B-Trees

CS 225 - Fall 2025

Mattox Beckman / Based on slides from Brad Solomon

Objectives

Objectives

- · Explain how engineering reality can affect trees
- · Explain how B Tree find and insert work

Announcements

- · There were a LOT of cases for MP Lists
- · Informal Early Feedback in the Discord

Pros:

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 $\mathcal{O}(\log n)$ insert

Optimal 1D range queries

Pros: Cons:

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Optimal 1D range queries

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 $\mathcal{O}(\log n)$ insert

Optimal 1D range queries

Cons:

 $\mathcal{O}(\log n)$ is actually slow

Needs a **LOT** of memory

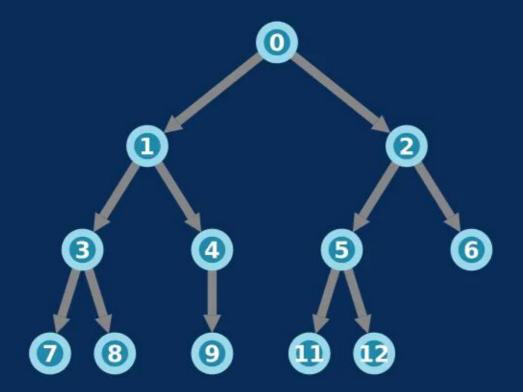
Engineering vs Theory

Introduction

Big-O assumes all operations take the same time

This is not always true!

Can you think of examples?



Where else can we keep our data?

Does this match our assumption that lookups are $\mathcal{O}(n)$?

· No! Just check your cell phone camera....

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· Hard Drives, the Cloud, Mass Storage....

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Where else can we keep our data?

· Hard Drives, the Cloud, Mass Storage....

Does this match our assumption that lookups are $\mathcal{O}(n)$?

· Nope. See https://gist.github.com/hellerbarde/2843375



Keep the number of seeks low

When possible store data locally

Make sure data is relevant

Keep the number of seeks low

· Make a tree that is wide and short When possible store data locally

Make sure data is relevant

B Tree Design Motivations Introduction

Keep the number of seeks low

- · Make a tree that is wide and short When possible store data locally
- · Store more than one key per node Make sure data is relevant

B Tree Design Motivations Introduction

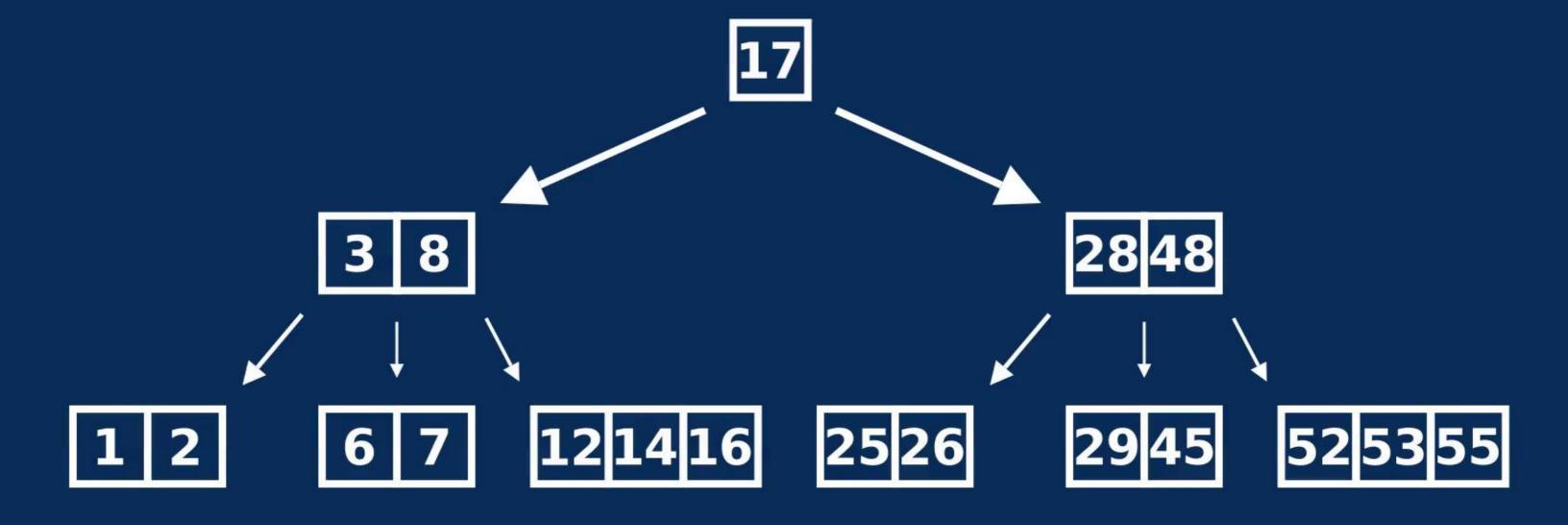
Keep the number of seeks low

- · Make a tree that is wide and short When possible store data locally
- · Store more than one key per node Make sure data is relevant
- · Make sure the tree is ordered

A B Tree of order m is an m-ary tree

Nodes are **ordered**, have up to m-1 keys and keys+1 children

All leaves are on the same level



- · Constructor
- · Insert
- · Find
- · Delete

- · Constructor
- · Insert

B Tree Node of Order m

- · Find
- · Delete

```
1 struct BTreeNode {
2    std::vector<DataPair> elements;
3    std::vector<BTreeNode*> children;
4 }
```

B Tree Design

Base Case

- root empty \Rightarrow return
- · leaf \Rightarrow do array find

•

Recursive Case

- Array find for first \geq match.
- · Recurse to appropriate child

B Tree Design

Base Case

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Recursive Case

· Array find for first \geq match.

Recurse to appropriate child

2848

1 2 6 7 121416 2526 2945 525355

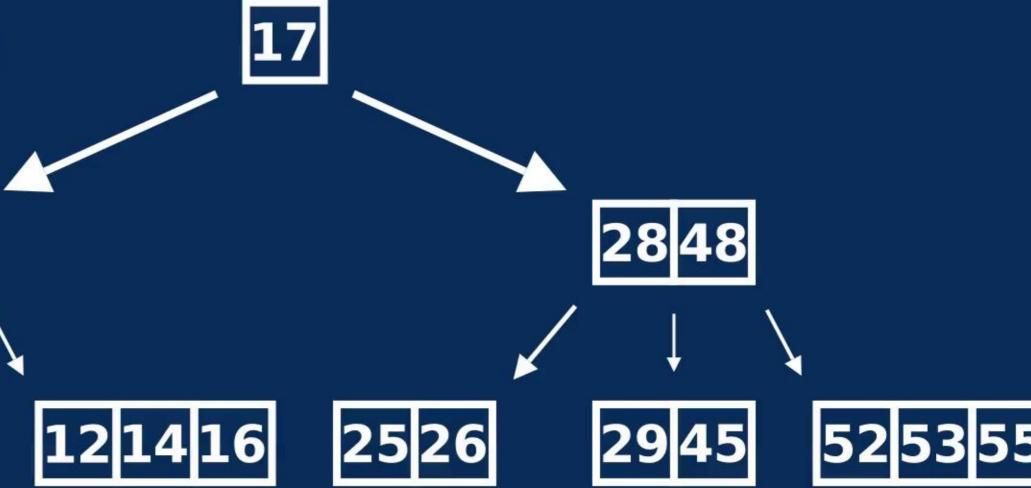
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find(6)

Recursive Case

· Array find for first \geq match.



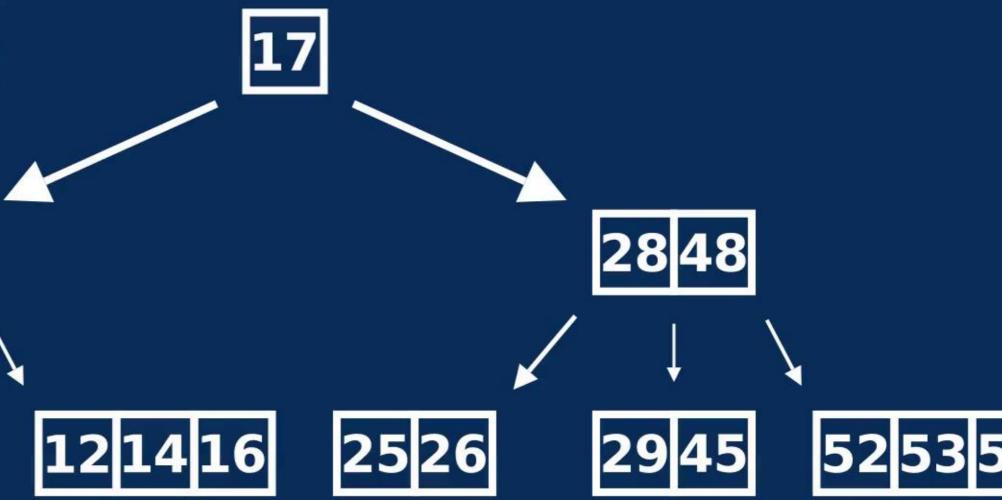
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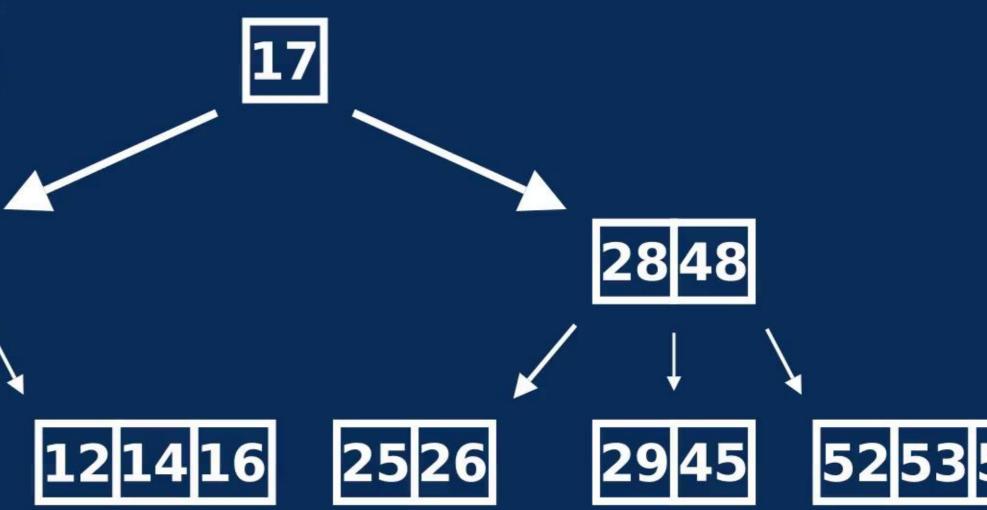
Base Case

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find(16)

Recursive Case

· Array find for first \geq match.



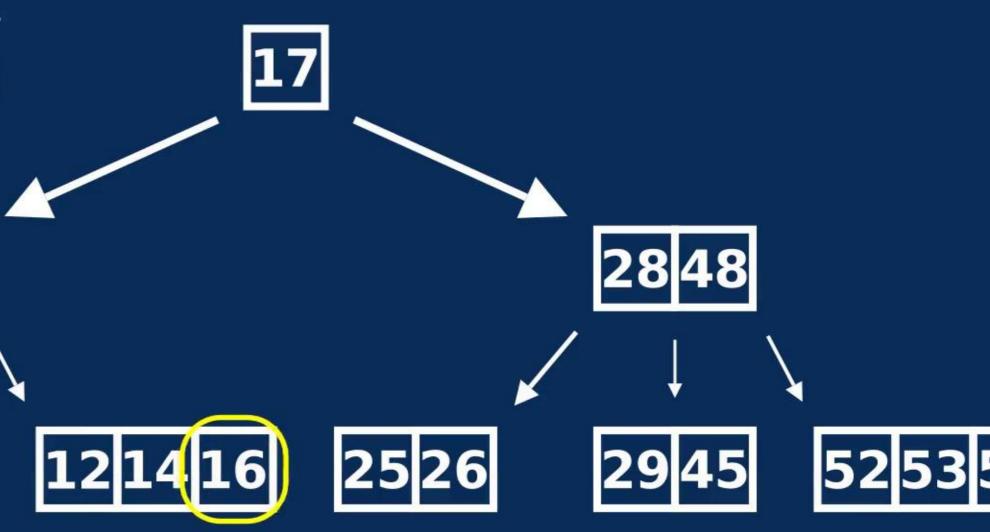
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find(16)

Recursive Case

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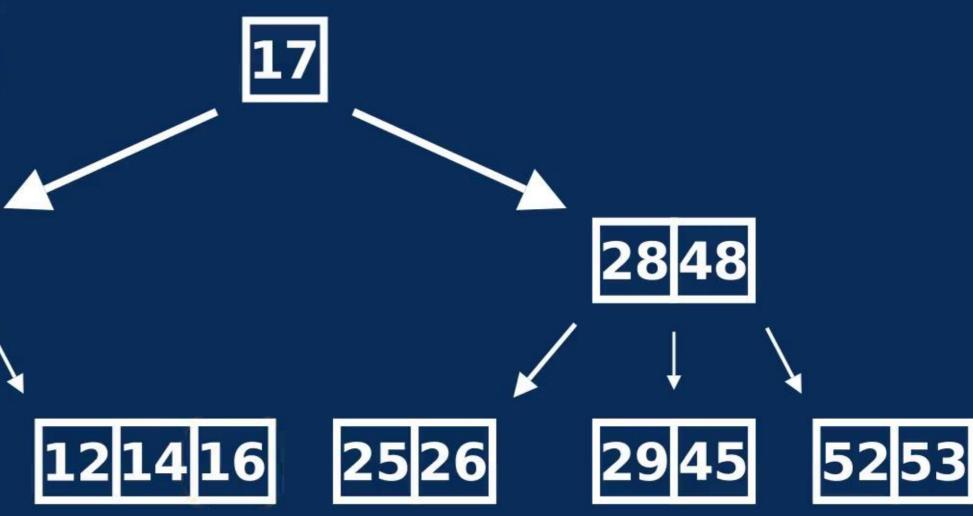
Base Case

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find(45)

Recursive Case

· Array find for first \geq match.



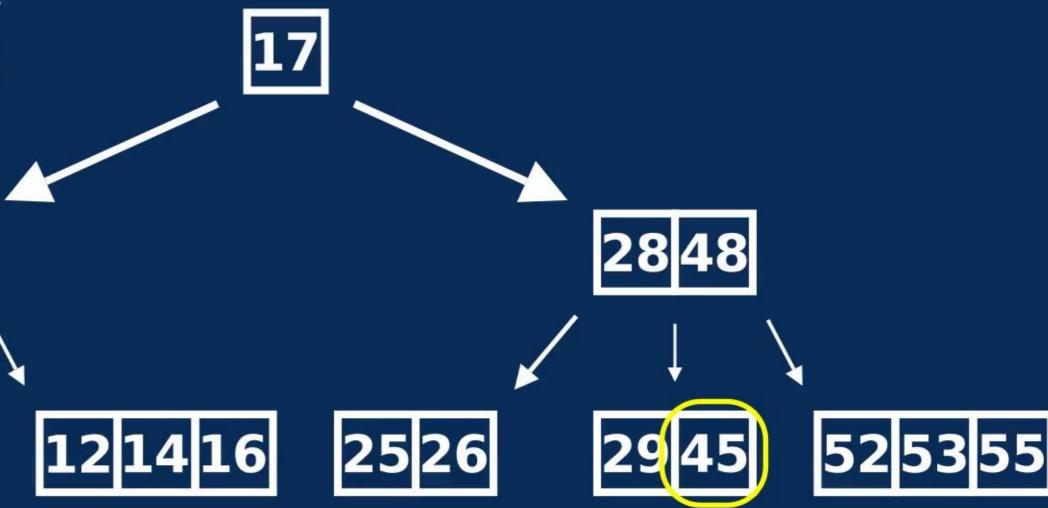
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find(45)

Recursive Case

- · Array find for first \geq match.
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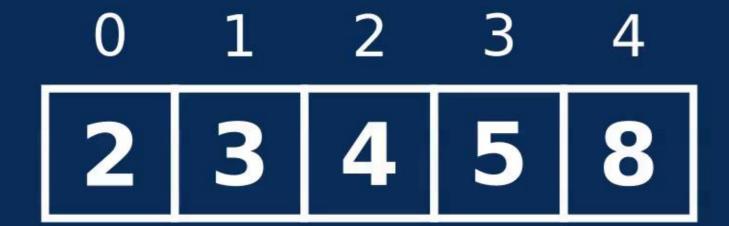






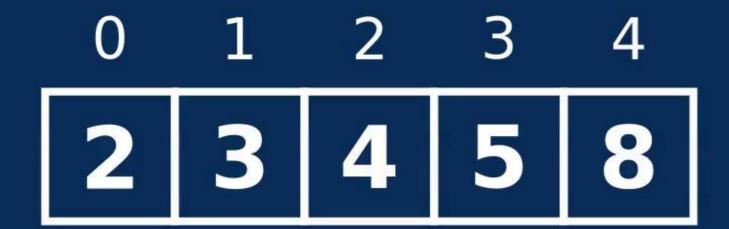


Insert 5, 3, 8, 2, 4



What is the time complexity of sorted array insertion?

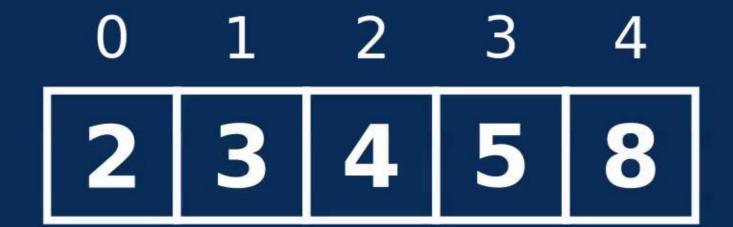
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What is the time complexity of sorted array insertion?

It's $\mathcal{O}(n)$. Is this a problem?

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It's $\mathcal{O}(n)$. Is this a problem?

No. m is constant, and memory operations are **fast**.

Splitting

B Tree Design

What do we do if the node gets full?

Split the node and promote the median.

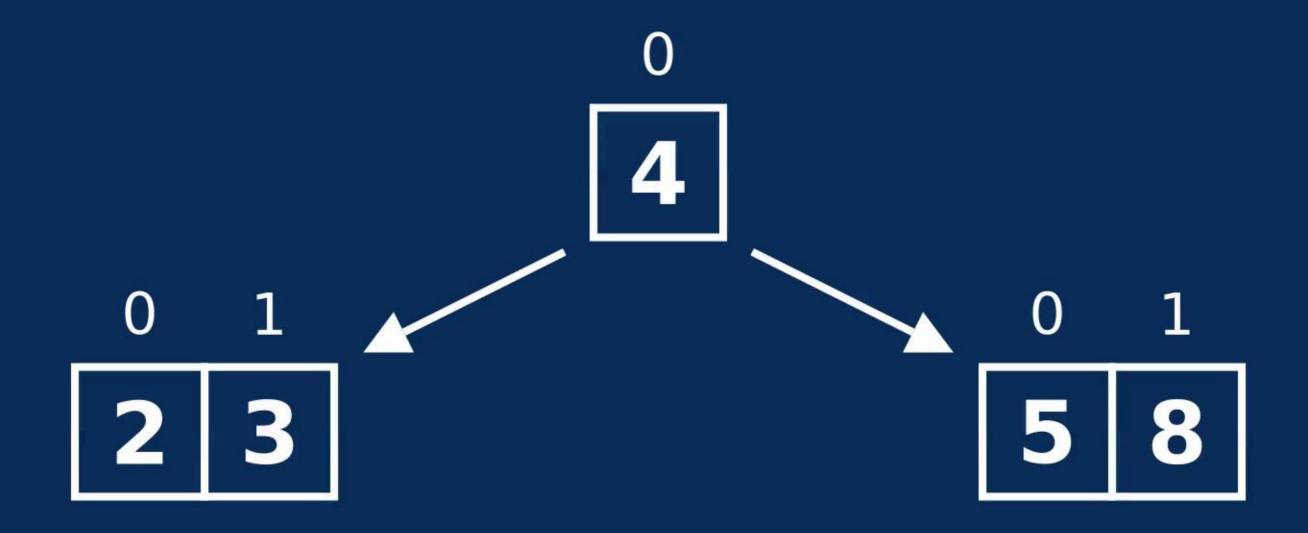
Let's suppose m = 5.



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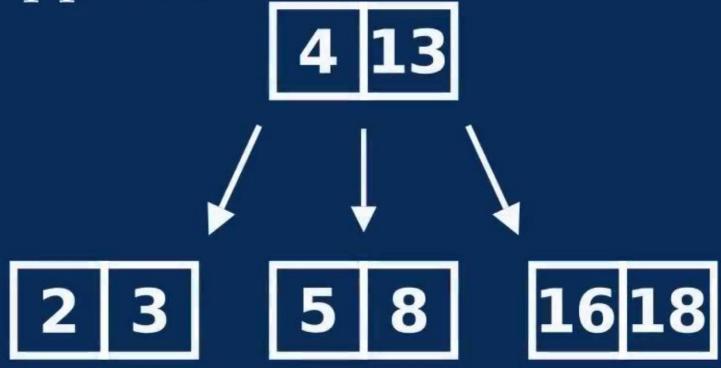
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Splitting can happen recursively.

Let m=3. Insert 25.

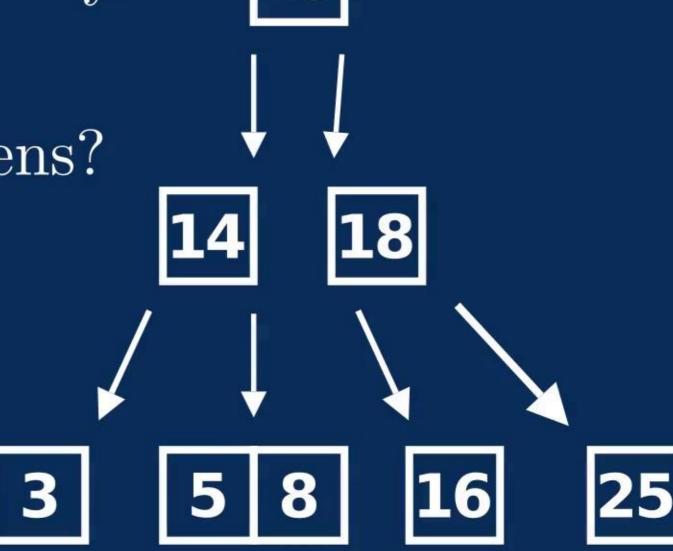
Can you predict what happens?



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Next time: B Tree delete and analysis