# CS 225

#### **Data Structures**

#### February 23 – BBST Range Search G Carl Evans

#### **Range-based Searches**

Balanced BSTs are useful structures for range-based and nearest-neighbor searches.

**Q:** Consider points in 1D:  $\mathbf{p} = {\mathbf{p}_1, \mathbf{p}_2, ..., \mathbf{p}_n}$ . ...what points fall in [11, 42]?



# **Range-based Searches**

**Q:** Consider points in 1D:  $p = \{p_1, p_2, ..., p_n\}$ . ...what points fall in [11, 42]?



#### Red-Black Trees in C++

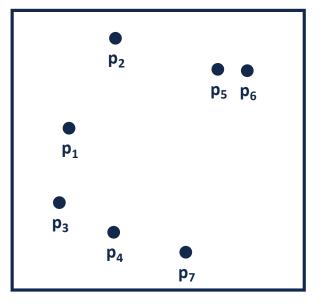
iterator std::map<K, V>::lower\_bound( const K & ); iterator std::map<K, V>::upper\_bound( const K & );

#### **Range-based Searches**

Consider points in 2D:  $p = \{p_1, p_2, ..., p_n\}$ .

Q: What points are in the rectangle: [ (x<sub>1</sub>, y<sub>1</sub>), (x<sub>2</sub>, y<sub>2</sub>) ]?

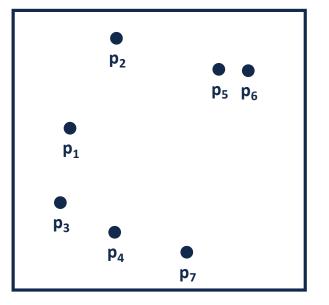
**Q:** What is the nearest point to  $(x_1, y_1)$ ?



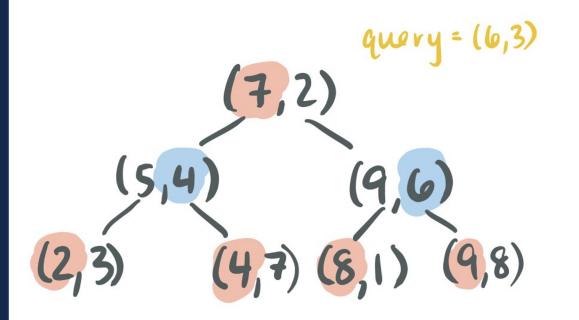
# **Range-based Searches**

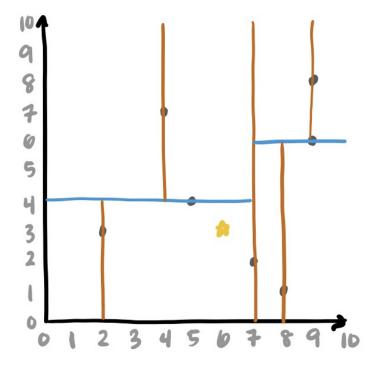
Consider points in 2D:  $\mathbf{p} = \{\mathbf{p}_1, \mathbf{p}_2, ..., \mathbf{p}_n\}$ .

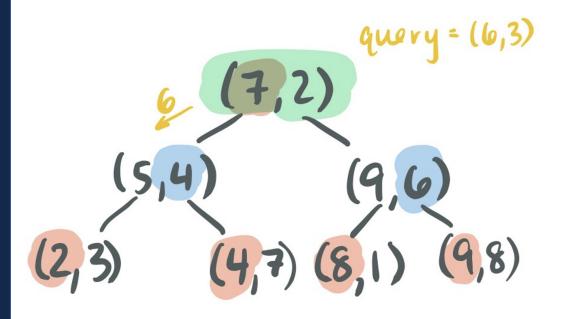
**Tree construction:** 

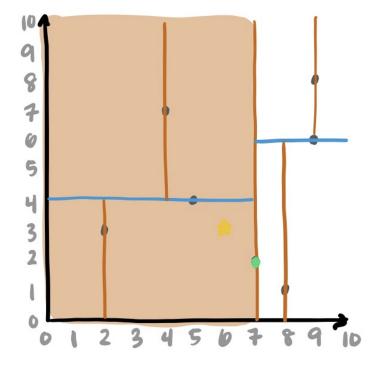


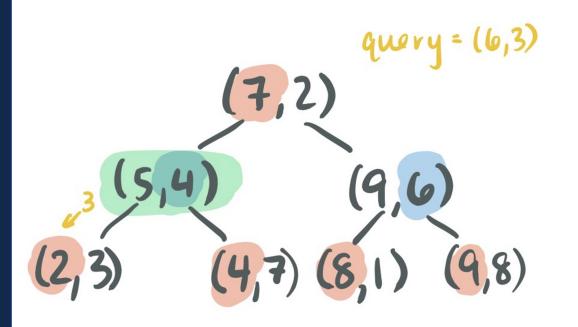
# Nearest Neighbor – k-d Tree

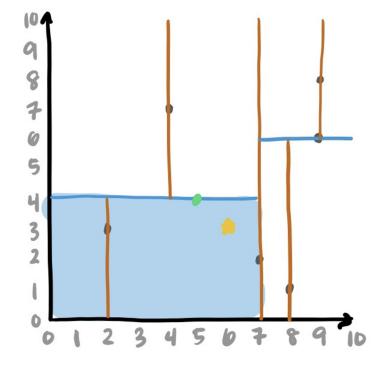


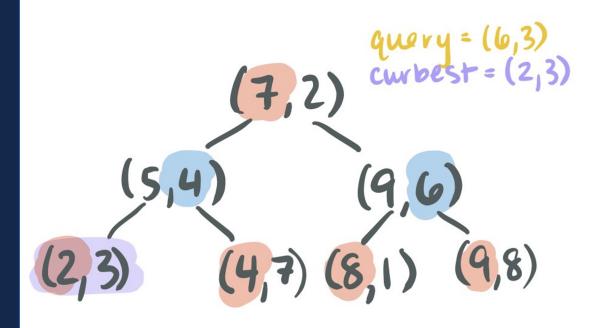


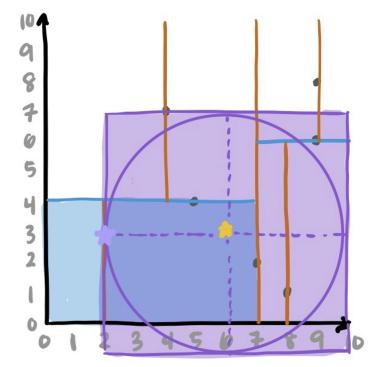




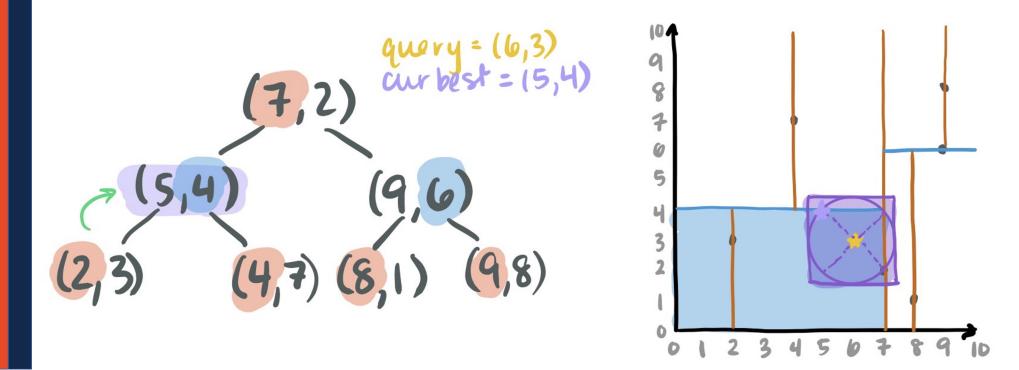


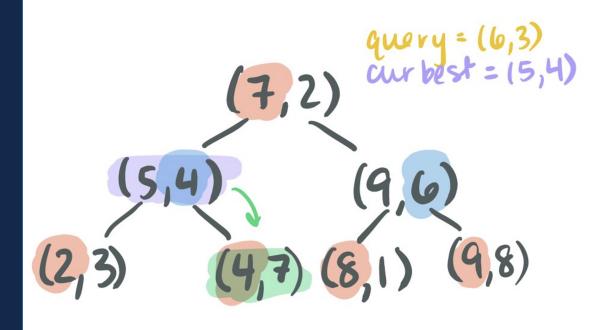


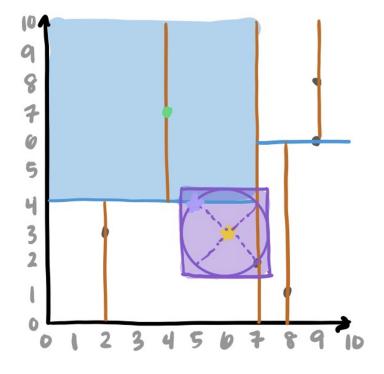




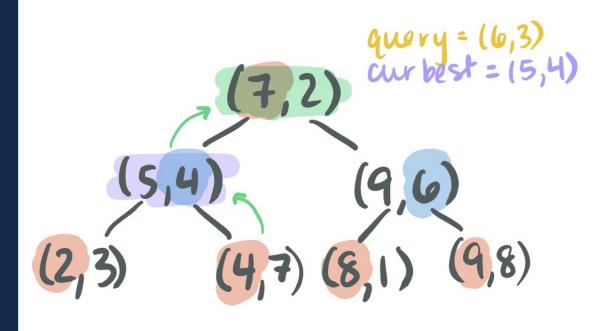
**Backtracking:** start recursing backwards -- store "best" possibility as you trace back

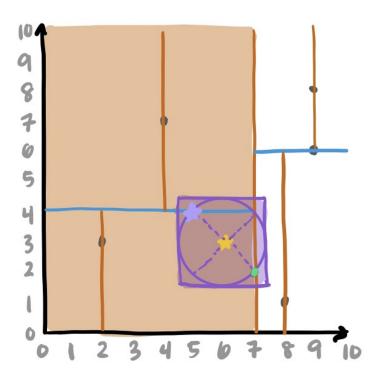


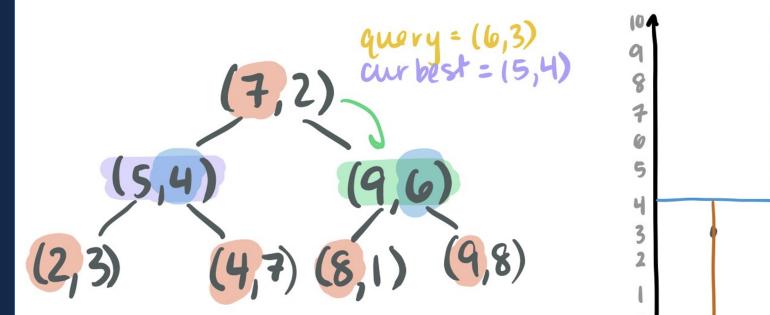


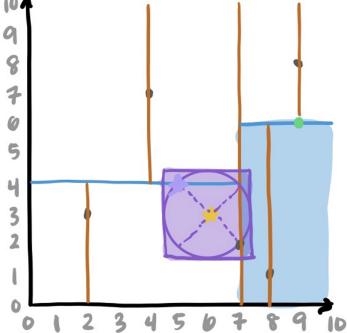


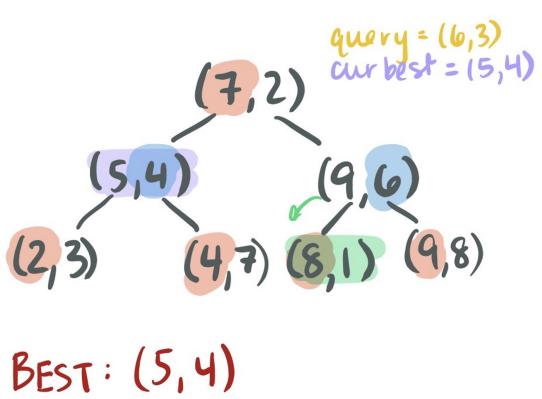
On ties, use smallerDimVal to determine which point remains curBest

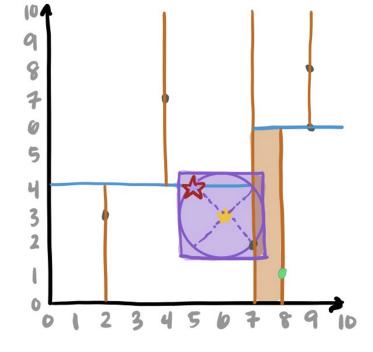








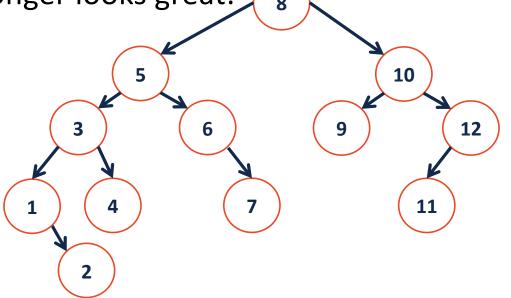




# **B-Tree Motivation**

In Big-O we have assumed uniform time for all operations, but this isn't always true.

However, seeking data from the cloud may take 40ms+. ...an O(lg(n)) AVL tree no longer looks great:

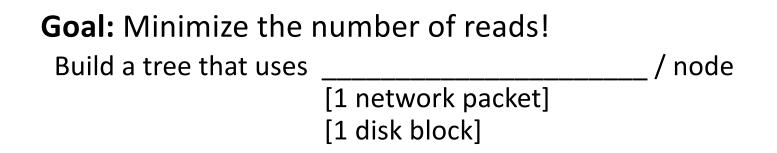


# **BTree Design Motivations**

Knowing that we have large seek times for data, we want to:

# BTree (of order m)

		-3	8	23	25	31	42	43	55	<b>m-0</b>
--	--	----	---	----	----	----	----	----	----	------------



# **BTree Insertion**

A **BTrees** of order **m** is an m-way tree:

- All keys within a node are ordered
- All leaves contain hold no more than **m-1** keys.

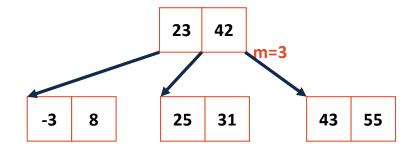


#### **BTree Insertion**

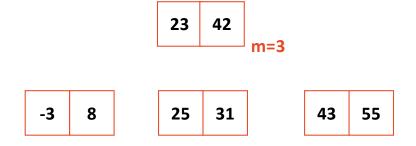
When a BTree node reaches **m** keys:



# **BTree Recursive Insert**



# **BTree Recursive Insert**



# BTree Visualization/Tool

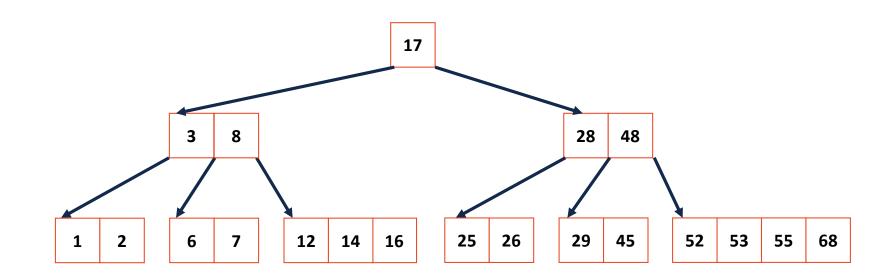
https://www.cs.usfca.edu/~galles/visualization/BTree.html

#### **Btree Properties**

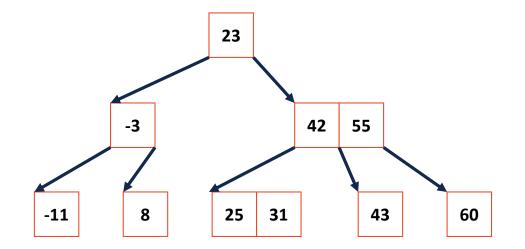
A **BTrees** of order **m** is an m-way tree:

- All keys within a node are ordered
- All leaves contain no more than **m-1** keys.
- All internal nodes have exactly one more child than keys
- Root nodes can be a leaf or have **[2, m]** children.
- All non-root, internal nodes have [ceil(m/2), m] children.
- All leaves are on the same level

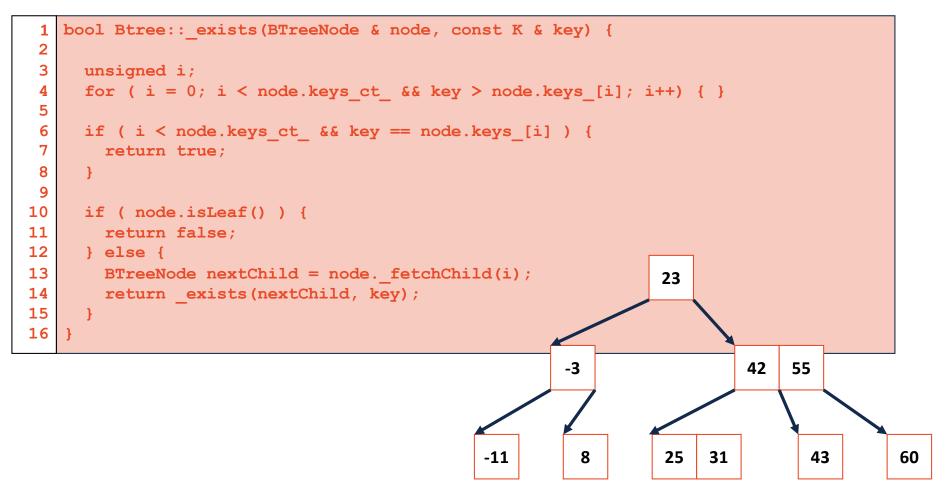




#### **BTree Search**



#### **BTree Search**



The height of the BTree determines maximum number of \_\_\_\_\_ possible in search data.

...and the height of the structure is: \_\_\_\_\_.

Therefore: The number of seeks is no more than \_\_\_\_

...suppose we want to prove this!

In our AVL Analysis, we saw finding an upper bound on the height (given **n**) is the same as finding a lower bound on the nodes (given **h**).

We want to find a relationship for BTrees between the number of keys (**n**) and the height (**h**).

#### Strategy:

We will first count the number of nodes, level by level.

Then, we will add the minimum number of keys per node (n).

The minimum number of nodes will tell us the largest possible height (**h**), allowing us to find an upper-bound on height.

The minimum number of **nodes** for a BTree of order m **at each level**:

root:

level 1:

level 2:

level 3:

... level h:

The total number of nodes is the sum of all of the levels:

The total number of keys:

The smallest total number of keys is:

So an inequality about **n**, the total number of keys:

Solving for **h**, since **h** is the number of seek operations:

Given **m=101**, a tree of height **h=4** has:

Minimum Keys:

Maximum Keys: