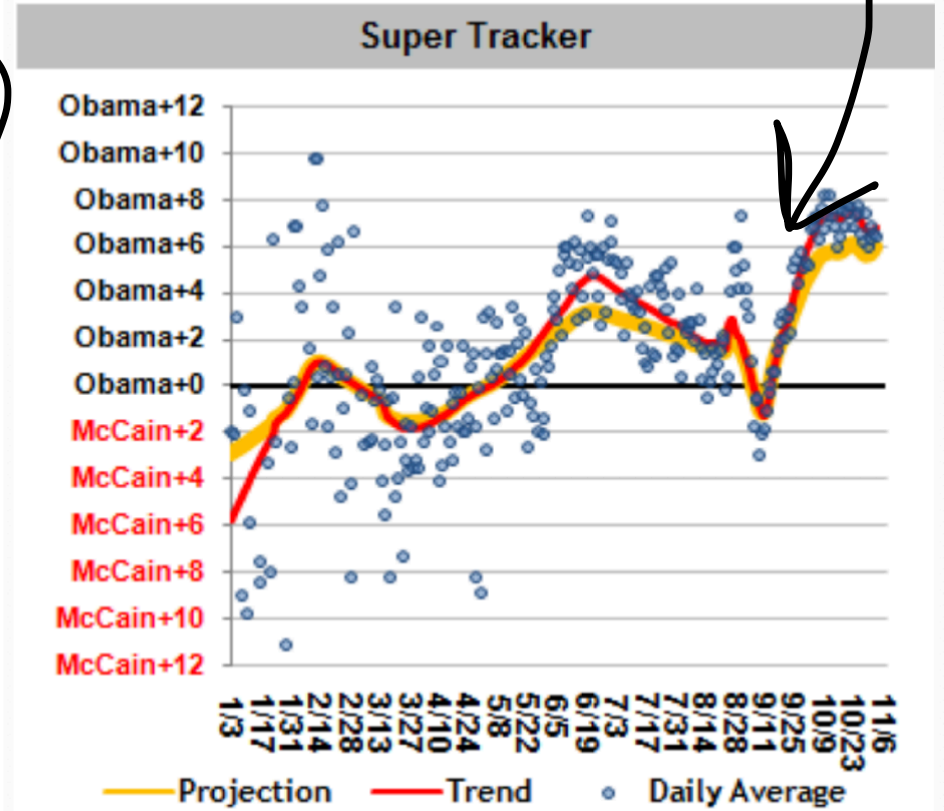
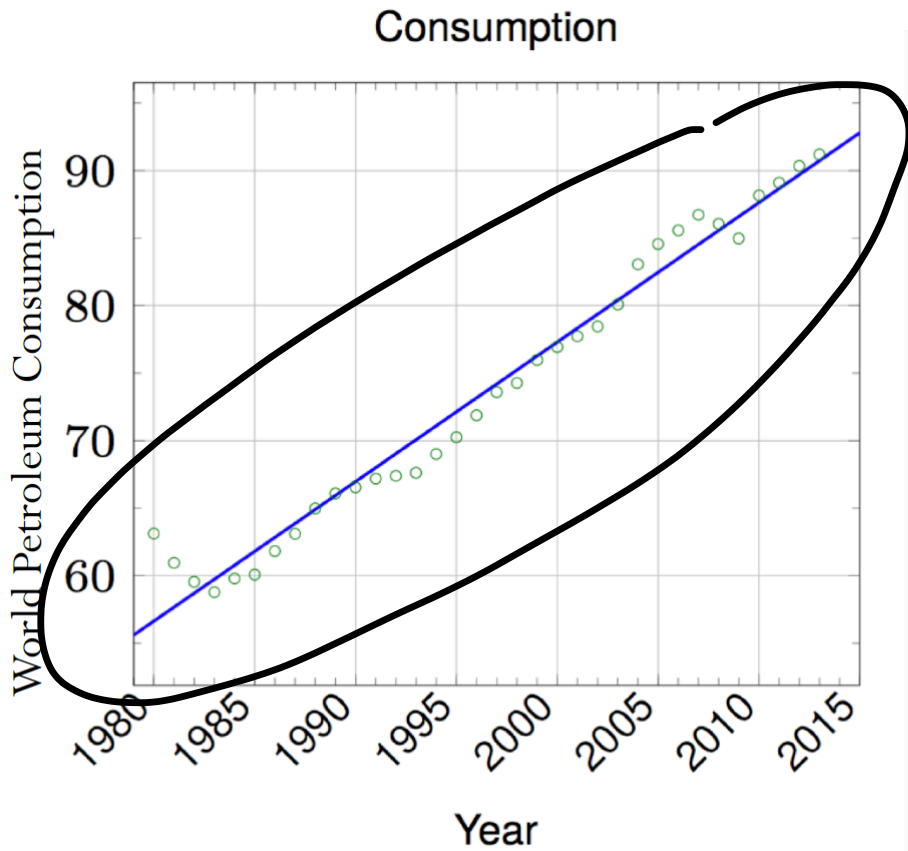


Least Squares and Data Fitting

Data fitting

How do we best fit a set of data points?



Linear Least Squares

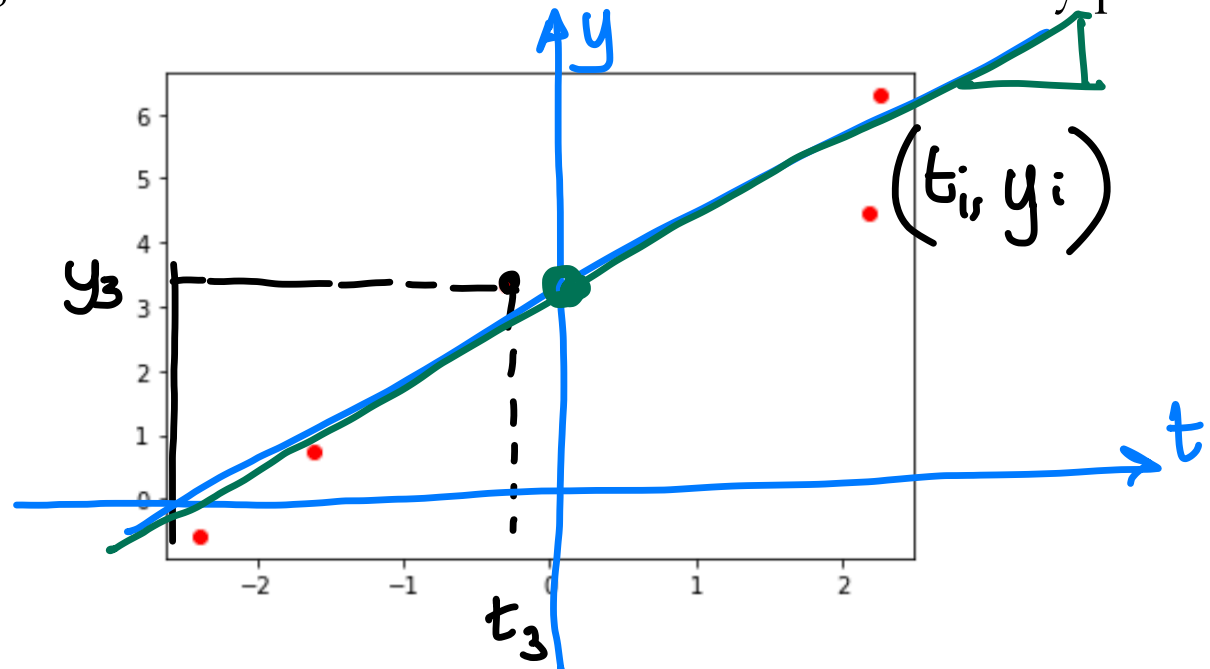
1) Fitting with a line

Given m data points $\{\{t_1, y_1\}, \dots, \{t_m, y_m\}\}$, we want to find the function

$$y = x_0 + x_1 t$$

that best fit the data (or better, we want to find the coefficients x_0, x_1).

Thinking geometrically, we can think “what is the line that most nearly passes through all the points?”



Given m data points $\{(t_1, y_1), \dots, (t_m, y_m)\}$, we want to find x_0 and x_1 such that

(t_i, y_i)

$$y_i = x_0 + x_1 t_i$$

$$\forall i \in [1, m]$$

$$\begin{cases} y_1 = x_0 + x_1 t_1 \\ y_2 = x_0 + x_1 t_2 \\ y_3 = x_0 + x_1 t_3 \\ \vdots \\ y_m = x_0 + x_1 t_m \end{cases}$$

}

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

=

$$\begin{bmatrix} 1 & t_1 \\ 1 & t_2 \\ \vdots & \vdots \\ 1 & t_m \end{bmatrix}$$

$$\begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$$

\tilde{x} $n \times 1$

\tilde{b} $m \times 1$

A $m \times n$

$$\tilde{b} = A \tilde{x}$$

overdetermined! $\boxed{m > n}$

$$\begin{matrix} \text{given} \nearrow & \tilde{b} & = & A & \tilde{x} \\ & \nearrow & & \nearrow & \nearrow \\ & & & \text{given} & \text{find} \end{matrix}$$

Given m data points $\{\{t_1, y_1\}, \dots, \{t_m, y_m\}\}$, we want to find x_0 and x_1 such that

$$y_i = x_0 + x_1 t_i \quad \forall i \in [1, m]$$

or in matrix form:

$$\begin{bmatrix} 1 & t_1 \\ \vdots & \vdots \\ 1 & t_m \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$$

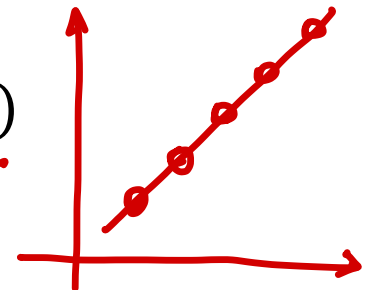
$m \times n$ $n \times 1$ $m \times 1$

$$\mathbf{A} \mathbf{x} = \mathbf{b}$$

Note that this system of linear equations has more equations than unknowns –
OVERDETERMINED
SYSTEMS

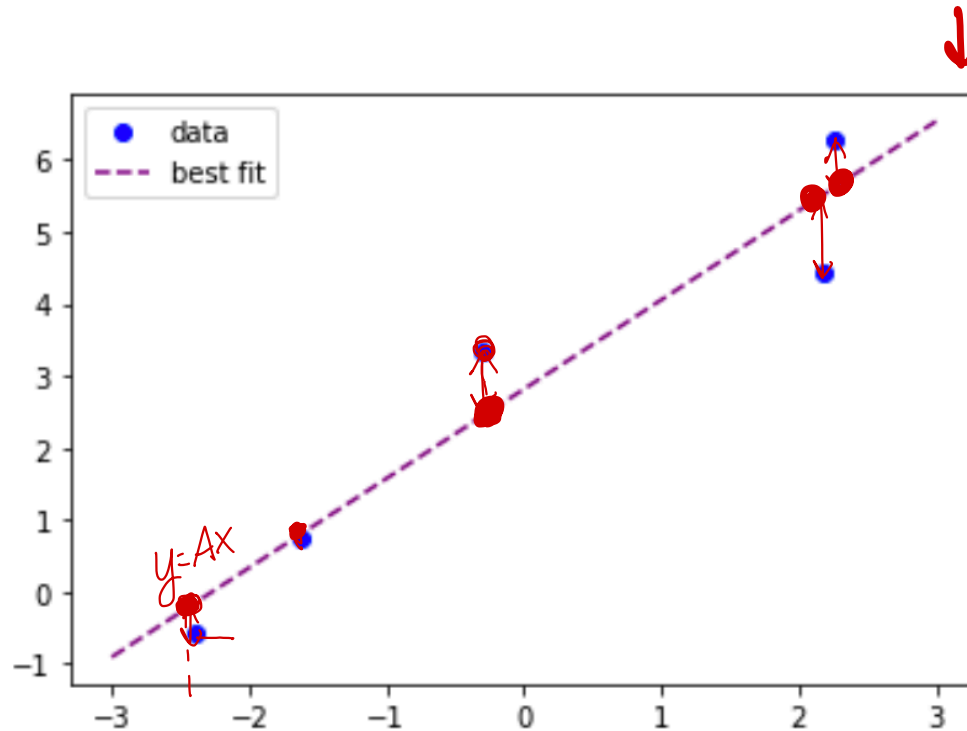
We want to find the appropriate linear combination of the columns of \mathbf{A} that makes up the vector \mathbf{b} .

If a solution exists that satisfies $\mathbf{A} \mathbf{x} = \mathbf{b}$ then $\mathbf{b} \in \text{range}(\mathbf{A})$



Linear Least Squares

- In most cases, $\mathbf{b} \notin \text{range}(\mathbf{A})$ and $\mathbf{A} \mathbf{x} = \mathbf{b}$ **does not have an exact solution!**



We want to
find \tilde{x} s.t
 $y = Ax$ better
approximates
 \tilde{b}

- Therefore, an overdetermined system is better expressed as

$$\mathbf{A} \mathbf{x} \cong \mathbf{b}$$

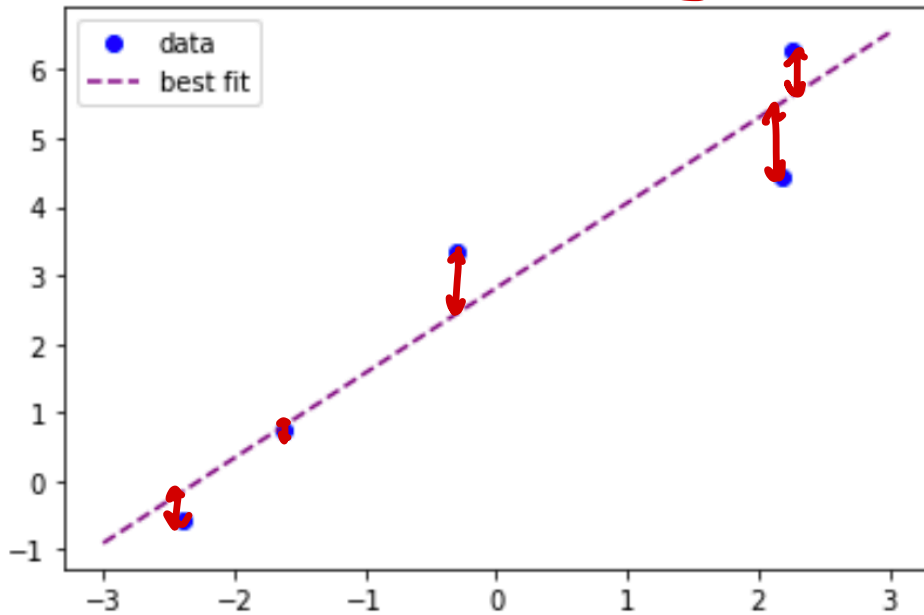
$$m > n$$

Linear Least Squares

$$\begin{pmatrix} A & x \end{pmatrix} = b$$

- Least Squares: find the solution x that minimizes the residual

\min $r = b - Ax = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_5 \end{bmatrix} = \begin{bmatrix} b_1 - y_1 \\ b_2 - y_2 \\ \vdots \\ b_5 - y_5 \end{bmatrix}$



r is a vector
 $\min \|r\|$

- Let's define the function ϕ as the square of the 2-norm of the residual

$\phi(x) = \|b - Ax\|_2^2$

Linear Least Squares

- **Least Squares:** find the solution \mathbf{x} that minimizes the residual

$$\mathbf{r} = \mathbf{b} - \mathbf{A}\mathbf{x}$$

- Let's define the function ϕ as the square of the 2-norm of the residual

$$\phi(\mathbf{x}) = \|\mathbf{b} - \mathbf{A}\mathbf{x}\|_2^2$$

- Then the least squares problem becomes

$$\min_{\mathbf{x}} \phi(\mathbf{x})$$

1d opt
1st order
2nd order

- Suppose $\phi: \mathcal{R}^m \rightarrow \mathcal{R}$ is a smooth function, then $\phi(\mathbf{x})$ reaches a (local) maximum or minimum at a point $\mathbf{x}^* \in \mathcal{R}^m$ only if

$$\nabla\phi(\mathbf{x}^*) = 0$$



How to find the minimizer?

- To minimize the 2-norm of the residual vector

stationary



→ 1st order necessary cond

$$\min_x \phi(x) = \|b - Ax\|_2^2 = (b - Ax)^T (b - Ax)$$

$$\begin{aligned} \nabla \phi &= -A^T(b - Ax) + (b - Ax)^T(-A) \\ &= -A^T b + A^T Ax - A^T b + A^T Ax \end{aligned}$$

$$= 2(A^T Ax - A^T b)$$

$$\nabla \phi = 0$$

$$\underbrace{\begin{pmatrix} A^T & A \end{pmatrix}}_{n \times m} \underbrace{x}_{m \times 1} = \underbrace{\begin{pmatrix} A^T \\ \end{pmatrix} b}_{n \times 1}$$

$n \times 1$

$$\underbrace{A^T A}_{\text{given}} x = \underbrace{A^T b}_{\text{given}}$$

Normal Equations

lin sys

$$\nabla(\nabla \phi) = ?$$

$$\underline{A}^T \underline{A} \underline{x} = \underline{A}^T \underline{b} \rightarrow \text{Normal equation}$$

\underline{x} : solution?

*if matrix A is full rank:

$$A = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}_{m \times n} \quad m > n \rightarrow \text{rank}(A) = n$$

$\text{rank}(A) = n \Rightarrow A$ has n L.I. columns

\Rightarrow has n singular values > 0

\Rightarrow has n eigenvalues > 0

$A^T A$ has n eigenvalues > 0
 $y^T A^T A y > 0$ for any $y \neq 0 \Rightarrow A^T A$ is positive def. & symmetric

$$\underline{x} = (\underline{A}^T \underline{A})^{-1} \underline{A}^T \underline{b} \Rightarrow \text{unique}$$

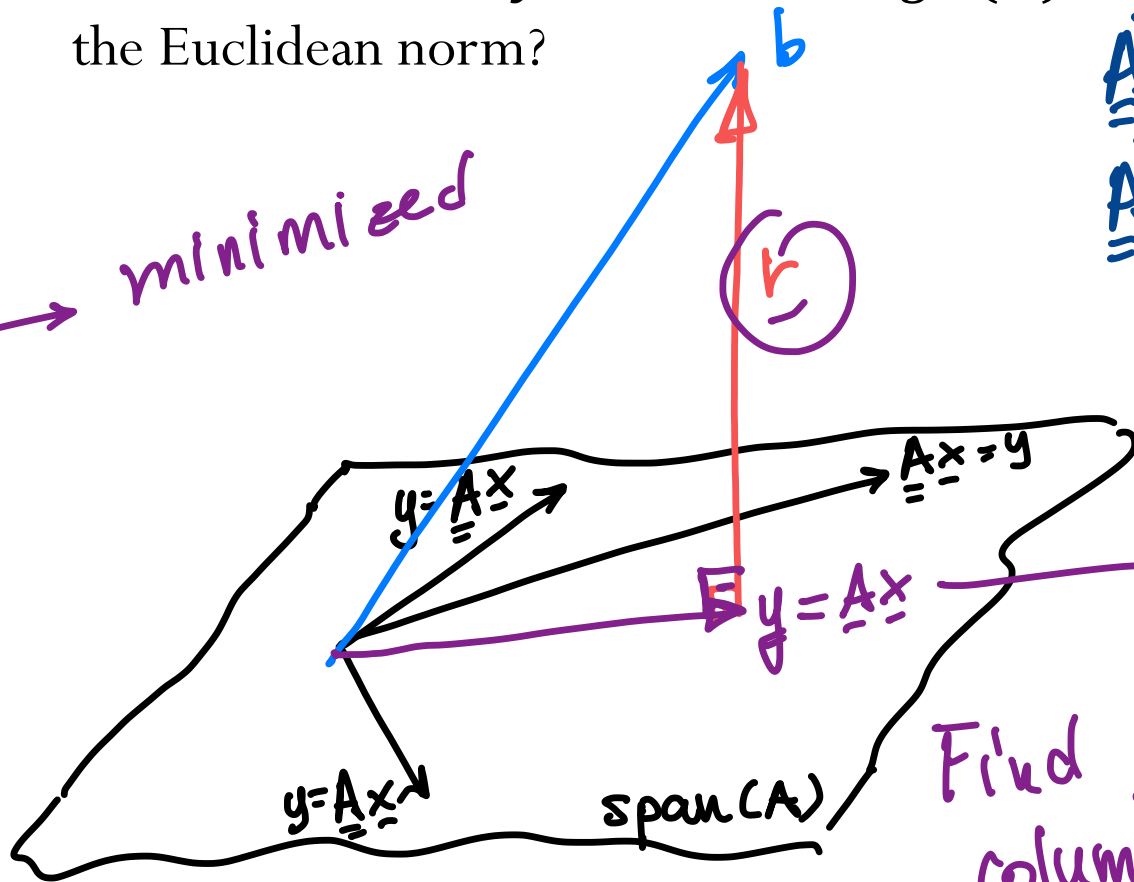
$\Rightarrow A^T A$ is invertible

$$\nabla \phi = 2(A^T A x - A^T b)$$
$$H = 2A^T A$$

x is minimizer

Linear Least Squares (another approach)

- Find $\mathbf{y} = \mathbf{A} \mathbf{x}$ which is closest to the vector \mathbf{b}
- What is the vector $\mathbf{y} = \mathbf{A} \mathbf{x} \in \text{range}(\mathbf{A})$ that is closest to vector \mathbf{y} in the Euclidean norm?



$$\begin{aligned} \underline{\underline{\mathbf{A}^T \mathbf{r}}} &= \underline{\underline{0}} \\ \underline{\underline{\mathbf{A}^T (\mathbf{b} - \mathbf{A} \mathbf{x})}} &= \underline{\underline{0}} \\ \underline{\underline{\mathbf{A}^T \mathbf{b} - \mathbf{A}^T \mathbf{A} \mathbf{x}}} &= \underline{\underline{0}} \\ \underline{\underline{\mathbf{A}^T \mathbf{A} \mathbf{x} = \mathbf{A}^T \mathbf{b}}} & \quad \checkmark \end{aligned}$$

projection of $\underline{\underline{\mathbf{b}}}$ in the column space of $\underline{\underline{\mathbf{A}}}$

Find $\underline{\underline{\mathbf{r}}}$ orthogonal to ALL columns of $\underline{\underline{\mathbf{A}}}$.

$$\Leftrightarrow \underline{\underline{\mathbf{A}^T \mathbf{r}}} = \underline{\underline{0}}$$

Summary:

- A is a $(m \times n)$ matrix, where $m > n$.
- m is the number of data pair points. n is the number of parameters of the “best fit” function.
- Linear Least Squares problem $A x \cong b$ *always* has solution.
- The Linear Least Squares solution x minimizes the square of the 2-norm of the residual:

$$\min_x \|b - Ax\|_2^2$$

- One method to solve the minimization problem is to solve the system of Normal Equations

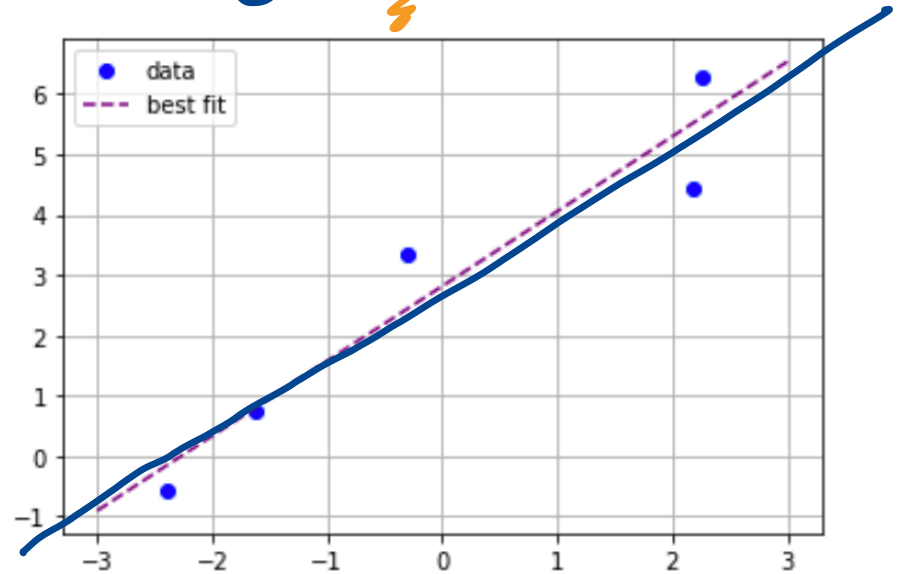
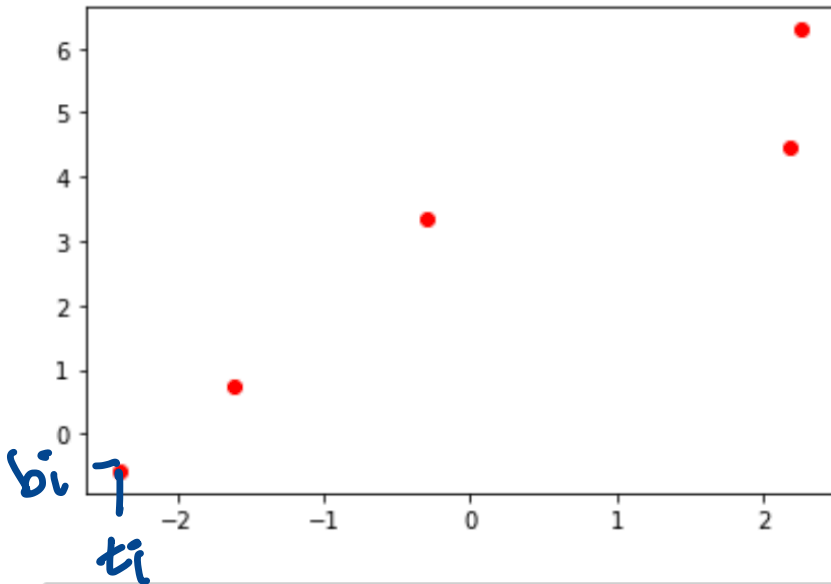
$$A^T A x = A^T b$$

→ x is unique
matrix is full
rank

- Let's see some examples and discuss the limitations of this method.

Example:

$$y = x_0 + x_1 t$$



t

array([-1.61477467, -2.3970584, -0.30372944, 2.26304537, 2.188127])

b

array([0.74112251, -0.57768693, 3.33523017, 6.29377547, 4.44786481])

Solve: $A^T A x = A^T b$

x

$x = \text{lsolve}(A^T A, A^T b)$

5×2

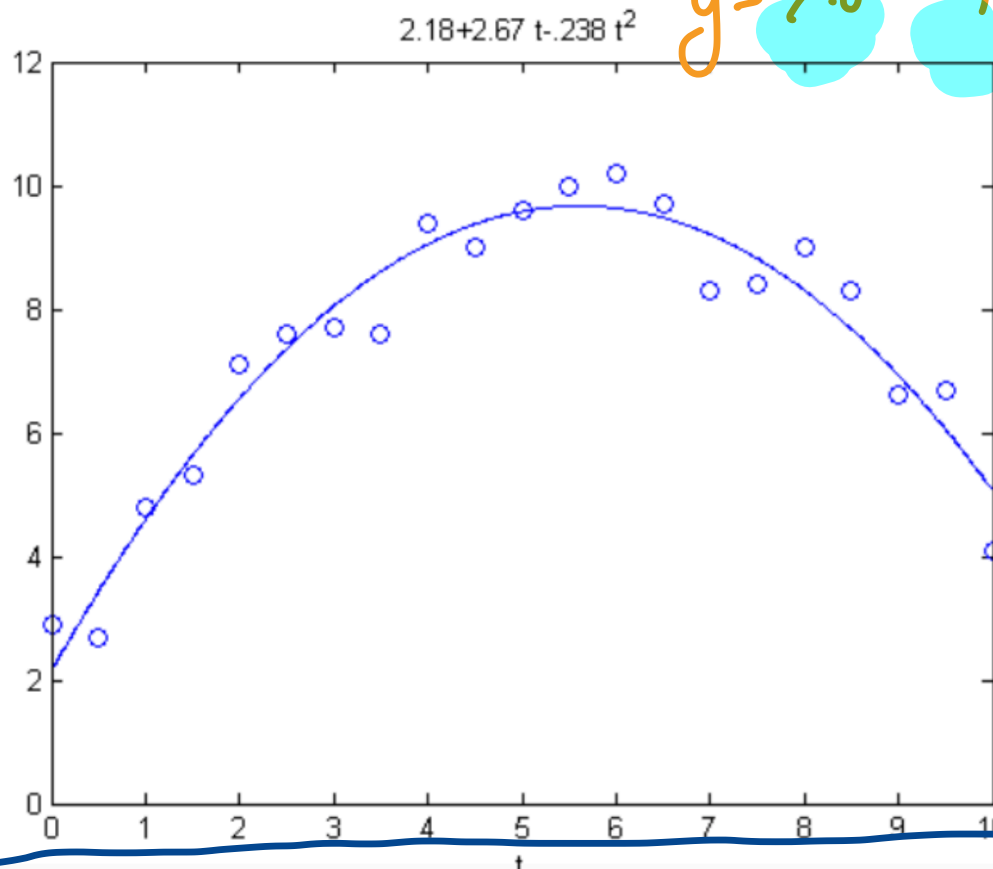
$$A = \begin{bmatrix} 1 & t_1 \\ 1 & t_2 \\ \vdots & \vdots \\ 1 & t_5 \end{bmatrix}$$

$$b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_5 \end{bmatrix}$$

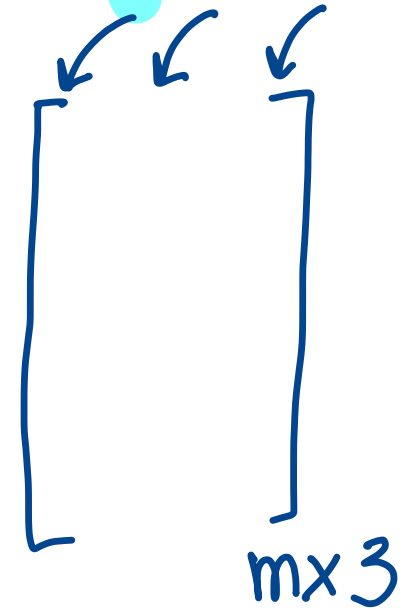
array([2.81441707, 1.24048133])

Data fitting - not always a line fit!

- Does not need to be a line! For example, here we are fitting the data using a quadratic curve.



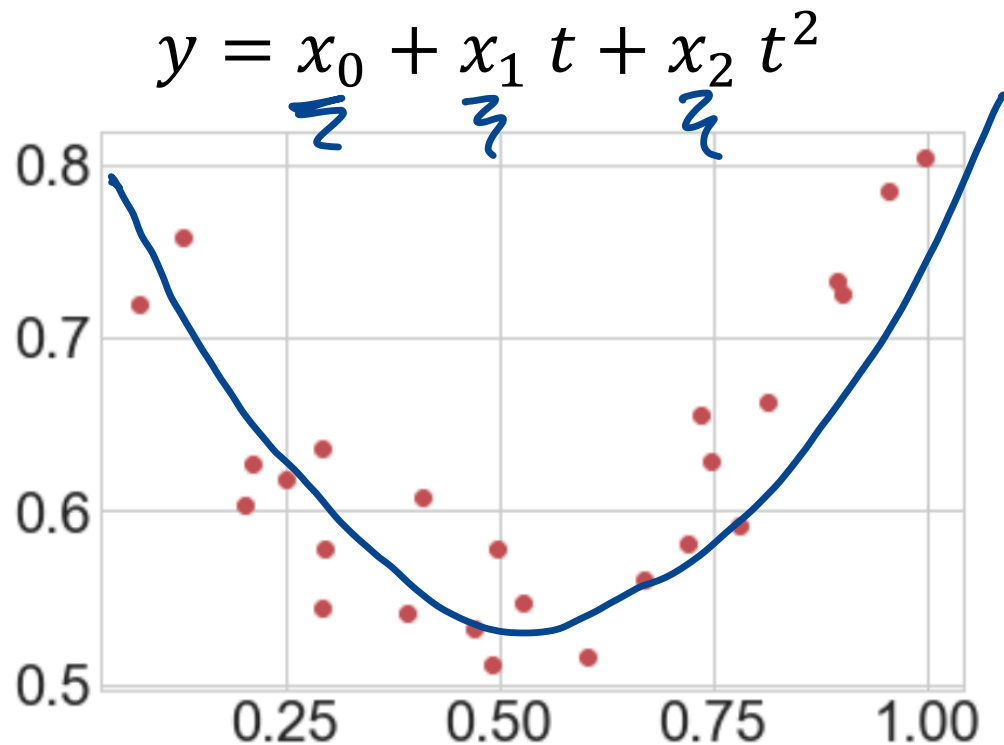
$$y = x_0 + x_1 t + x_2 t^2$$



Linear Least Squares: The problem is **linear in its coefficients!**

Another example

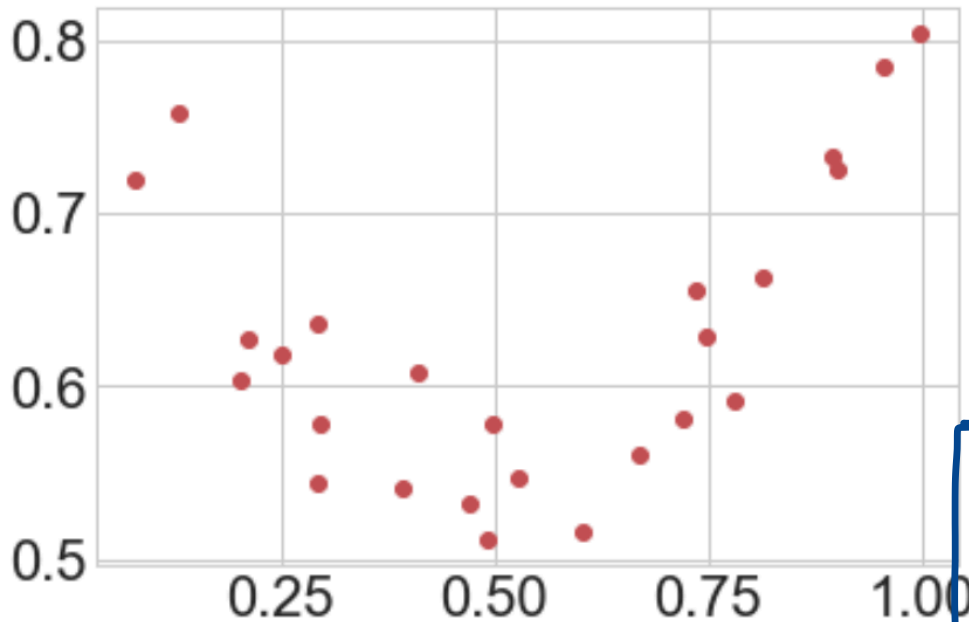
We want to find the coefficients of the quadratic function that best fits the data points:



We would not want our “fit” curve to pass through the data points exactly as we are looking to model the general trend and not capture the noise.

Data fitting

$$y = x_0 + x_1 t + x_2 t^2$$



$m \times 1$

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

$$= \begin{bmatrix} 1 & t_1 & t_1^2 \\ 1 & t_2 & t_2^2 \\ \vdots & \vdots & \vdots \\ 1 & t_m & t_m^2 \end{bmatrix}$$

$$\stackrel{\text{A}}{=} \begin{bmatrix} t_1^2 \\ t_2^2 \\ t_3^2 \\ \vdots \\ t_m^2 \end{bmatrix}$$

$$\begin{bmatrix} x_0 \\ x_1 \\ x_2 \end{bmatrix}$$

3x1
(1x1)

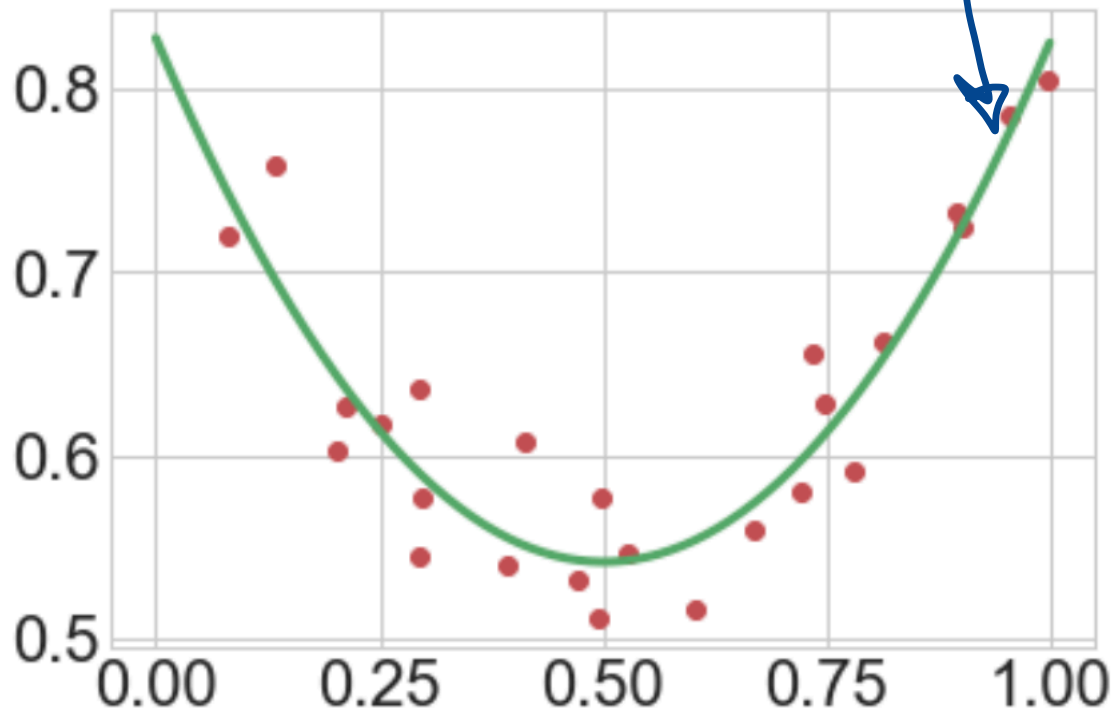
$$\begin{aligned} y_1 &= x_0 + x_1 t_1 + x_2 t_1^2 \\ y_2 &= x_0 + x_1 t_2 + x_2 t_2^2 \\ &\vdots \\ y_m &= x_0 + x_1 t_m + x_2 t_m^2 \end{aligned}$$

Data fitting

$$\begin{bmatrix} 1 & t_1 & t_1^2 \\ \vdots & \vdots & \vdots \\ 1 & t_m & t_m^2 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$$

$$\underline{\underline{A}} \underline{\underline{b}} \rightarrow \underline{\underline{A}} \underline{\underline{x}} \approx \underline{\underline{b}}$$

Solve: $\mathbf{A}^T \mathbf{A} \mathbf{x} = \mathbf{A}^T \mathbf{b}$



Which function is not suitable for linear least squares?

A) $y = a + bx + cx^2 + dx^3$

B) $y = x(a + bx + cx^2 + dx^3)$

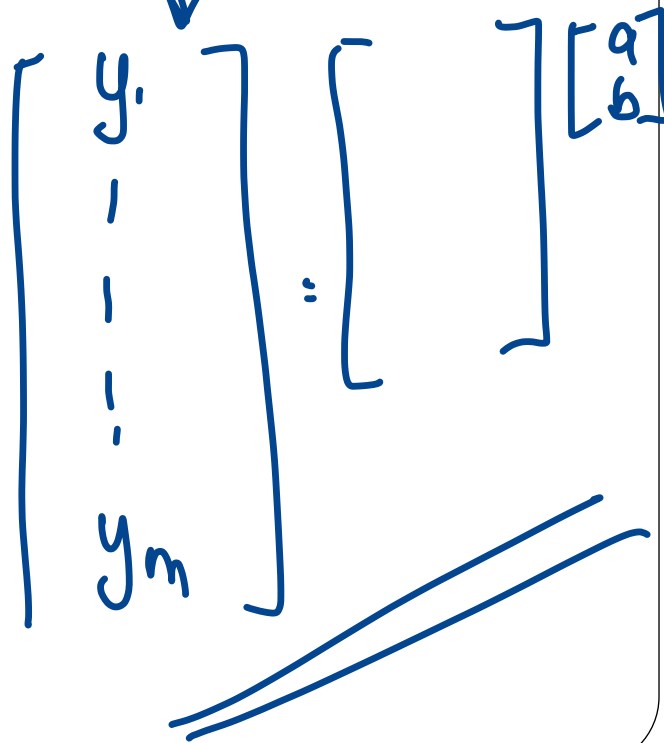
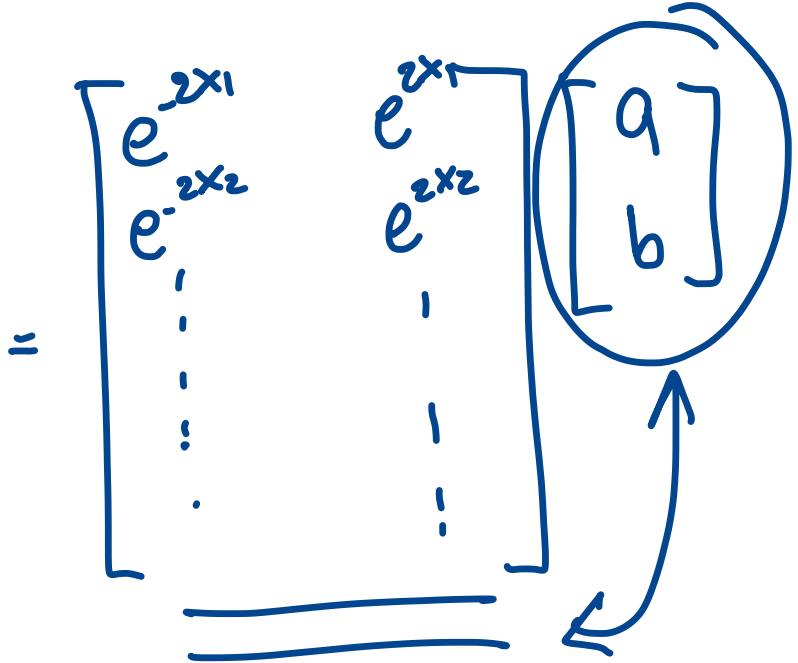
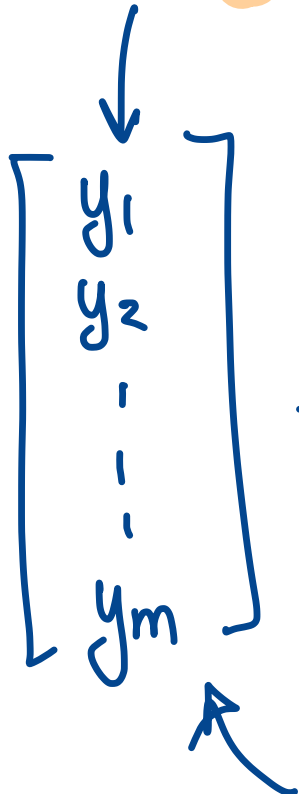
C) $y = a \sin(x) + b / \cos(x)$

D) $y = a \sin(x) + x / \cos(bx)$

E) $y = a e^{-2x} + b e^{2x}$

$y = x_0 + x_1 t$
 $y = x_0 + x_1 t + x_2 t^2$

$Ax = b$



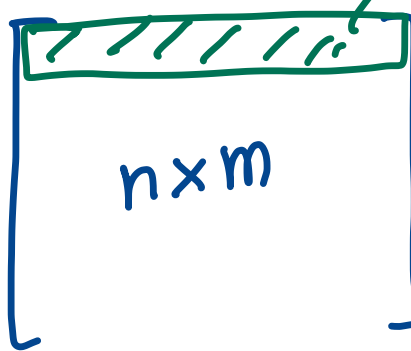
Computational Cost

$$A^T A x = A^T b$$

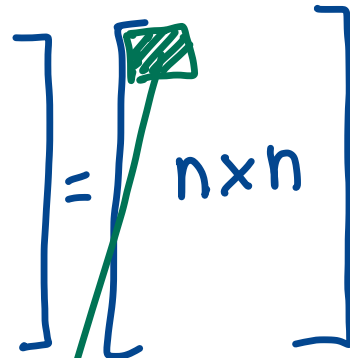
$A_{m \times n}$

inner product
 $O(m)$

① Construct $A^T A \Rightarrow$



$m \times n$



② Factorize

$A^T A$
 $n \times n$

$\Rightarrow O(n^3)$

③ Solve

$\Rightarrow O(n^2)$

overall cost: $O(mn^2)$ ($m \geq n$)

$O(m)$

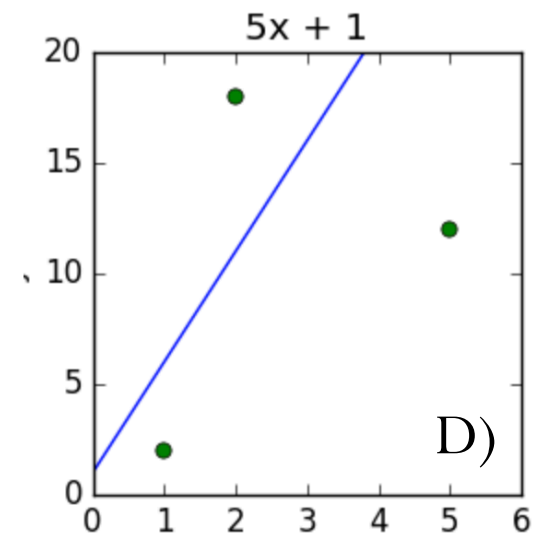
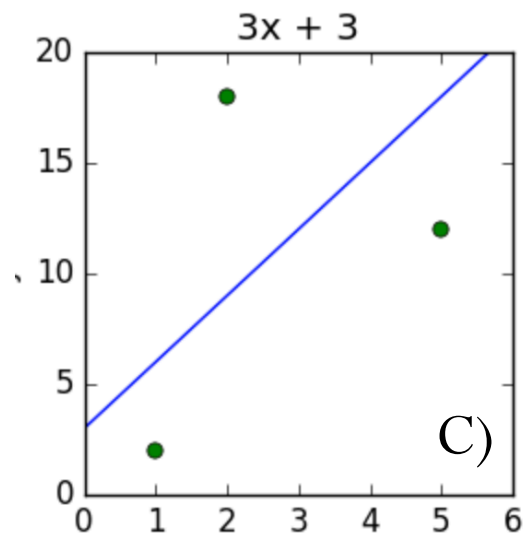
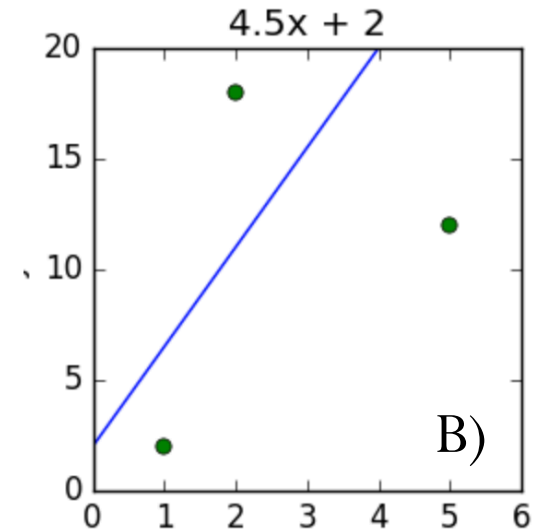
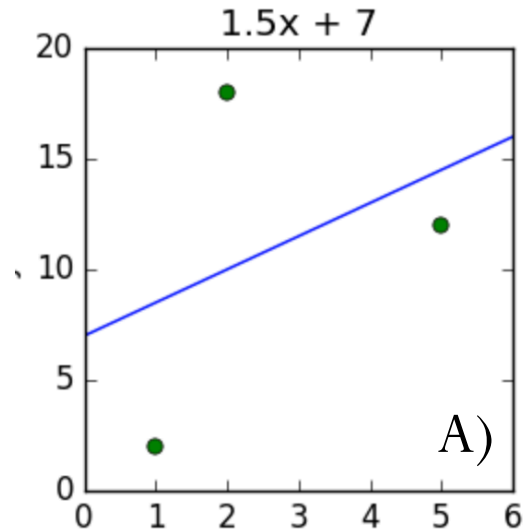
n^2 times

$O(mn^2)$

Short questions

Given the data in the table below, which of the plots shows the line of best fit in terms of least squares?

x	1	2	5
y	2	18	12



Short questions

Given the data in the table below, and the least squares model

$$y = c_1 + c_2 \sin(t\pi) + c_3 \sin(t\pi/2) + c_4 \sin(t\pi/4)$$

written in matrix form as

$$A \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{bmatrix} \cong \mathbf{y}$$

determine the entry A_{23} of the matrix \mathbf{A} .

Note that indices start with 1.

- A) -1.0
- B) 1.0
- C) -0.7
- D) 0.7
- E) 0.0

t_i	y_i
0.5	0.72
1.0	0.79
1.5	0.72
2.0	0.97
2.5	1.03
3.0	0.96
3.5	1.00