

Unconstrained Optimization ND

What is the optimal solution? (ND)

$$f(\mathbf{x}^*) = \min_{\mathbf{x}} f(\mathbf{x})$$

(First-order) Necessary condition

$$1D: f'(x) = 0$$

(Second-order) Sufficient condition

$$1D: f''(x) > 0$$

Taking derivatives...

From linear algebra:

A symmetric $n \times n$ matrix \mathbf{H} is **positive definite** if $\mathbf{y}^T \mathbf{H} \mathbf{y} > \mathbf{0}$ for any $\mathbf{y} \neq \mathbf{0}$

A symmetric $n \times n$ matrix \mathbf{H} is **positive semi-definite** if $\mathbf{y}^T \mathbf{H} \mathbf{y} \geq \mathbf{0}$ for any $\mathbf{y} \neq \mathbf{0}$

A symmetric $n \times n$ matrix \mathbf{H} is **negative definite** if $\mathbf{y}^T \mathbf{H} \mathbf{y} < \mathbf{0}$ for any $\mathbf{y} \neq \mathbf{0}$

A symmetric $n \times n$ matrix \mathbf{H} is **negative semi-definite** if $\mathbf{y}^T \mathbf{H} \mathbf{y} \leq \mathbf{0}$ for any $\mathbf{y} \neq \mathbf{0}$

A symmetric $n \times n$ matrix \mathbf{H} that is not negative semi-definite and not positive semi-definite is called **indefinite**

$$f(\mathbf{x}^*) = \min_{\mathbf{x}} f(\mathbf{x})$$

First order necessary condition: $\nabla f(\mathbf{x}) = \mathbf{0}$

Second order sufficient condition: $\mathbf{H}(\mathbf{x})$ is positive definite

How can we find out if the Hessian is positive definite?

Types of optimization problems

$$f(\mathbf{x}^*) = \min_{\mathbf{x}} f(\mathbf{x})$$

f : nonlinear, continuous
and smooth

Gradient-free methods

Evaluate $f(\mathbf{x})$

Gradient (first-derivative) methods

Evaluate $f(\mathbf{x}), \nabla f(\mathbf{x})$

Second-derivative methods

Evaluate $f(\mathbf{x}), \nabla f(\mathbf{x}), \nabla^2 f(\mathbf{x})$

Example (ND)

Consider the function $f(x_1, x_2) = 2x_1^3 + 4x_2^2 + 2x_2 - 24x_1$

Find the stationary point and check the sufficient condition

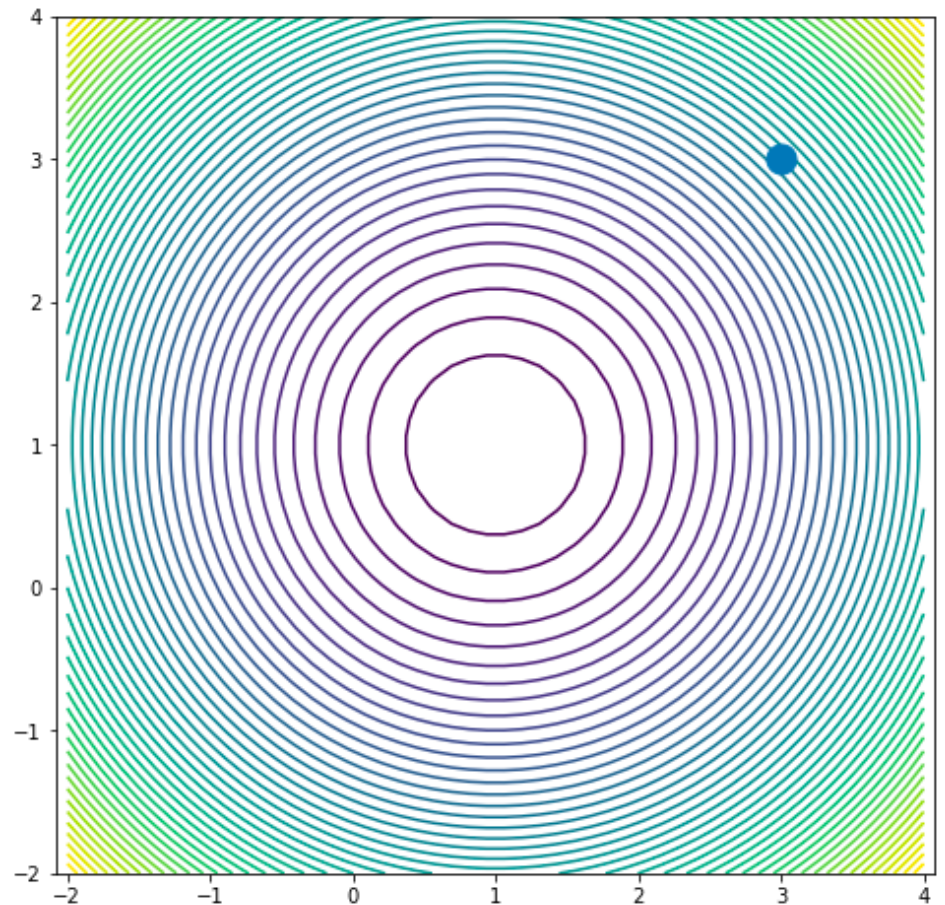
Optimization in ND: Steepest Descent Method

Given a function

$f(\mathbf{x}): \mathcal{R}^n \rightarrow \mathcal{R}$ at a point
 \mathbf{x} , the function will decrease
its value in the direction of
steepest descent: $-\nabla f(\mathbf{x})$

What is the steepest descent
direction?

$$f(x_1, x_2) = (x_1 - 1)^2 + (x_2 - 1)^2$$



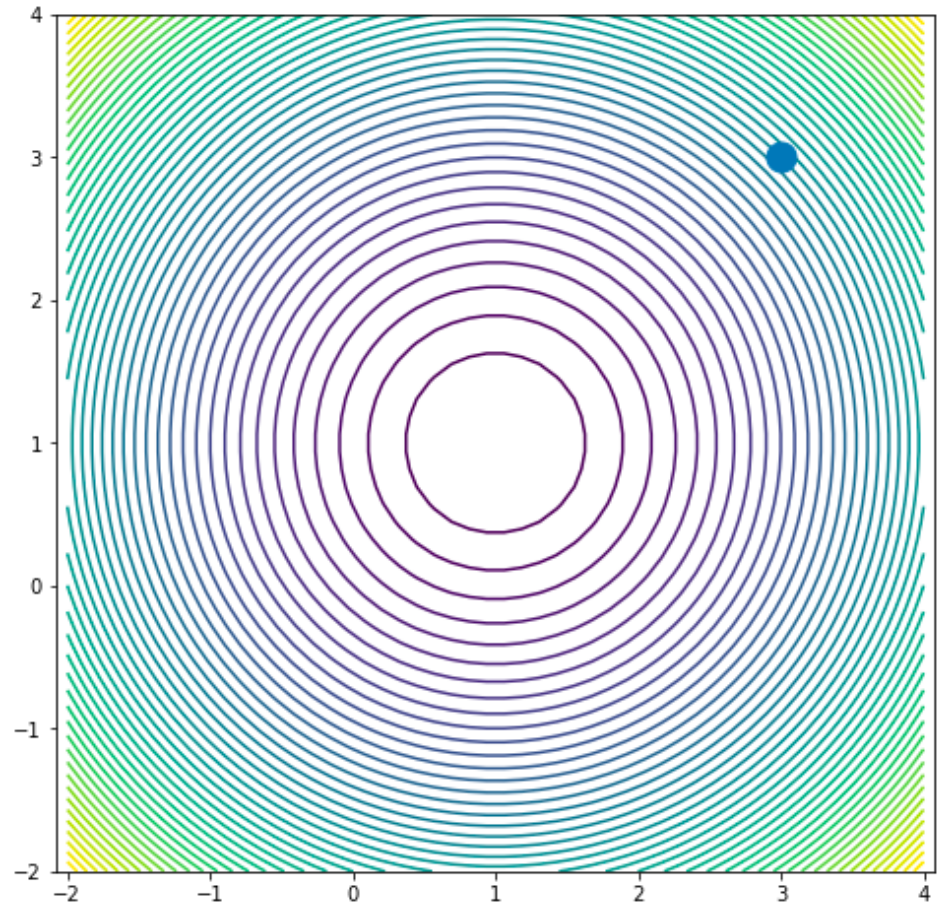
Steepest Descent Method

Start with initial guess:

$$\mathbf{x}_0 = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$$

Check the update:

$$f(x_1, x_2) = (x_1 - 1)^2 + (x_2 - 1)^2$$



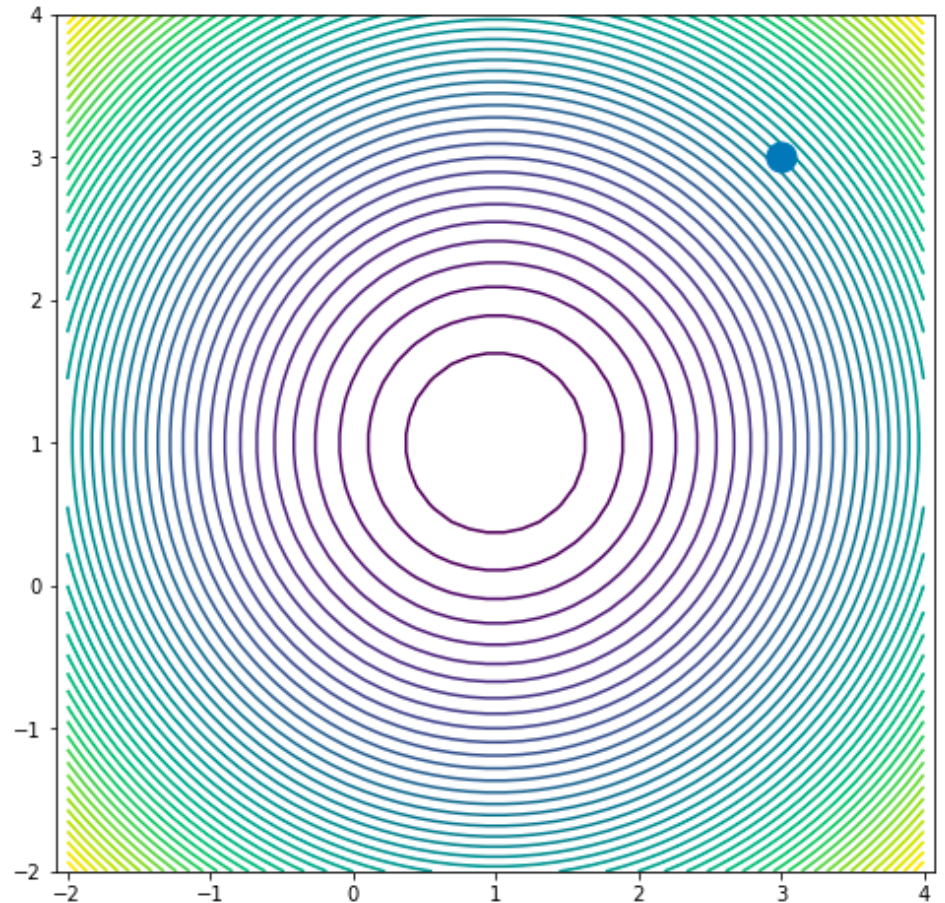
Steepest Descent Method

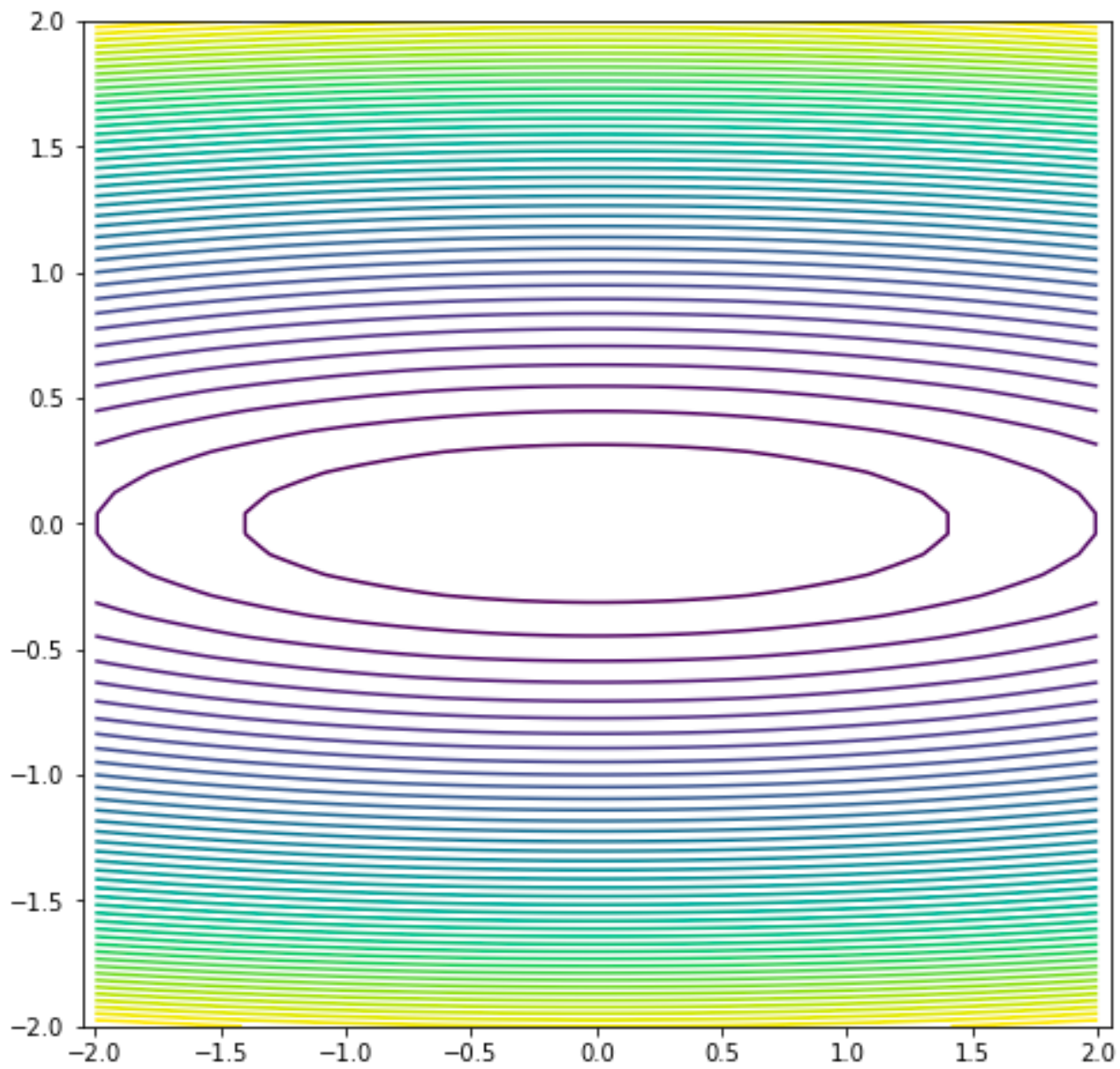
Update the variable with:

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \alpha_k \nabla f(\mathbf{x}_k)$$

How far along the gradient should we go? What is the “best size” for α_k ?

$$f(x_1, x_2) = (x_1 - 1)^2 + (x_2 - 1)^2$$





Steepest Descent Method

Algorithm:

Initial guess: \mathbf{x}_0

Evaluate: $\mathbf{s}_k = -\nabla f(\mathbf{x}_k)$

Perform a line search to obtain α_k (for example, Golden Section Search)

$$\alpha_k = \operatorname{argmin}_{\alpha} f(\mathbf{x}_k + \alpha \mathbf{s}_k)$$

Update: $\mathbf{x}_{k+1} = \mathbf{x}_k + \alpha_k \mathbf{s}_k$

Line Search

Example

Consider minimizing the function

$$f(x_1, x_2) = 10(x_1)^3 - (x_2)^2 + x_1 - 1$$

Given the initial guess

$$x_1 = 2, x_2 = 2$$

what is the direction of the first step of gradient descent?

Newton's Method

Using Taylor Expansion, we build the approximation:

Newton's Method

Algorithm:

Initial guess: \mathbf{x}_0

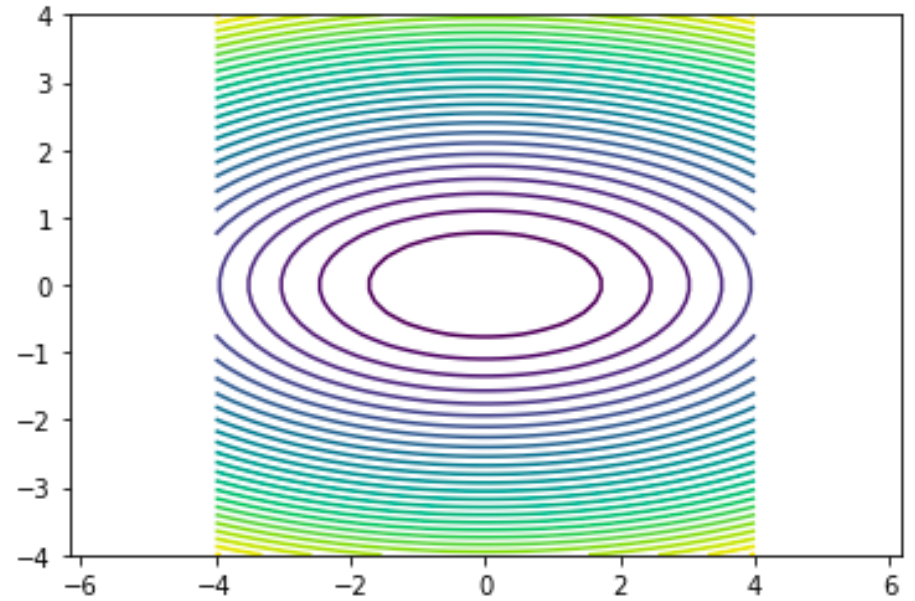
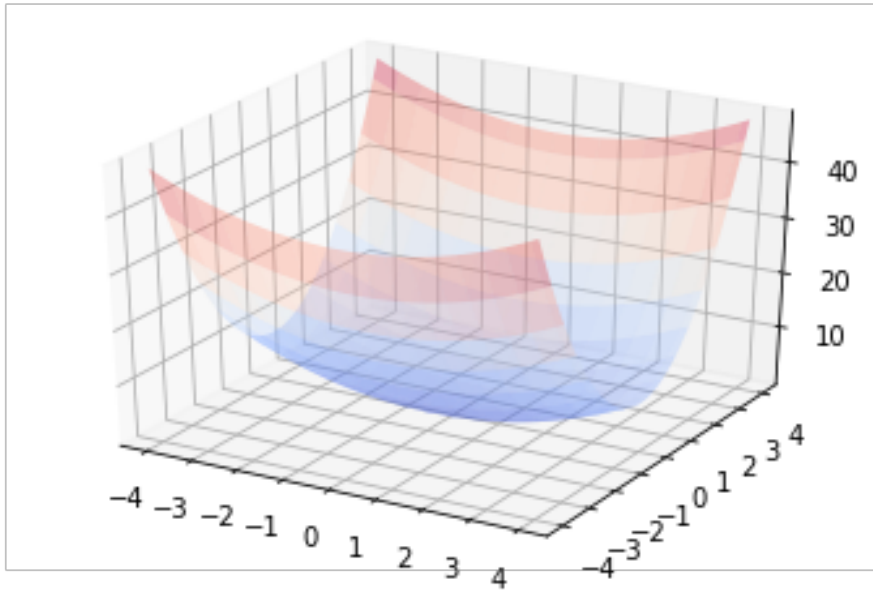
Solve: $\mathbf{H}_f(\mathbf{x}_k) \mathbf{s}_k = -\nabla f(\mathbf{x}_k)$

Update: $\mathbf{x}_{k+1} = \mathbf{x}_k + \mathbf{s}_k$

Note that the Hessian is related to the curvature and therefore contains the information about how large the step should be.

Try this out!

$$f(x, y) = 0.5x^2 + 2.5y^2$$



When using the Newton's Method to find the minimizer of this function, estimate the number of iterations it would take for convergence?

- A) 1 B) 2-5 C) 5-10 D) More than 10 E) Depends on the initial guess

Newton's Method Summary

Algorithm:

Initial guess: \mathbf{x}_0

Solve: $\mathbf{H}_f(\mathbf{x}_k) \mathbf{s}_k = -\nabla f(\mathbf{x}_k)$

Update: $\mathbf{x}_{k+1} = \mathbf{x}_k + \mathbf{s}_k$

About the method...

- Typical quadratic convergence 😊
- Need second derivatives ☹️
- Local convergence (start guess close to solution)
- Works poorly when Hessian is nearly indefinite
- Cost per iteration: $O(n^3)$