

Data Structures and Algorithms

Bloom Filters 2

(Mostly review plus analysis)

CS 225

November 20, 2024

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Learning Objectives

Throwing out information



Review conceptual understanding of bloom filter

Review probabilistic data structures and explore one-sided error

Formalize the math behind the bloom filter

Discuss bit vector operations and potential extensions to bloom filters



Memory-Constrained Data Structures

What method would you use to build a search index on a collection of objects *in a memory-constrained environment*?

Constrained by Big Data (Large N)

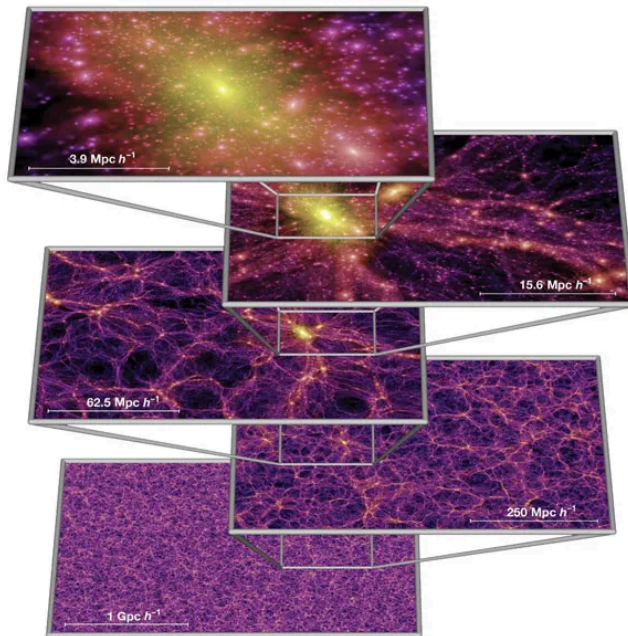


Image: <https://doi.org/10.1038/nature03597>

Sky Survey Projects	Data Volume
DPOSS (The Palomar Digital Sky Survey)	3 TB
2MASS (The Two Micron All-Sky Survey)	10 TB
GBT (Green Bank Telescope)	20 PB
GALEX (The Galaxy Evolution Explorer)	30 TB
SDSS (The Sloan Digital Sky Survey)	40 TB
SkyMapper Southern Sky Survey	500 TB
PanSTARRS (The Panoramic Survey Telescope and Rapid Response System)	~ 40 PB expected
LSST (The Large Synoptic Survey Telescope)	~ 200 PB expected
SKA (The Square Kilometer Array)	~ 4.6 EB expected

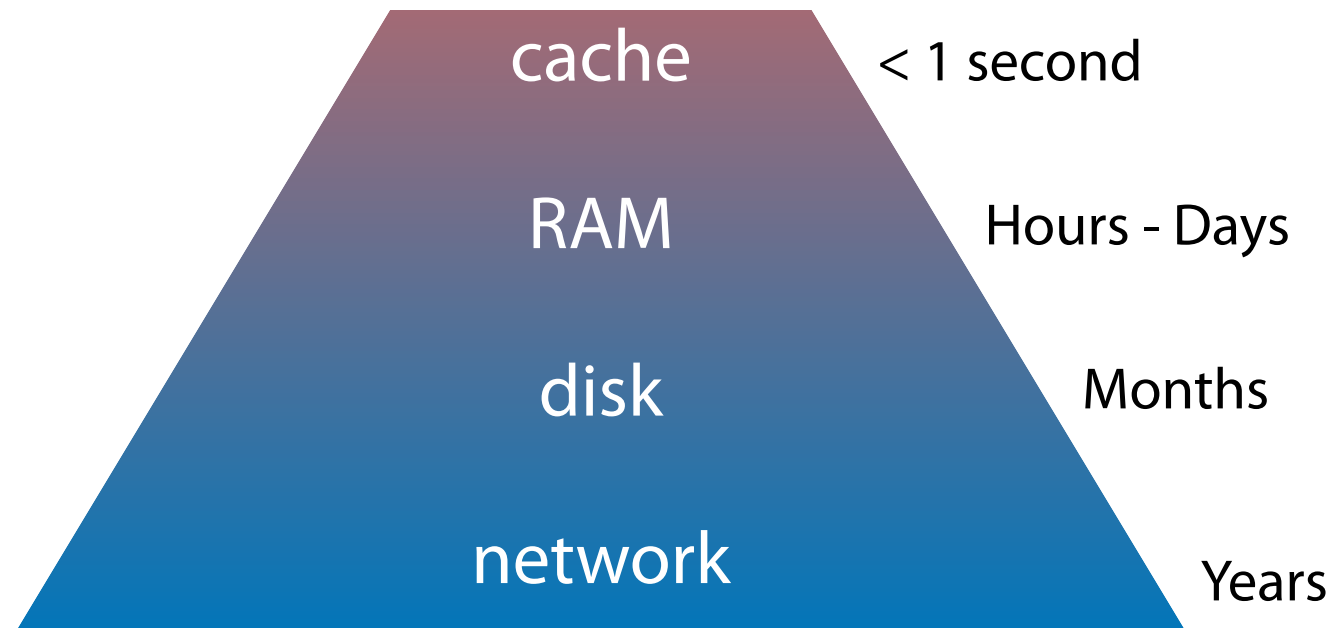
Table: <http://doi.org/10.5334/dsj-2015-011>

Estimated total volume of one array: 4.6 EB

Memory-Constrained Data Structures

What method would you use to build a search index on a collection of objects *in a memory-constrained environment*?

Constrained by resource limitations



(Estimates are Time x 1 billion courtesy of <https://gist.github.com/hellerbarde/2843375>)

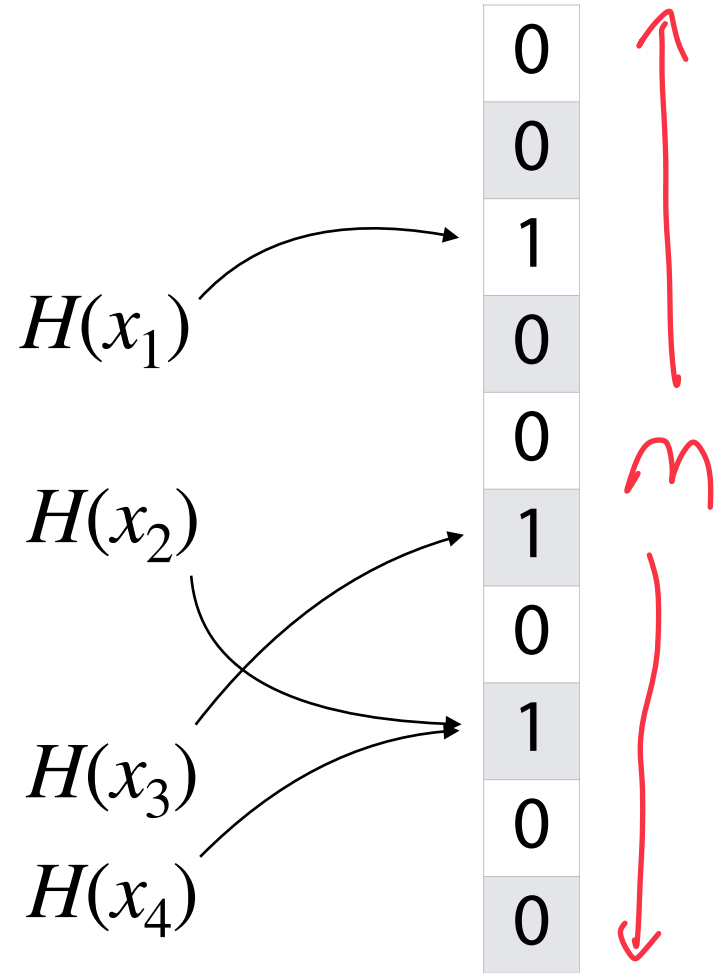
Bloom Filter: Insertion

1) Hash the input key to get its **hash value**

0 (1)

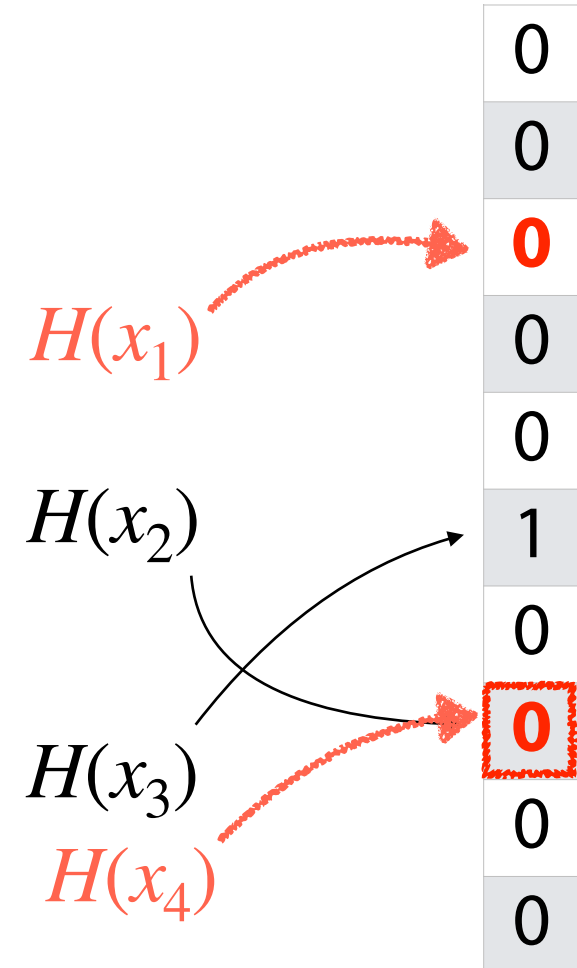
2) Set the bit at the hash value address to 1

If the bit was already one, it stays 1



Bloom Filter: Deletion

Due to hash collisions and lack of information, **items cannot be deleted!**



Bloom Filter: Search

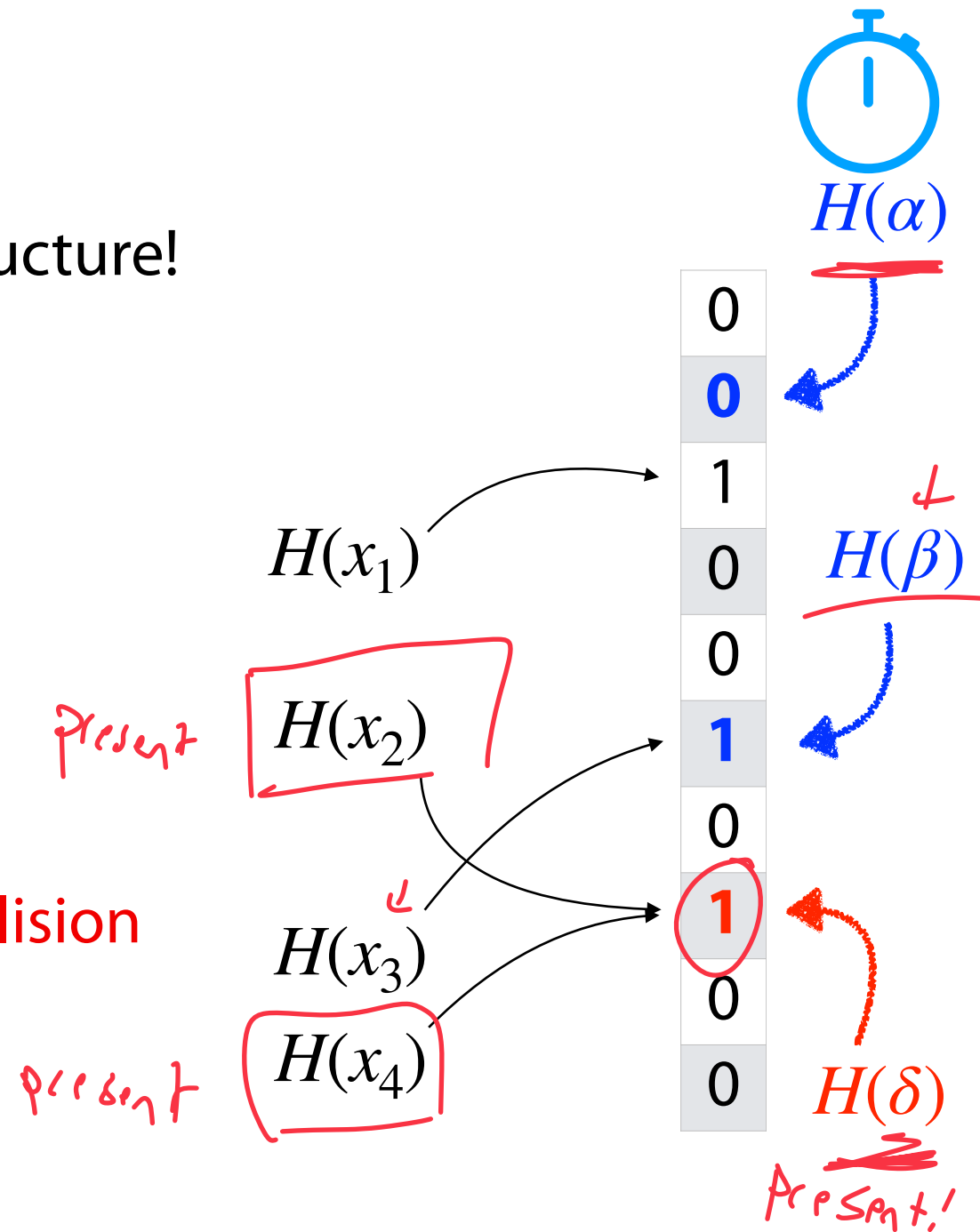
The bloom filter is a *probabilistic* data structure!

If the value in the BF is 0:

100% of time, we know it is not present

If the value in the BF is 1:

It **may** be present or it may be a hash collision

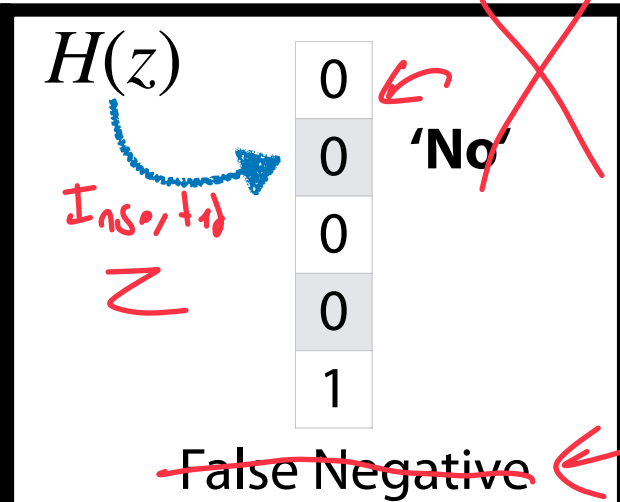
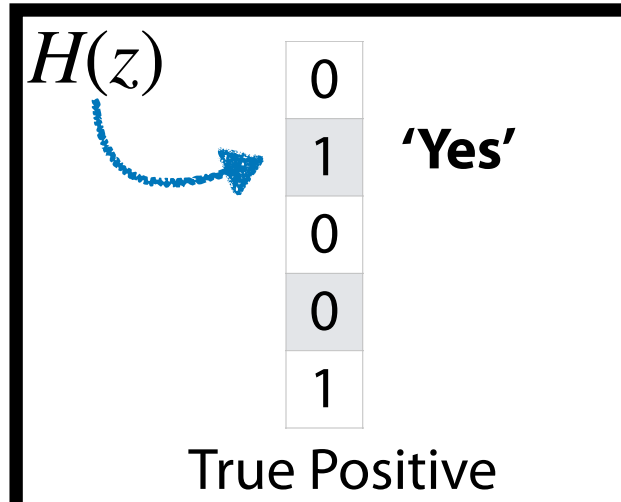


Probabilistic Accuracy in a Bloom Filter

Bit Value = 1

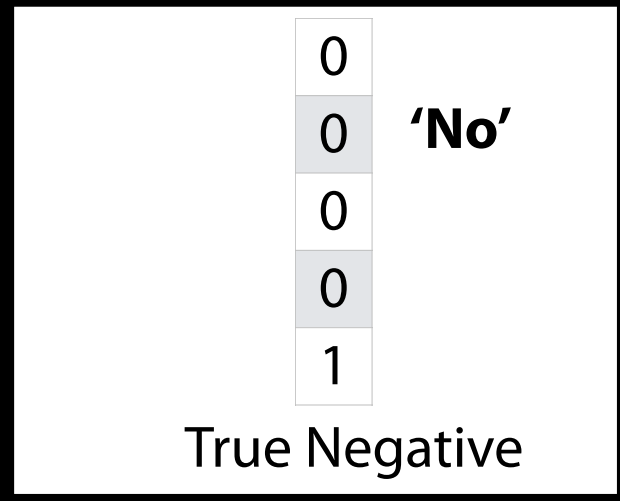
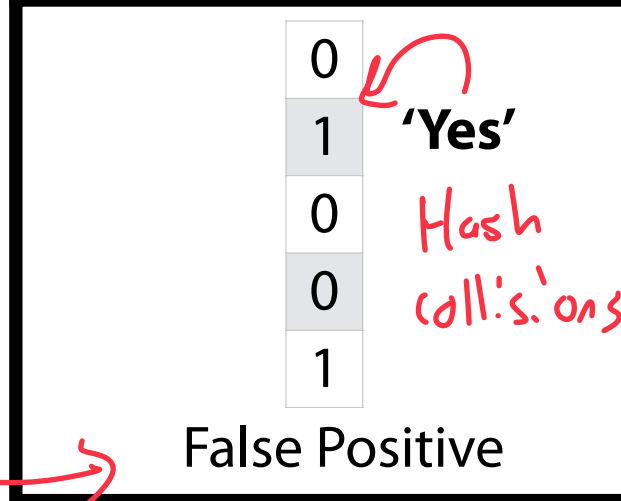
Bit Value = 0

Item Inserted

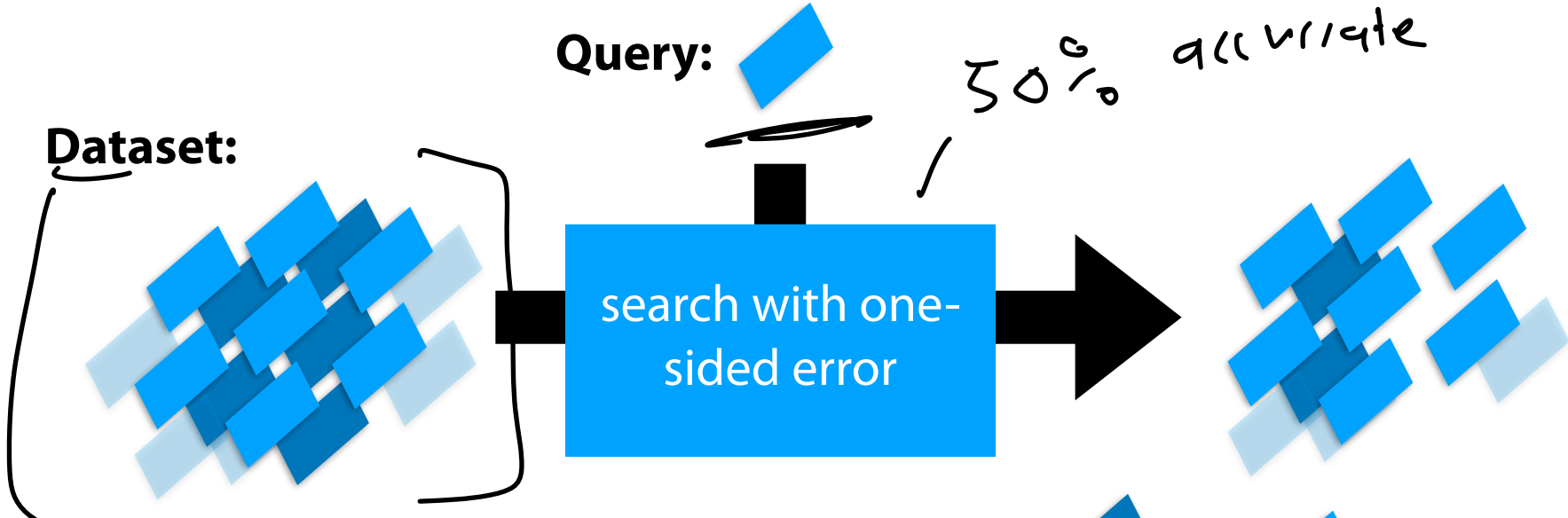


Not possible!
↳ B/c no removal

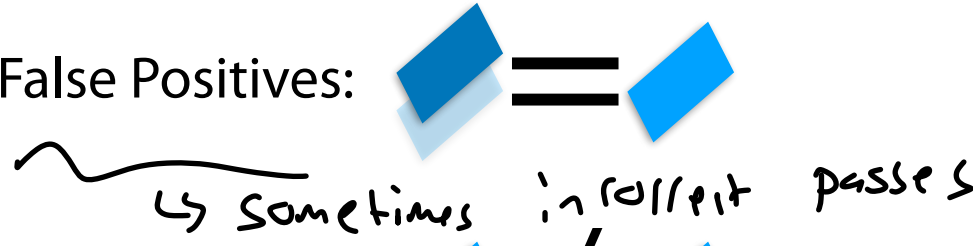
Item NOT inserted



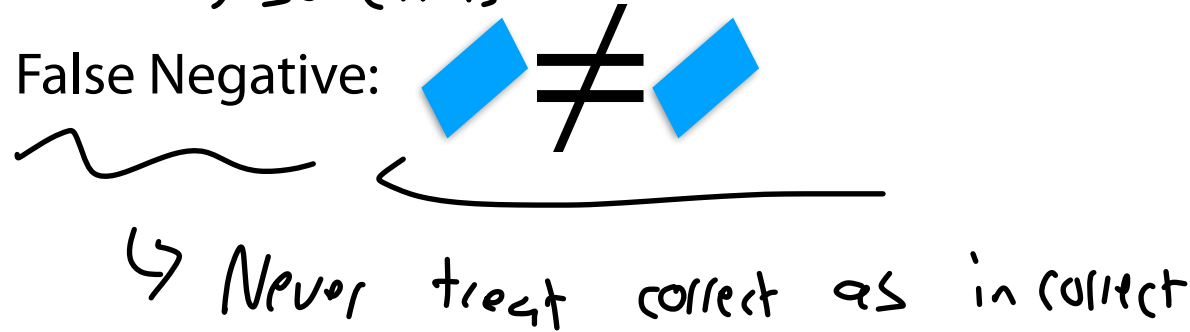
Probabilistic Accuracy: One-sided error



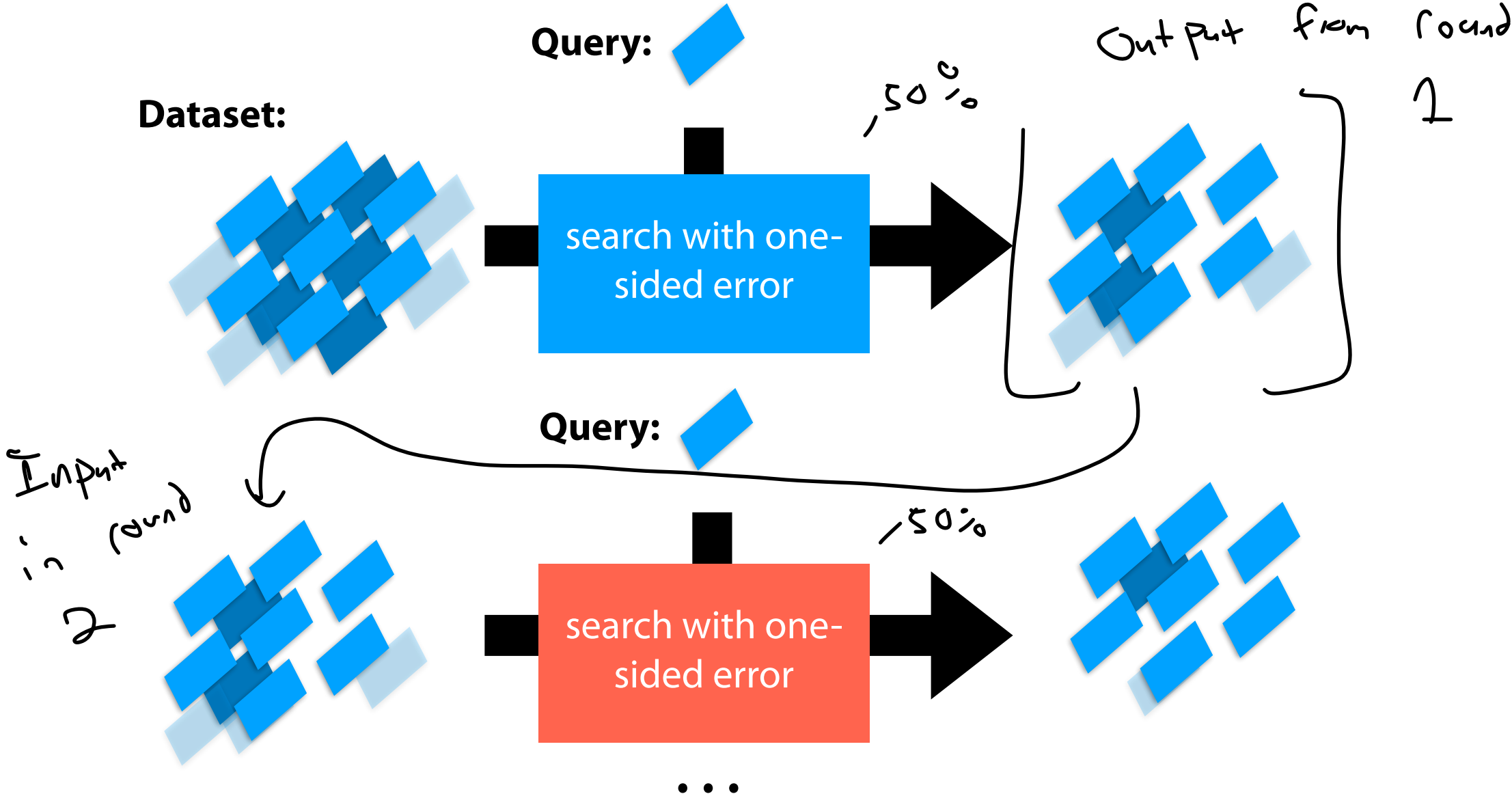
We will get some False Positives:



We will NEVER have a False Negative:

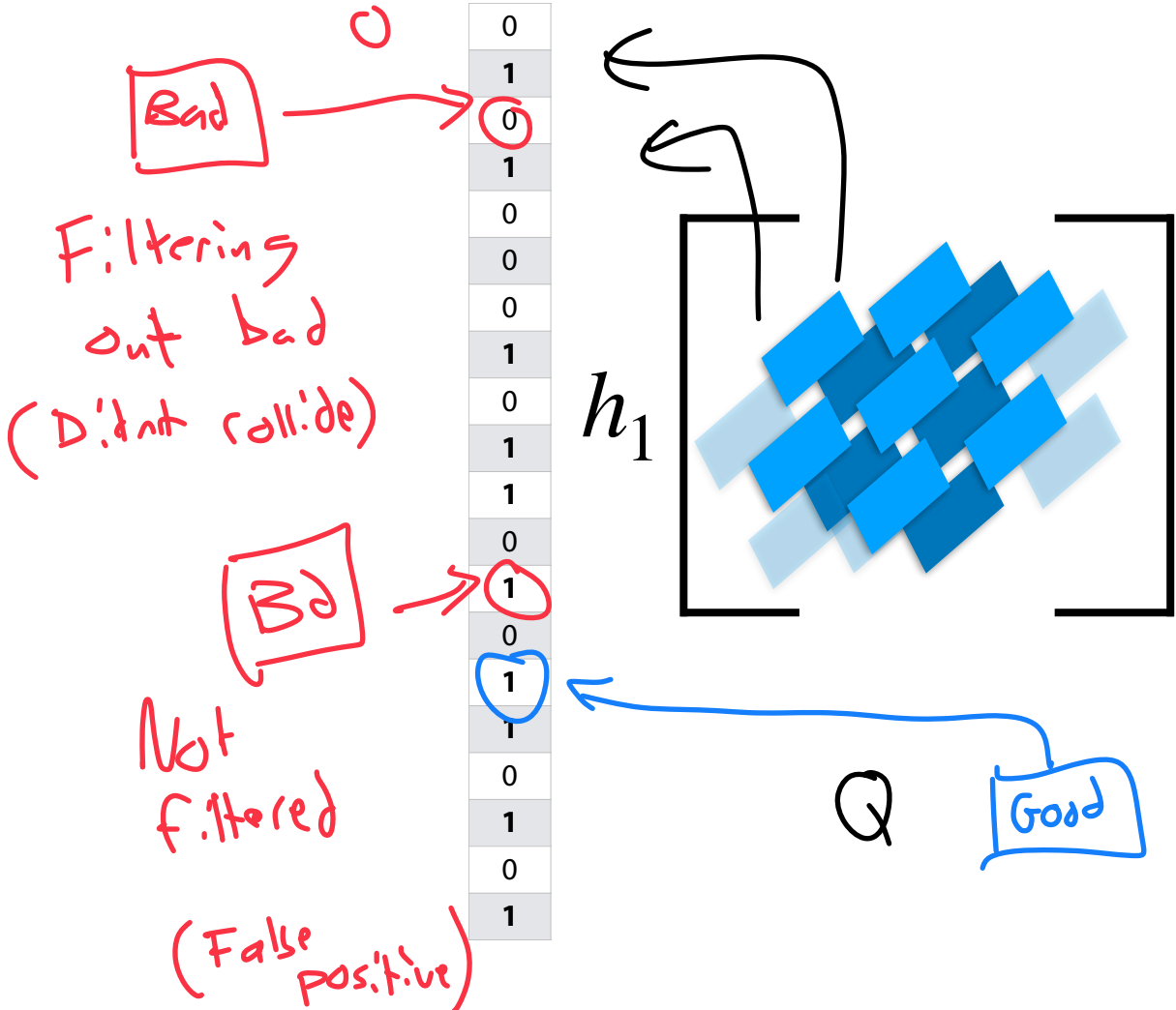


Probabilistic Accuracy: One-sided error



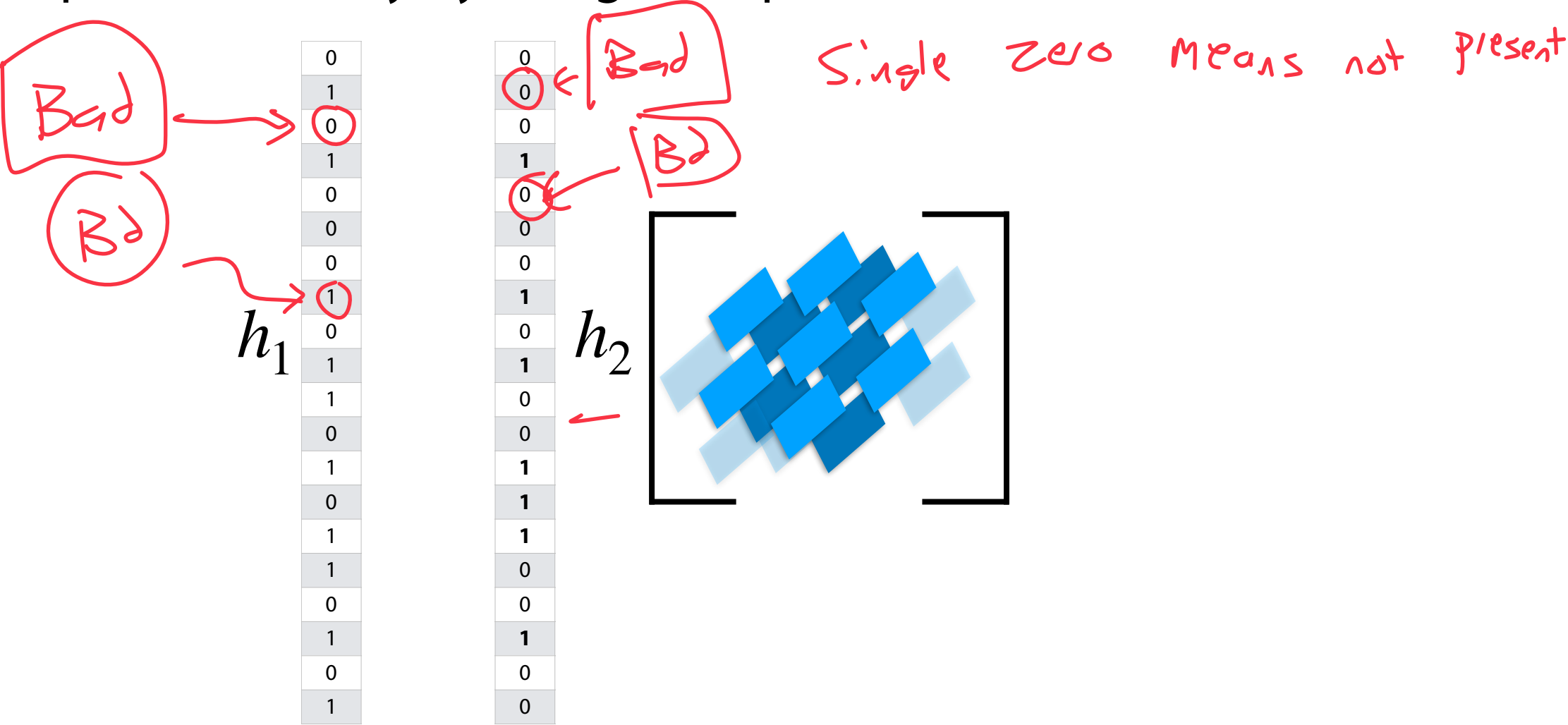
Bloom Filter: Repeated Trials

Improve accuracy by using multiple hash functions as a 'filter'



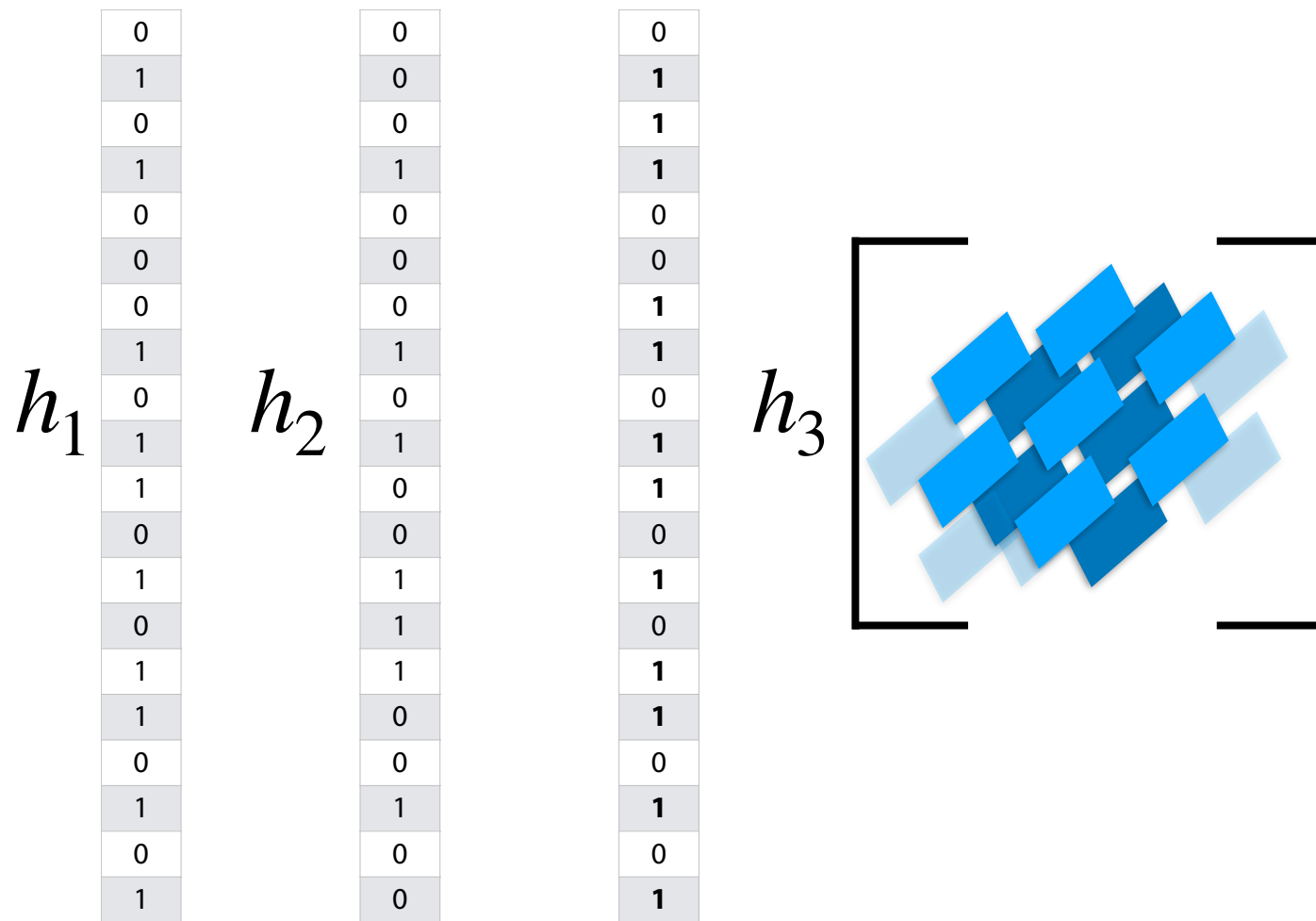
Bloom Filter: Repeated Trials

Improve accuracy by using multiple hash functions as a 'filter'



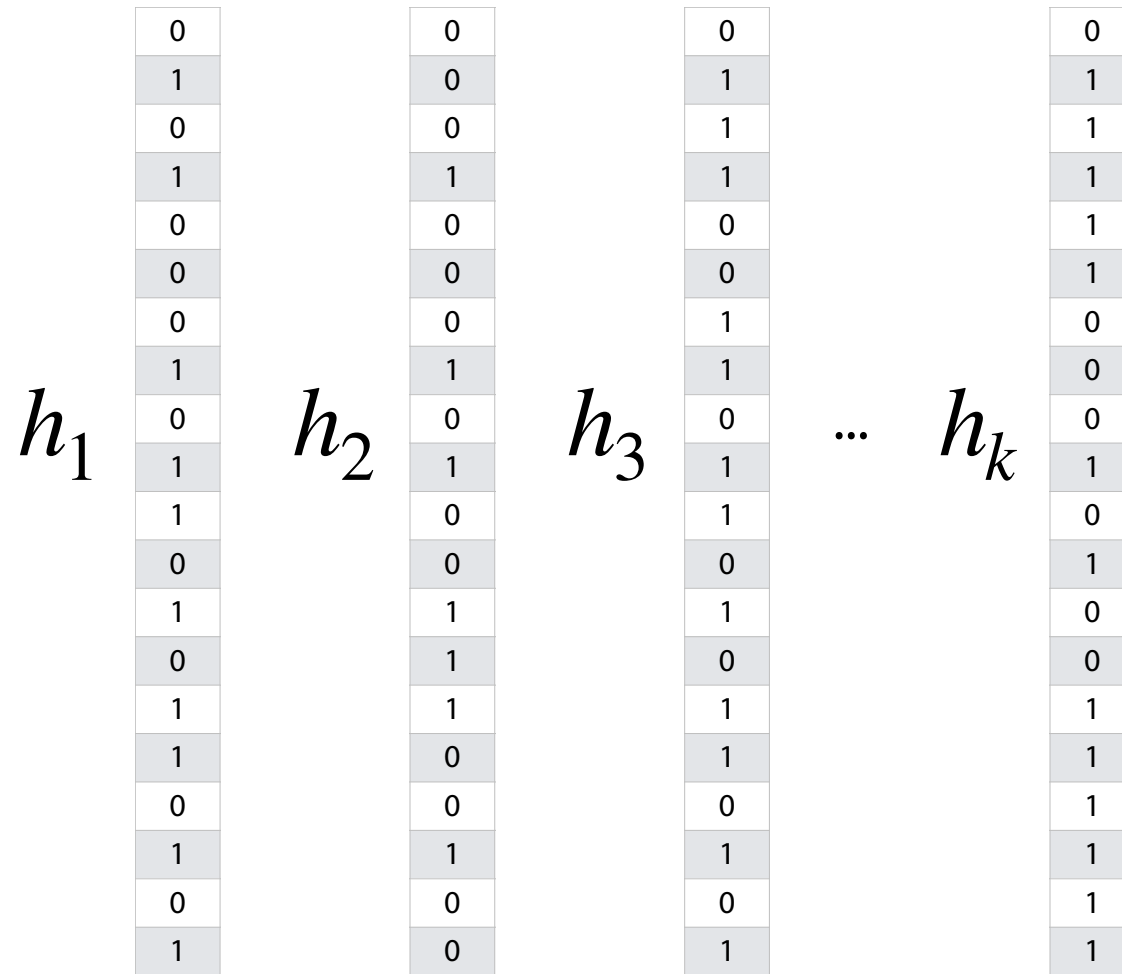
Bloom Filter: Repeated Trials

Improve accuracy by using multiple hash functions as a 'filter'



Bloom Filter: Repeated Trials

Each of these k Bloom Filters is a repeated trial — improved accuracy!



Bloom Filter: Repeated Trials

Each of these k Bloom Filters is a repeated trial — improved accuracy!

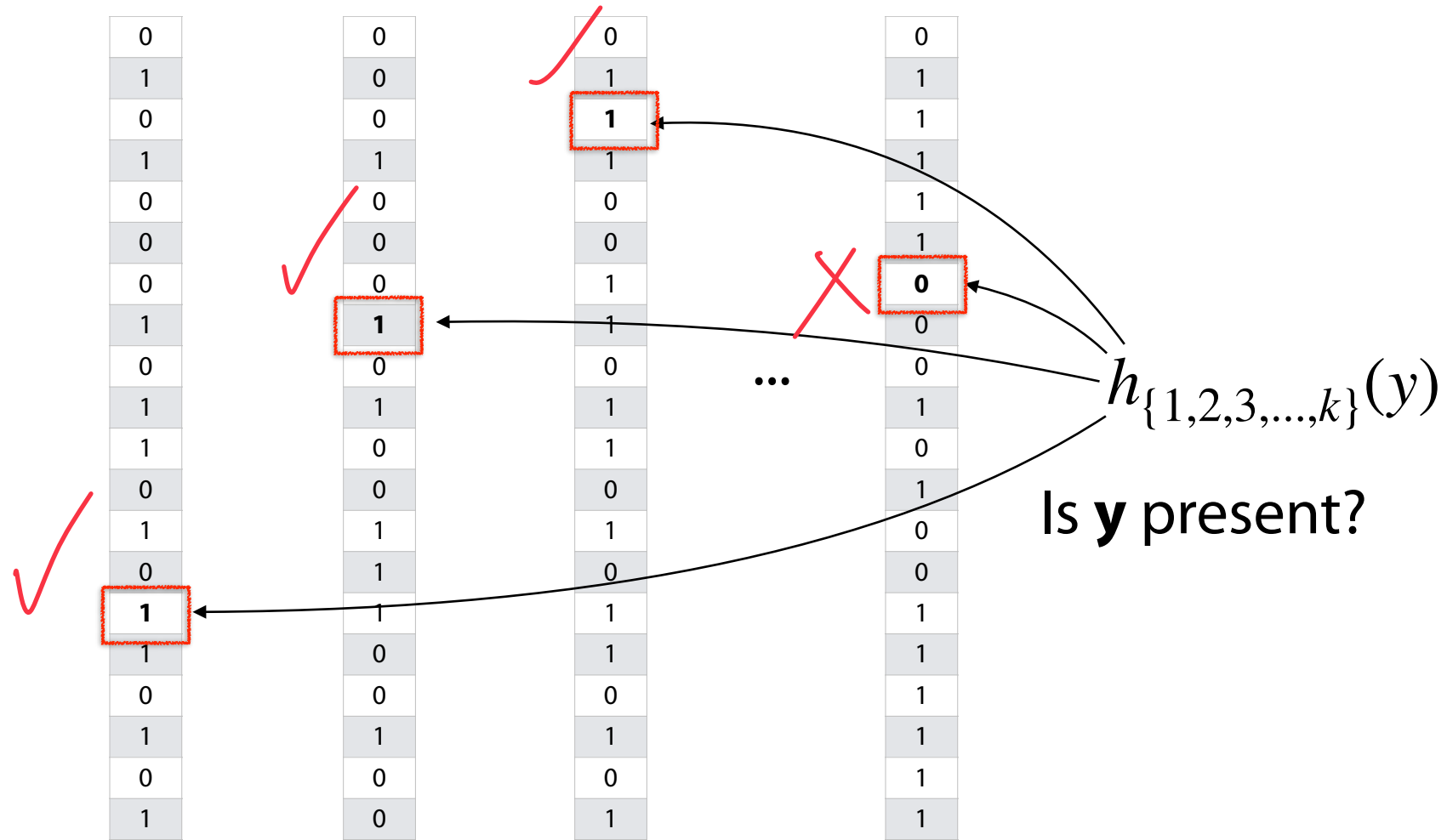
0	0	0	...	0
1	0	1		1
0	0	1		1
1	1	1		1
0	0	0		1
0	0	0		1
0	0	1		0
1	1	1		0
0	0	0		0
1	1	1		1
0	0	0		0
1	1	1		0
0	0	0		1
1	1	1		1
0	0	0		1
1	0	1		1

We insert x k times

$$h_{\{1,2,3,\dots,k\}}(y)$$

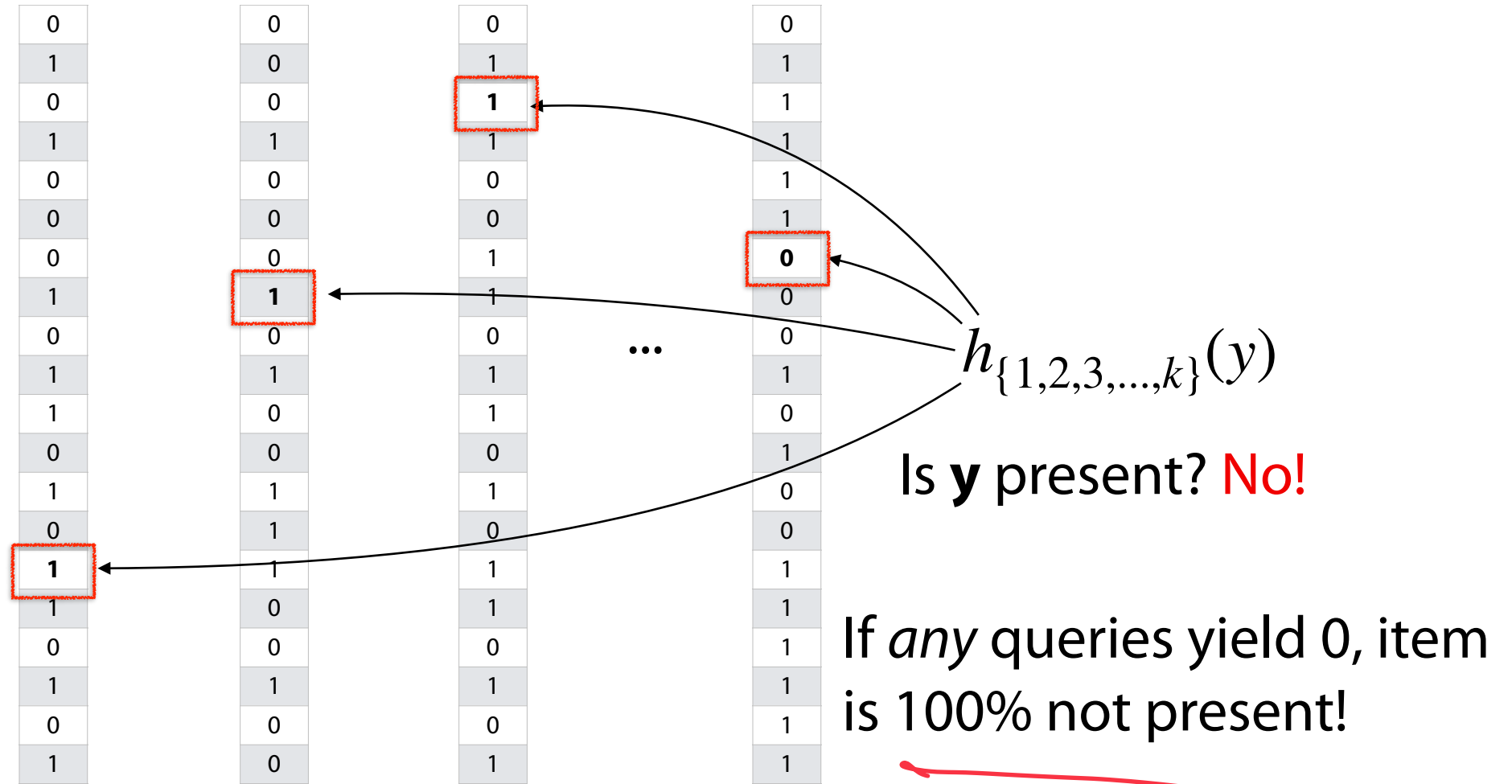
Bloom Filter: Repeated Trials

Each of these k Bloom Filters is a repeated trial — improved accuracy!



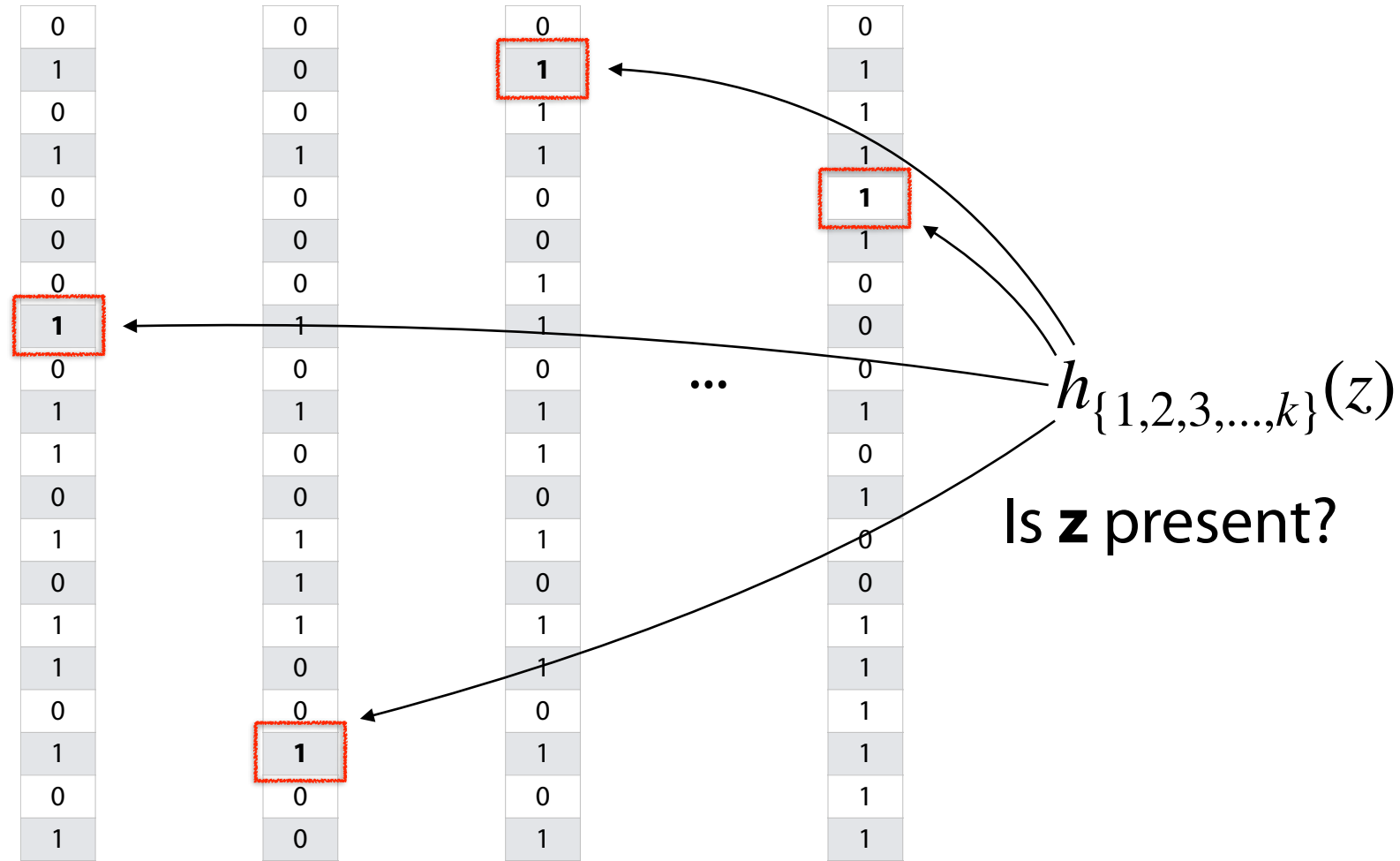
Bloom Filter: Repeated Trials

Each of these k Bloom Filters is a repeated trial — improved accuracy!



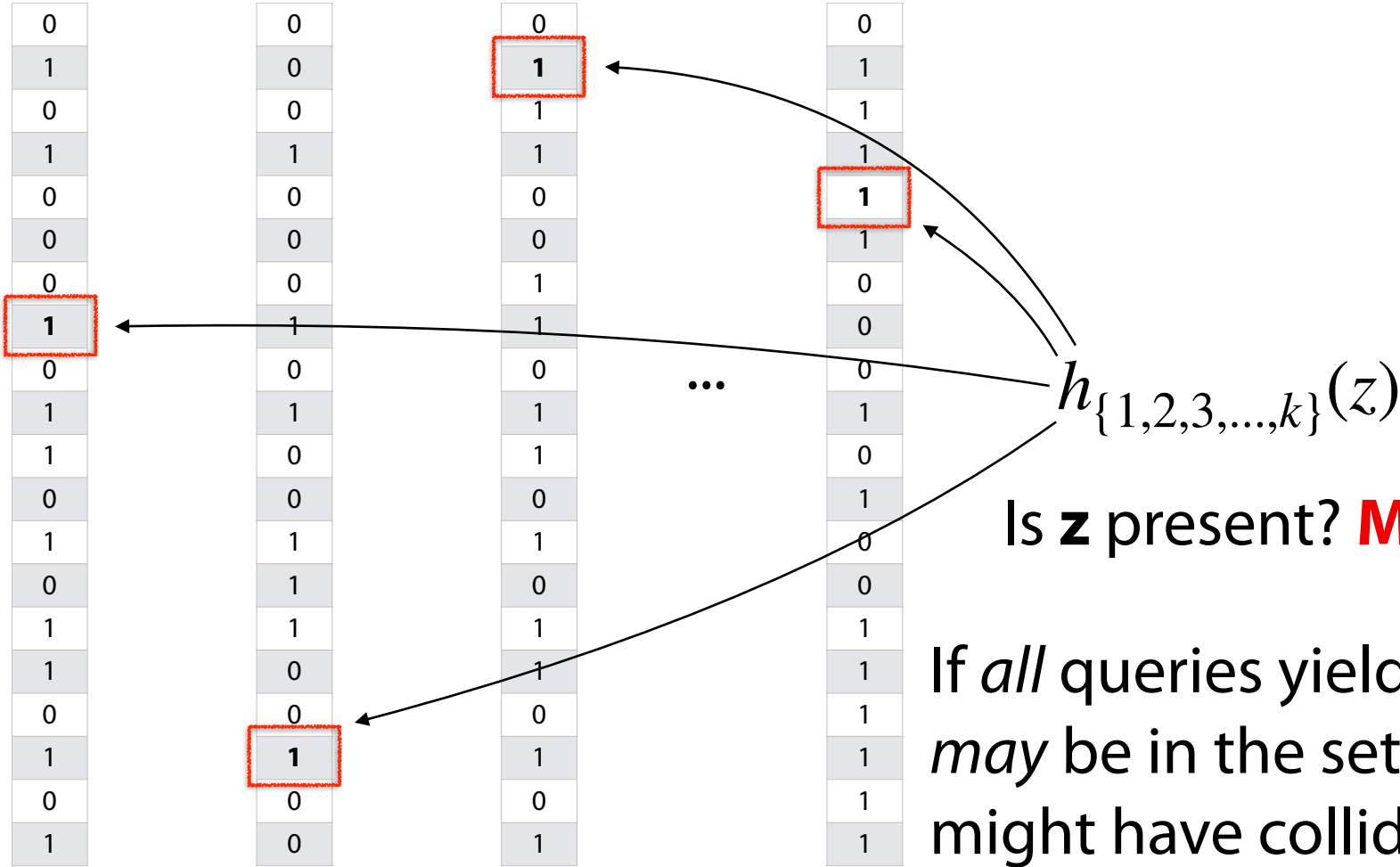
Bloom Filter: Repeated Trials

Each of these k Bloom Filters is a repeated trial — improved accuracy!



Bloom Filter: Repeated Trials

Each of these k Bloom Filters is a repeated trial — improved accuracy!



Is z present? **Maybe!**

If *all* queries yield 1, item *may* be in the set; or we might have collided k times

False positive still possible!

Bloom Filter: Repeated Trials

Using repeated trials, even a very bad filter can still have a very low FPR!

If we have k bloom filter, each with a FPR p , what is the likelihood that **all** filters return the value '1' for an item we didn't insert?

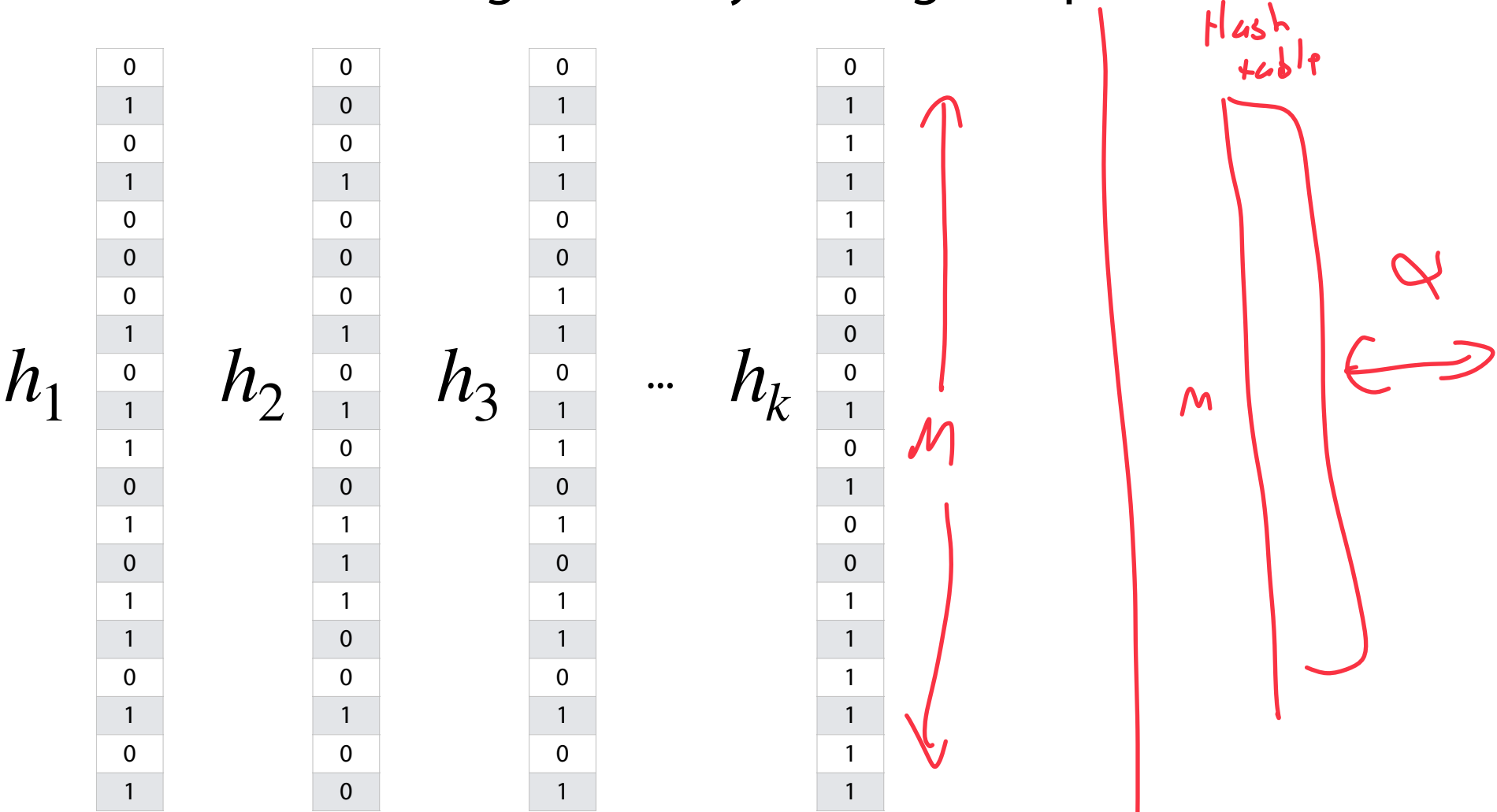
h_1	h_2	h_3	h_4
0	0	0	0
1	0	1	1
0	0	1	1
1	1	1	1
0	0	0	1
0	0	0	1
0	0	1	0
1	1	1	0
0	0	0	0
1	1	1	0

$$(P)^k = (0.5)^k$$

$$\frac{1}{2^k}$$

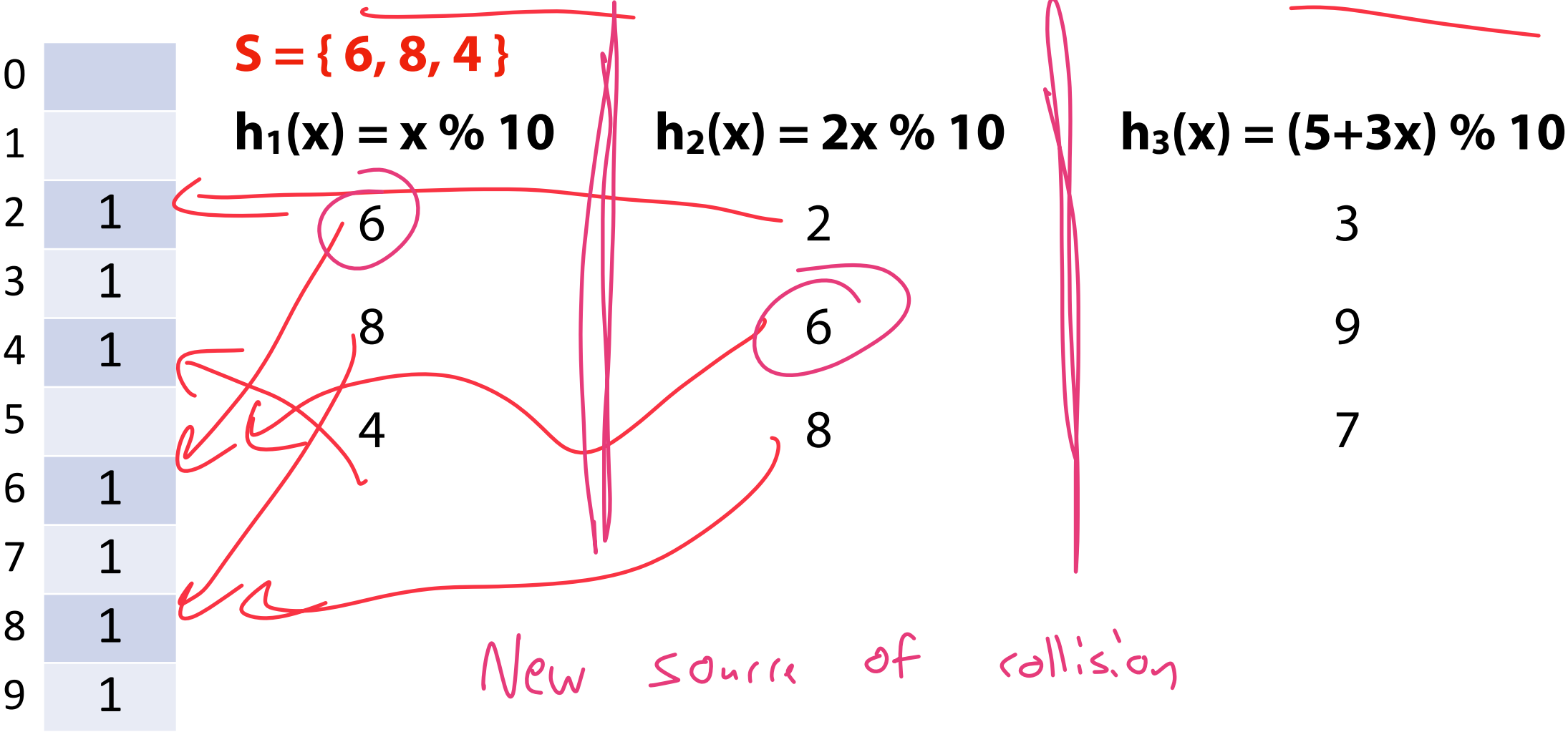
Bloom Filter: Repeated Trials

But doesn't this hurt our storage costs by storing k separate filters?



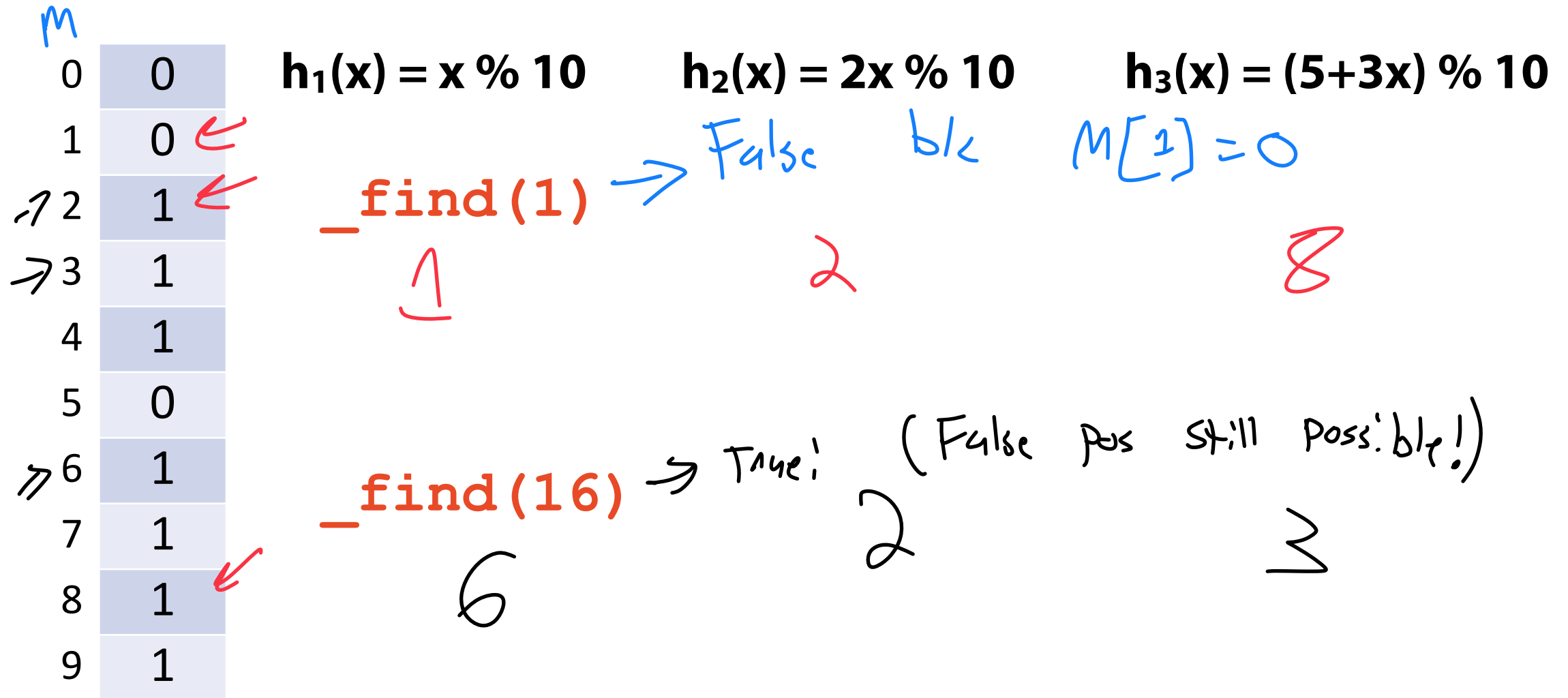
Bloom Filter: Repeated Trials

Rather than use a new filter for each hash, one filter can use k hashes



Bloom Filter: Repeated Trials

Rather than use a new filter for each hash, one filter can use k hashes



Bloom Filter

A probabilistic data structure storing a set of values

Built from a bit vector of length m and k hash functions

Insert / Find runs in: $\frac{O(k)}{O(1)}$

Delete is not possible (yet)!



$$H = \{h_1, h_2, \dots, h_k\}$$

0
0
1
0
0
1
0
1
0
0



Bloom Filter: Error Rate

Given bit vector of size m and k SUHA hash function

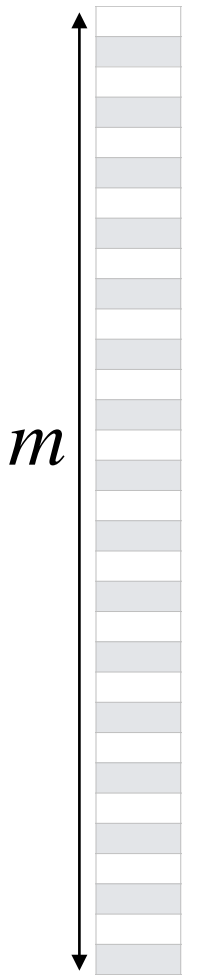
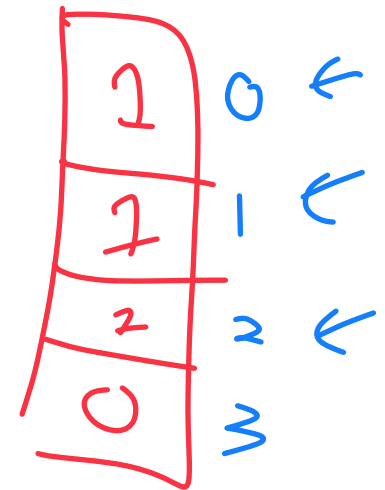
What is our expected FPR after n objects are inserted?

$h_{\{1,2,3,\dots,k\}}$

$\hookrightarrow \left(\text{Prob a bit is 1} \right)^k$

↑
How do we get
prob bit = 1?

$H_1 \rightarrow 3/4$
 $H_2 \rightarrow 3/4$
 $H_3 \dots$



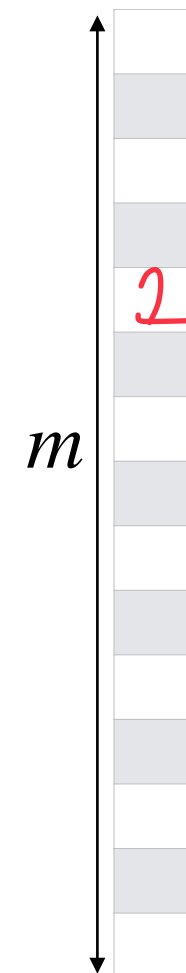
Bloom Filter: Error Rate

Given bit vector of size m and 1 SUHA hash function

What's the probability a specific bucket is 1 after one object is inserted?

$$1/m$$

$h_{\{1,2,3,\dots,k\}}$



Same probability given k SUHA hash function?

$$\left(\frac{1}{m}\right)^k$$

→ This prob approaches 0 as k increases

Not correct!
↳ This is hard to write

Bloom Filter: Error Rate

$h_{\{1,2,3,\dots,k\}}$

Given bit vector of size m and 1 SUHA hash function

$\rightarrow k$

Probability a specific bucket is 0 after one object is inserted?

$$1 - \left(\frac{1}{m}\right)$$

← After 1 insert

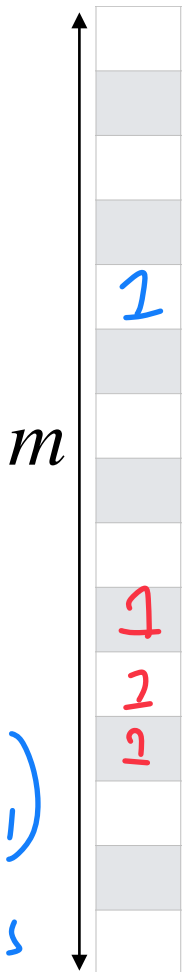
↑
prob bucket is 1

After n objects are inserted? ← Am I still 0? (B/c SUHA math is trivial)

likelihood that
after n
inserts my
bucket is
still 0

$$\left[\left(1 - \frac{1}{m} \right) \right]^k \text{ hashes} \rightarrow nk \text{ SUHA inserts}$$

n repeated trials

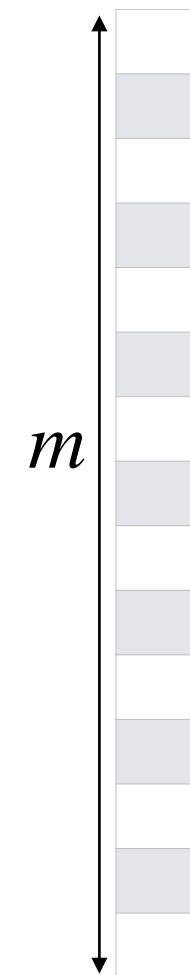


Bloom Filter: Error Rate

Given bit vector of size m and k SUHA hash function

What's the probability a specific bucket is 1 after n objects are inserted?

$h_{\{1,2,3,\dots,k\}}$



$$\left(1 - \left(1 - \frac{1}{m} \right)^{nk} \right)$$

prob bucket is 0

What is my FPR?

$$\left(\text{prob bucket is 1} \right)^k$$

Bloom Filter: Error Rate

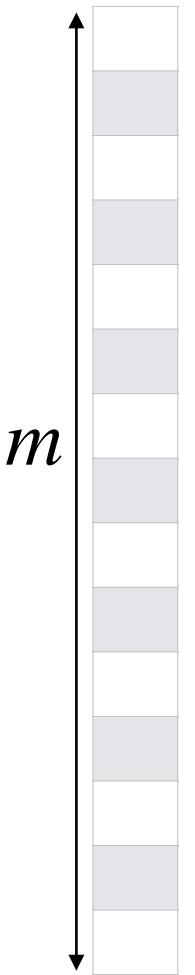
Given bit vector of size m and k SUHA hash function

What is our expected FPR after n objects are inserted?

The probability my bit is 1 after n objects inserted

$$\left(1 - \left(1 - \frac{1}{m} \right)^{nk} \right)^k$$

The number of [assumed independent] trials



$h_{\{1,2,3,\dots,k\}}$

Bloom Filter: Error Rate

Vector of size m , k SUHA hash function, and n objects

To minimize the FPR, do we prefer...

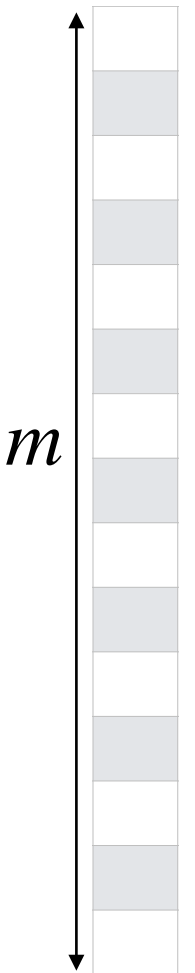
(A) large k

(B) small k

$$\left(1 - \left(1 - \frac{1}{m} \right)^{nk} \right)^k$$

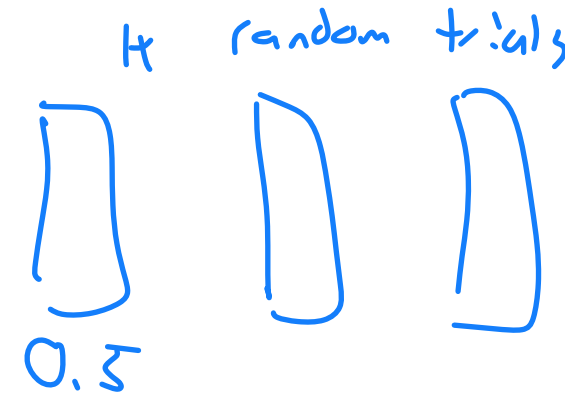
Both are right!

$h_{\{1,2,3,\dots,k\}}$



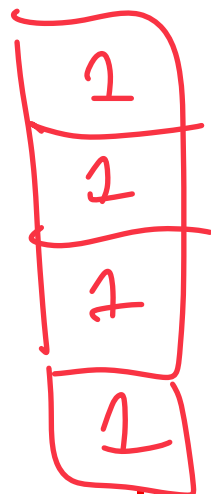
Bloom Filter: Error Rate

Vector of size m , k SUHA hash function, and n objects



(A) large k

$$\left(1 - \left(1 - \frac{1}{m} \right)^{nk} \right)^k$$



As k increases, this gets smaller!

Prob bit is zero

↳ k too large saturates filter

(B) small k

$$\left(1 - \left(1 - \frac{1}{m} \right)^{nk} \right)^k$$

$k=1 \rightarrow \text{FPR} = 50\%$

2

25%

3

12.5

1

As k decreases, this gets smaller!

Bloom Filter: Optimal Error Rate

To build the optimal hash function, fix m and n !

Claim: The optimal hash function is when $k^* = \ln 2 \cdot \frac{m}{n}$

$$(1) \left(1 - \left(1 - \frac{1}{m} \right)^{nk} \right)^k \approx \left(1 - e^{\frac{-nk}{m}} \right)^k$$

$$(2) \frac{d}{dk} \left(1 - e^{\frac{-nk}{m}} \right)^k \approx \frac{d}{dk} \left(k \ln \left(1 - e^{\frac{-nk}{m}} \right) \right)$$

Bloom Filter: Optimal Error Rate

Claim 1: $\left(1 - \left(1 - \frac{1}{m}\right)^{nk}\right)^k \approx \left(1 - e^{\frac{-nk}{m}}\right)^k$

$$\left(1 - \frac{1}{m}\right)^{nk} = e^{\ln\left[\left(1 - \frac{1}{m}\right)^{nk}\right]}$$

Bloom Filter: Optimal Error Rate

Claim 1: $\left(1 - \left(1 - \frac{1}{m}\right)^{nk}\right)^k \approx \left(1 - e^{\frac{-nk}{m}}\right)^k$

$$\begin{aligned}\left(1 - \frac{1}{m}\right)^{nk} &= e^{\ln\left[\left(1 - \frac{1}{m}\right)^{nk}\right]} \\ &= e^{\ln\left[1 - \frac{1}{m}\right]nk}\end{aligned}$$

Bloom Filter: Optimal Error Rate

Taylor's expansion of $\ln(1 + x)$: $x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots$

"Mercator Series"

$$\left(1 - \frac{1}{m}\right)^{nk} \approx e^{\frac{-nk}{m}}$$

Bloom Filter: Optimal Error Rate

Claim 1: $\left(1 - \left(1 - \frac{1}{m}\right)^{nk}\right)^k \approx \left(1 - e^{\frac{-nk}{m}}\right)^k$

$$\left(1 - \frac{1}{m}\right)^{nk} = e^{\ln\left[\left(1 - \frac{1}{m}\right)^{nk}\right]}$$

$$= e^{\ln\left[1 - \frac{1}{m}\right]nk}$$

$$\approx e^{\frac{-nk}{m}}$$

Bloom Filter: Optimal Error Rate

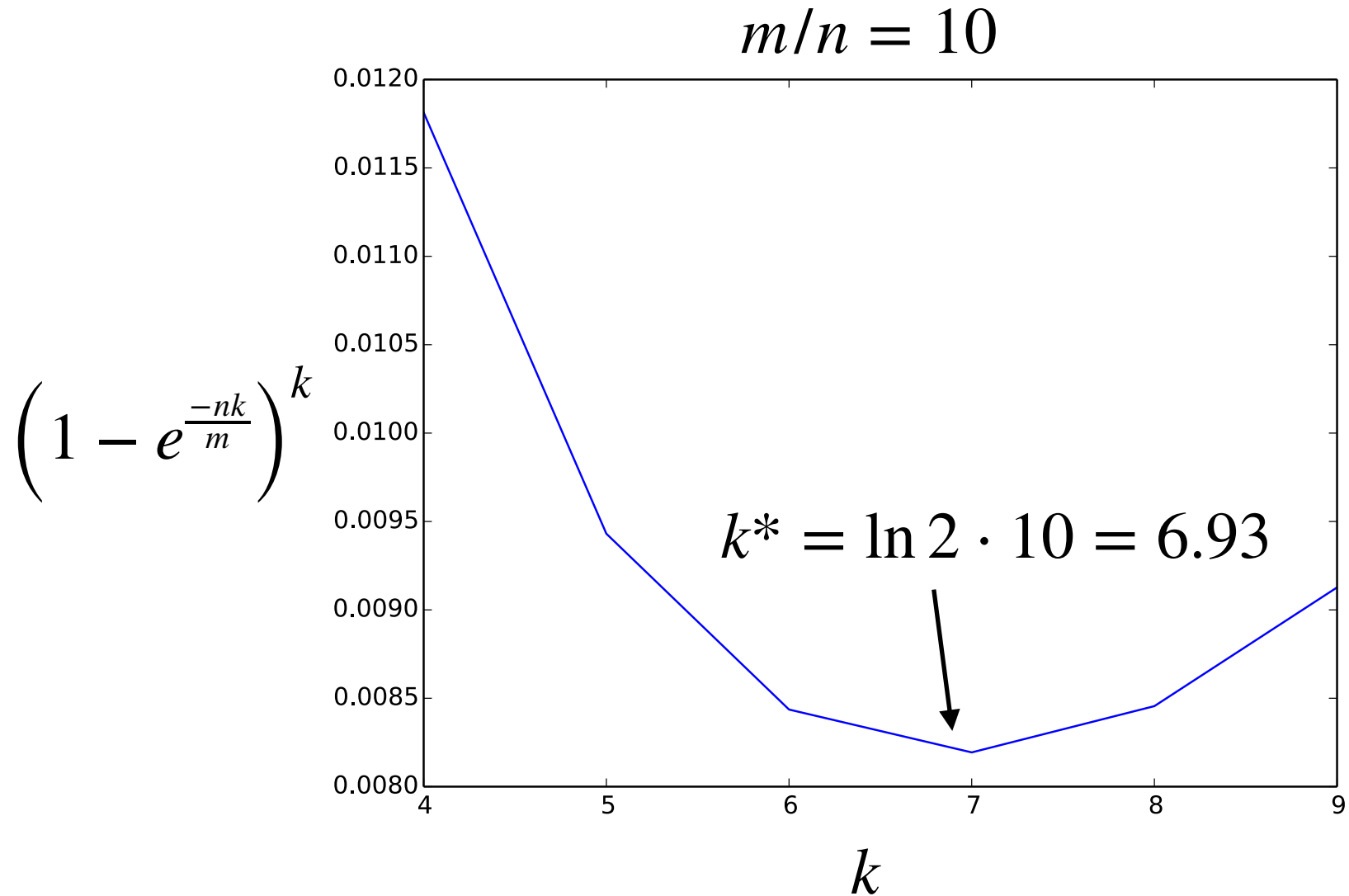
Claim 2: $\frac{d}{dk} \left(1 - e^{-\frac{nk}{m}} \right)^k \approx \frac{d}{dk} \left(k \ln \left(1 - e^{-\frac{nk}{m}} \right) \right)$

Fact: $\frac{d}{dx} \ln f(x) = \frac{1}{f(x)} \frac{df(x)}{dx}$

TL;DR: $\min [f(x)] = \min [\ln f(x)]$

Derivative is zero when $k^* = \ln 2 \cdot \frac{m}{n}$

Bloom Filter: Error Rate



Bloom Filter: Optimal Parameters

$$k^* = \ln 2 \cdot \frac{m}{n}$$

Given any two values, we can optimize the third

$$n = 100 \text{ items} \quad k = 3 \text{ hashes} \quad m =$$

$$m = 100 \text{ bits} \quad n = 20 \text{ items} \quad k =$$

$$m = 100 \text{ bits} \quad k = 2 \text{ items} \quad n =$$

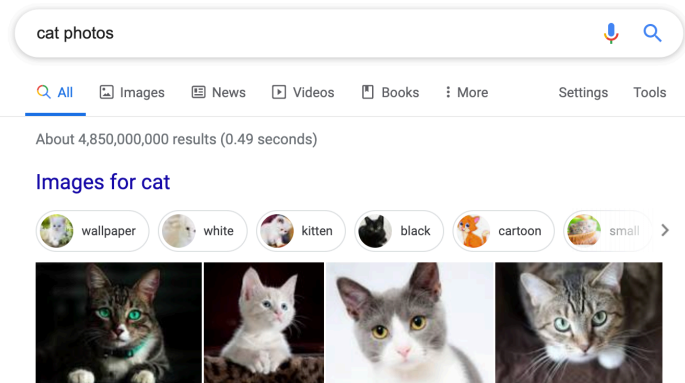
Bloom Filter: Optimal Parameters

$$m = \frac{nk}{\ln 2} \approx 1.44 \cdot nk$$

Optimal hash function is still $O(m)$!



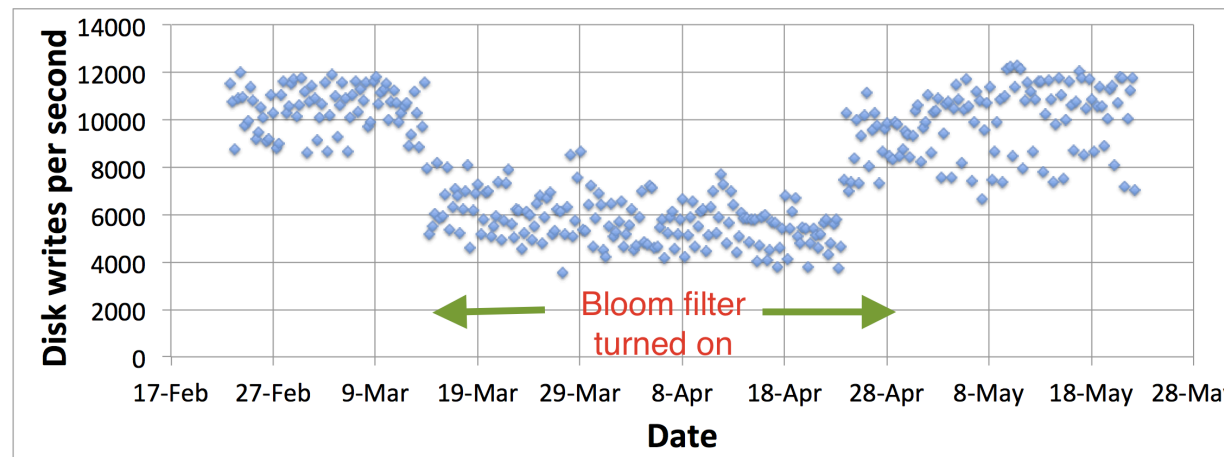
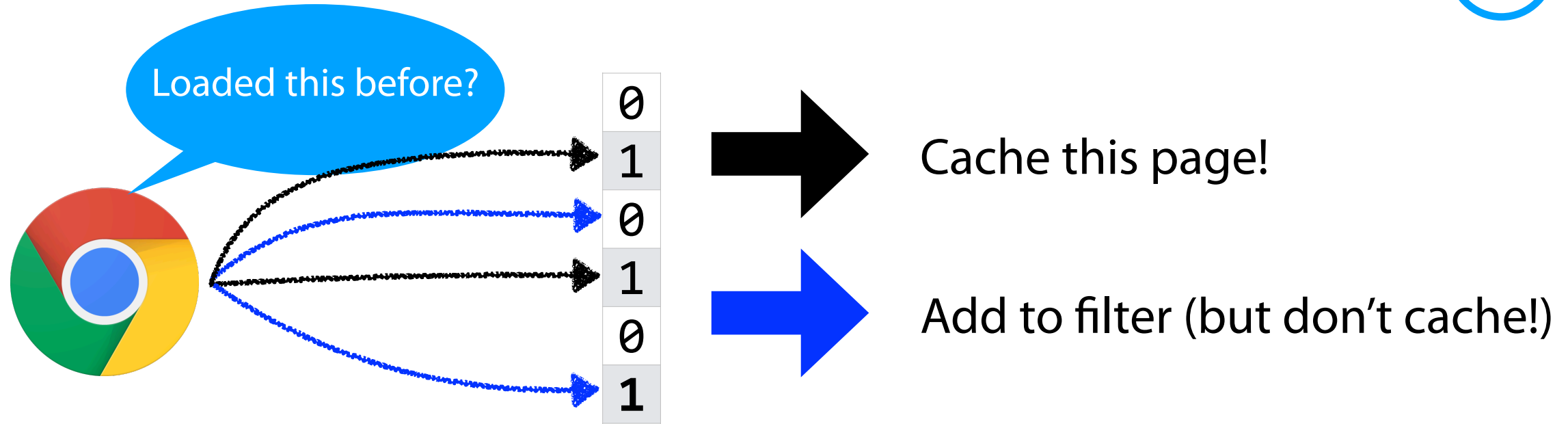
$n = 250,000$ files vs $\sim 10^{15}$ nucleotides vs 260 TB



$n = 60$ billion — 130 trillion



Bloom Filter: Website Caching



Bitwise Operators in C++

How can we encode a bit vector in C++?

Bitwise Operators in C++

Traditionally, bit vectors are read from RIGHT to LEFT

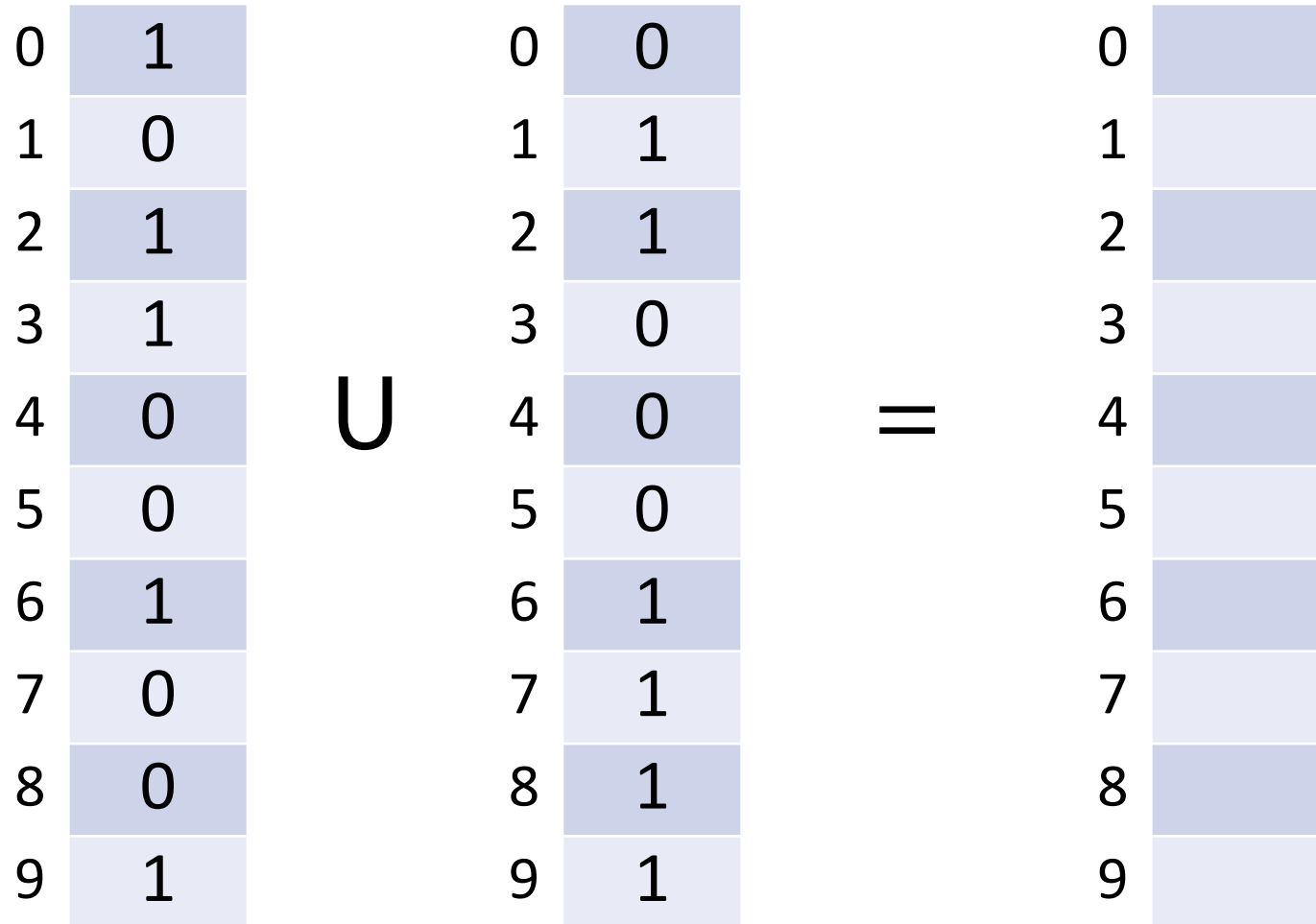
Warning: Lab_Bloom won't do this but MP_Sketching will!

0	0	0	0	1	1	1
---	---	---	---	---	---	---

1	0	0	1	0	1	0
---	---	---	---	---	---	---

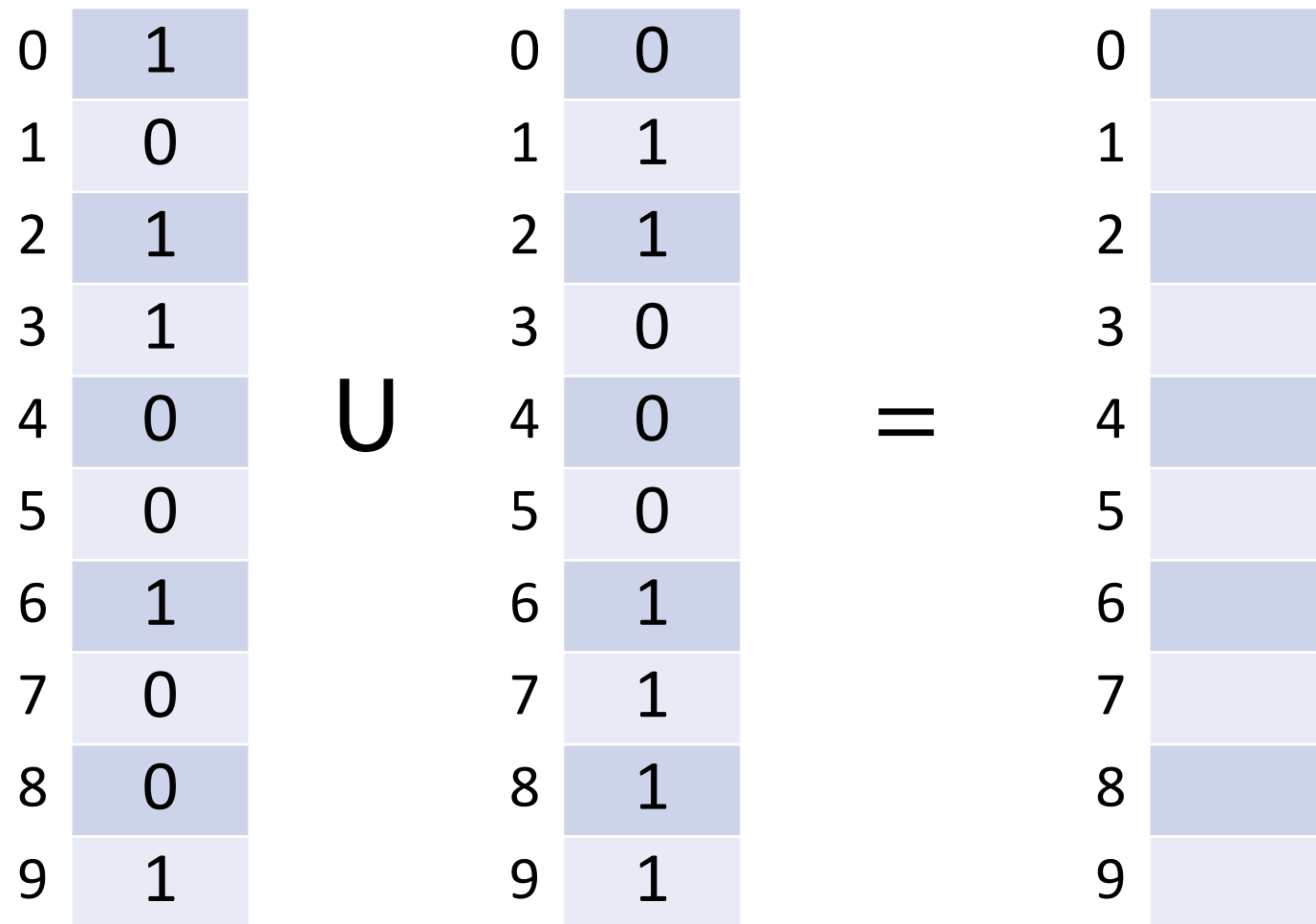
Bloom Filters: Unioning

Bloom filters can be trivially merged using bit-wise union.



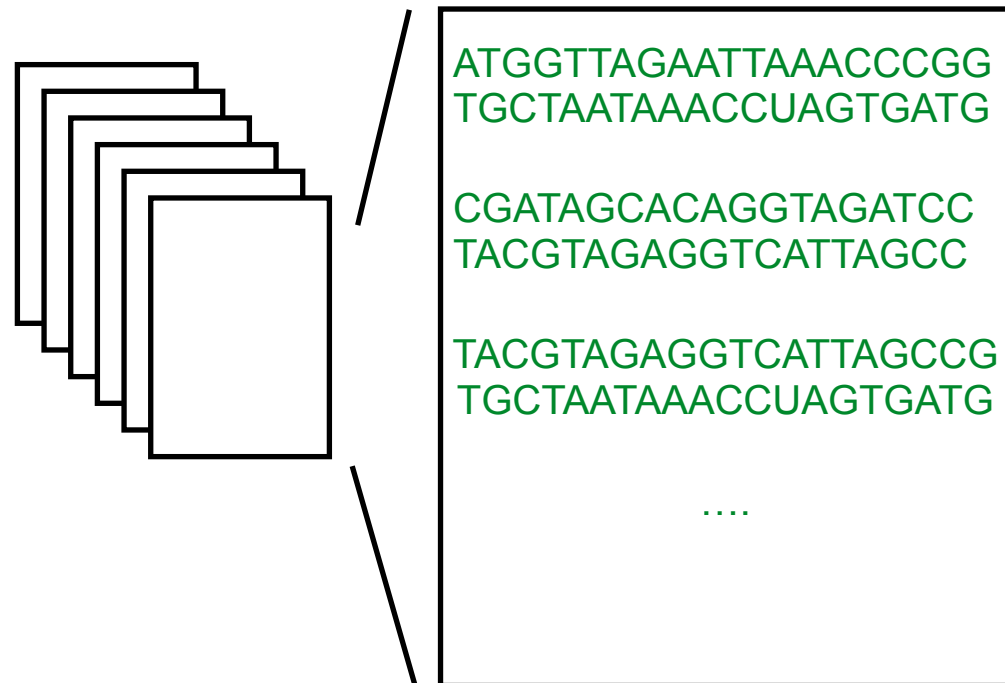
Bloom Filters: Intersection

Bloom filters can be trivially merged using bit-wise intersection.

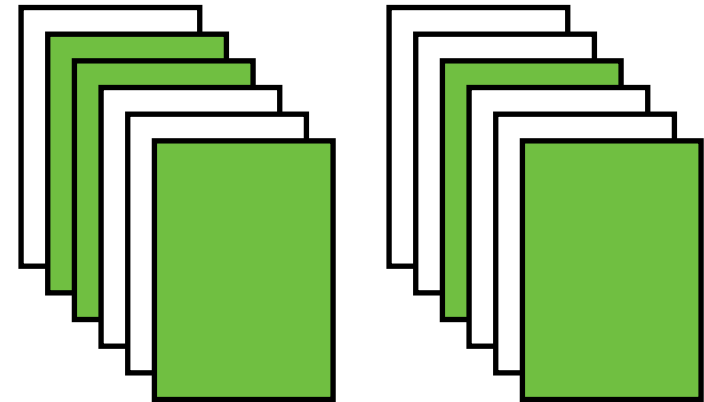


Sequence Bloom Trees

Imagine we have a large collection of text...



And our goal is to search these files for a query of interest...



Bit Vector Merging

What is the conceptual meaning behind **union** and **intersection**?



SRA 00001



SRA 00002



SRA 00003



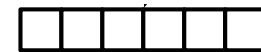
SRA 00004



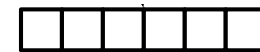
SRA 00005



SRA 00006



SRA 00007

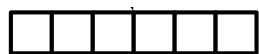


SRA 00008

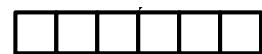
Sequence Bloom Trees



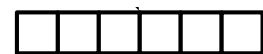
SRA 00001



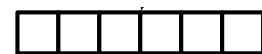
SRA 00002



SRA 00003



SRA 00004



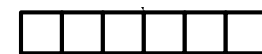
SRA 00005



SRA 00006

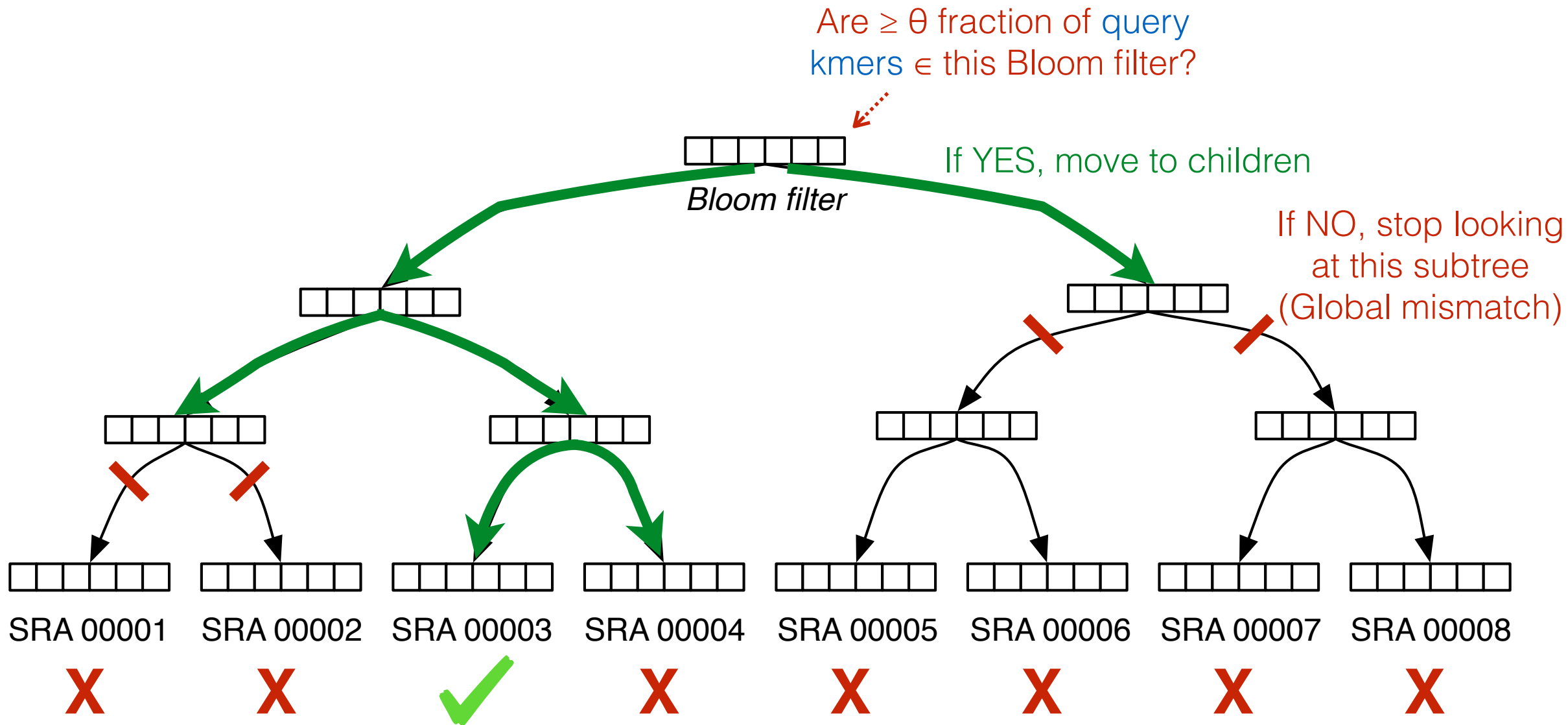


SRA 00007

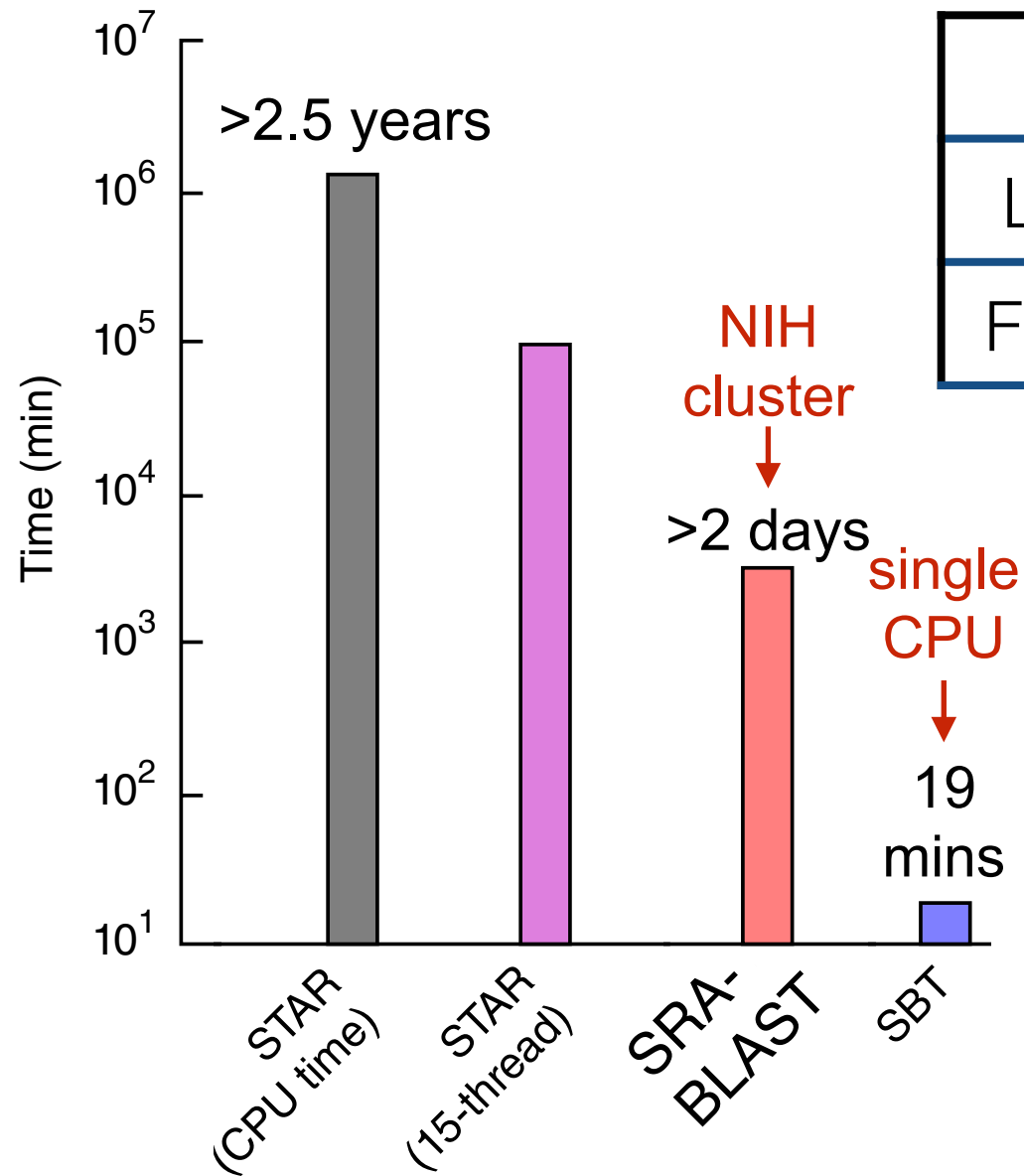


SRA 00008

Sequence Bloom Trees



Sequence Bloom Trees



	SRA	FASTA.gz	SBT
Leaves	4966 GB	2692 GB	63 GB
Full Tree	-	-	200 GB

Solomon, Brad, and Carl Kingsford. "Fast search of thousands of short-read sequencing experiments." *Nature biotechnology* 34.3 (2016): 300-302.

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Bloom Filters: Tip of the Iceberg



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There are many more than shown here...