Nonlinear Equations

## How can we solve these equations?

- Spring force:
$F=k x$

What is the displacement when $F=2 \mathrm{~N}$ ?

$F=k x$

$$
x=\frac{F}{k}=\frac{2 \mathrm{~N}}{40 \mathrm{~N} / \mathrm{m}}=0.05 \mathrm{~m}
$$

$x^{\sim}=0.05 \mathrm{~m}$

## How can we solve these equations?

- Drag force:
$F=0.5{\underset{\Xi}{d}}_{C_{d}} \rho A v^{2}=\mu_{d} v^{2}$
What is the velocity when $F=20 \mathrm{~N}$ ?


$$
\begin{aligned}
& F=\mu v^{2} \Rightarrow \underbrace{F-\mu v^{2}}_{f(v)=0}=0 \\
& f(v)=\mu_{d} v^{2}-F=0
\end{aligned}
$$

Find the root (zero) of the nonlinear equation $f(v)$


## Nonlinear Equations in 1D

Goal: Solve $f(x)=0$ for $f \mathcal{R} \rightarrow \mathcal{R}$

$$
f(\sigma)=0
$$

root of $f$ Often called Root Finding


* Define interval that

Bisection method


Bisection method

$$
\begin{aligned}
& t_{0}=|b-a|=10 \\
& t_{1}=\frac{|b-a|}{2}=\frac{t_{0}}{2} \\
& t_{2}=\frac{t_{1}}{2}=\frac{t_{0}}{2.2} \\
& t_{3}=\frac{t_{2}}{2}=\frac{t_{0}}{8}
\end{aligned}
$$

$$
t_{k}=\frac{t_{0}}{2^{k}}
$$

$t_{0}=10$

* every iteration, the interval is divided by 2 !


## Convergence

An iterative method converges with rate $r$ if:

$$
\lim _{k \rightarrow \infty} \frac{\left\|e_{k+1}\right\|}{\left\|e_{k}\right\|^{r}}=C, \quad 0<C<\infty \quad r=1 \text { : linear convergence }
$$

Linear convergence gains a constant number of accurate digits each step (and $C<1$ matters!)

For example: Power Iteration

$$
\begin{aligned}
& \lim _{k \rightarrow \infty} \frac{\|\left(e_{k+1} \|\right.}{\left\|e_{k}\right\|^{r=1}}=\left|\frac{\lambda_{2}}{\lambda_{l}}\right|=\text { constant }=\frac{c}{4} \Longrightarrow \text { linear convergnce } \\
& \forall \lambda_{2} \sim \lambda_{1} \rightarrow \text { constant } \approx 1 \longrightarrow \text { slow convergence } \\
& \lambda_{1}=\alpha \lambda_{2} \longrightarrow c=\frac{1}{\alpha} \longrightarrow \text { faster convergence as } \\
& \alpha \text { increases }
\end{aligned}
$$

## Convergence

An iterative method converges with rate $r$ if:
$\lim _{k \rightarrow \infty} \frac{\left\|e_{k+1}\right\|}{\left\|e_{k}\right\|^{r}}=C, \quad 0<C<\infty$
$r=1$ : linear convergence
$r>1$ : superlinear convergence $1<r<2$
$r=2$ : quadratic convergence

Linear convergence gains a constant number of accurate digits each step (and $C<1$ matters!)

Quadratic convergence doubles the number of accurate digits in each step (however it only starts making sense once $\left\|e_{k}\right\|$ is small (and $C$ does not matter much)

Convergence $x^{*}$ is the root

- The bisection method does not estimate $x_{k}$, the approximation of the desired root $x$. It instead finds an interval smaller than a given
$f(x)$ tolerance that contains the root.

$$
\begin{aligned}
& 1 \quad t_{k}<\text { tola } \longrightarrow \text { stop } \\
& \frac{\text { (to }}{2^{k} R}<\text { col } \\
& \text { error }=t_{k} \\
& \frac{x\left|e_{k+1}\right|}{\left|e_{k}\right|^{r}}=\frac{|b-a| / 2^{k+1}}{|b-a| / 2^{k}}=\frac{1}{2}=c \\
& r=1 \\
& C=\frac{1}{2} \Rightarrow \text { linear } \\
& \text { convergence! }
\end{aligned}
$$

in general: $t_{k}<$ bol
Example:
Consider the nonlinear equation

$$
f(x)=0.5 x^{2}-2{\frac{2}{k} \operatorname{cog}_{2}\left(\frac{|b-a|}{b-1}\right)}^{\left.k>\log ^{k}\right)}
$$

and solving $f(x)=0$ using the Bisection Method. For each of the initial intervals below, how many iterations are required to ensure the root is

$$
\begin{aligned}
& \text { accurate within } 2^{-4} \text { ? } \\
& \text { A) } \begin{array}{l}
f(a) \quad f(b) \\
{[-10,-1.8]}
\end{array} \\
& f(a) . f(b)<0 \rightarrow 0 k! \\
& \int k_{1}>\log _{2}\left(\frac{8.2}{2^{-4}}\right) \cong 7.3 \\
& \text { ( } 8 \text { iterations) } \\
& \begin{array}{l}
\text { BR } 1 \geq 3, \geq \geq 2] f(a) \cdot f(b) \geq 0 \rightarrow \text { not or! } \int()_{k}>\log _{2}\left(\frac{5.9}{2^{-4}}\right) \approx 6.56 \\
\text { C) }[-4,1.9] f(a) . f(b)<0 \rightarrow \text { ok! iterations) }
\end{array}
\end{aligned}
$$

## Bisection method


$f(a), f(b), f(m)$ new fec evaluation


Algorithm:

1. Take two points, $a$ and $b$, on each side of the root such that $f(a)$ and $f(b)$ have opposite signs.
2. Calculate the midpoint $m=\frac{a+b}{2}$
3. Evaluate $f(m)$ and use $m$ to replace either $a$ or $b$, keeping the signs of the endpoints opposite.

## Bisection Method - summary

$\square$ The function must be continuous with a root in the interval $[a, b]$
$\square$ Requires only one function evaluations for each iteration!

- The first iteration requires two function evaluations.
$\square$ Given the initial internal $[a, b]$, the length of the interval after $k$ iterations is $\frac{b-a}{2^{k}}$
$\square$ Has linear convergence

Newton's method

- Recall we want to solve $f(x)=0$ for $f: \mathcal{R} \rightarrow \mathcal{R}$
- The Taylor expansion: $\downarrow$ nonlinear linear approximation of $f(x)$
gives a linear approximation for the nonlinear function $f$ near $x_{k}$.



Example

$$
\begin{aligned}
& x_{1}=? \\
& x_{0}=0
\end{aligned}
$$

Consider solving the nonlinear equation

$$
5=2.0 e^{x}+x^{2}
$$

$$
\Rightarrow \Rightarrow f(x)=2 e^{x}+x^{2}-5=0
$$

What is the result of applying one iteration of Newton's method for solving nonlinear equations with initial starting guess $x_{0}=0$, i.e. what is $x_{1}$ ?
A) -2

$$
x_{k+1}=x_{k}+h \quad h=-\frac{f\left(x_{k}\right)}{f^{\prime}\left(x_{k}\right)}
$$

B) 0.75
C) -1.5

$$
f^{\prime}(x)=2 e^{x}+2 x
$$

D) 1.5
E) 3.0

$$
\begin{array}{cc}
x_{0} \Rightarrow f\left(x_{0}\right)=2-5=-3 \\
f^{\prime}\left(x_{0}\right)=2 \\
x_{1}=x_{0}+h=0+1.5 & \Rightarrow \frac{-f}{f^{\prime}}=\frac{-(-3)}{2} \\
h=1.5
\end{array}
$$

## Newton's Method - summary

Must be started with initial guess close enough to root (convergence is only local). Otherwise it may not converge at all.
$\square$ Requires function and first derivative evaluation at each iteration (think about two function evaluations)
$\square$ Typically has quadraticenvence

$$
\lim _{k \rightarrow \infty}\left(\frac{\left\|e_{k+1}\right\|}{\left\|e_{k}\right\|^{2}}=C, \quad \begin{array}{r} 
\\
r=2
\end{array}\right.
$$

$\square$ What can we do when the derivative evaluation is too costly (or difficult to evaluate)?

Secant method $\quad d f \Rightarrow$ approximation for $f^{\prime}(x)$
Also derived from Taylor expansion, but instead of using $f^{\prime}\left(x_{k}\right)$, it approximates the tangent with the secant line:

$$
\begin{aligned}
& \text { approximates the tangent with the secant line: } \\
& x_{k+1}=x_{k}-f\left(x_{k}\right) / \frac{f^{\prime}\left(x_{k}\right)}{5} \longrightarrow x_{k+1}=x_{k}-\frac{f\left(x_{k}\right)}{d f\left(x_{k}\right)}
\end{aligned}
$$



## Secant Method - summary

Still local convergence
$\square$ Requires only one function evaluation per iteration (only the first iteration requires two function evaluations)
$\square$ Needs two starting guesses
$\square$ Has slower convergence than Newton's Method - superlinear convergence

$$
\lim _{k \rightarrow \infty} \frac{\left\|e_{k+1}\right\|}{\left\|e_{k}\right\|^{r}}=C, \quad 1<r<2, ~(f)
$$

## 1D methods for root finding:

| Method | Update | Convergence | Cost |
| :--- | :--- | :--- | :--- |
| Bisection | Check signs of $f(a)$ and <br> $f(b)$ | Linear $(r=1$ and $\mathrm{c}=0.5)$ | One function evaluation per <br> iteration, no need to <br> compute derivatives |
| Secant | $x_{k+1}=x_{k}+h$ <br> $h=-f\left(x_{k}\right) / f^{\prime}\left(x_{k}\right)$ | Superlinear $(r=1.618)$, <br> local convergence properties, <br> convergence depends on the <br> initial guess | One function evaluation per <br> iteration (two evaluations for <br> the initial guesses only), no <br> need to compute derivatives |
| Newton | $x_{k+1}=x_{k}+h$ | Quadratic $(r=2)$, local <br> convergence properties, <br> convergence depends on the <br> initial guess | Two function evaluations per <br> iteration, requires first order <br> derivatives |
| $h=-f\left(x_{k}\right) / d f a$ |  |  |  |
| $d f a=\frac{f\left(x_{k}\right)-f\left(x_{k-1}\right)}{\left(x_{k}-x_{k-1}\right)}$ |  |  |  |

