

Adding more capabilities to TMs make them easier to program

But doesn't change what TMs can do:
whatever the new variant can do, can be simulated
in the original variant
(with a lot more steps, sometimes)



Extension: multiple tracks



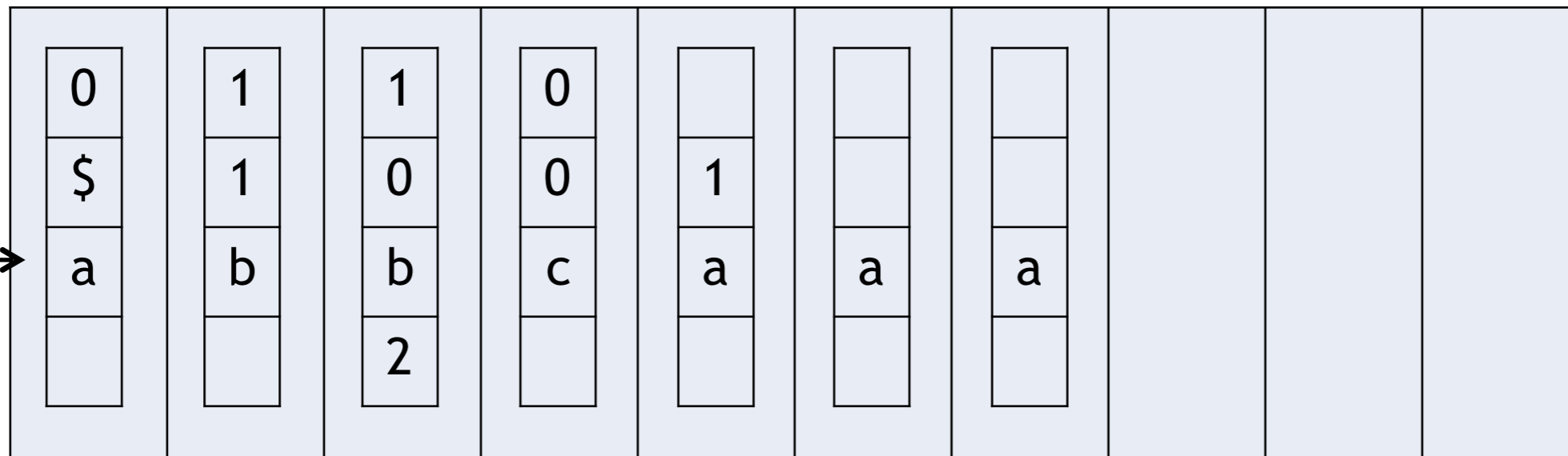
4 tracks

0	1	1	0						
\$	1	0	0	1					
a	b	b	c	a	a	a			
		2							

infinite tape →

M can address any particular track in the cell it is scanning

Can simulate multiple tracks with a single track machine, using extra “stacked” characters:



single new character →

Extension: multiple tracks

4 tracks

0	1	1	0						
\$	1	0	0	1					
a	b	b	c	a	a	a			
		2							

infinite tape →

$$M: \delta(q, -, 0, -, -) = (p, -, -, -, 1, R)$$

“If in state q reading 0 on second track, then go to state p , write 1 on fourth track, and move right”

Then in M' $\delta(q, \begin{matrix} x \\ 0 \\ y \\ z \end{matrix}) = (p, \begin{matrix} x \\ 0 \\ y \\ 1 \end{matrix}, R)$ for every $x, y, z \in \Gamma$



Extension: multiple tracks

4 tracks

0	1	1	0						
\$	1	0	0	1					
a	b	b	c	a	a	a			
		2							

infinite tape →

$$M: \delta(q, -, 0, -, -) = (p, -, -, -, 1, R)$$

“If in state q reading 0 on second track, then go to state p , write 1 on fourth track, and move right”

Transition function:

$$\delta : Q \times \Gamma_1 \times \Gamma_2 \times \Gamma_3 \times \Gamma_4 \rightarrow Q \times \Gamma_1 \times \Gamma_2 \times \Gamma_3 \times \Gamma_4 \times \{ L, R \}$$



Extension: multiple tracks



4 tracks

0	1	1	0						
\$	1	0	0	1					
a	b	b	c	a	a	a			
		2							

infinite tape →

$$M: \delta(q, -, 0, -, -) = (p, -, -, -, 1, R)$$

“If in state q reading 0 on second track, then go to state p , write 1 on fourth track, and move right”

Transition function:

$$\delta : Q \times (\Gamma_1 \times \Gamma_2 \times \Gamma_3 \times \Gamma_4) \rightarrow Q \times (\Gamma_1 \times \Gamma_2 \times \Gamma_3 \times \Gamma_4) \times \{L, R\}$$

Extension: multiple tracks

Sometimes intuitively better with multiple tracks
e.g assume I want to copy this string.

0	1	1	0	1	0				
\$	\$.					

0	1	1	0	1	0	1			
\$	\$	\$.					

0	1	1	0	1	0	1	1		
\$	\$	\$	\$.					

0	1	1	0	1	0	1	1	0	
\$	\$	\$	\$	\$					



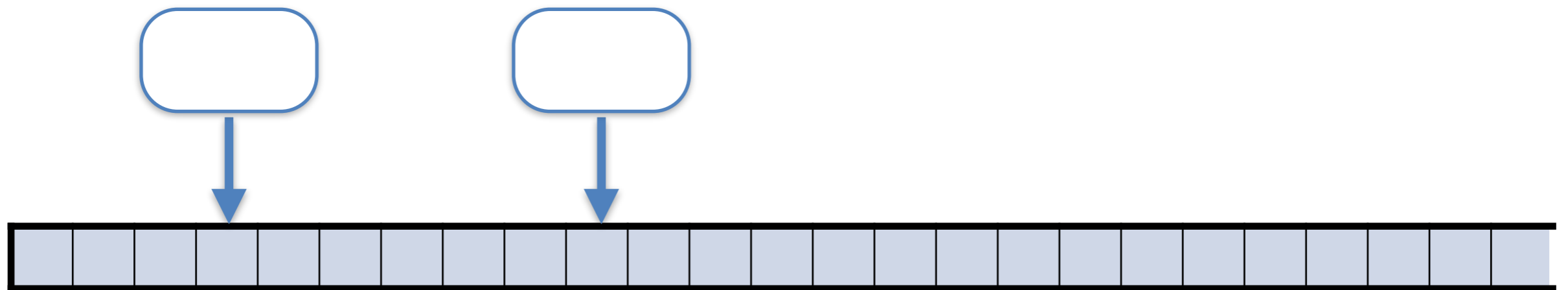
Extension: multiple tracks

Sometimes intuitively better with multiple tracks
e.g assume I want to copy this string.

0	1	1	0	1	0	1	1	0	1
\$	\$	\$	\$	\$					



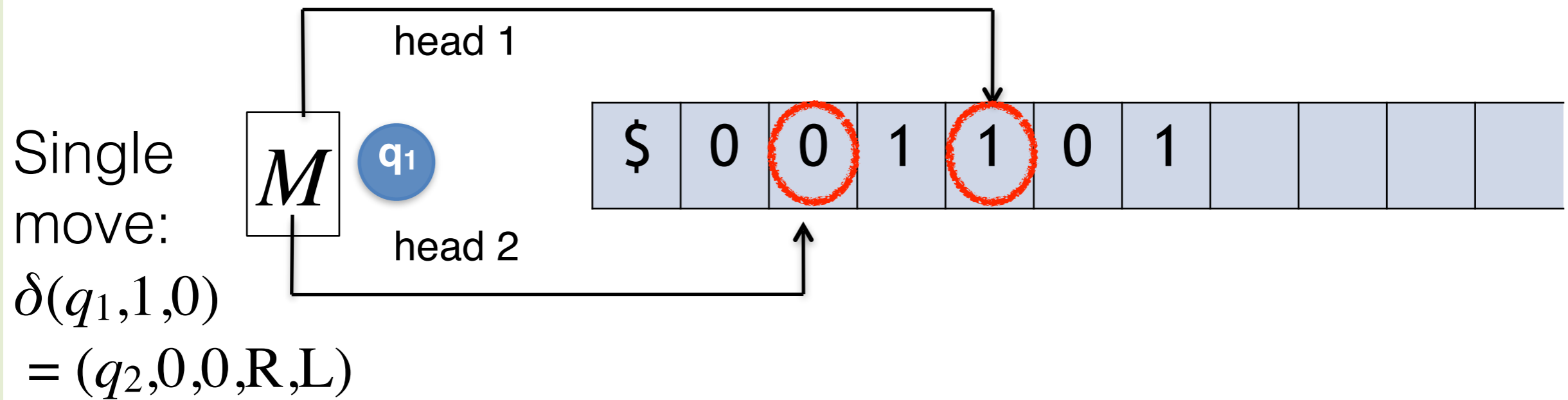
Extension: multiple heads



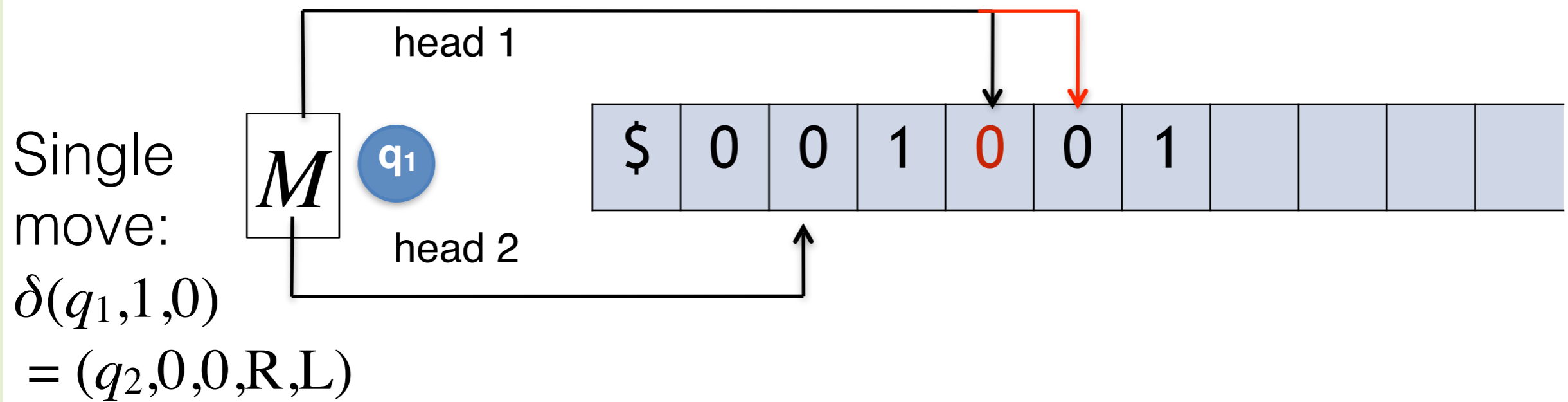
Transition function:

$$\delta : Q \times \Gamma^2 \rightarrow Q \times \Gamma^2 \times \{L, R\}^2$$

Snapshot of simulation (2 heads)

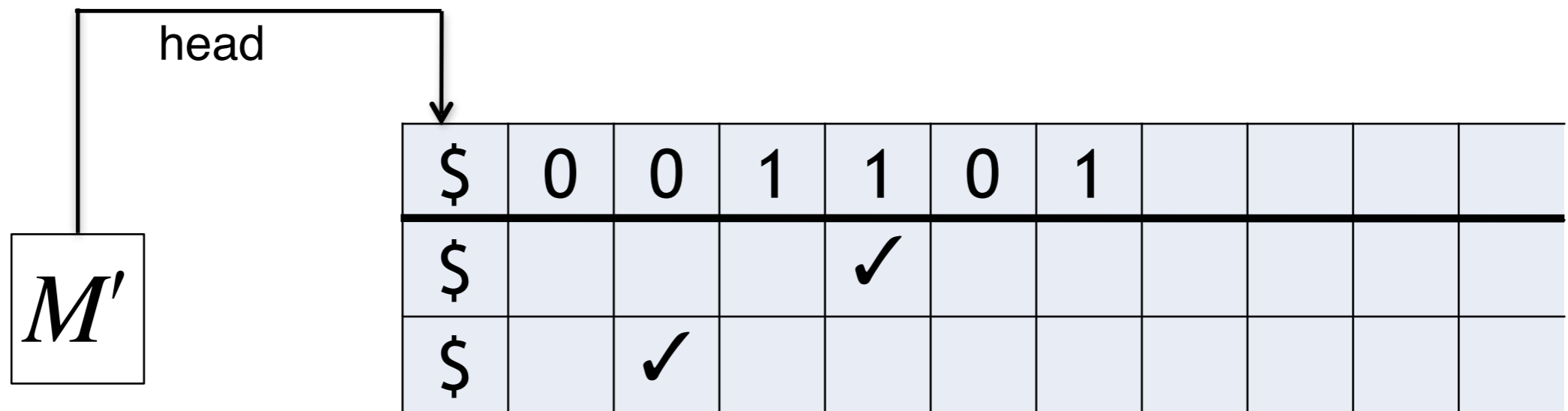
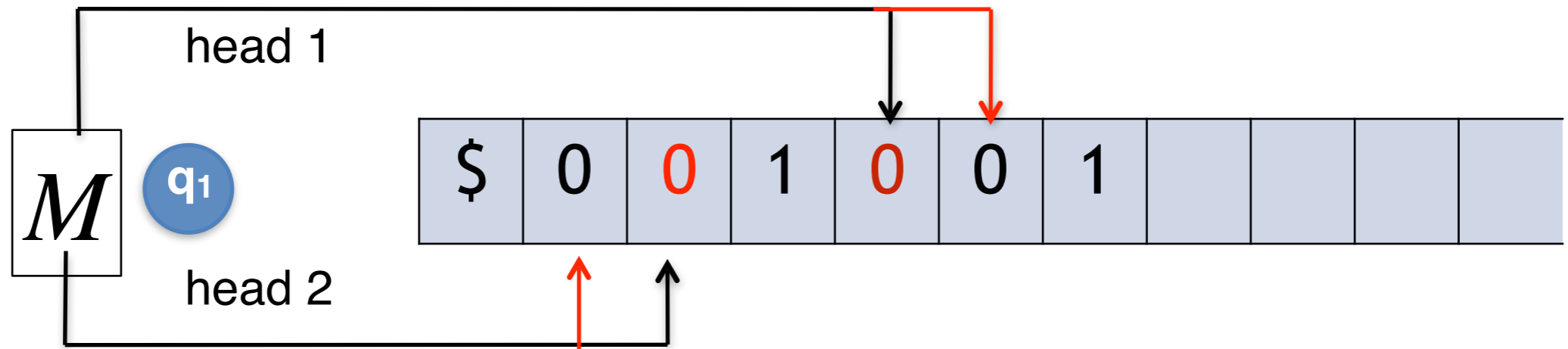


Snapshot of simulation (2 heads)



Snapshot of simulation (2 heads)

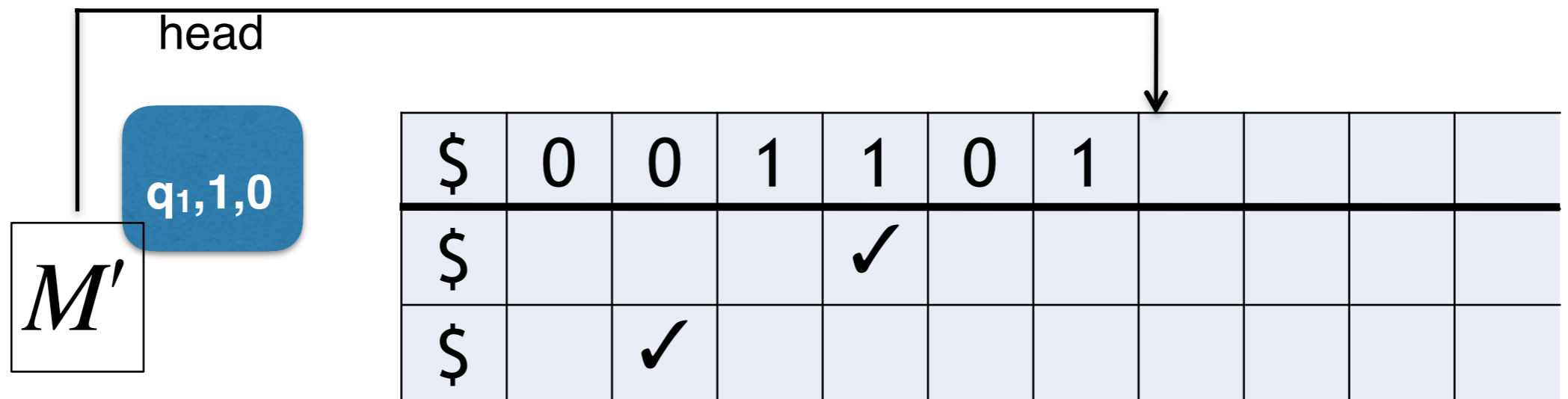
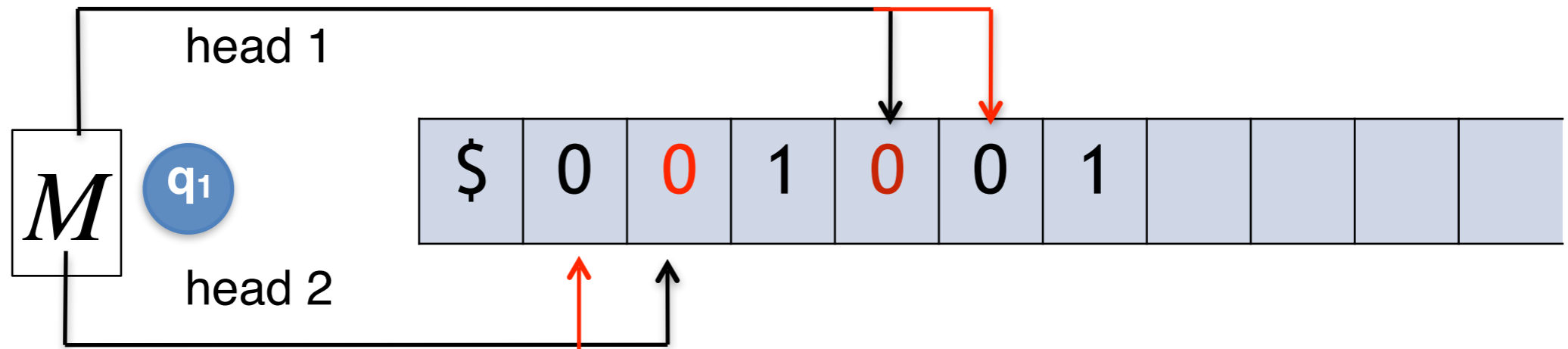
Single move:
 $\delta(q_1, 1, 0)$
 $= (q_2, 0, 0, R, L)$



- Simulate with multiple tracks. Special mark on track 1 and 2 for head positions. Track 0 has input.
- Make sweeps over the entire tape

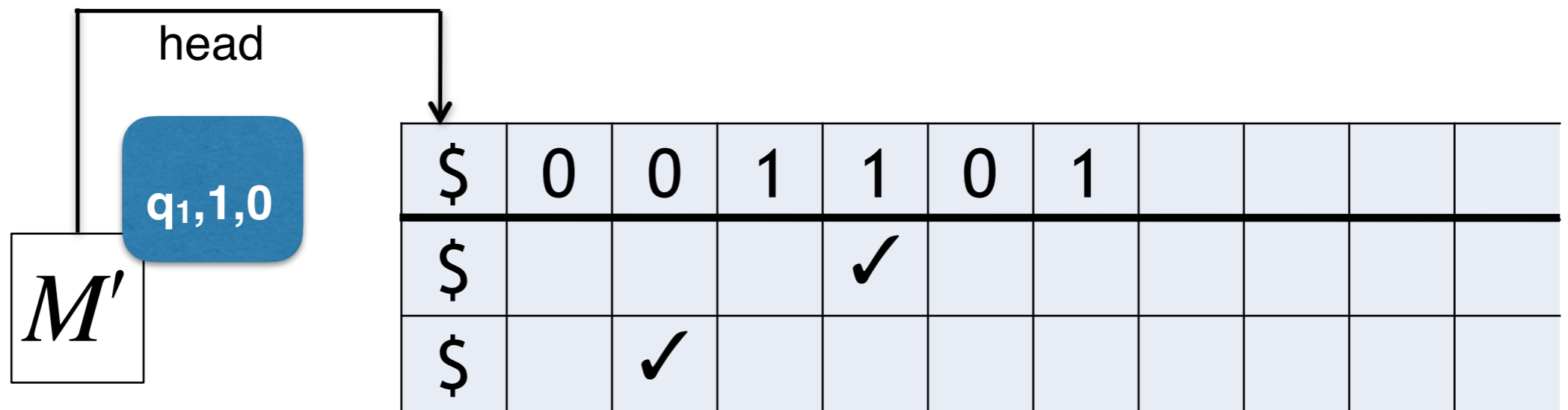
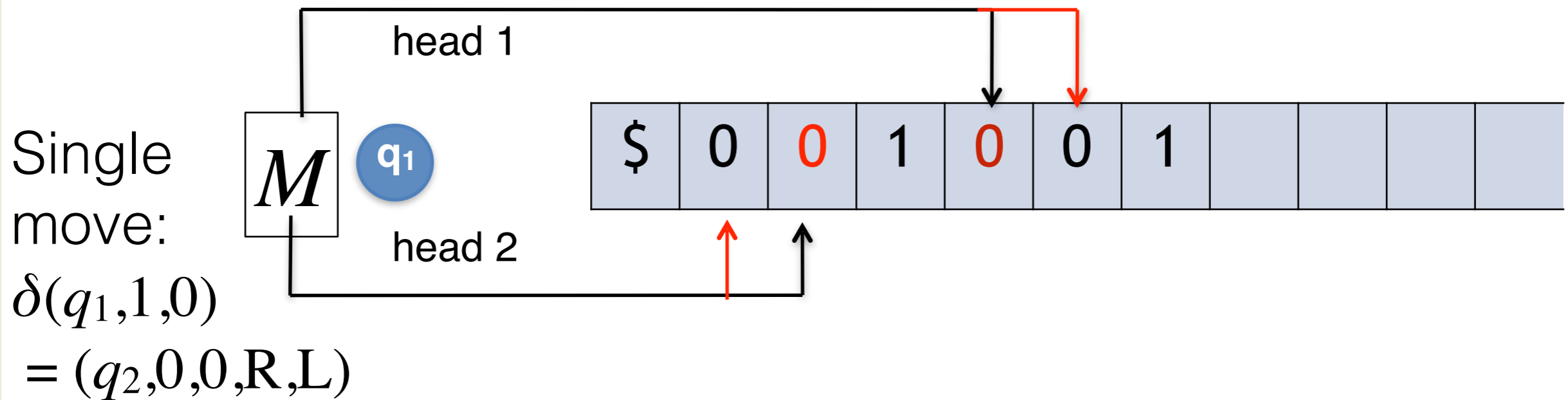
Snapshot of simulation (2 heads)

Single move:
 $\delta(q_1, 1, 0)$
 $= (q_2, 0, 0, R, L)$



- 1) Scan to the right to find the mark on track i , read the corresponding symbol from track 0 into our internal state, and then return to the left end of the tape.

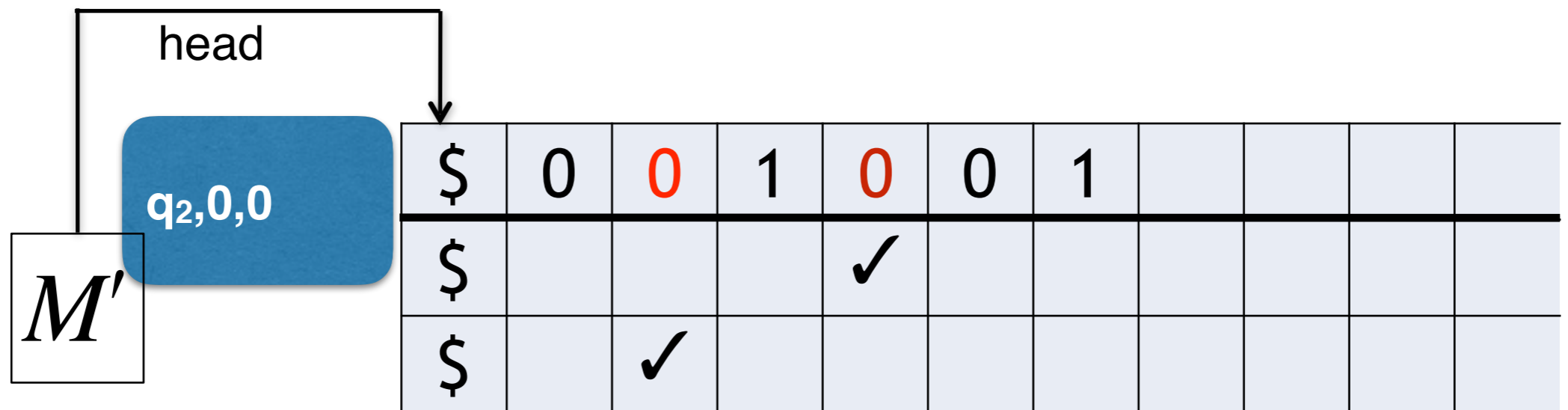
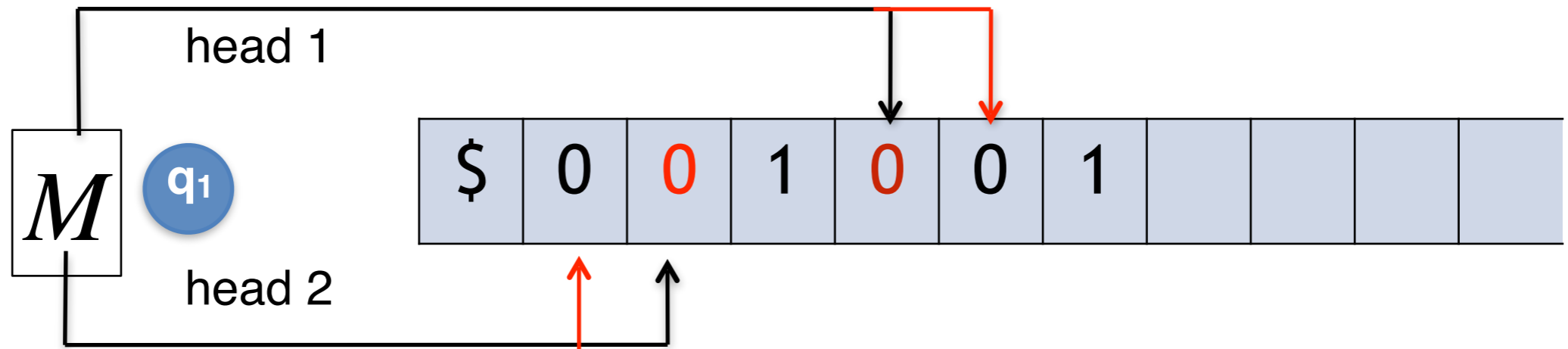
Snapshot of simulation (2 heads)



2) Using M 's transition function, the internal state records M 's next state, the symbol to be written by each head, and the direction to move each head.

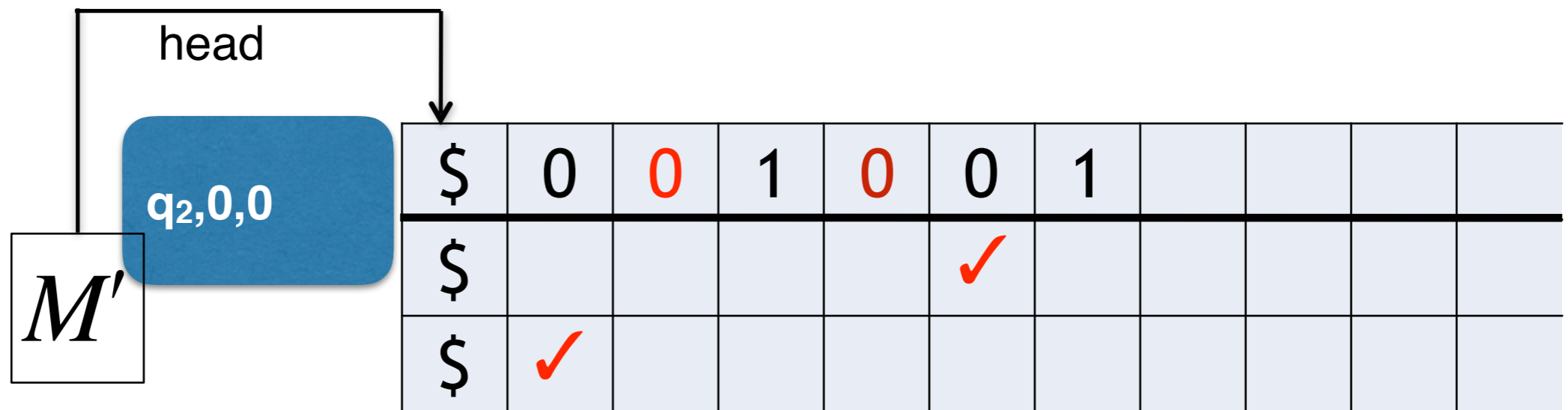
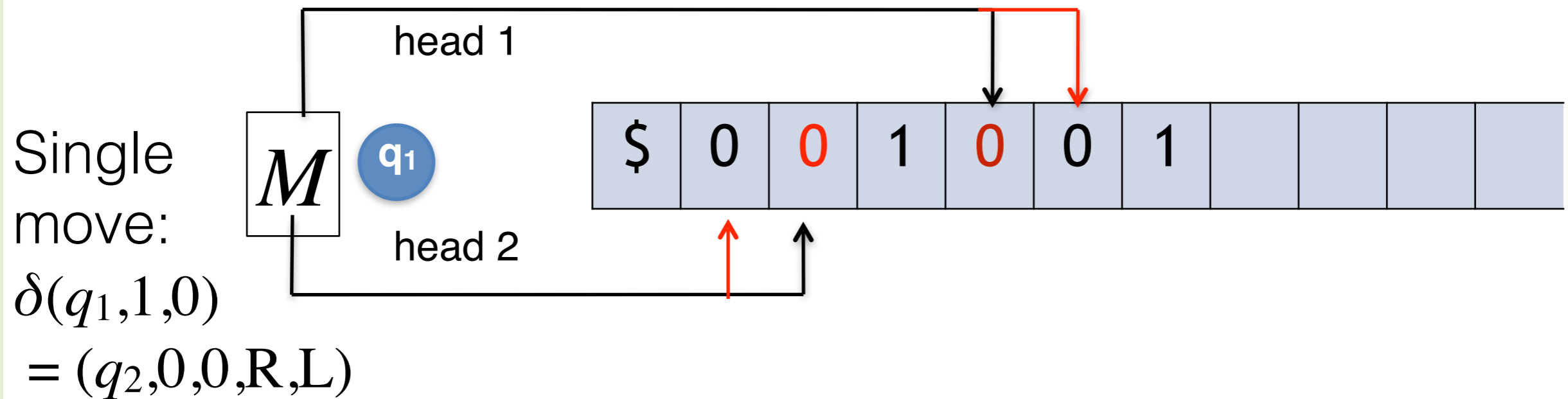
Snapshot of simulation (2 heads)

Single move:
 $\delta(q_1, 1, 0)$
 $= (q_2, 0, 0, R, L)$



- 3) Scan to the right to find the mark on track i , write the correct symbol onto track 0, move the mark on track i one step left or right, and then return to the left end of the tape.

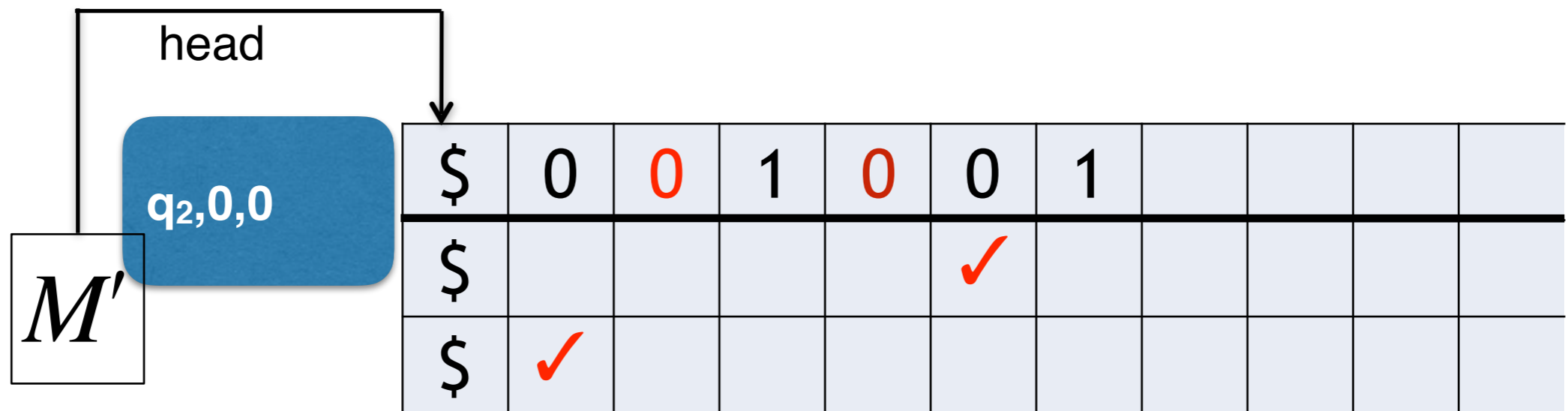
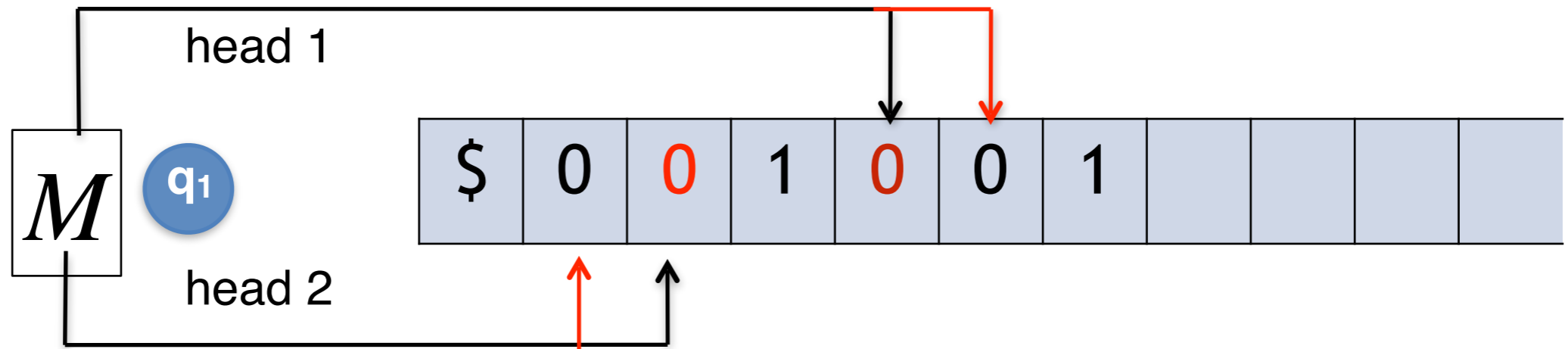
Snapshot of simulation (2 heads)



- 3) Scan to the right to find the mark on track i , write the correct symbol onto track 0, move the mark on track i one step left or right, and then return to the left end of the tape.

Snapshot of simulation (2 heads)

Single move:
 $\delta(q_1, 1, 0)$
 $= (q_2, 0, 0, R, L)$



- Subroutine!
- However, seriously slows down the process but we don't care about running time right now

Extension: multiple tapes

k -tape TM

k different (2-way infinite) tapes

k different independently controllable heads

input initially on tape 1; tapes 2, 3, ..., k , blank.

Single move:

read symbols under all heads

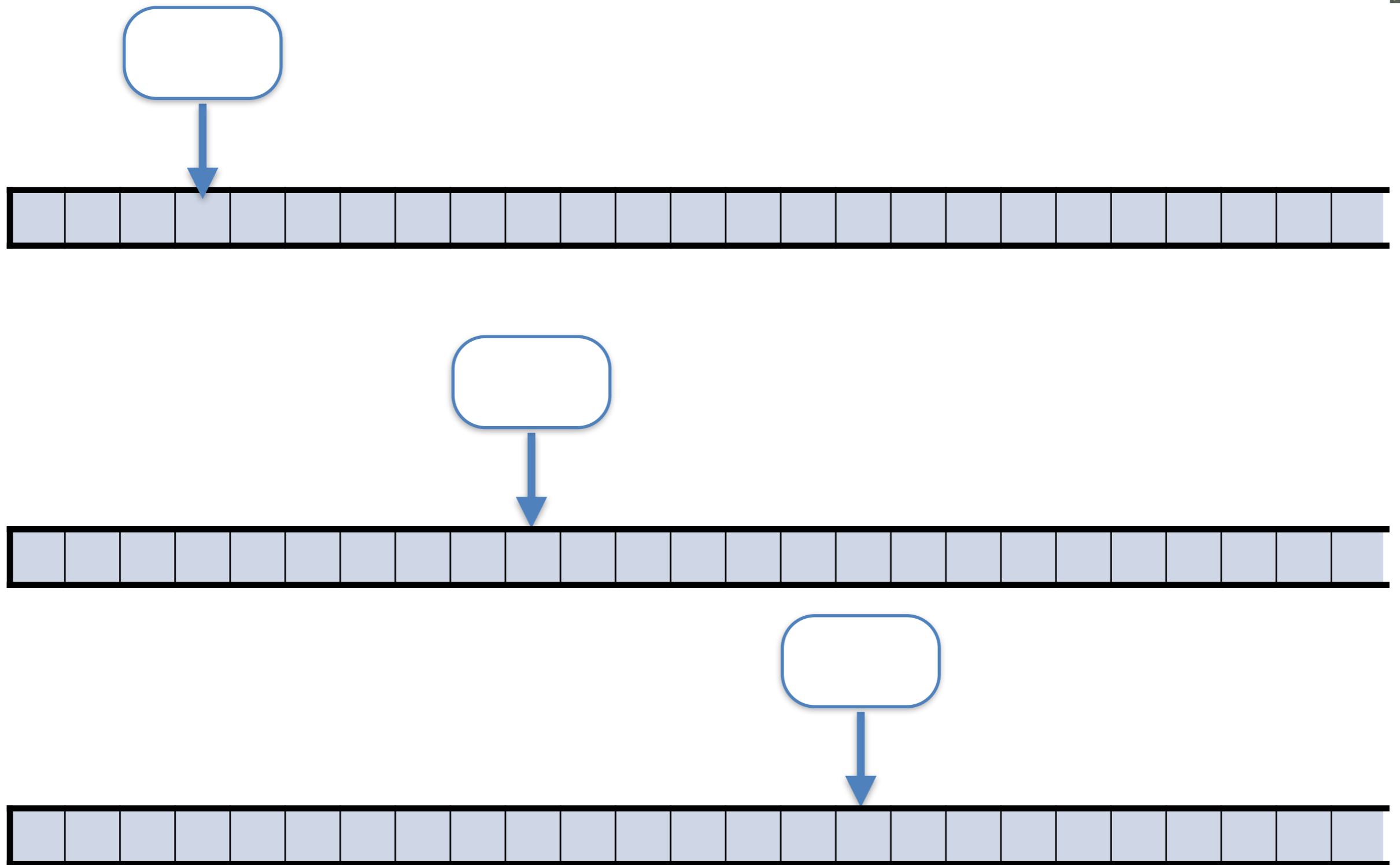
print (possibly different) symbols under heads

move all heads (possibly in different directions)

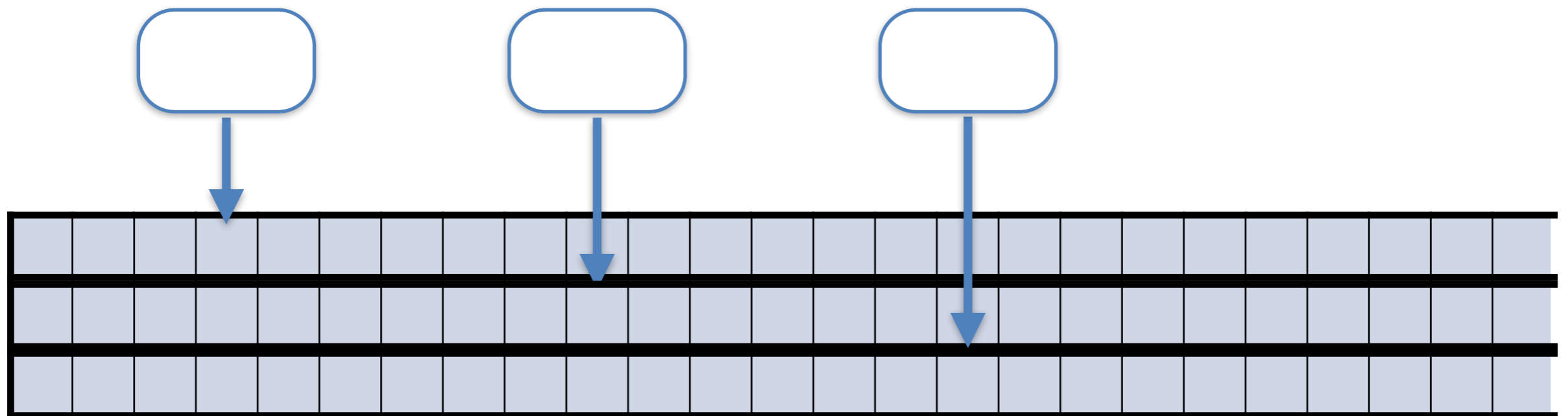
go to new state



Extension: multiple tapes



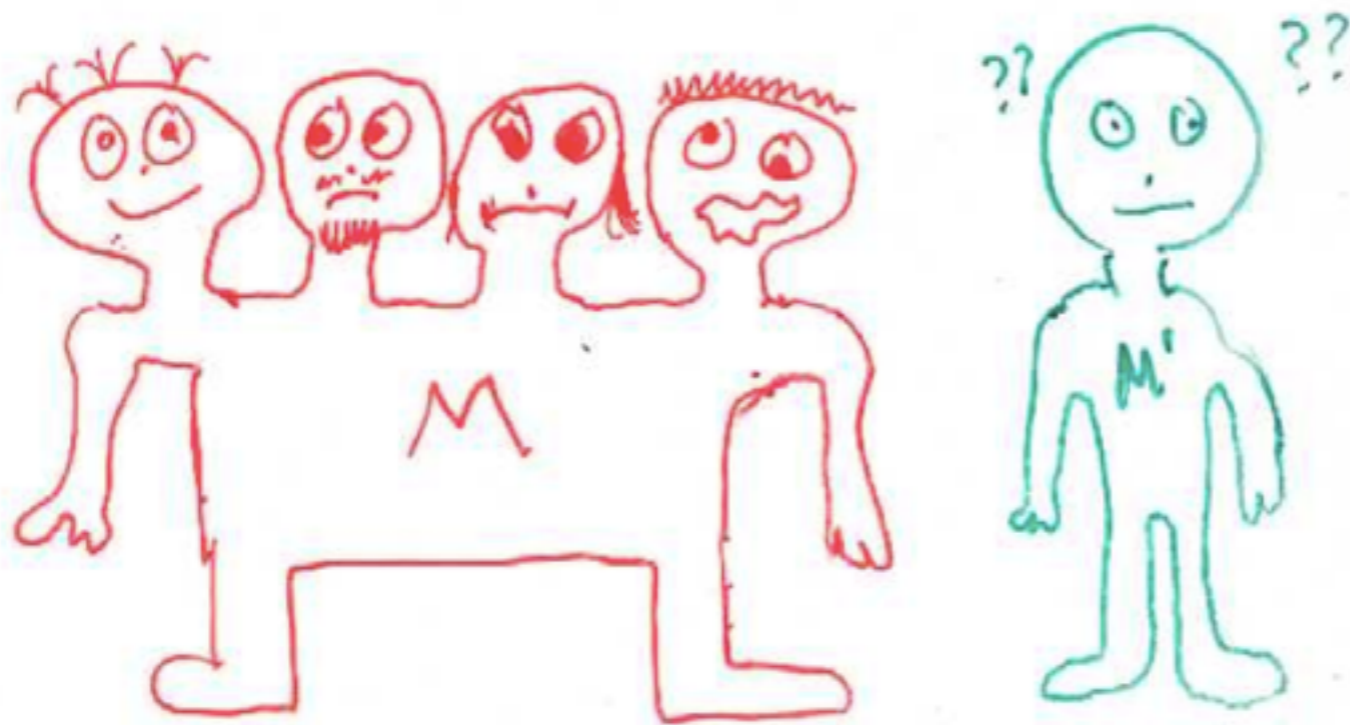
Extension: multiple tapes



Can't compute more with k tapes

Theorem: If L is accepted by a k -tape TM M , then L is accepted by some 1-tape TM M' .

Idea: M' uses k tracks to simulate tapes of M

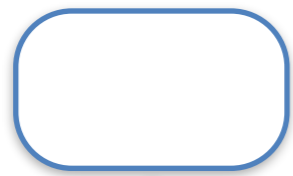


BUT....
M has k heads!

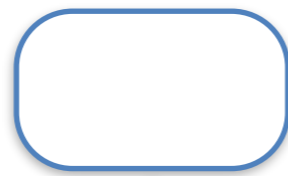
How can M' be in
 k places at once?

M' will use $2k$ tracks to simulate tapes+heads of M

Convention for TM



Input tape (read only, finite)



Work tape (read/write)



Output tape (write only)



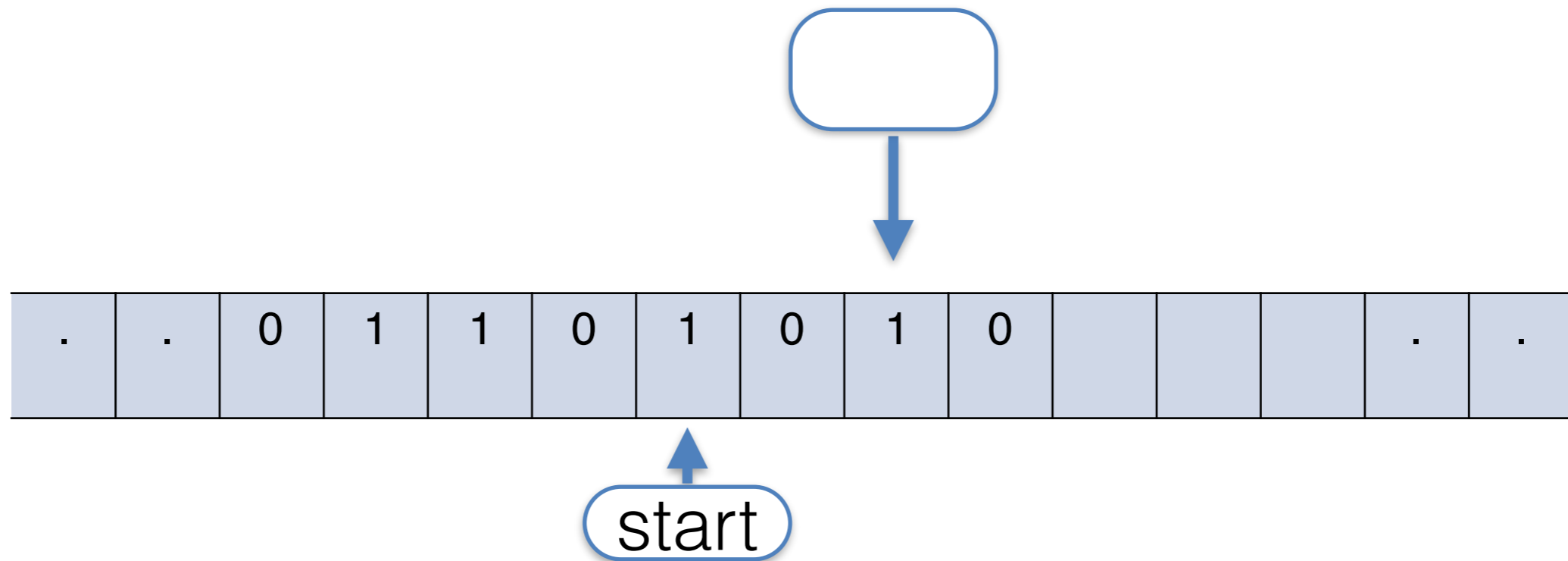
Convention for TM

More convenient!

- Output doesn't clash with input
- Don't have to clean work tape
- Just remember to copy what I need to output tape



Extension: 2-Way Infinite Tape



How to do it with one infinite direction?

2-Way Infinite Tape: Folding

.	.	-5	-4	-3	-2	-1	0	1	2	3	4	5	.	.
---	---	----	----	----	----	----	---	---	---	---	---	---	---	---

Simulating it in the original TM variant:

▶	0	1	-1	2	-2	3	-3	4	-4	5	-5	6	.	.	.
---	---	---	----	---	----	---	----	---	----	---	----	---	---	---	---

Modify transitions:

Remember in control if +ve or -ve side of tape
(contents of 0 cell will be marked).

If positive: $R \rightarrow RR$ & $L \rightarrow LL$

If negative: $R \rightarrow LL$ & $L \rightarrow RR$

At 0: $R \rightarrow R$ & $L \rightarrow RR$

At 1?



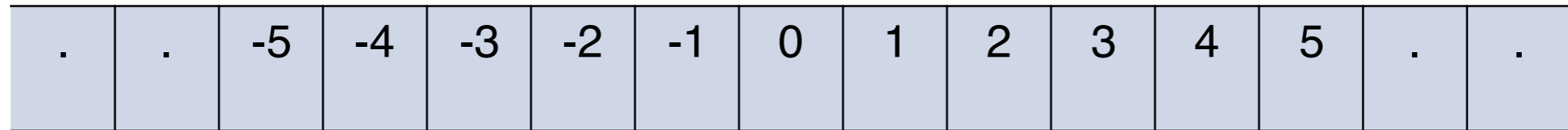
2-Way Infinite Tape: multiple tracks

.	.	-5	-4	-3	-2	-1	0	1	2	3	4	5	.	.
---	---	----	----	----	----	----	---	---	---	---	---	---	---	---

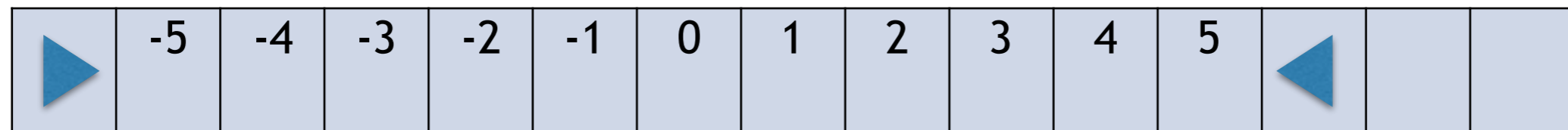
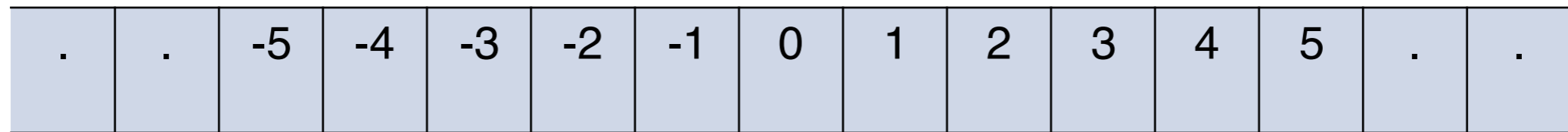
0	1	2	3	4	5									
▶	-1	-2	-3	-4	-5									



2-Way Infinite Tape: shifting



2-Way Infinite Tape: shifting

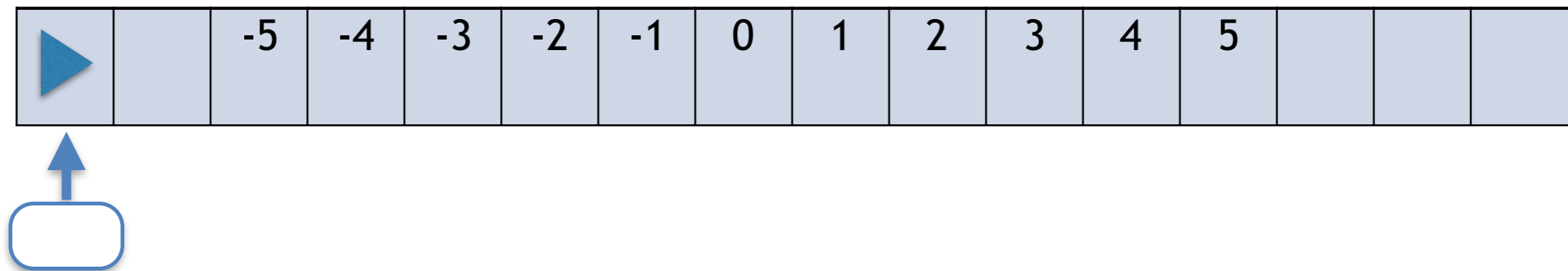


When the machine reads ◀ write a blank, move right, write a ▶, move right and proceed as if we had read a blank.

When the machine reads ▶ shift the entire contents of the tape to the right. Move back to the ▶, move right, write a blank and proceed as if we had read a blank.



2-Way Infinite Tape: shifting



When the machine reads ▶ shift the entire contents of the tape to the right. Move back to the ▶, move right, write a blank and proceed as if we had read a blank.



Subroutine calls

Mechanism for M_1 to “call” M_2 on an argument

Goal:

I need to be able to do two things:

- `push(q)` : push the state in some stack, save it.
- `pop(q)`: pop whatever state is on top of stack and make it current state.



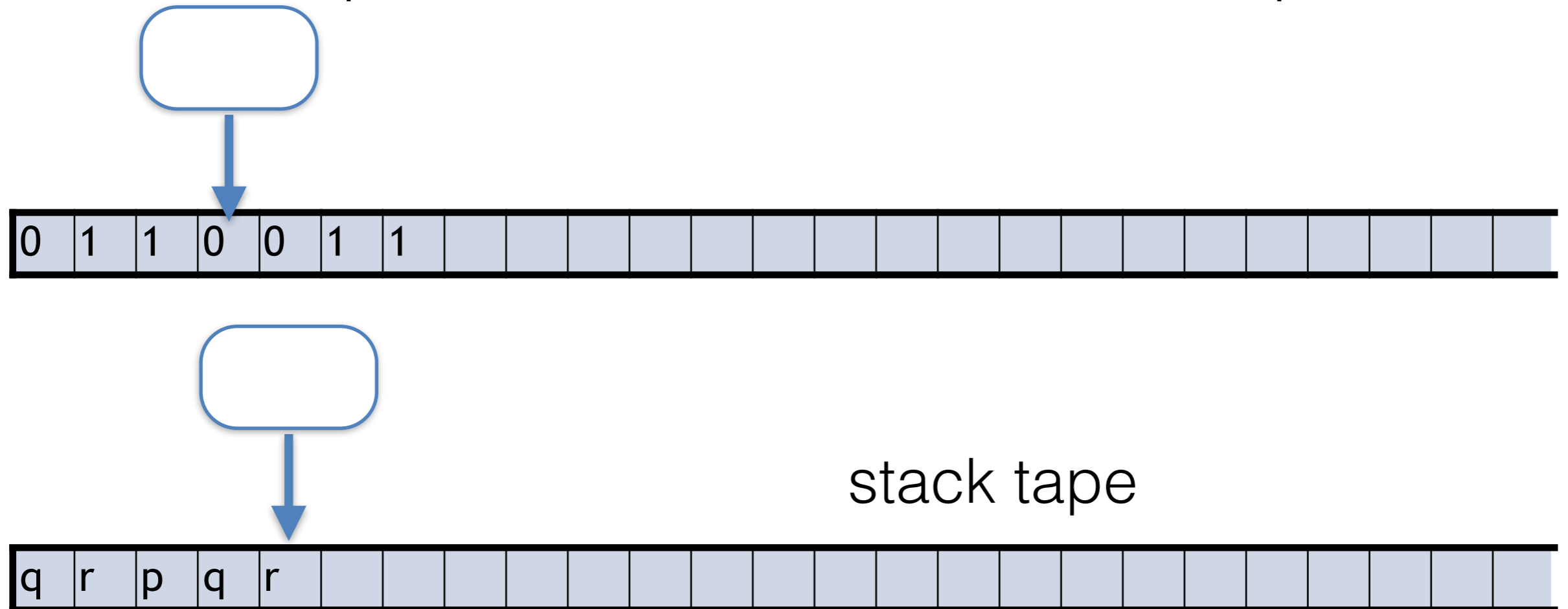
call



return

Subroutine calls

Implement the Stack with a new tape



- For push, write a new symbol to stack and move R
- For pop read symbol, write blank, move head L



Subroutine calls



- Recursion (e.g. Fibonacci)
- Can take existing TMs and call them as subroutines.
- Call = jump to start state of the TM subroutine
- Halt = return

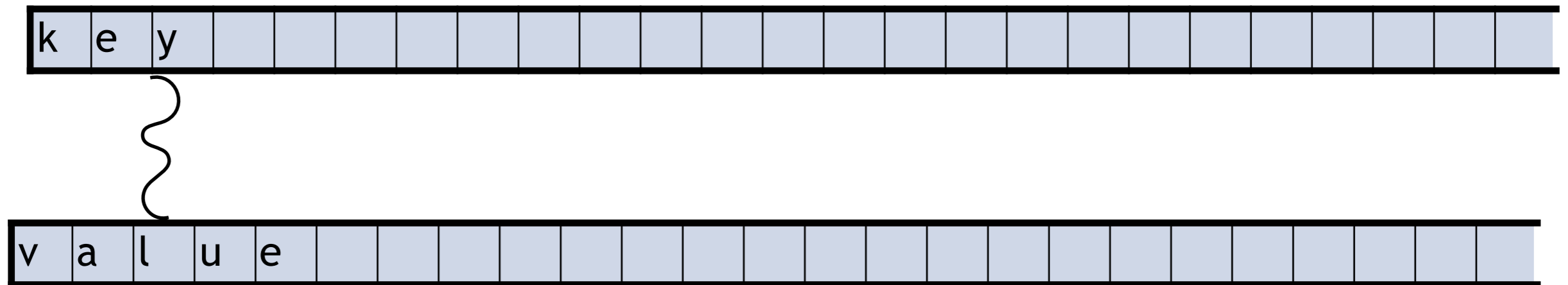
Random Access Memory (RAM)



- By definition can only access memory directly under the head.
- How to do associative memory?
- Memory is made up from pairs [key,value]
- $\text{key} \in \{0,1\}^*$, $\text{value} \in \{0,1\}^*$

Random Access Memory (RAM)

- Would like a subroutine that starts with “key” written at the beginning of a tape and ends with “value” written at the beginning of the same tape



for any key a most one value

Random Access Memory (RAM)



Ram tape $\Sigma = \{[], 0, 1\}$



Address tape



Value tape

Random Access Memory (RAM)



- If I have an RAM also that runs in time $T(n)$, I can simulate it in one tape, one head, one track TM in time $T(n)^2$

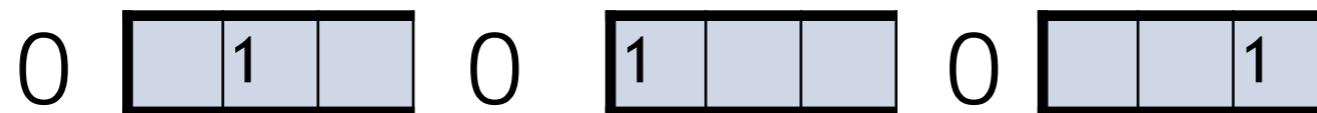
Universal Turing Machine

- "Turing machine interpreter written in Turing machine".
- Just as the input to a Python interpreter is a string of Python source code, the input to our universal Turing machine U is a string $\langle M, w \rangle$ that encodes an arbitrary Turing machine M and a string w in the input alphabet of M .
- Given these encodings, U simulates the execution of M on input w ; in particular,
 - U accepts $\langle M, w \rangle$ if and only if M accepts w .
 - U rejects $\langle M, w \rangle$ if and only if M rejects w .



Universal Turing Machine

- How to encode a Turing Machine as a binary string:
 - $01\Gamma|01\Sigma|01Q|0[\dots]$ where $[\dots]$ is some encoding (brute force) of all possible transitions as pattern of bits.
 - Encode the tape as a bit string: (e.g. tape alphabet of 3 symbols $\{a,b,c\}$)



:tape was bac

