

Data Structures

MST 2

CS 225

November 1, 2024

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ILLINOIS
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Learning Objectives

Review the minimum spanning tree (with weights)

Review Kruskal's / Prim's MST Algorithms

Focus on determining Big O of complex pseudocode

Compare implementations under different conditions

Summary: DFS and BFS

$$|V| = n, |E| = m$$

Both are $O(n+m)$ traversals! They label every edge and every node

BFS

Solves unweighted MST

Solves shortest path

Solves cycle detection

Memory bounded by width

DFS

Solves unweighted MST

Solves cycle detection

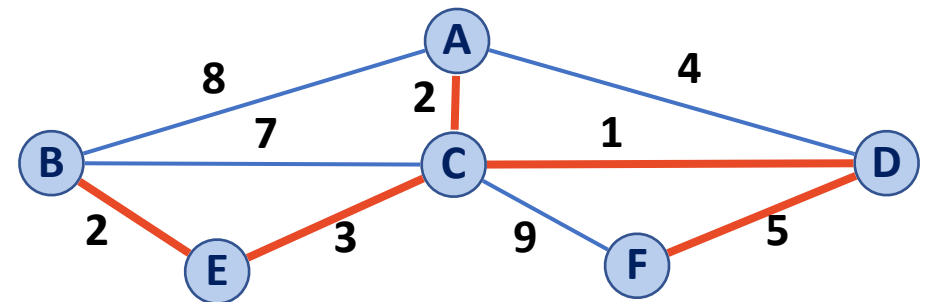
Memory bounded by longest path

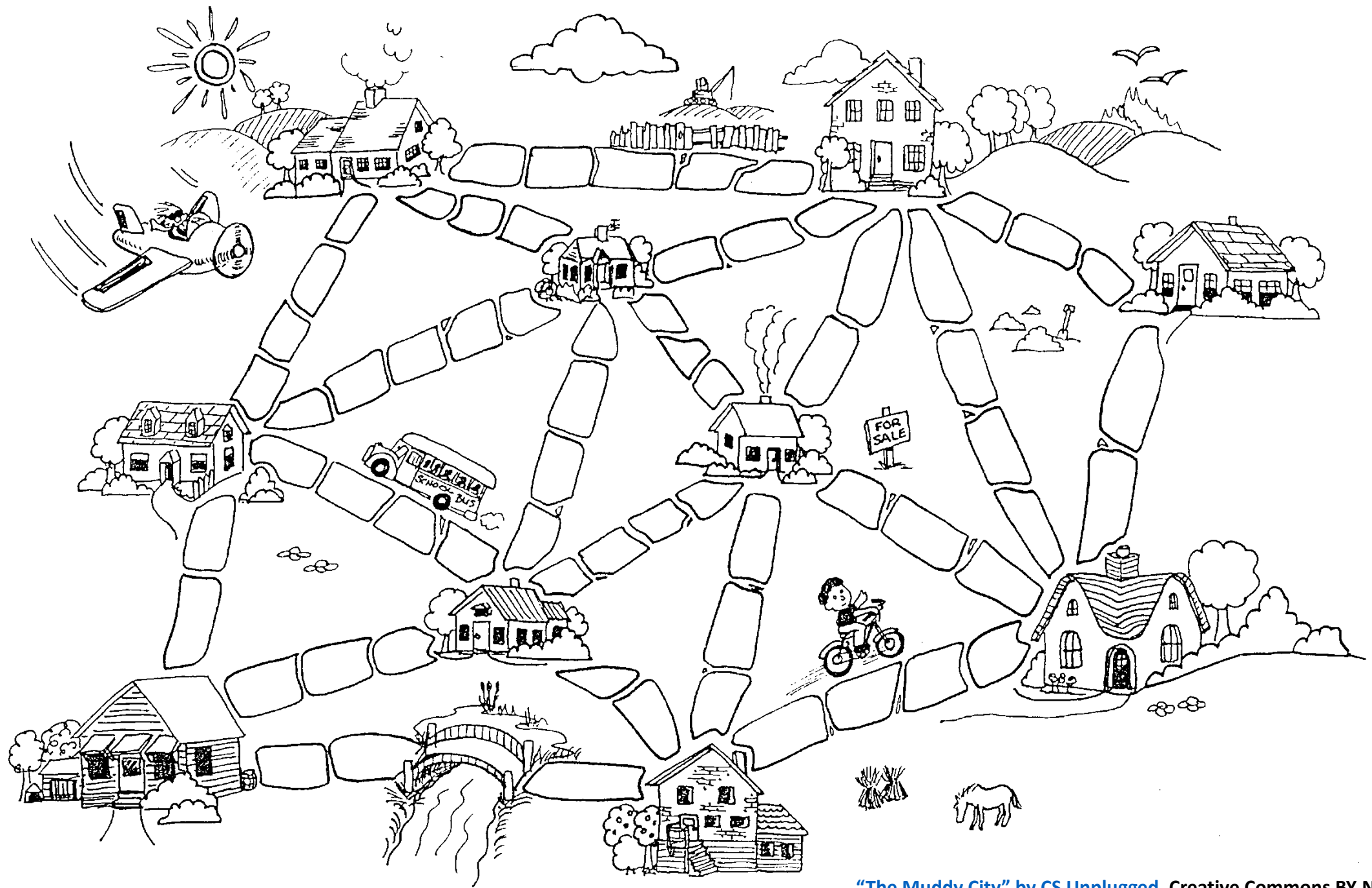
Minimum Spanning Tree Algorithms

Input: Connected, undirected graph G with edge weights (unconstrained, but must be additive)

Output: A graph G' with the following properties:

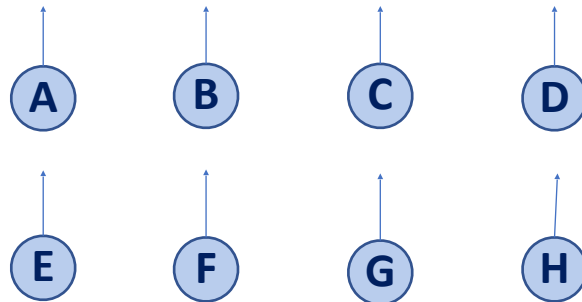
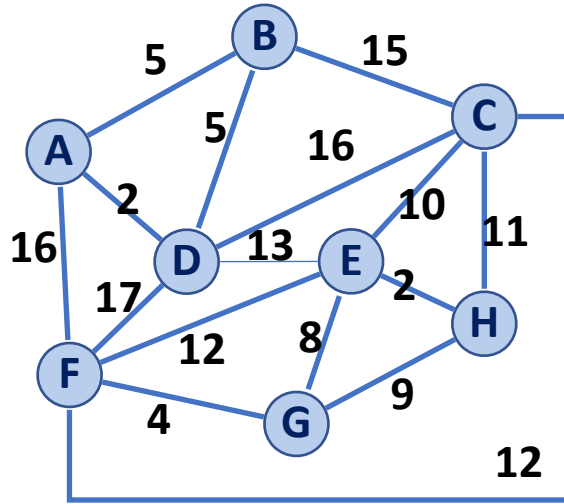
- G' is a spanning graph of G
- G' is a tree (connected, acyclic)
- G' has a minimal total weight among all spanning trees





Kruskal's Algorithm

(A, D)
(E, H)
(F, G)
(A, B)
(B, D)
(G, E)
(G, H)
(E, C)
(C, H)
(E, F)
(F, C)
(D, E)
(B, C)
(C, D)
(A, F)
(D, F)



1) Build a **priority queue** on edges

2) Build a **disjoint set** on vertices

3) Repeatedly find min edge

If edge connects two sets

Union and record edge

4) Stop after $n-1$ edges recorded

Kruskal's Algorithm

```
1 KruskalMST(G):
2   DisjointSets forest
3   foreach (Vertex v : G.vertices()):
4     forest.makeSet(v)
5
6   PriorityQueue Q // min edge weight
7   Q.buildFromGraph(G.edges())
8
9   Graph T = (V, {})
10
11  while |T.edges()| < n-1:
12    Vertex (u, v) = Q.removeMin()
13    if forest.find(u) != forest.find(v):
14      T.addEdge(u, v)
15      forest.union( forest.find(u),
16                  forest.find(v) )
17
18  return T
19
```

1) Build a **priority queue** on edges

2) Build a **disjoint set** on vertices

3) Repeatedly find min edge
If edge connects two sets
Union and record edge

4) Stop after $n-1$ edges recorded

Kruskal's Algorithm

(A, D)

(E, H)

(F, G)

(A, B)

(B, D)

(G, E)

(G, H)

(E, C)

(C, H)

(E, F)

(F, C)

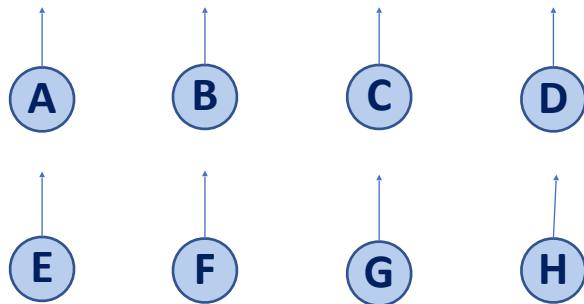
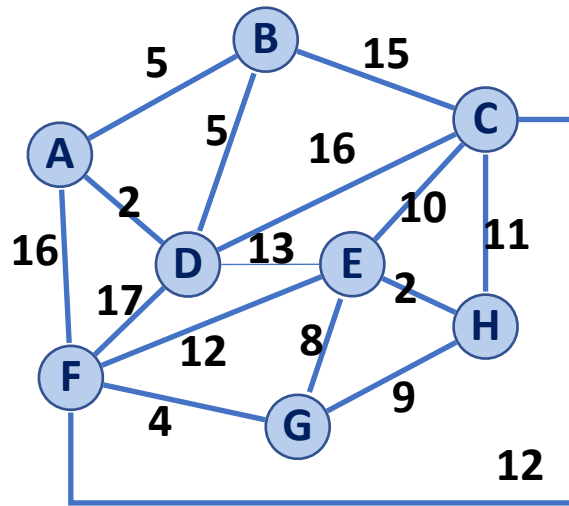
(D, E)

(B, C)

(C, D)

(A, F)

(D, F)



```

1  KruskalMST(G) :
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Kruskal's Algorithm

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```

Kruskal's Algorithm

Priority Queue:	Heap	Sorted Array
Building :7		
Each removeMin :12		

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19
```

Kruskal's Algorithm



Priority Queue:	Total Running Time
Heap	
Sorted Array	

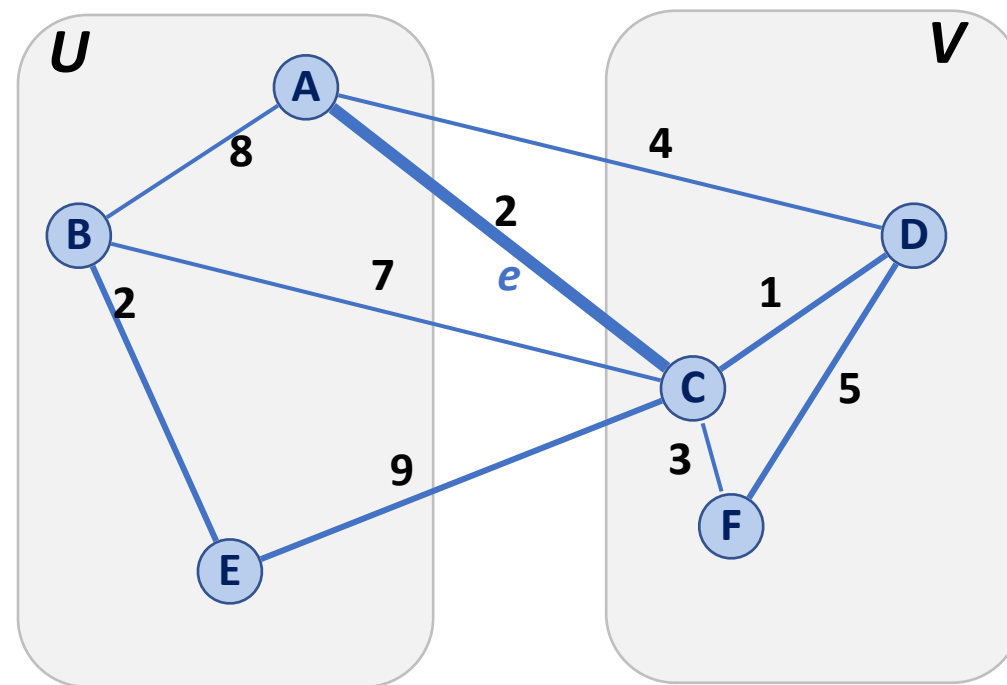
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Partition Property

Consider an arbitrary partition of the vertices on G into two subsets U and V .

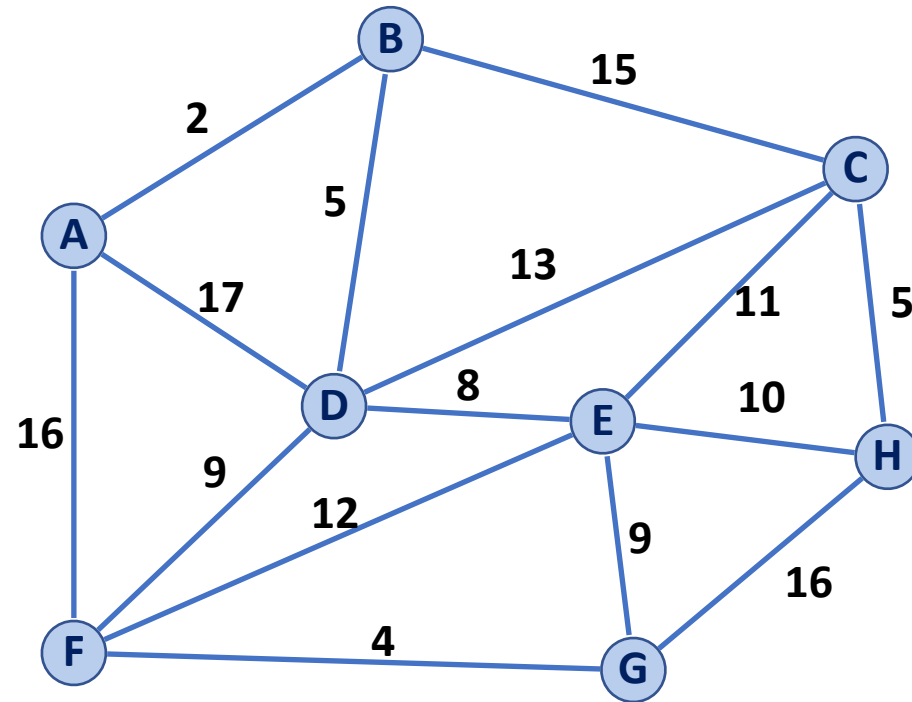
Let e be an edge of minimum weight across the partition.

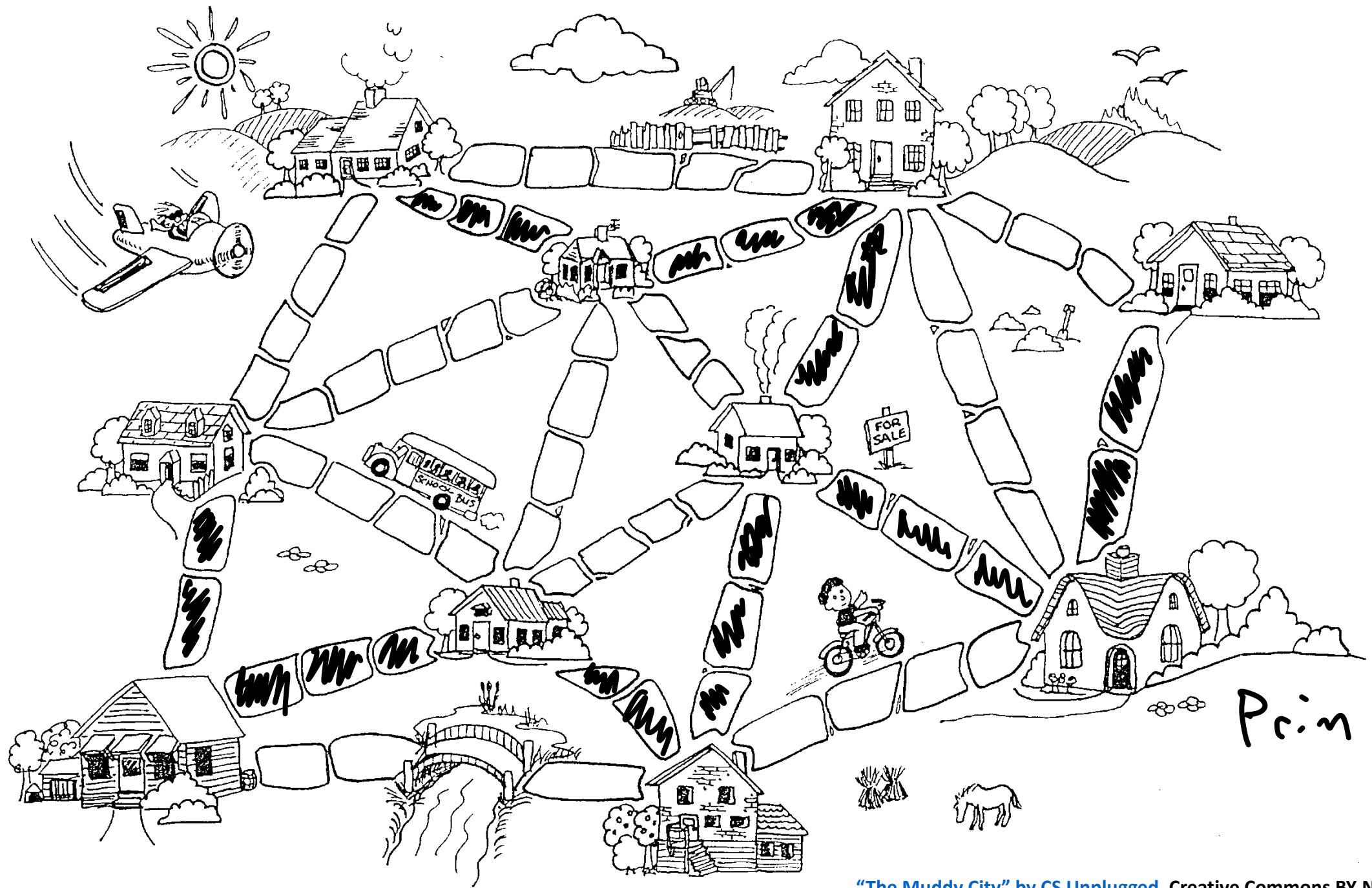
Then e is part of some minimum spanning tree.



Partition Property

The partition property suggests an algorithm:

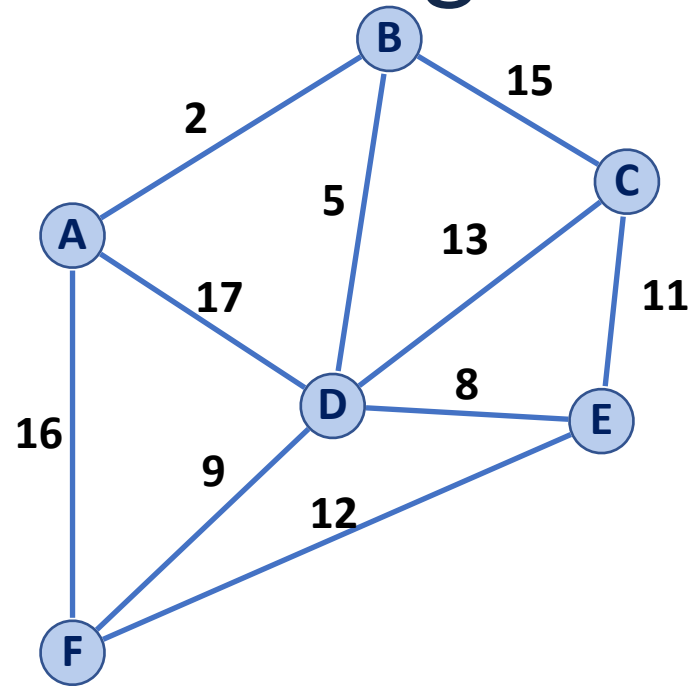




Print



Prim's Algorithm

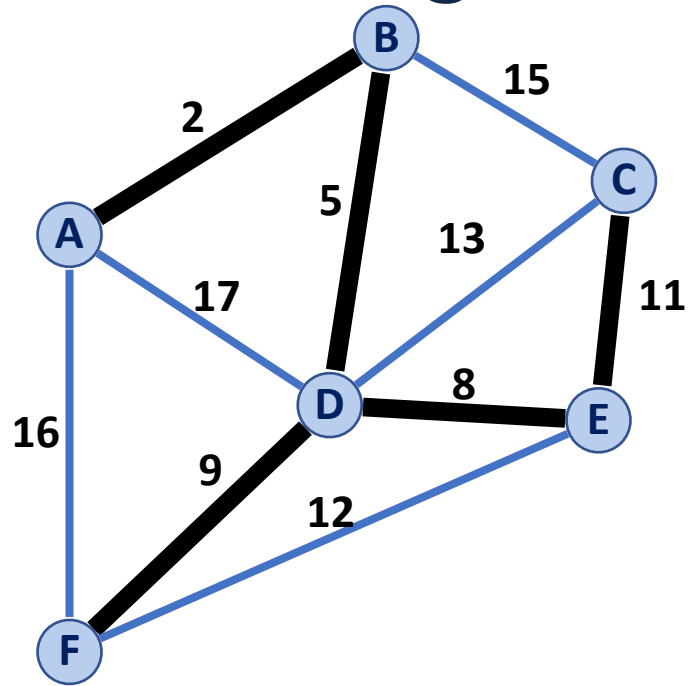


A	B	C	D	E	F

```
1 PrimMST(G, s):
2   Input: G, Graph;
3         s, vertex in G, starting vertex
4   Output: T, a minimum spanning tree (MST) of G
5
6   foreach (Vertex v : G.vertices()):
7     d[v] = +inf
8     p[v] = NULL
9   d[s] = 0
10
11  PriorityQueue Q // min distance, defined by d[v]
12  Q.buildHeap(G.vertices())
13  Graph T // "labeled set"
14
15  repeat n times:
16    Vertex m = Q.removeMin()
17    T.add(m)
18    foreach (Vertex v : neighbors of m not in T):
19      if cost(v, m) < d[v]:
20        d[v] = cost(v, m)
21        p[v] = m
22
23  return T
```



Prim's Algorithm



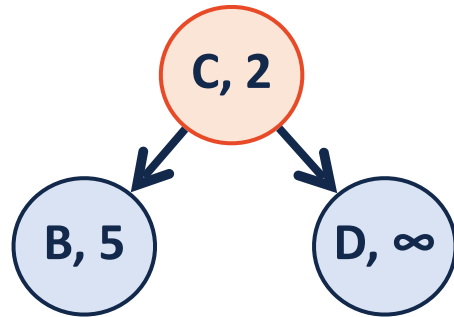
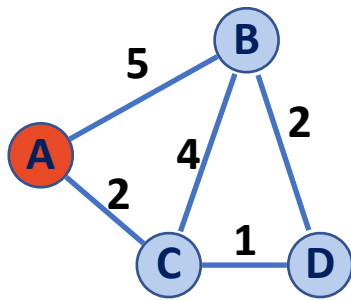
A	B	C	D	E	F
0, —	2, A	11, E	5, B	8, D	9, D

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Prim's Big O

```
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22        p[v] = m
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```

A	B	C	D
0	5	2	∞



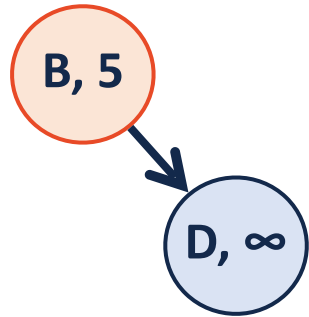
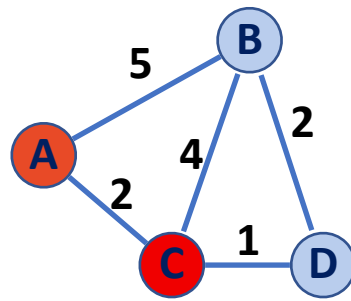
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```

	Adj. Matrix	Adj. List
Heap	$O(n) + \underline{\hspace{2cm}} + O(n^2) + \underline{\hspace{2cm}}$	$O(n) + \underline{\hspace{2cm}} + O(m) + \underline{\hspace{2cm}}$

A	B	C	D
0	5	2, A	∞



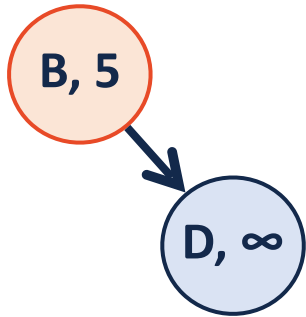
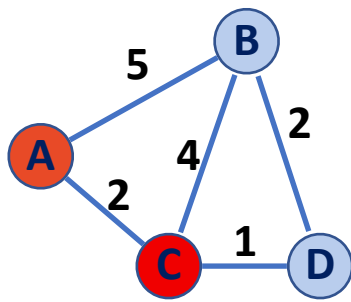
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```

	Adj. Matrix	Adj. List
Heap	$O(n) + O(n \log n) + O(n^2) + \underline{\hspace{2cm}}$	$O(n) + O(n \log n) + O(m) + \underline{\hspace{2cm}}$

A	B	C	D
0	5	2, A	∞



```

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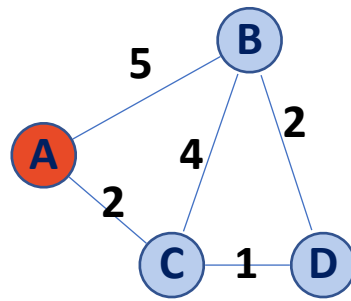
```

1) Change minheap value
2) HeapifyUp()



	Adj. Matrix	Adj. List
Heap	$O(n) + O(n \log n) + O(n^2) + O(m \log n)$	$O(n) + O(n \log n) + O(m) + O(m \log n)$

(A, 0)
(D, ∞)
(C, 2)
(B, 5)



```

6 PrimMST(G, s):
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21        d[v] = cost(v, m)
22        p[v] = m
23

```

	Adj. Matrix	Adj. List
Heap	$O(n^2 + m \lg(n))$	$O(n \lg(n) + m \lg(n))$
Unsorted Array		

Prim's Algorithm

Sparse Graph:

Dense Graph:

```
6 PrimMST(G, s):
7   foreach (Vertex v : G.vertices()):
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9     p[v] = NULL
10  d[s] = 0
11
12  PriorityQueue Q // min distance, defined by d[v]
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21        d[v] = cost(v, m)
22        p[v] = m
23
```



	Adj. Matrix	Adj. List
Heap	$O(n^2 + m \lg(n))$	$O(n \lg(n) + m \lg(n))$
Unsorted Array	$O(n^2)$	$O(n^2)$

MST Algorithm Runtime:

Kruskal's Algorithm:
 $O(n + m \log(n))$

Prim's Algorithm:
 $O(n \log(n) + m \log(n))$

Sparse Graph:

Dense Graph:

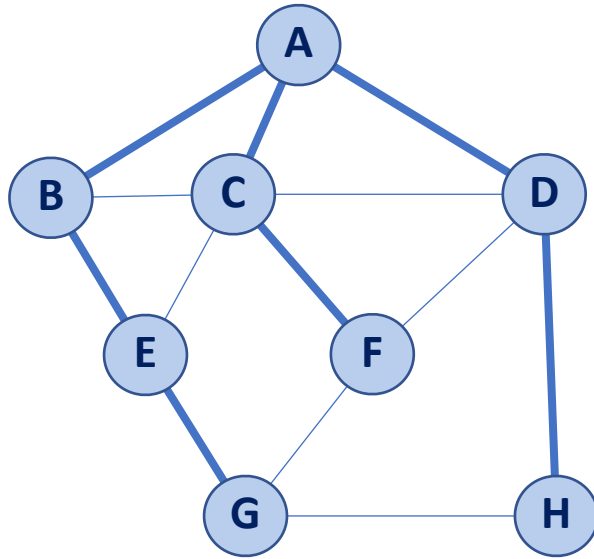
Suppose I have a new heap:

	Binary Heap	Fibonacci Heap
Remove Min	$O(\lg(n))$	$O(\lg(n))$
Decrease Key	$O(\lg(n))$	$O(1)^*$

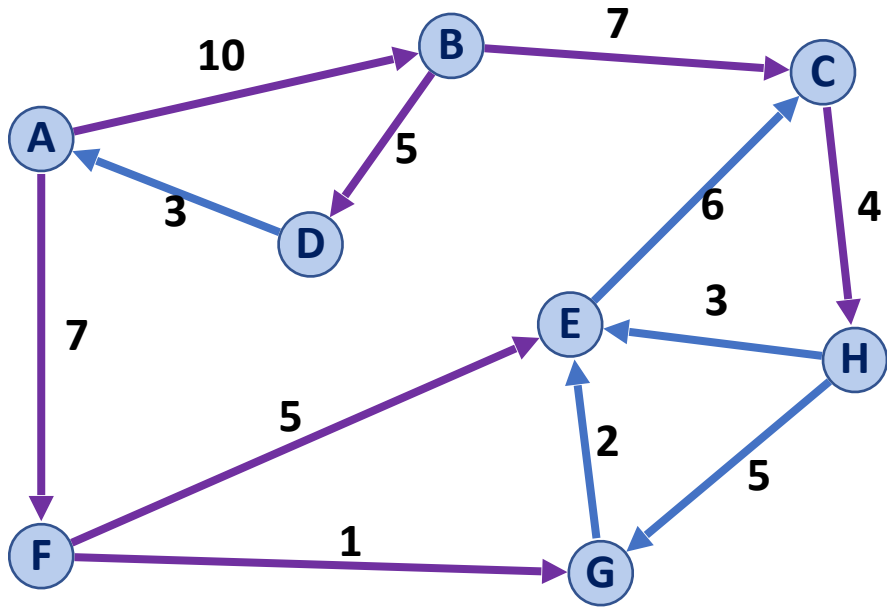
What's the updated running time?

```
PrimMST(G, s):
6  foreach (Vertex v : G.vertices()):
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9      d[s] = 0
10
11  PriorityQueue Q // min distance, defined by d[v]
12  Q.buildHeap(G.vertices())
13  Graph T          // "labeled set"
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15  repeat n times:
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18      foreach (Vertex v : neighbors of m not in T):
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```


Shortest Path



Dijkstra's Algorithm (SSSP)



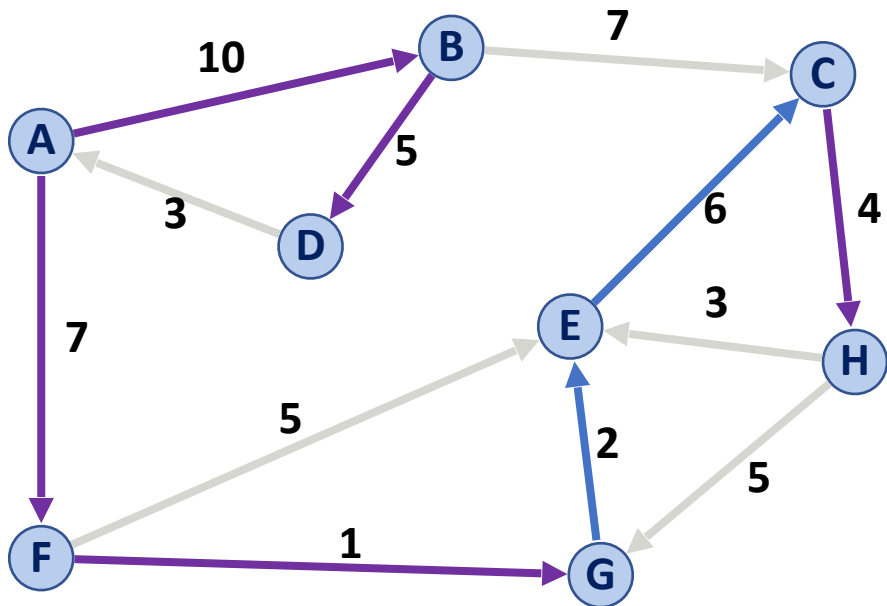
```

DijkstraSSSP(G, s):
6  foreach (Vertex v : G.vertices()):
7    d[v] = +inf
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11  PriorityQueue Q // min distance, defined by d[v]
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13  Graph T          // "labeled set"
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15  repeat n times:
16    Vertex u = Q.removeMin()
17    T.add(u)
18    foreach (Vertex v : neighbors of u not in T):
19      if _____ < d[v]:
20        d[v] = _____
21        p[v] = u
  
```

A	B	C	D	E	F	G	H
--							
0							



Dijkstra's Algorithm (SSSP)



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15  repeat n times:
16      Vertex u = Q.removeMin()
17      T.add(u)
18      foreach (Vertex v : neighbors of u not in T):
19          if cost(u, v) + d[u] < d[v]:
20              d[v] = cost(u, v) + d[u]
21              p[v] = u
```

A	B	C	D	E	F	G	H
--	A	E	B	G	A	F	C
0	10	16	15	10	7	8	20

Dijkstra's Algorithm (SSSP)

What is the running time of Dijkstra's Algorithm?

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