

Classical Synchronization Problems



[This lecture]

- Goals

- Introduce classical synchronization problems

- Topics

- Producer-Consumer Problem
- Reader-Writer Problem
- Dining Philosophers Problem
- Sleeping Barber's Problem



[Producer-consumer problem]



- Chefs cook items and put them on a conveyer belt



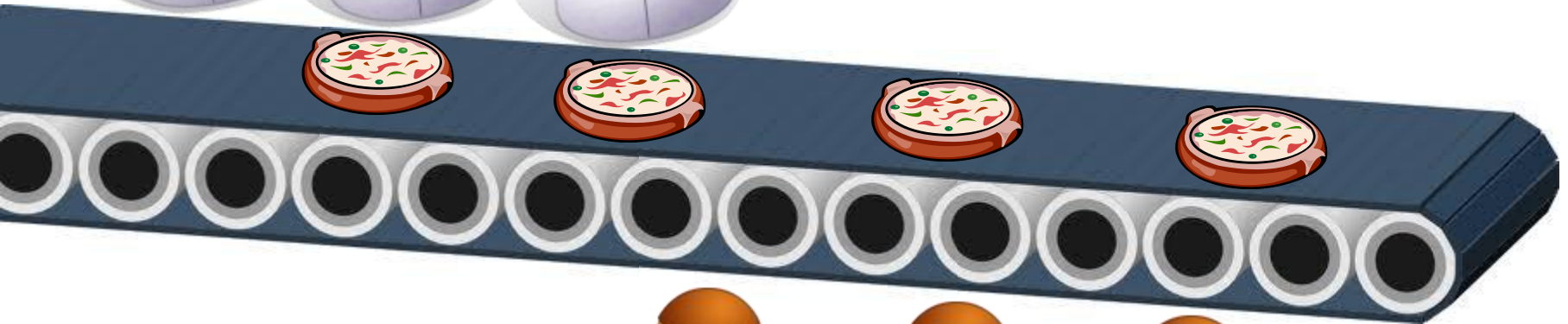
- Waiters pick items off the belt



Producer-consumer problem



- Now imagine many chefs!



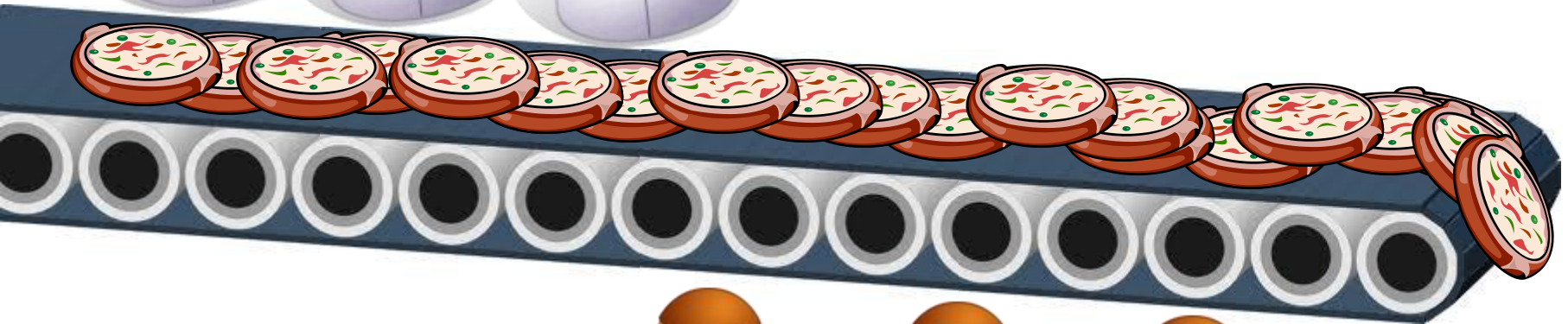
- And many waiters!



Producer-consumer problem



- A potential mess!



[Producer-Consumer Problem]

Chef (Producer)



inserts items

Waiter (Consumer)



removes items

Shared resource:
bounded buffer

Efficient implementation:
circular fixed-size buffer

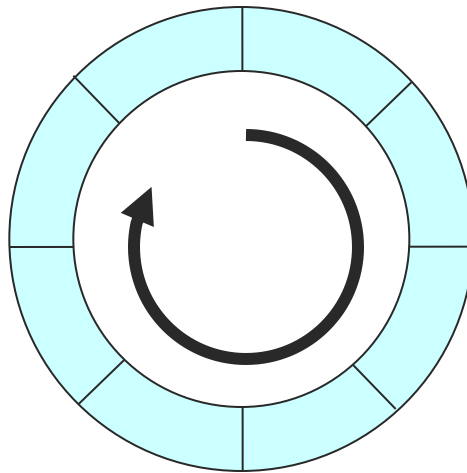


[Producer-Consumer]



Chef
Waiter

= Producer
= Consumer

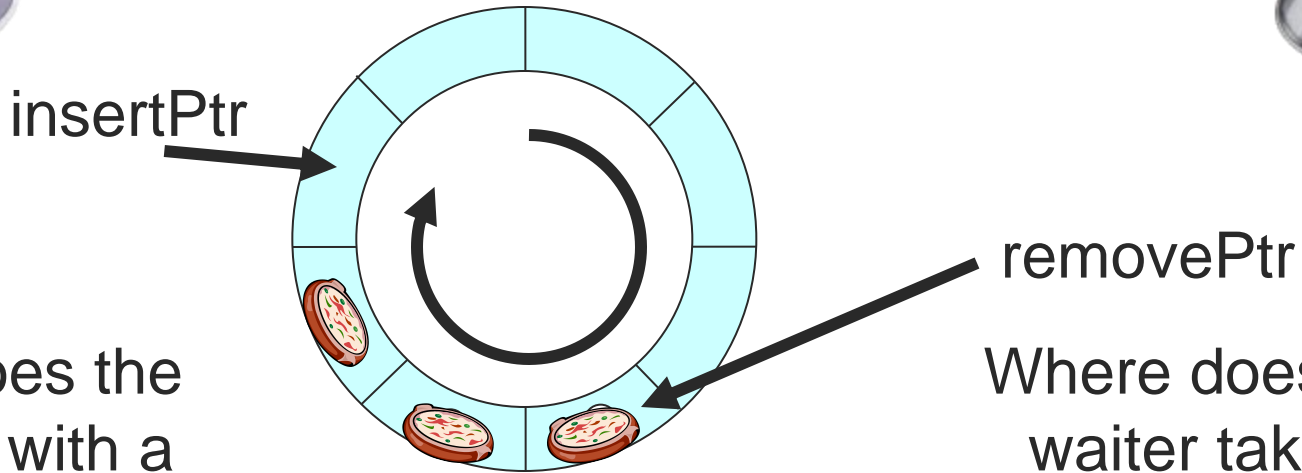


Producer-Consumer



Chef
Waiter

= Producer
= Consumer



What does the chef do with a new pizza?



Where does the waiter take a pizza from?

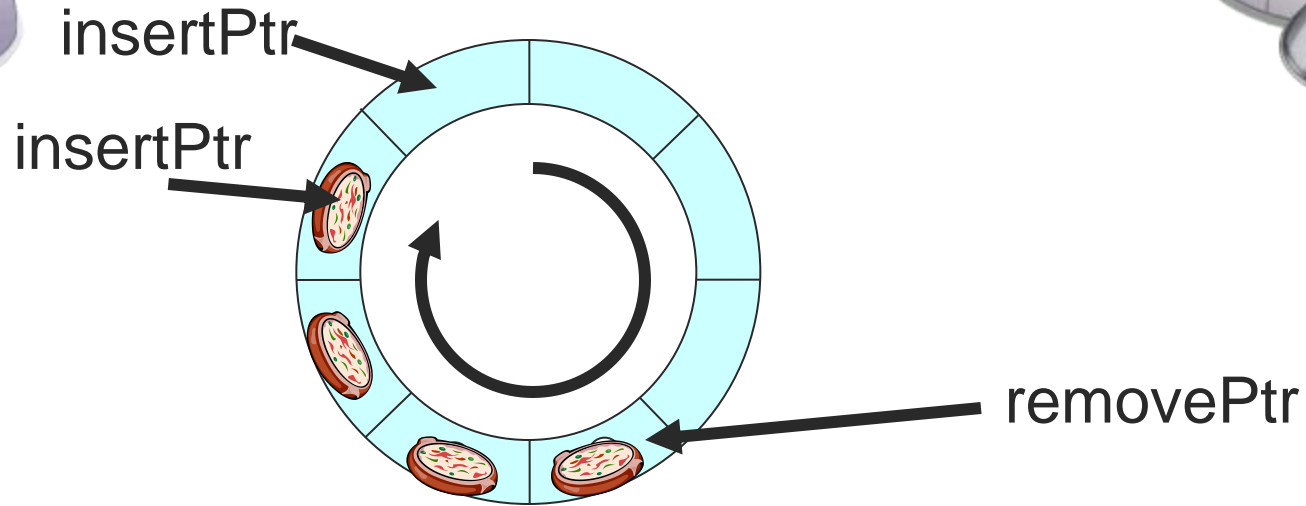


Producer-Consumer



Chef
Waiter

= Producer
= Consumer



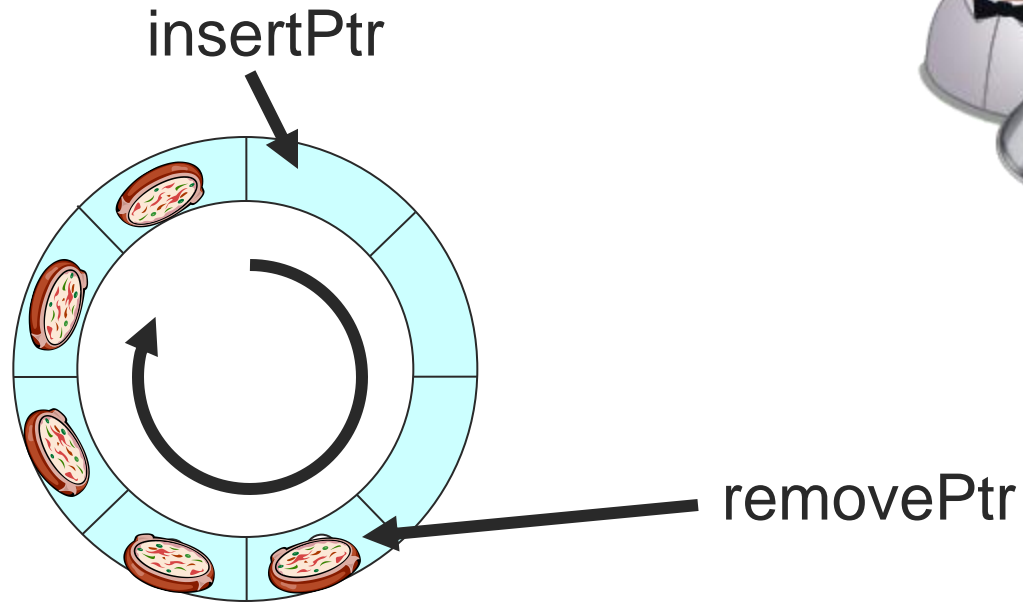
Insert pizza



[Producer-Consumer]



Chef = Producer
Waiter = Consumer



Insert pizza

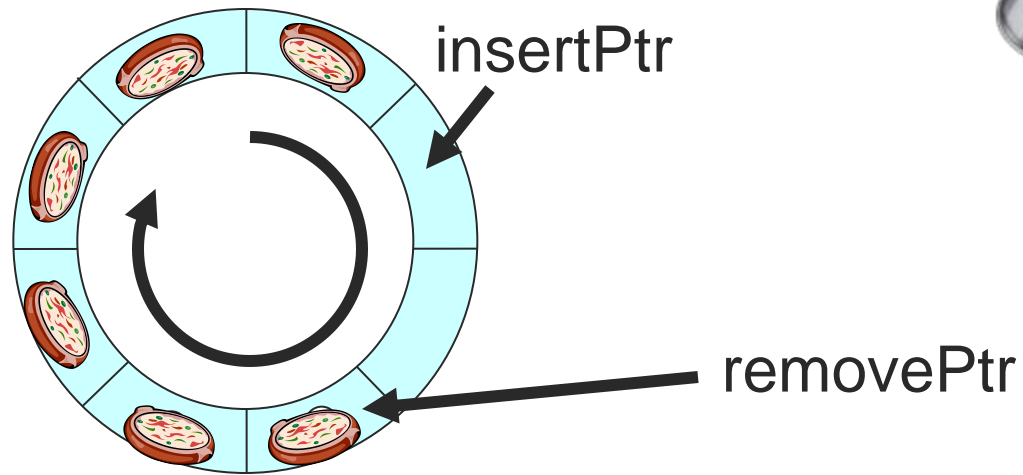


[Producer-Consumer]



Chef
Waiter

= Producer
= Consumer



Insert pizza

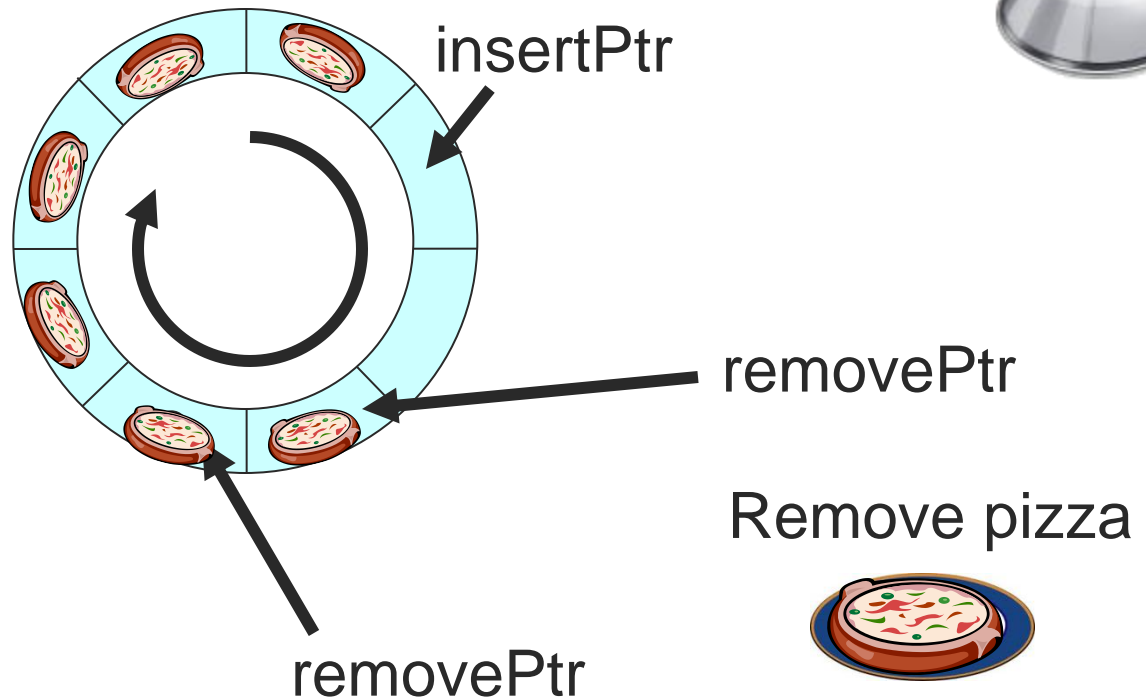


[Producer-Consumer]



Chef
Waiter

= Producer
= Consumer

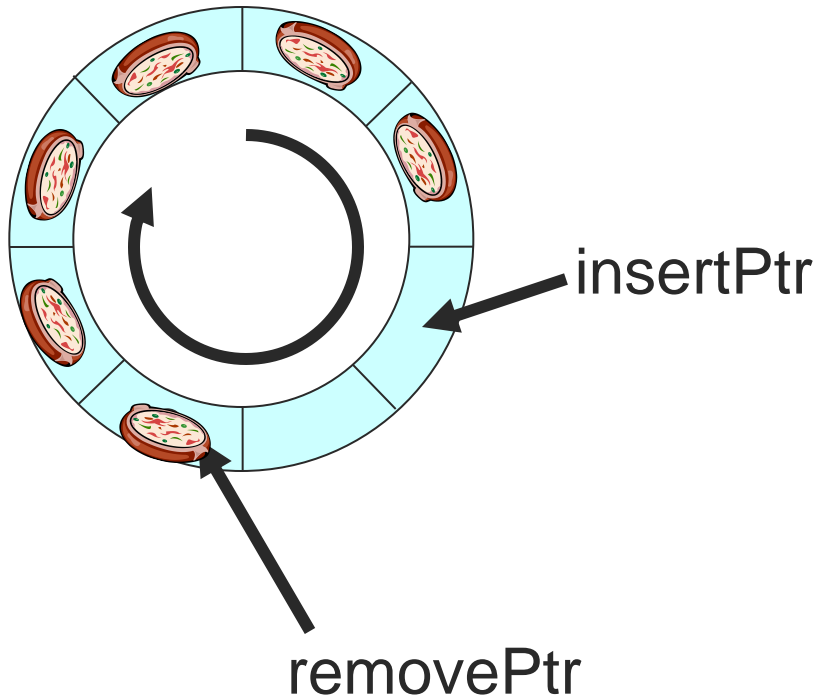


[Producer-Consumer]



Chef
Waiter

= Producer
= Consumer



Insert pizza

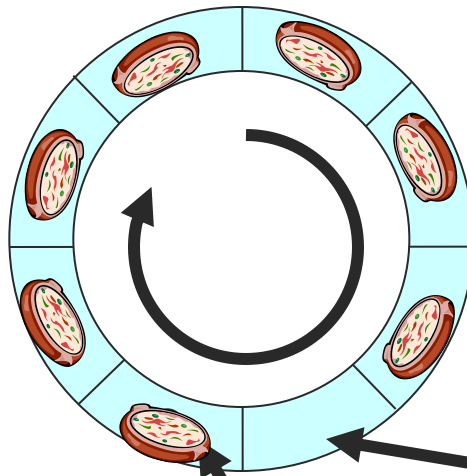


[Producer-Consumer]



Chef
Waiter

= Producer
= Consumer



Insert pizza



insertPtr

removePtr



[Producer-Consumer]

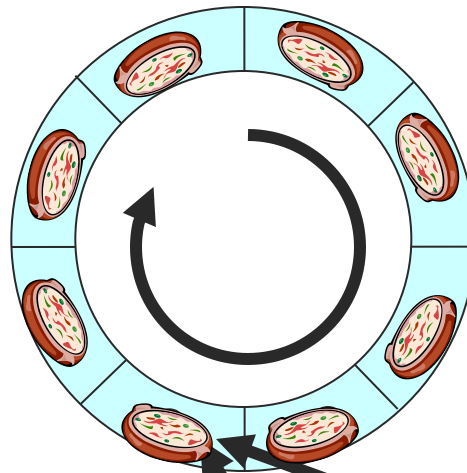


Chef
Waiter

= Producer
= Consumer



BUFFER FULL:
Producer must be
blocked!



Insert pizza



insertPtr
removePtr

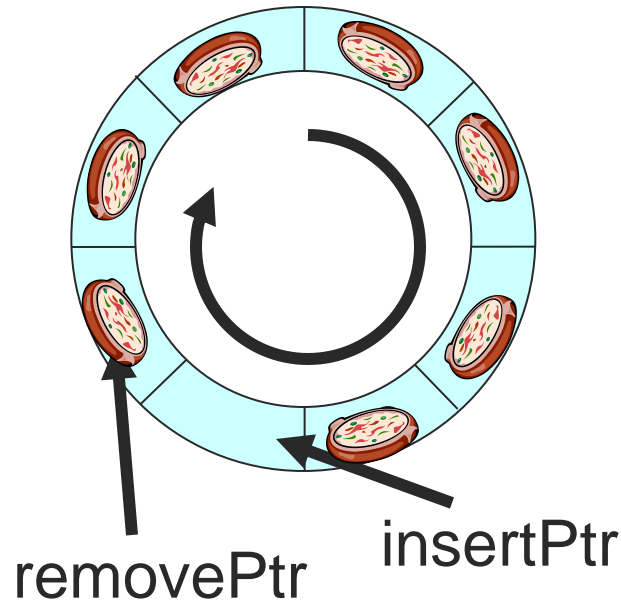


[Producer-Consumer]



Chef
Waiter

= Producer
= Consumer



Remove pizza

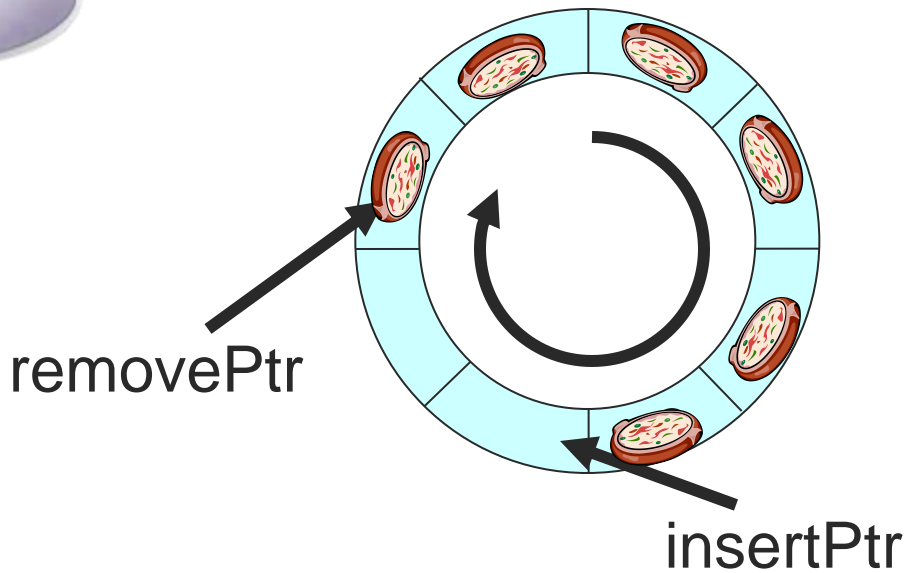


Producer-Consumer



Chef
Waiter

= Producer
= Consumer



Remove pizza



Producer-Consumer

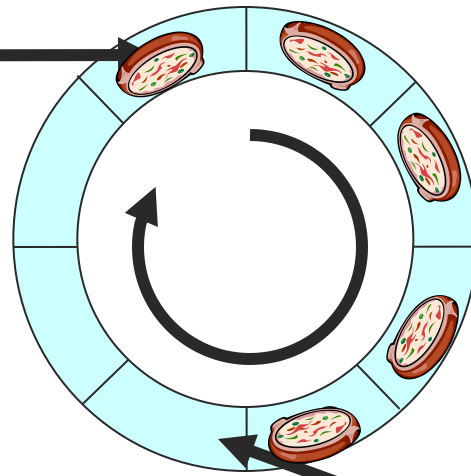


Chef
Waiter

= Producer
= Consumer



removePtr



insertPtr

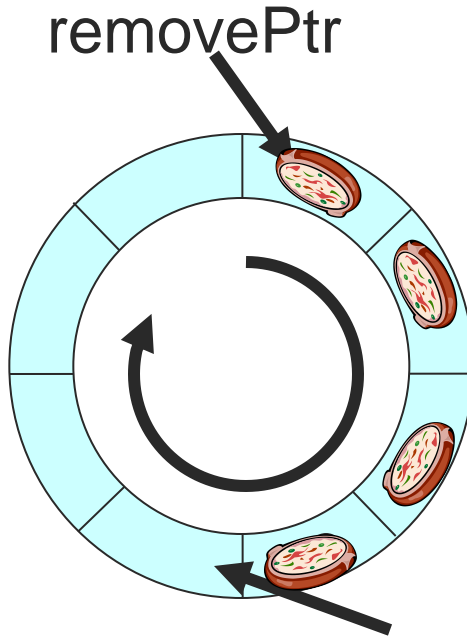
Remove pizza



[Producer-Consumer]



Chef = Producer
Waiter = Consumer



insertPtr

Remove pizza

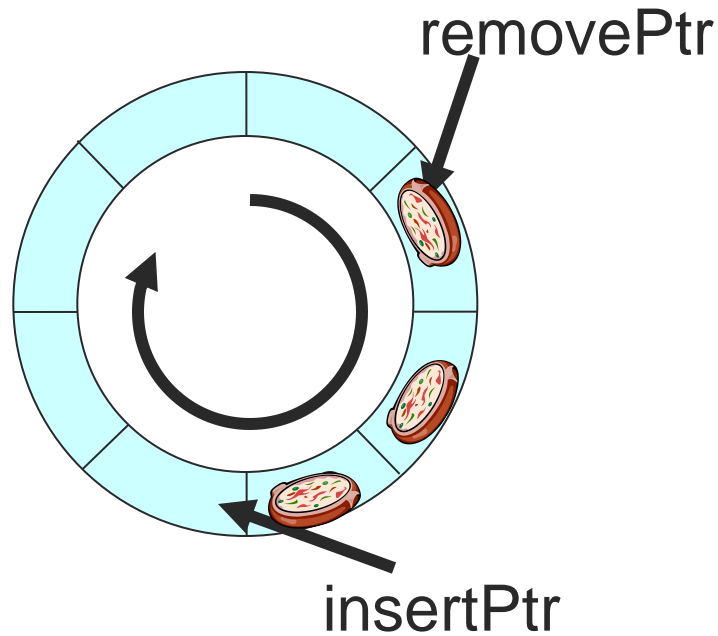


[Producer-Consumer]



Chef
Waiter

= Producer
= Consumer



Remove pizza

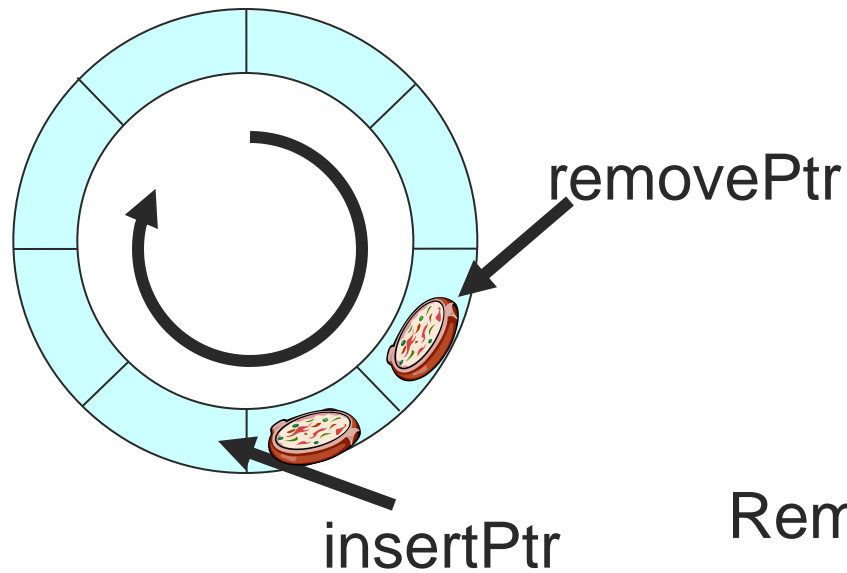


[Producer-Consumer]



Chef
Waiter

= Producer
= Consumer



Remove pizza

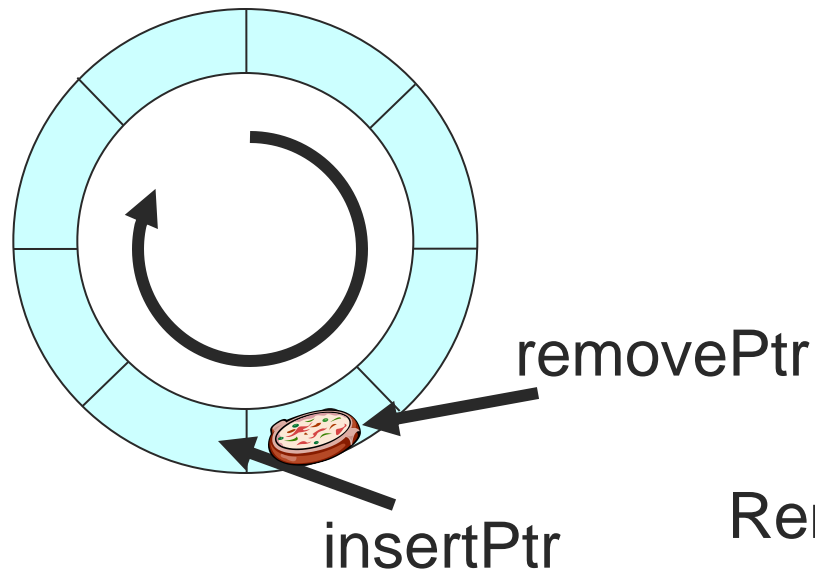


[Producer-Consumer]



Chef
Waiter

= Producer
= Consumer



Remove pizza



[Producer-Consumer]

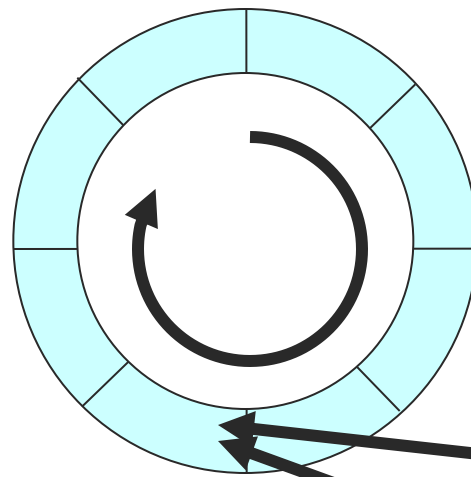


Chef
Waiter

= Producer
= Consumer



BUFFER EMPTY:
Consumer must be
blocked!



removePtr
Remove pizza
insertPtr



Producer-Consumer Summary

- **Producer**
 - Insert items
 - Update insertion pointer
- **Consumer**
 - Execute destructive read on the buffer
 - Update removal pointer
- **Both**
 - Update information about how full/empty the buffer is
- **Solution**
 - Must allow multiple producers and consumers



[Designing a solution]

Chef (Producer)



Wait for empty slot
Insert item
Signal item arrival

Waiter (Consumer)



Wait for item arrival
Remove item
Signal empty slot available

What synchronization do we need?



[Challenges]

- Prevent buffer overflow
- Prevent buffer underflow
- Mutual exclusion when modifying the buffer data structure



Assembling the solution

- Producer
 - `sem_wait(slots), sem_signal(slots)`
 - Initialize semaphore `slots` to `N`
- Consumer
 - `sem_wait(items), sem_signal(items)`
 - Initialize semaphore `items` to `0`
- Synchronization
 - `mutex_lock(m), mutex_unlock(m)`
- Buffer management
 - `insertptr = insertptr+1`
 - `removalptr = removalptr+1`



Assembling the solution

- Producer
 - `sem_wait(slots)`, `sem_signal(slots)`
 - Initialize semaphore `slots` to `N`
- Consumer
 - `sem_wait(items)`, `sem_signal(items)`
 - Initialize semaphore `items` to `0`
- Synchronization
 - `mutex_lock(m)`, `mutex_unlock(m)`
- Buffer management
 - `insertptr = (insertptr+1) % N`
 - `removalptr = (removalptr+1) % N`





[Producer-Consumer Code



Critical Section: move insert pointer

```
buffer[ insertPtr ] =  
    data;  
insertPtr = (insertPtr  
    + 1) % N;
```



Critical Section: move remove pointer

```
result =  
    buffer[removePtr];  
removePtr = (removePtr  
    +1) % N;
```



[Producer-Consumer Code]



Counting semaphore – check and decrement the number of free slots



```
sem_wait(slots);  
mutex_lock(mutex);  
buffer[insertPtr] =  
    data;  
insertPtr = (insertPtr  
    + 1) % N;  
mutex_unlock(mutex);
```

Block if there are no free slots



```
sem_signal(items);
```

Done – increment the number of available items



Counting semaphore – check and decrement the number of available items

```
sem_wait(items);  
mutex_lock(mutex);  
result =  
    buffer[removePtr];  
removePtr = (removePtr  
    + 1) % N;  
mutex_unlock(mutex);  
sem_signal(slots);
```



Block if there are no items to take



Done – increment the number of free slots



Consumer Pseudocode:

getItem()

```
sem_wait(items);  
mutex_lock(mutex);  
result = buffer[removePtr];  
removePtr = (removePtr + 1) % N;  
mutex_unlock(mutex);  
sem_signal(slots);
```

Error checking/EINTR handling not shown



Producer Pseudocode:

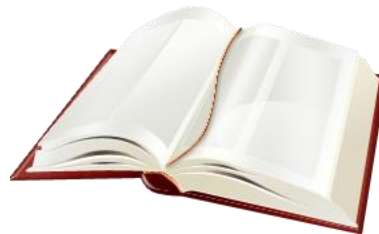
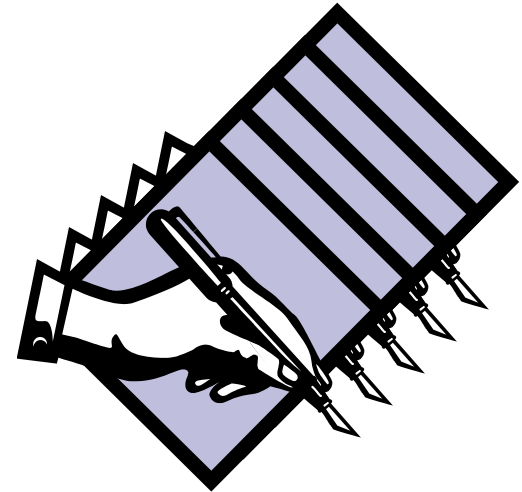
`putItem (data)`

```
sem_wait(slots);  
mutex_lock(mutex);  
buffer[ insertPtr ] = data;  
insertPtr = (insertPtr + 1) % N;  
mutex_unlock(mutex);  
sem_signal(items);
```

Error checking/EINTR handling not shown

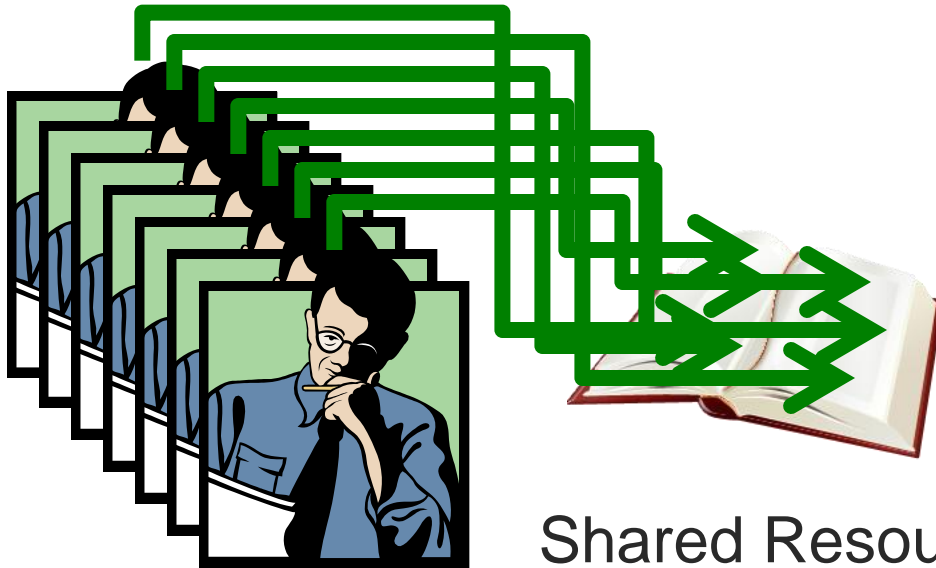


[Readers-Writers Problem]



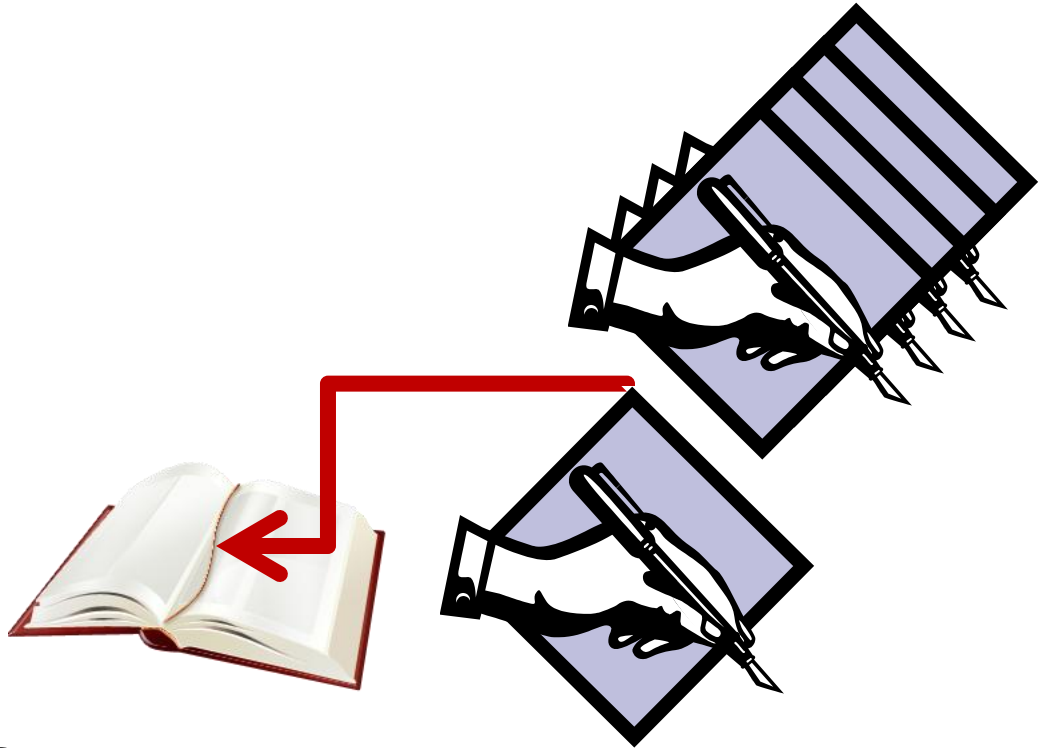
Shared Resource

Readers-Writers Problem



Shared Resource

[Readers-Writers Problem]



Shared Resource

Reader-Writer Problem

- Readers read data
- Writers write data
- Rules
 - **Multiple readers** may read the data simultaneously
 - **Only one writer** can write the data at any time
 - A reader and a writer cannot access data simultaneously
- Locking table
 - Whether any two can be in the critical section simultaneously

	Reader	Writer
Reader	OK	No
Writer	No	No



Reader-Writer: First Solution

```
reader() {
    while(TRUE) {
        <other stuff>;
        sem_wait(mutex);
        readCount++;

        if(readCount == 1)
            sem_wait(writeBlock);
        sem_signal(mutex);

        /* Critical section */
        access(resource);

        sem_wait(mutex);
        readCount--;
        if(readCount == 0)
            sem_signal(writeBlock);
        sem_post(mutex);
    }
}
```

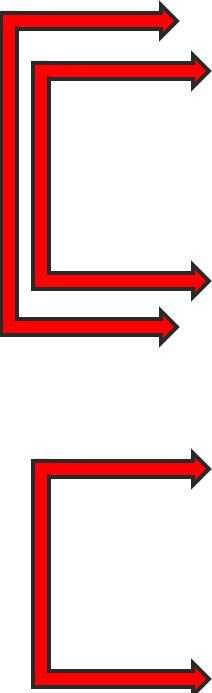
```
int readCount = 0;
semaphore mutex = 1;
semaphore writeBlock = 1;
```

```
writer() {
    while(TRUE) {
        <other computing>;
        sem_wait(writeBlock);
        /* Critical section */
        access(resource);
        sem_signal(writeBlock);
    }
}
```

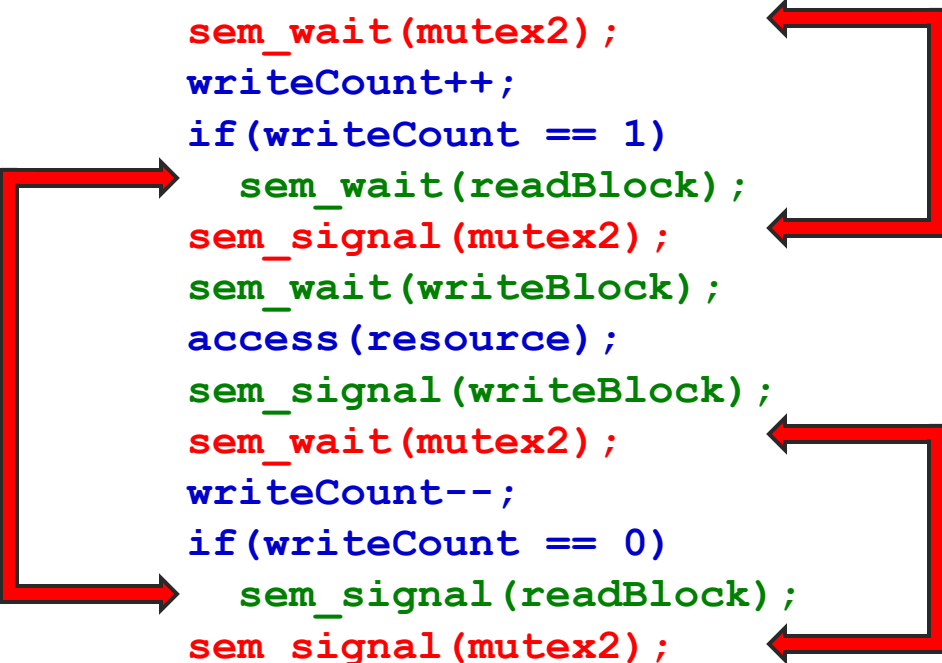


Reader-Writer: Second Solution

```
reader() {  
    while(TRUE) {  
        <other computing>;  
        sem_wait(readBlock);  
        sem_wait(mutex1);  
        readCount++;  
        if(readCount == 1)  
            sem_wait(writeBlock);  
        sem_signal(mutex1);  
        sem_signal(readBlock);  
  
        access(resource);  
        sem_wait(mutex1);  
        readCount--;  
        if(readCount == 0)  
            sem_signal(writeBlock);  
        sem_signal(mutex1);  
    }  
}
```



```
int readCount=0, writeCount=0;  
semaphore mutex1=1, mutex2=1;  
Semaphore readBlock=1,writeBlock=1  
  
writer() {  
    while(TRUE) {  
        <other computing>;  
        sem_wait(mutex2);  
        writeCount++;  
        if(writeCount == 1)  
            sem_wait(readBlock);  
        sem_signal(mutex2);  
        sem_wait(writeBlock);  
        access(resource);  
        sem_signal(writeBlock);  
        sem_wait(mutex2);  
        writeCount--;  
        if(writeCount == 0)  
            sem_signal(readBlock);  
        sem_signal(mutex2);  
    }  
}
```



Better R-W solution idea

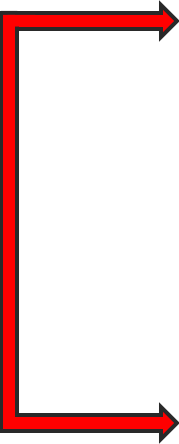
- Idea: serve requests in order
 - Once a writer requests access, any entering readers have to block until the writer is done
- Advantage?
- Disadvantage?



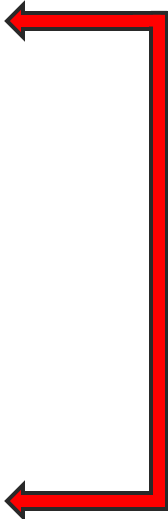
Reader-Writer: Fairer Solution?

```
int readCount = 0, writeCount = 0;
semaphore mutex1 = 1, mutex2 = 1;
semaphore readBlock = 1, writeBlock = 1, writePending = 1;
```

```
reader() {
    while(TRUE) {
        <other computing>;
        sem_wait(writePending);
        sem_wait(readBlock);
        sem_wait(mutex1);
        readCount++;
        if(readCount == 1)
            sem_wait(writeBlock);
        sem_signal(mutex1);
        sem_signal(readBlock);
        sem_signal(writePending);
        access(resource);
        sem_wait(mutex1);
        readCount--;
        if(readCount == 0)
            sem_signal(writeBlock);
        sem_signal(mutex1);
    }
}
```



```
writer() {
    while(TRUE) {
        <other computing>;
        sem_wait(writePending);
        sem_wait(mutex2);
        writeCount++;
        if(writeCount == 1)
            sem_wait(readBlock);
        sem_signal(mutex2);
        sem_wait(writeBlock);
        access(resource);
        sem_signal(writeBlock);
        sem_signal(writePending);
        sem_wait(mutex2);
        writeCount--;
        if(writeCount == 0)
            sem_signal(readBlock);
        sem_signal(mutex2);
    }
}
```



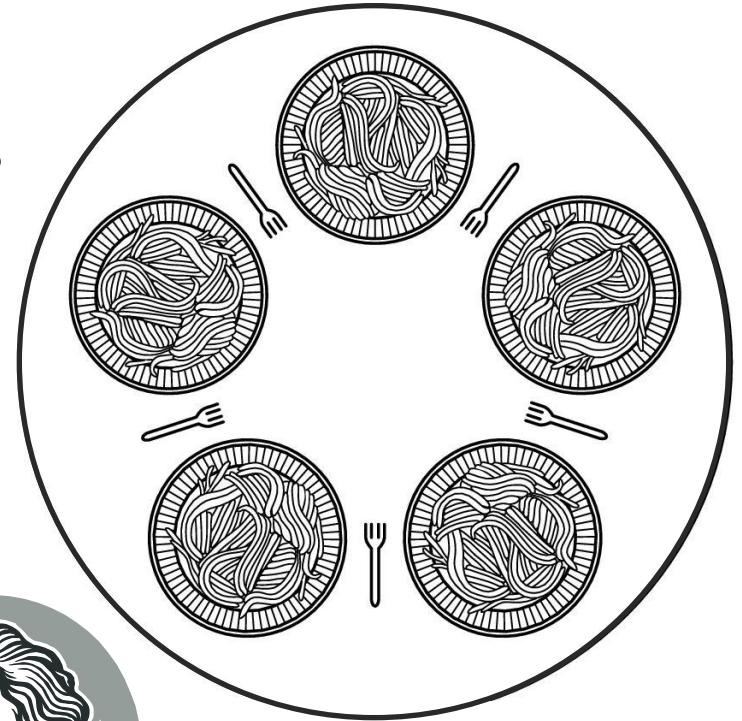
[Summary]

- Classic synchronization problems
 - Producer-Consumer Problem
 - Reader-Writer Problem
- Saved for next time:
 - Sleeping Barber's Problem
 - Dining Philosophers Problem



Dining Philosophers

- N philosophers and N forks
 - Philosophers eat/think
 - Eating needs 2 forks
 - Pick one fork at a time



Descartes Aristotle Deocrates Thoreau Raine