



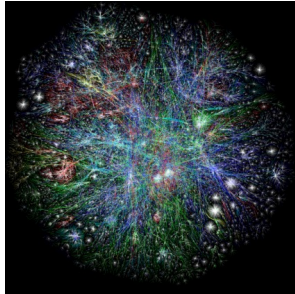
CS 225

Data Structures

April 3 – Minimum Spanning Tree

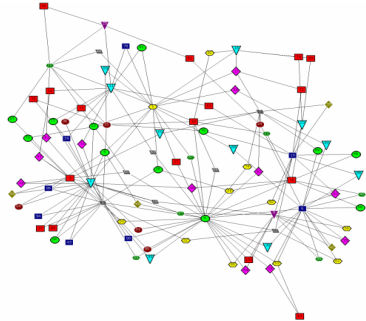
G Carl Evans

Graphs



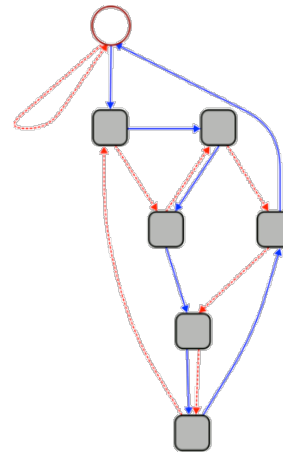
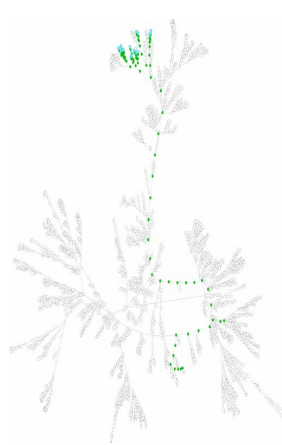
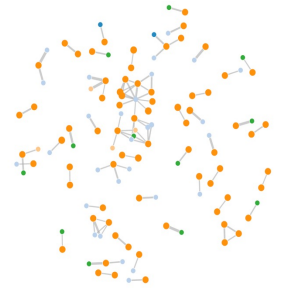
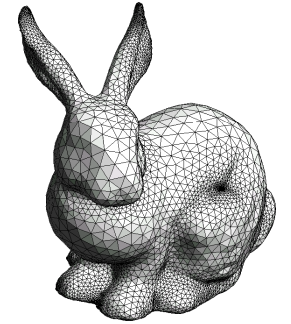
HAMLET

TROILUS AND CRESSIDA



To study all of these structures:

1. A common vocabulary
2. Graph implementations
3. Graph traversals
4. Graph algorithms



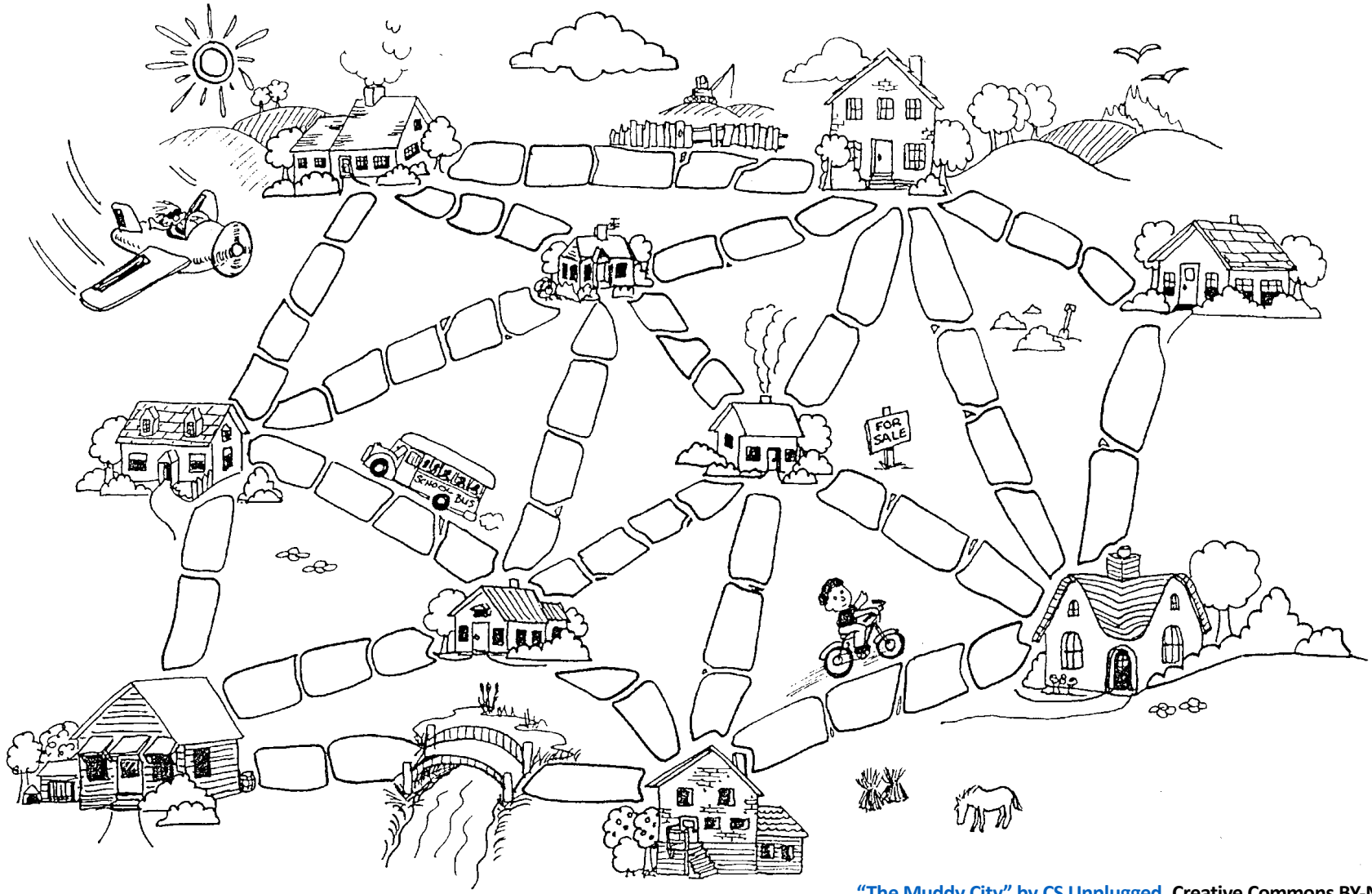
```
heapify(int*, unsigned int):  
  push rbp  
  mov rsi, rbp  
  sub rbp, 20  
  mov dword ptr [rbp + 8], rsi  
  mov dword ptr [rbp + 12], esi  
  mov dword ptr [rbp + 16], 1  
  jmp .LBB_4
```

```
heapify(int*, unsigned int):  
  mov rax, qword ptr [rbp - 8]  
  mov ecx, dword ptr [rbp - 12]  
  mov ecx, ecx  
  mov rax, qword ptr [rax + 4*rdi]  
  mov rax, qword ptr [rbp - 8]  
  mov esi, dword ptr [rbp - 12]  
  shr esi, 1  
  mov esi, esi  
  mov ecx, qword ptr [rax + 4*rdi]  
  jmp .LBB_3
```

```
heapify(int*, unsigned int):  
  mov rax, qword ptr [rbp - 8]  
  mov rax, qword ptr [rbp - 8]  
  mov ecx, qword ptr [rbp - 12]  
  mov ecx, ecx  
  mov rax, qword ptr [rax + 4*rdi]  
  mov rax, qword ptr [rbp - 8]  
  mov esi, dword ptr [rbp - 12]  
  shr esi, 1  
  mov esi, esi  
  mov ecx, qword ptr [rax + 4*rdi], ecx  
  mov rax, qword ptr [rbp - 8]  
  mov ecx, qword ptr [rbp - 12]  
  shr ecx, 1  
  mov esi, ecx  
  call heapify(int*, unsigned int)
```

```
.LBB_3:  
  jmp .LBB_1
```

```
.LBB_4:  
  add rbp, 20  
  pop rbp  
  ret
```



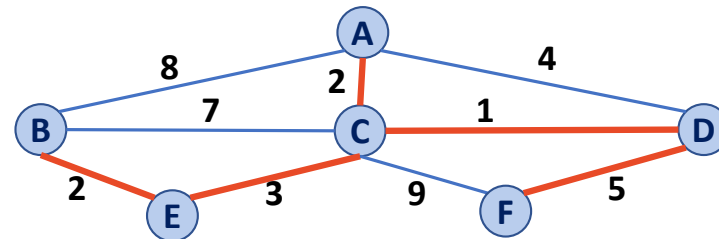
["The Muddy City"](#) by CS Unplugged, Creative Commons BY-NC-SA 4.0

Minimum Spanning Tree Algorithms

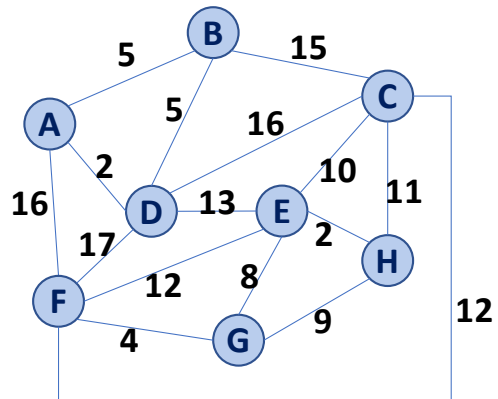
Input: Connected, undirected graph G with edge weights (unconstrained, but must be additive)

Output: A graph G' with the following properties:

- G' is a spanning graph of G
- G' is a tree (connected, acyclic)
- G' has a minimal total weight among all spanning trees

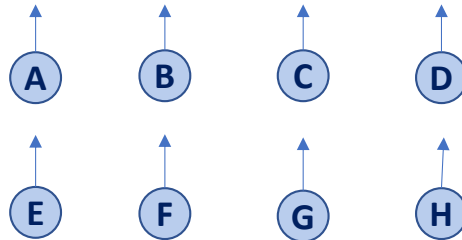
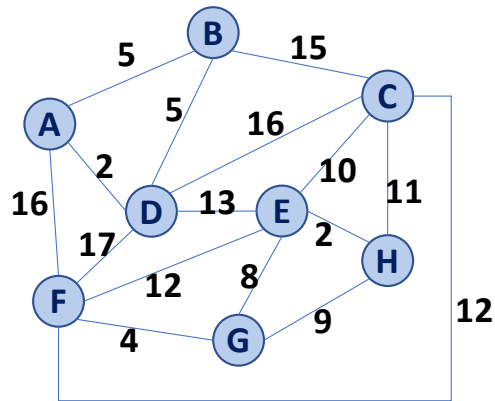


Kruskal's Algorithm



(A, D)
(E, H)
(F, G)
(A, B)
(B, D)
(G, E)
(G, H)
(E, C)
(C, H)
(E, F)
(F, C)
(D, E)
(B, C)
(C, D)
(A, F)
(D, F)

Kruskal's Algorithm



(A, D)
(E, H)
(F, G)
(A, B)
(B, D)
(G, E)
(G, H)
(E, C)
(C, H)
(E, F)
(F, C)
(D, E)
(B, C)
(C, D)
(A, F)
(D, F)

Kruskal's Algorithm

Priority Queue:	Heap	Sorted Array
Building :7-9		
Each removeMin :13		

```
1 KruskalMST(G) :
2   DisjointSets forest
3   foreach (Vertex v : G) :
4     forest.makeSet(v)
5
6   PriorityQueue Q    // min edge weight
7   foreach (Edge e : G) :
8     Q.insert(e)
9
10  Graph T = (V, {})
11
12  while |T.edges()| < n-1:
13    Vertex (u, v) = Q.removeMin()
14    if forest.find(u) != forest.find(v) :
15      T.addEdge(u, v)
16      forest.union( forest.find(u) ,
17                  forest.find(v) )
18
19  return T
```

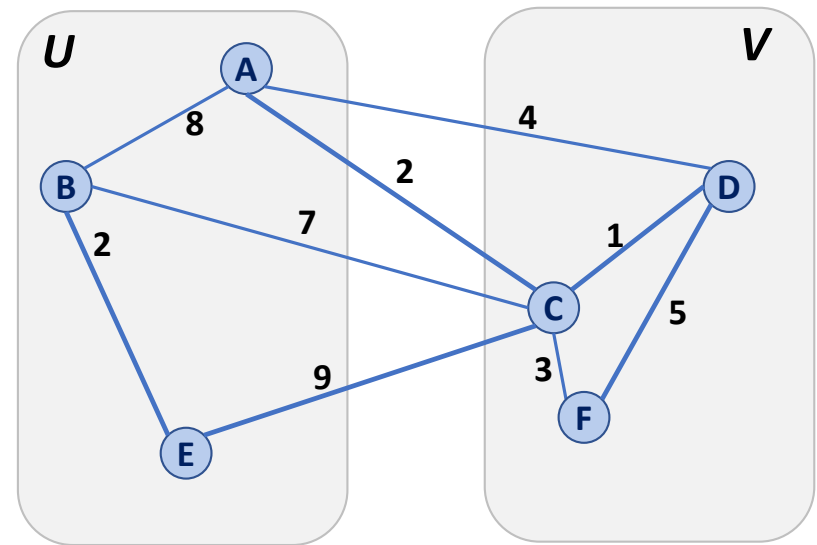

Kruskal's Algorithm

Priority Queue:	Total Running Time
Heap	
Sorted Array	

```
1 KruskalMST(G):
2   DisjointSets forest
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17                  forest.find(v) )
18
19  return T
```

Partition Property

Consider an arbitrary partition of the vertices on \mathbf{G} into two subsets \mathbf{U} and \mathbf{V} .

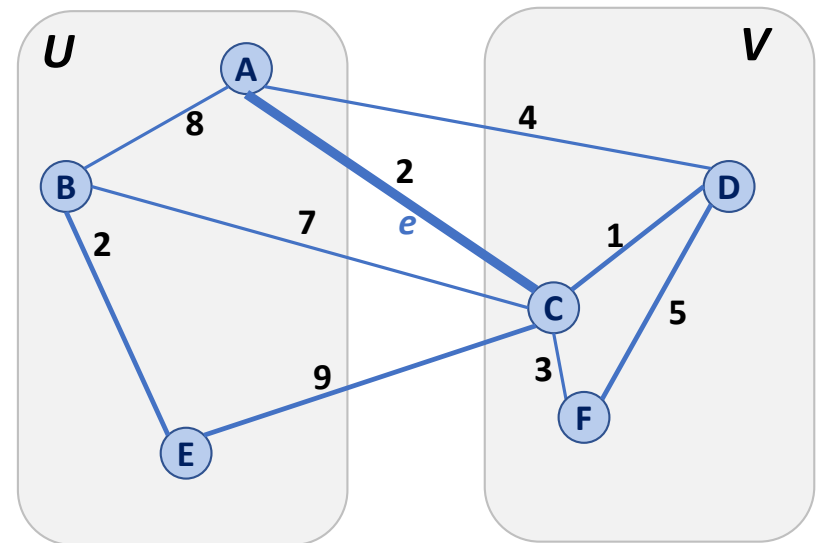


Partition Property

Consider an arbitrary partition of the vertices on G into two subsets U and V .

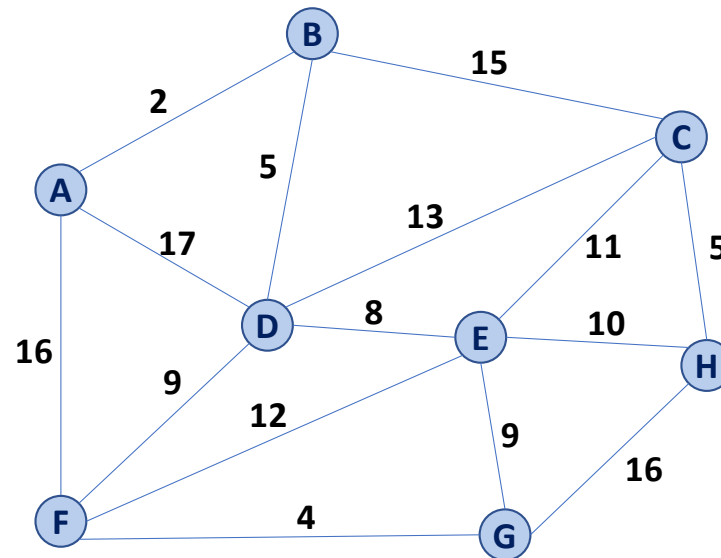
Let e be an edge of minimum weight across the partition.

Then e is part of some minimum spanning tree.

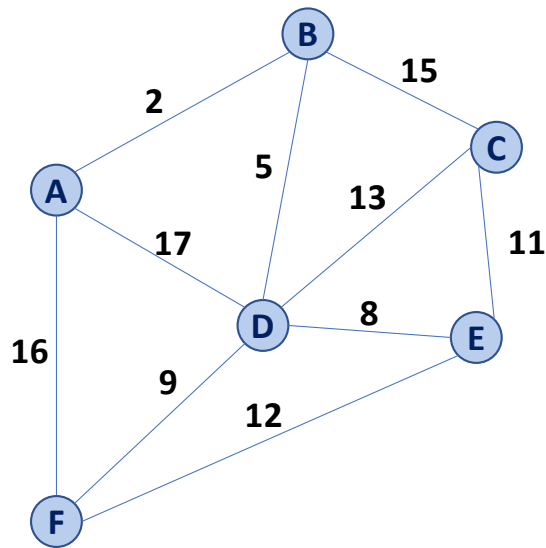


Partition Property

The partition property suggests an algorithm:



Prim's Algorithm



```
1 PrimMST(G, s):
2   Input: G, Graph;
3         s, vertex in G, starting vertex
4   Output: T, a minimum spanning tree (MST) of G
5
6   foreach (Vertex v : G):
7     d[v] = +inf
8     p[v] = NULL
9   d[s] = 0
10
11  PriorityQueue Q // min distance, defined by d[v]
12  Q.buildHeap(G.vertices())
13  Graph T // "labeled set"
14
15  repeat n times:
16    Vertex m = Q.removeMin()
17    T.add(m)
18    foreach (Vertex v : neighbors of m not in T):
19      if cost(v, m) < d[v]:
20        d[v] = cost(v, m)
21        p[v] = m
22
23  return T
```

Prim's Algorithm

```
6 PrimMST(G, s):
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```

	Adj. Matrix	Adj. List
Heap		
Unsorted Array		

Prim's Algorithm

Sparse Graph:

Dense Graph:

```
6 PrimMST(G, s):
7   foreach (Vertex v : G):
8     d[v] = +inf
9     p[v] = NULL
10  d[s] = 0
11
12  PriorityQueue Q // min distance, defined by d[v]
13  Q.buildHeap(G.vertices())
14  Graph T          // "labeled set"
15
16  repeat n times:
17    Vertex m = Q.removeMin()
18    T.add(m)
19    foreach (Vertex v : neighbors of m not in T):
20      if cost(v, m) < d[v]:
21        d[v] = cost(v, m)
22        p[v] = m
```

	Adj. Matrix	Adj. List
Heap	$O(n^2 + m \lg(n))$	$O(n \lg(n) + m \lg(n))$
Unsorted Array	$O(n^2)$	$O(n^2)$



MST Algorithm Runtime:

- Kruskal's Algorithm:

$$O(n + m \lg(n))$$

- Prim's Algorithm:

$$O(n \lg(n) + m \lg(n))$$

- What must be true about the connectivity of a graph when running an MST algorithm?

- How does n and m relate?



MST Algorithm Runtime:

- Kruskal's Algorithm:
 $O(n + m \lg(n))$

- Prim's Algorithm:
 $O(n \lg(n) + m \lg(n))$