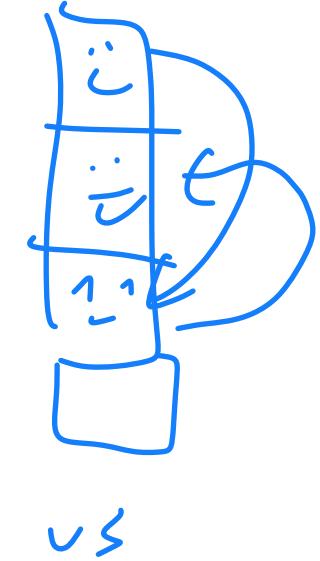


# Data Structures and Algorithms

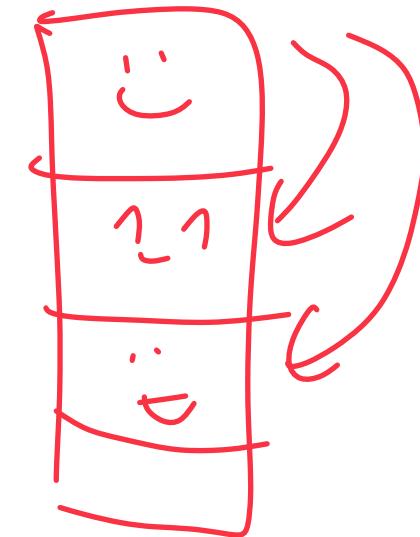
## Hashing 3

CS 225  
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November 15, 2024



vs



Department of Computer Science

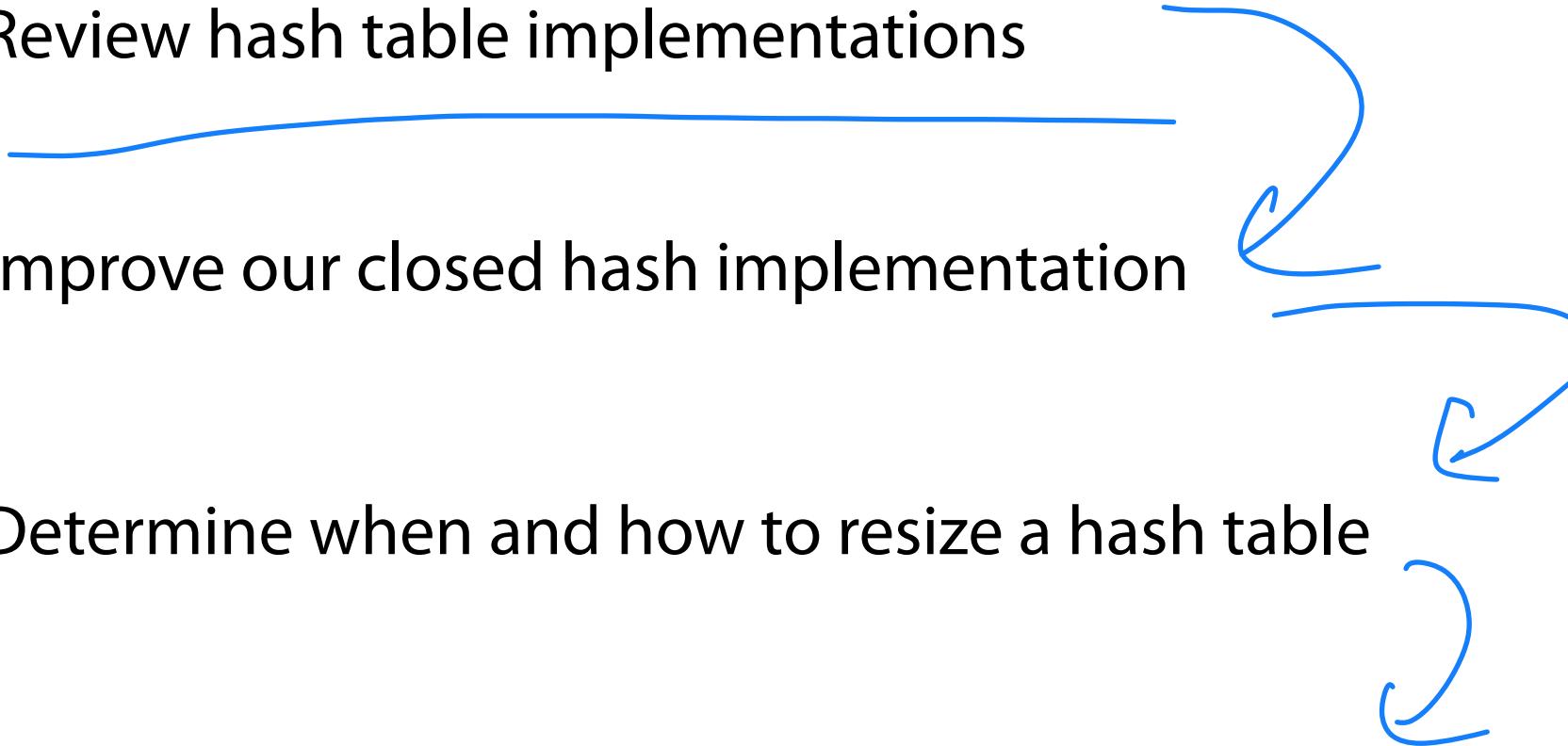
# Learning Objectives

Review hash table implementations

Improve our closed hash implementation

Determine when and how to resize a hash table

Justify when to use different index approaches



# Simple Uniform Hashing Assumption

Given table of size  $m$ , a simple uniform hash,  $h$ , implies

$$\forall k_1, k_2 \in U \text{ where } k_1 \neq k_2, \Pr(h[k_1] = h[k_2]) = \frac{1}{m}$$

**Uniform:** All keys equally likely to hash to any position

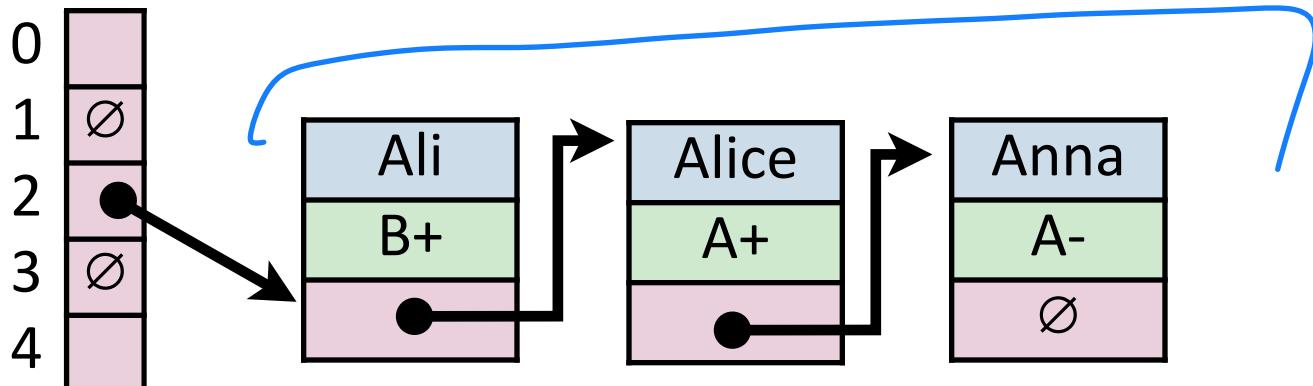
$$\Pr(h[k_1]) = \frac{1}{m}$$

**Independent:** All key's hash values are independent of other keys

# Open vs Closed Hashing

Addressing hash collisions depends on your storage structure.

- **Open Hashing:** store  $k,v$  pairs externally



- **Closed Hashing:** store  $k,v$  pairs in the hash table

0	Anna, A-
1	
2	Ali, B+
3	Alice, A+

# Separate Chaining Under SUHA



Under SUHA, a hash table of size  $m$  and  $n$  elements:

Find runs in:  $O(1+\alpha)$ .

$$\alpha = \frac{n}{m}$$

$\alpha$  Constant we control

Insert runs in:  $O(1)$ .

Remove runs in:  $O(1+\alpha)$ .

0	
1	
2	
3	
4	
5	
6	
7	
8	
9	
10	

expected length  
at every position

Load Factor  $(\alpha)$

00  
00  
00  
02

$1/m$

# Collision Handling: Linear Probing

$$S = \{ 16, 8, 4, 13, 29, 11, 22 \} \quad |S| = n$$

$$h(k) = k \% 7 \quad |\text{Array}| = m$$

0	22
1	8
2	16
3	29
4	4
5	11
6	13

$$h(k, i) = (k + i) \% 7$$

Try  $h(k) = (k + 0) \% 7$ , if full...

Try  $h(k) = (k + 1) \% 7$ , if full...

Try  $h(k) = (k + 2) \% 7$ , if full...

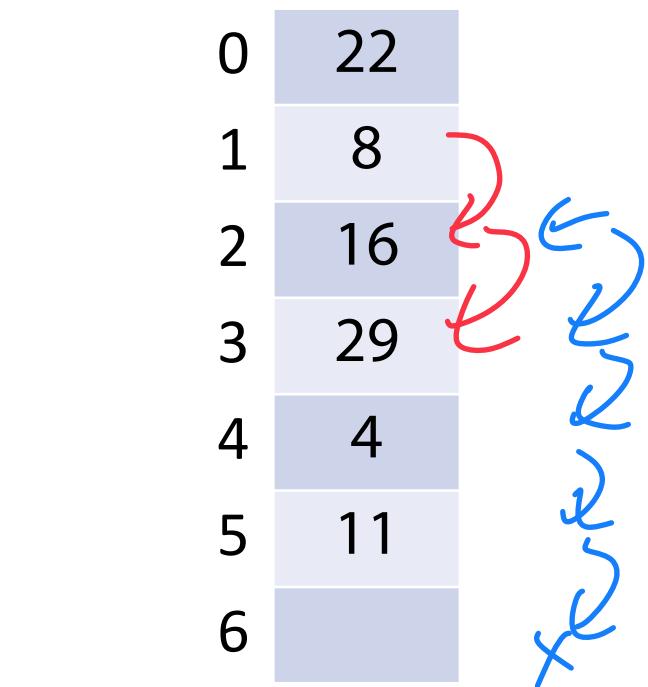
Try ...

Next available space +1

# Collision Handling: Linear Probing

$$S = \{ 16, 8, 4, 13, 29, 11, 22 \} \quad |S| = n$$

$$h(k, i) = (k + i) \% 7 \quad |\text{Array}| = m$$



Find(30)  $30 \% 7 = 2$

## — find(29)

- 1) Hash the input key [  $h(29)=1$  ]
- 2) Look at hash value (address) position  
If present, return (k, v)  
If not look at **next available space**

Ideal  $O(1)$

Stop when:

- 1) We find the object we are looking for
- 2) We have searched every position in the array
- 3) We find a blank space

# Collision Handling: Linear Probing

$$S = \{ 16, 8, 4, 13, 29, 11, 22 \} \quad |S| = n$$

$$h(k, i) = (k + i) \% 7 \quad |\text{Array}| = m$$

0	22
1	8
2	16
3	29
4	4
5	11
6	13

→ 1 ← record that something here only

remove (16)

- 1) Hash the input key [  $h(16)=2$  ]
  - 2) Find the actual location (if it exists)
  - 3) Remove the  $(k, v)$  at hash value (address)
- Don't resize the array! Tombstone!

Find(29)

↳ Blank space stop only if no tombstone

# A Problem w/ Linear Probing



**Primary Clustering:** “Rich get richer”

0	
1	1 <sub>1</sub>
2	1 <sub>2</sub>
3	3 <sub>1</sub>
4	1 <sub>3</sub>
5	3 <sub>2</sub>
6	
7	
8	
9	

## Description:

- Collisions create long runs of filled-in indices
- Should have a  $1/m$  chance to hash anywhere
- Instead have a **(size of cluster) / m** chance to hash at end

If hash value is  $1 \rightarrow 6$   
 $2 \rightarrow 6$   
...  
 $6 \rightarrow 6$

## Remedy:

# A Problem w/ Linear Probing



**Primary Clustering:** “Rich get richer”

0	
1	$1_1$
2	$1_2$
3	$3_1$
4	$1_3$
5	$3_2$
6	
7	
8	
9	

## Description:

Collisions create long runs of filled-in indices

Should have a  $1/m$  chance to hash anywhere

Instead have a **(size of cluster) / m** chance to hash at end

## Remedy:

Pick a better “next available” position!

# Collision Handling: Quadratic Probing

$$S = \{ 16, 8, 4, 13 / 29, 12, 22 \}$$

$$h(k) = k \% 7$$

$$12 \% 7 = 5$$

$$|S| = n$$

$$|\text{Array}| = m$$

One weakness  
 ↪ can be slower than  $m$  to find next available

④	0	12	
	1	8	↖ 1
③ →	2	16	↖ 2+1
	3	22	
	4	4	
⑤ ↑	5	29	↖ 1+4
⑤+1 →	6	13	

$$h(k, i) = (k + i*i) \% 7$$

Try  $h(k) = (k + 0) \% 7$ , if full...

Try  $h(k) = (k + 1*1) \% 7$ , if full...

Try  $h(k) = (k + 2*2) \% 7$ , if full...

Try ...

$$3 \cdot 3$$

$$29 \% 7 = 1$$

$$2$$

$$2+4$$

$$1+9 = 10 \% 7 = 3$$

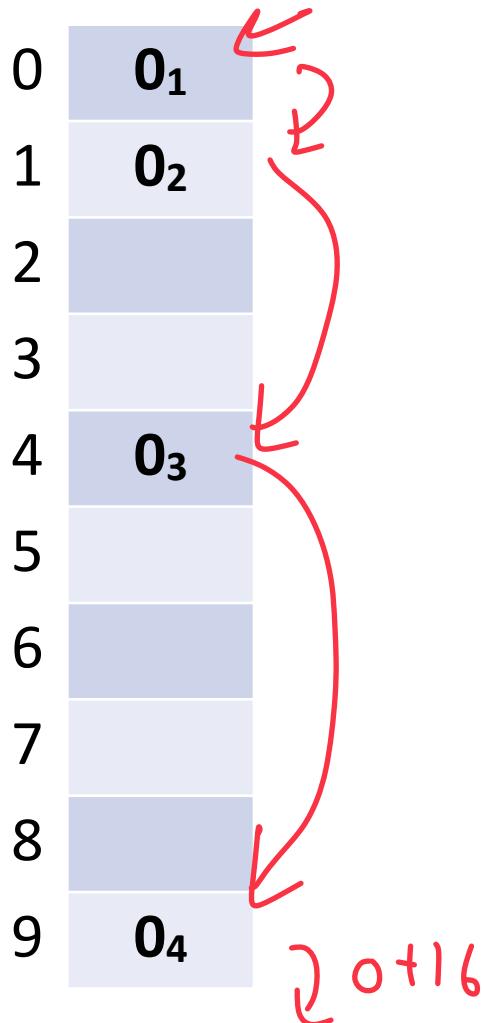
$$(5+4) \% 7 = 2$$

$$(5+9) \% 7 = 0$$

$$29 \% 7 = 1$$

# A Problem w/ Quadratic Probing

**Secondary Clustering:** We haven't solved coll's'ns



## Description:

Imagine 4 keys hash to 0

↳ All will systematically collide

(collisions still form long chains over  
Many positions)

## Remedy:

↳ Be less consistent but still deterministic

# Collision Handling: Double Hashing

$$S = \{ 16, 8, 4, 13 | 29, 11, 22 \}$$

$$h_1(k) = k \% 7$$

$$h_2(k) = 5 - (k \% 5)$$

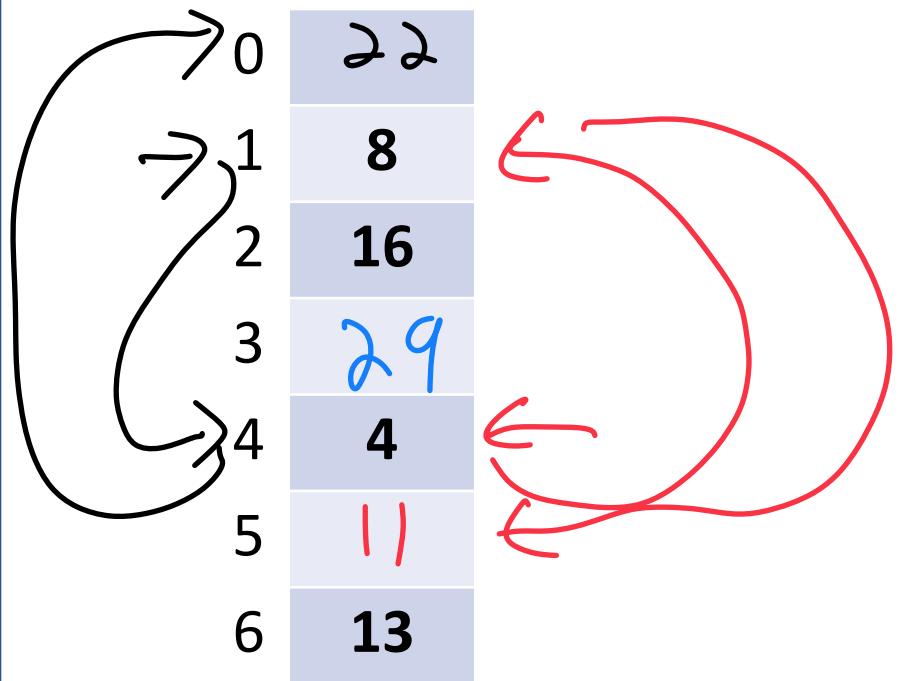
1 4 1

1 4 3

$$|S| = n$$

$$|\text{Array}| = m$$

To work well  
 1) M should be prime  
 2)  $h_2$  needs to be (arbitrarily) independent of  $h_1$



$$h(k, i) = (h_1(k) + i * h_2(k)) \% 7$$

Try  $h(k) = (k + 0 * h_2(k)) \% 7$ , if full...

Try  $h(k) = (k + 1 * h_2(k)) \% 7$ , if full...

Try  $h(k) = (k + 2 * h_2(k)) \% 7$ , if full...

Try ...

$$\underline{29}$$

$$\underline{1}$$

$$\underline{1+1}$$

$$\underline{1+2}$$

$$\underline{11}$$

$$\underline{4}$$

$$\underline{8 \% 7 = 1}$$

$$\underline{18 \% 7 = 5}$$

$$\underline{22}$$

$$\underline{1}$$

$$\underline{1+3}$$

$$(1+3) = 4$$

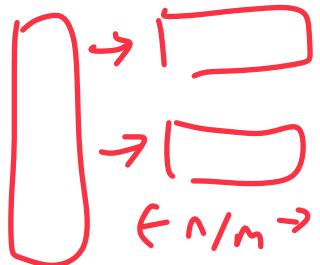
$$1+6 = 7 \% 7 = 0$$

# Running Times

(Expectation under SUHA)

*(Understand why we have these rough forms)*

## Open Hashing:



$$\text{insert: } \underline{\quad 1 \quad}.$$

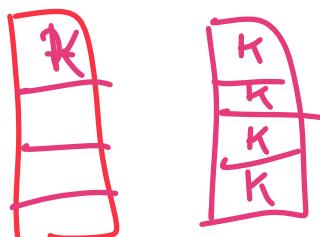
$$\lambda = \text{Load factor} = \frac{n}{m}$$

$$[0 \leq \lambda \leq \infty]$$

$$\text{find/ remove: } \underline{\quad 1 + \lambda \quad}.$$

## Closed Hashing:

$\alpha$ 's load factor



$$\lambda = 0.25 \quad \alpha = 1$$

$$\text{insert: } \underline{\quad \frac{1}{1-\lambda} \quad}.$$

$$[0 \leq \lambda < 1]$$

up to  $m$  items  
( $n$  is at most  $m-1$ )

Runtime:

$$\underline{\quad 1 + 1 \cdot \lambda + 1 \cdot \lambda^2 + 1 \cdot \lambda^3 + \lambda^4 + \dots \quad}$$

flash insert

$$\frac{1}{1-\lambda}$$

Collide once

go

again

Collide twice

$$\text{find/ remove: } \underline{\quad \frac{1}{1-\lambda} \quad}.$$

$$\text{All above } \approx \frac{1}{1-\lambda} \text{ (Taylor series)}$$

# Running Times (Expectation under SUHA)



**Open Hashing:**  $0 \leq \alpha \leq \infty$  (Length of chain)

insert:  $\frac{1}{1 + \alpha}$ .

find/ remove:  $\frac{1 + \alpha}{1 + \alpha}$ .

**Closed Hashing:**  $0 \leq \alpha < 1$  (<sup>fraction</sup><sub>full</sub>)

insert:  $\frac{1}{\frac{1 - \alpha}{1}}$ .

find/ remove:  $\frac{1}{1 - \alpha}$ .

**Observe:**

- As  $\alpha$  increases:

OH:  $\alpha \rightarrow \infty$ , runtime  $\rightarrow \infty$

(H:  $\alpha \rightarrow 1$ , runtime  $\rightarrow \infty$ )

\* - If  $\alpha$  is constant:

OH is constant  
(H is constant)  $\Rightarrow O(1)^*$



# Running Times *(Don't memorize these equations, no need.)*

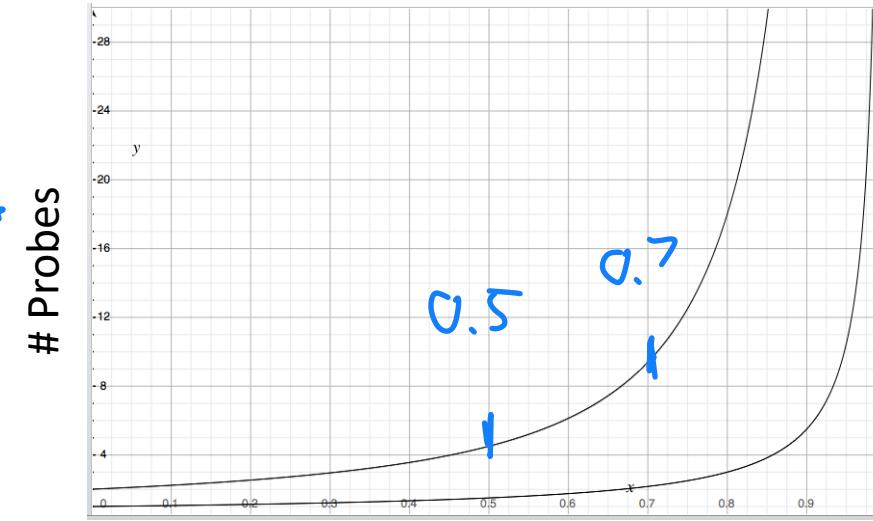
The expected number of probes for  $\text{find}(\text{key})$  under SUHA

$\infty$

## Linear Probing:

- Successful:  $\frac{1}{2}(1 + 1/(1-\alpha))$
- Unsuccessful:  $\frac{1}{2}(1 + 1/(1-\alpha))^2$

Running



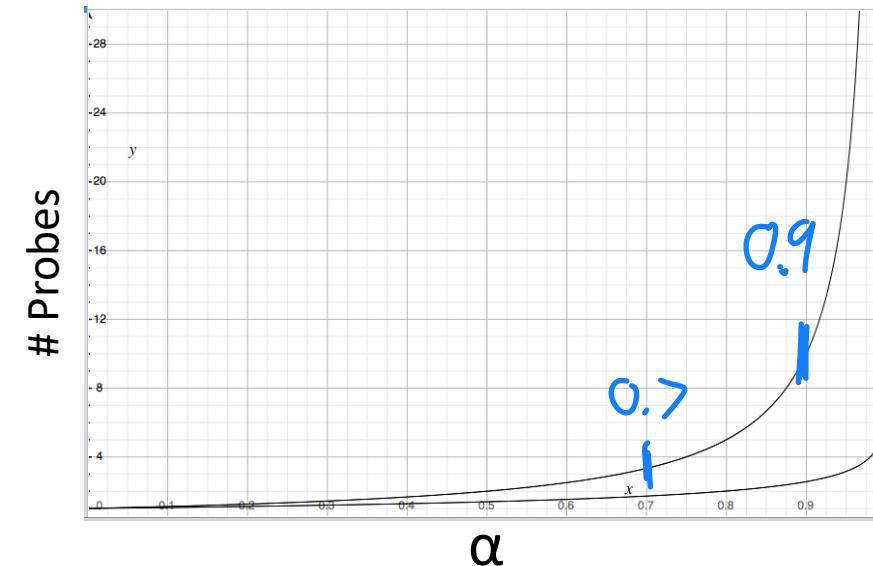
$\alpha$

$\infty$

## Double Hashing:

- Successful:  $1/\alpha * \ln(1/(1-\alpha))$
- Unsuccessful:  $1/(1-\alpha)$

Running



$\alpha$

## When do we resize?

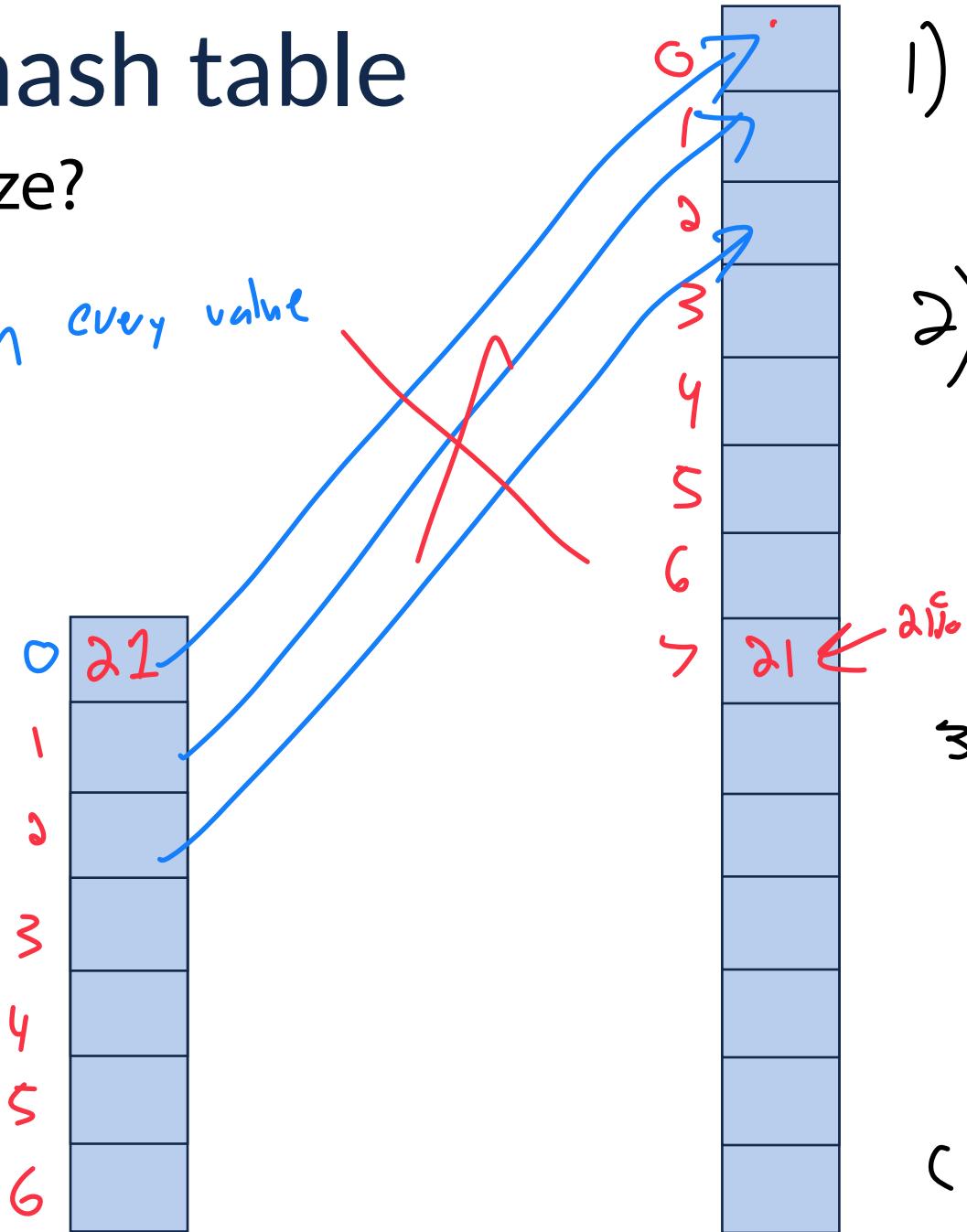
Linear  $\sim 0.7 - 0.8$

Double  $\sim 0.7 - 0.4$

# Resizing a hash table

How do you resize?

- 1) Double array size
- 2) Have to rehash every value



1) Pseudo-amortized  
↳ Resize every  $O(1) \cdot n$

2) SUHA expectation  
↳ Every rehash may be slow

3) Expectation  
↳ This is a probability

(claim)  $O(1)^{***}$

# Which collision resolution strategy is better?

- Big Records:
- Structure Speed:



## What structure do hash tables implement?

## What constraint exists on hashing that doesn't exist with BSTs?

## Why talk about BSTs at all?

# std::map in C++

T& map<K, V>::operator[]

pair<iterator, bool> map<K, V>::insert()

iterator map<K, V>::erase()

iterator map<K, V>::lower\_bound( const K & );

iterator map<K, V>::upper\_bound( const K & );

# std::unordered\_map in C++

```
T& unordered_map<K, V>::operator[]  
pair<iterator, bool> unordered_map<K, V>::insert()  
iterator unordered_map<K, V>::erase()
```

~~```
iterator map<K, V>::lower_bound( const K & );  
iterator map<K, V>::upper_bound( const K & );
```~~  
~~```
float unordered_map<K, V>::load_factor();  
void unordered_map<K, V>::max_load_factor(float m);
```~~

# Running Times



|               | Hash Table   | AVL                   | Linked List      |
|---------------|--|-----------------------|------------------|
| Find          | Expectation*: $\mathcal{O}(1)^{***}$<br>Worst Case: $\mathcal{O}(n)$ | $\mathcal{O}(\log n)$ | $\mathcal{O}(n)$ |
| Insert        | Expectation*: $\mathcal{O}(1)^{***}$<br>Worst Case: $\mathcal{O}(n)$ | $\mathcal{O}(\log n)$ | $\mathcal{O}(1)$ |
| Storage Space | $\mathcal{O}(n)$   | $\mathcal{O}(n)$      | $\mathcal{O}(n)$ |

# Bonus Slides

# Hash Table

Worst-Case behavior is bad — but what about randomness?

1) Fix  $h$ , our hash, and assume it is good for *all keys*:

Simple Uniform Hashing Assumption

(Assume our dataset hashes optimally)

2) Create a *universal hash function family*:

Given a collection of hash functions, pick one randomly

Like **random quicksort** if pick of hash is random, good expectation!

# Hash Function (Division Method)

Hash of form:  $h(k) = k \% m$

**Pro:**

**Con:**

# Hash Function (Mid-Square Method)

Hash of form:  $h(k) = (k * k)$  and take  $b$  bits from middle ( $m = 2^b$ )

# Hash Function (Mid-Square Method)

Hash of form:  $h(k) = (k * k)$  and take  $b$  bits from middle ( $m = 2^b$ )

# Hash Function (Multiplication Method)

Hash of form:  $h(k) = \lfloor m(kA \% 1) \rfloor$ ,  $0 \leq A \leq 1$

**Pro:**

**Con:**

# Hash Function (Universal Hash Family)

Hash of form:  $h_{ab}(k) = ((ak + b) \% p) \% m$ ,  $a, b \in Z_p^*, Z_p$

$$\forall k_1 \neq k_2, \Pr_{a,b}(h_{ab}[k_1] = h_{ab}[k_2]) \leq \frac{1}{m}$$

**Pro:**

**Con:**