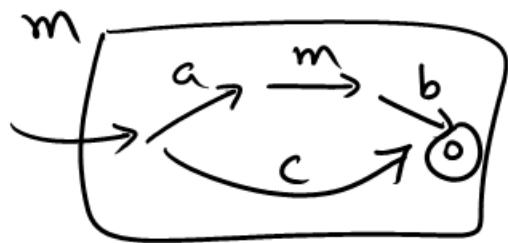


# Recursive Automata



$a \ b \ b \ a \ b$   
 $\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow$   
 $S \rightarrow aSb \mid \epsilon$  .  
 $a a \dots a b \quad b b$

## Formal definition of recursive automata

Each module  $m$   
is an NFA  
over  $\Sigma \cup M$



A recursive automaton over  $\Sigma$  is  
 a tuple  $(M, m_0, \{ (Q_m, \Sigma^M, \delta_m, q_0^m, F_m) \}_{m \in M})$

where :

- $M$  is a finite set (called modules/ procedures)
- $m_0 \in M$  (initial module)
- For every  $m \in M$ ,  
 $(Q_m, \Sigma^M, \delta_m, q_0^m, F_m)$   
 is an NFA.  
 [  $Q_m$  is a finite set ;  $\delta_m : Q_m \times (\Sigma \cup \{\epsilon\}^M) \rightarrow P(Q_m)$   
 $q_0^m \in Q_m$  ;  $F_m \subseteq Q_m$  ]  
 Also  $Q_m \cap Q_{m'} = \emptyset$   
 for any  $m, m'$ ,  $m \neq m'$

A configuration<sup>of RA</sup> is a pair  $(q, s)$

where  $q \in \bigcup_m Q_m$ ,  $s \in Q^*$ .

A recursive automaton  $(M, m_0, f(Q_m, \Sigma^*, \delta_m, q_0^m, F_m))$

accepts a word  $w = a_1 a_2 a_3 \dots a_n$

if there exists  $y_1 \dots y_t = a_1 \dots a_n$

and each  $y_i \in \Sigma \cup \{\epsilon\}$  and there is

a sequence of configurations  $c_0, c_1, \dots, c_t$

•  $c_0 = (q_0^{m_0}, \epsilon)$       •  $c_t = (q, \epsilon)$   
    where  $q \in F_{m_0}$

$\forall i = 0, \dots t-1$

$$C_i \xrightarrow{y_{i+1}} C_{i+1}$$

$$y_{i+1} = \epsilon$$

$$q \in F_m$$

$$C_{i+1} = (q', s')$$

$$\text{where } s = q' s'$$

return

$$C_i = (q, s)$$

$$q \in Q_m$$

internal

call

$$q' \in \delta_m(q, y_{i+1})$$

$$C_{i+1} = (q', s)$$

$$y_{i+1} = \epsilon$$

$$C_{i+1} = (q^m, q^m s)$$

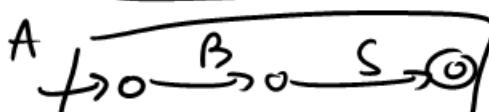
The language accepted by an RA  
 $A$ ,  
 $L(A) = \{w \mid A \text{ accepts } w\}$

CFGs  $\hookrightarrow$  RAs.

$$S \rightarrow aSbb \mid A$$

$$A \rightarrow BS$$

$$B \rightarrow bB \mid \epsilon$$



General construction:

- Create a procedure for each variable.
- Create the state-machine for module  $V$  as any NFA accepting all the words  $w$  such that  $V \rightarrow w$  is a rule.

RAs  $\hookrightarrow$  CFGs

Variables: one for each state

$X_q$

Start variable :  $X_{q_1}$

$$X_{q_1} \rightarrow a X_{q_2}$$

$$X_{q_2} \rightarrow X_{p_1} X_{q_2}$$

$$X_{q_3} \rightarrow \epsilon$$



$$\left. \begin{array}{l} X_{p_1} \rightarrow X_{q_1} X_{p_2} \\ X_{p_2} \rightarrow \epsilon \end{array} \right\} X_{p_1} \rightarrow X_{q_1} X_{p_2} \quad | \quad c X_{q_3}$$

RAs to CFGs.

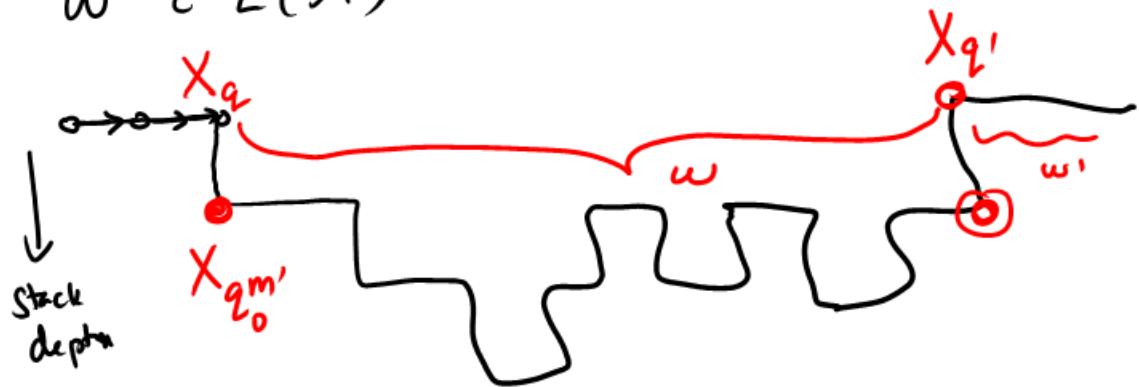
Let  $A = (M, m_0, \{Q_m, \Sigma \cup M, \delta_m, q_0^m, F_m\})$   
be a RA.

Let CFG  $G = (V, \Sigma, R, S)$

where  $V = \{X_q \mid q \in Q_m, m \in M\}$   
 $S = X_{q_0^{m_0}}$

$$R = \left\{ \begin{array}{ll} X_q \rightarrow a X_{q'} & q' \in \delta_m(q, a), a \in \Sigma \cup M \\ X_q \rightarrow X_{q_0^m} X_{q'} & q' \in \delta_m(q, m) \\ X_q \rightarrow \epsilon & q \in \bigcup_{m \in M} F_m. \end{array} \right.$$

$w \in L(A)$



$$X_q \rightarrow X_{q_0^m} X_{q_1^m}$$

$CFLs \equiv RA$ .

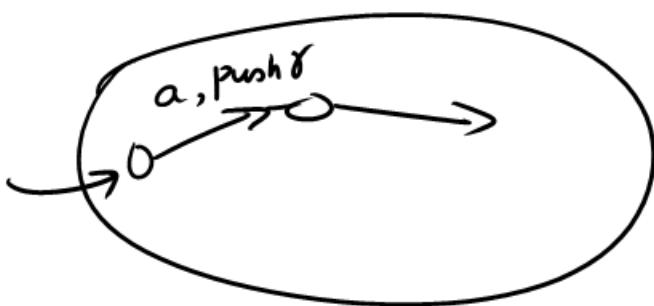
$RA$  are not closed under intersection.

$RA_1$  and  $RA_2$

You can't simulate both  $RA_1$   
and  $RA_2$  together.

RAs can't accept  $\{a^n b^n c^n \mid n \in N\}$

### Pushdown automata



Pushdown automata  $\equiv$  CFLs  $\equiv$  RAs.