



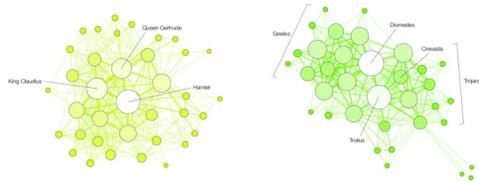
CS 225

Data Structures

October 28 – Minimum Spanning Tree

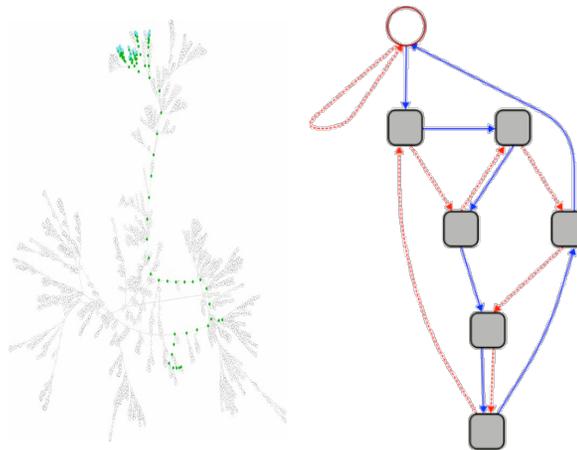
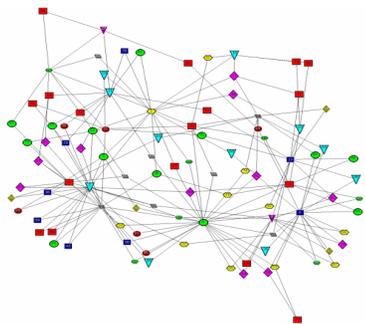
G Carl Evans

Graphs



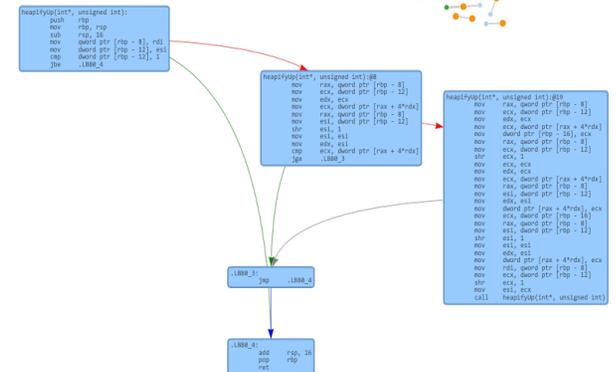
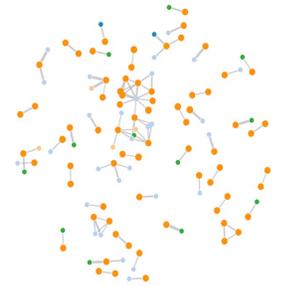
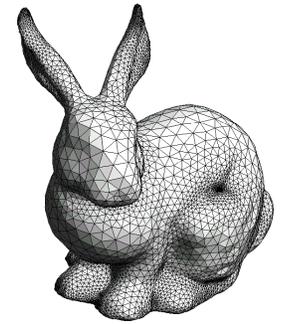
HAMLET

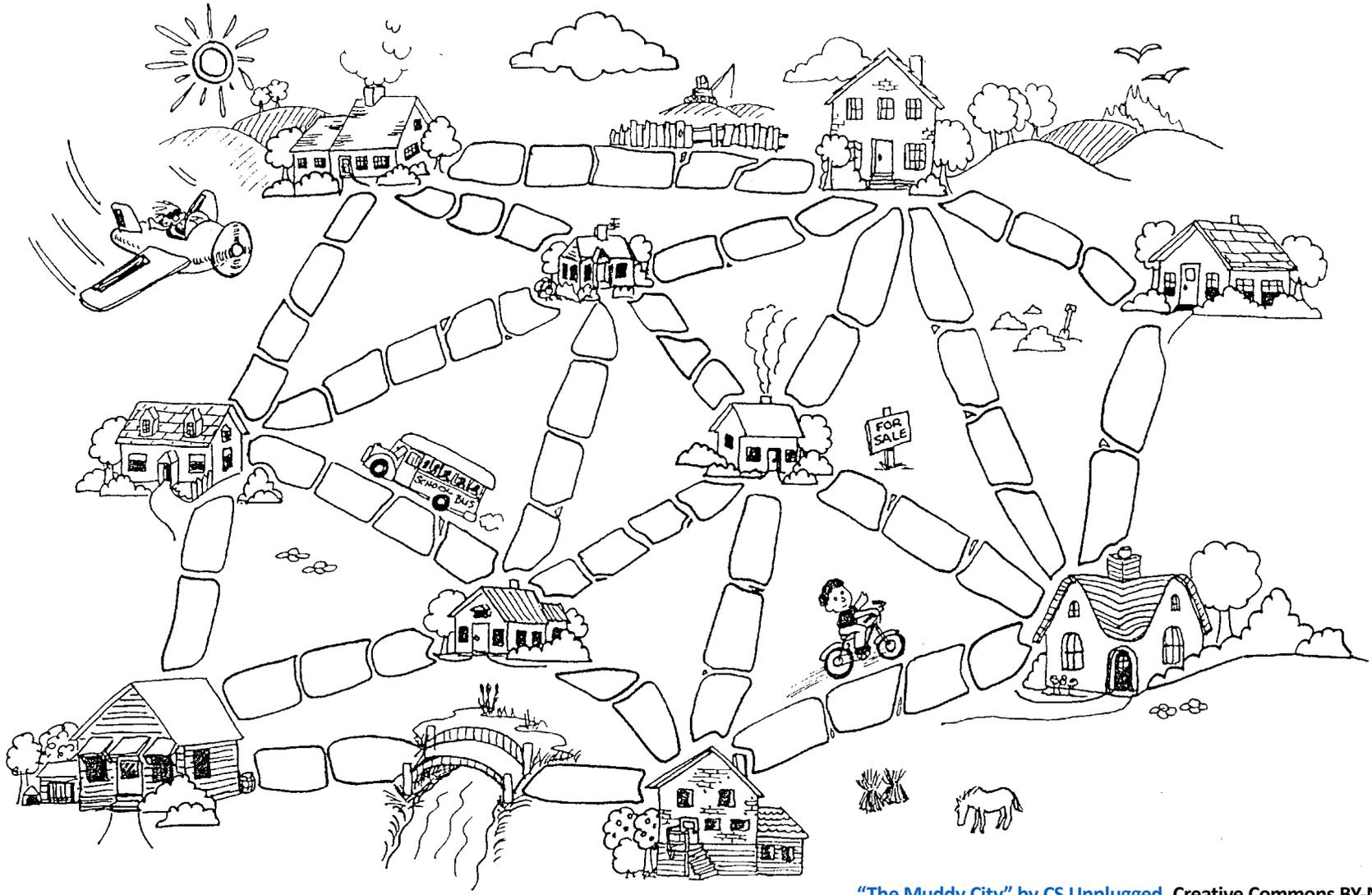
TROILUS AND CRESSIDA



To study all of these structures:

1. A common vocabulary
2. Graph implementations
3. Graph traversals
4. Graph algorithms





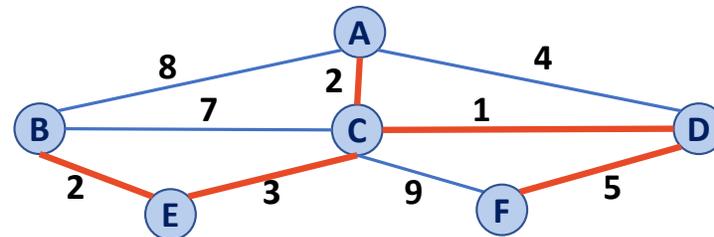
["The Muddy City"](#) by CS Unplugged, Creative Commons BY-NC-SA 4.0

Minimum Spanning Tree Algorithms

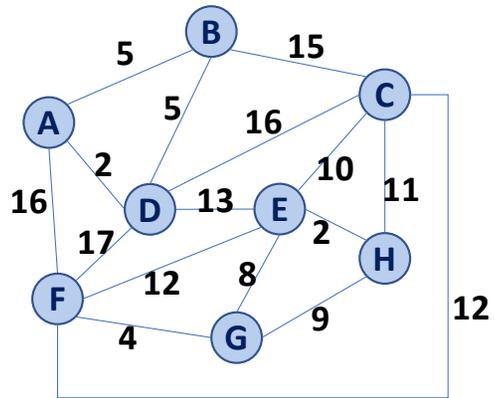
Input: Connected, undirected graph G with edge weights (unconstrained, but must be additive)

Output: A graph G' with the following properties:

- G' is a spanning graph of G
- G' is a tree (connected, acyclic)
- G' has a minimal total weight among all spanning trees

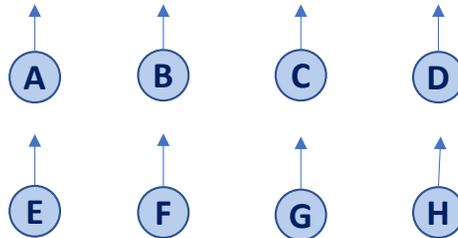
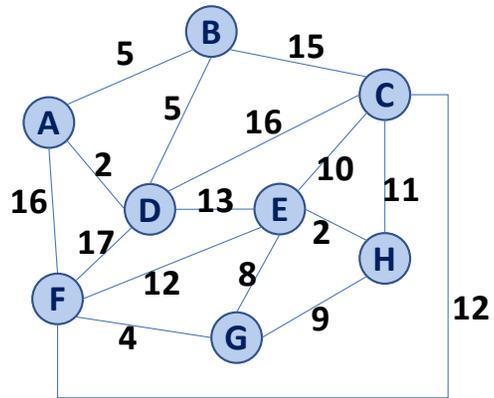


Kruskal's Algorithm



(A, D)
(E, H)
(F, G)
(A, B)
(B, D)
(G, E)
(G, H)
(E, C)
(C, H)
(E, F)
(F, C)
(D, E)
(B, C)
(C, D)
(A, F)
(D, F)

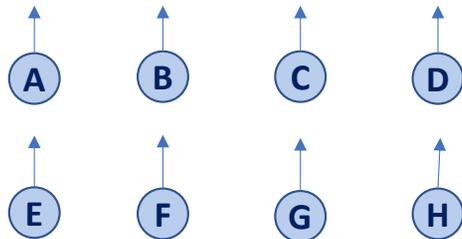
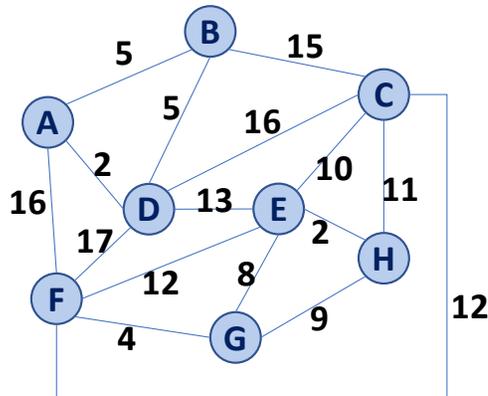
Kruskal's Algorithm



(A, D)
(E, H)
(F, G)
(A, B)
(B, D)
(G, E)
(G, H)
(E, C)
(C, H)
(E, F)
(F, C)
(D, E)
(B, C)
(C, D)
(A, F)
(D, F)

Kruskal's Algorithm

(A, D)
(E, H)
(F, G)
(A, B)
(B, D)
(G, E)
(G, H)
(E, C)
(C, H)
(E, F)
(F, C)
(D, E)
(B, C)
(C, D)
(A, F)
(D, F)



```

1 KruskalMST(G):
2   DisjointSets forest
3   foreach (Vertex v : G):
4     forest.makeSet(v)
5
6   PriorityQueue Q // min edge weight
7   foreach (Edge e : G):
8     Q.insert(e)
9
10  Graph T = (V, {})
11
12  while |T.edges()| < n-1:
13    Vertex (u, v) = Q.removeMin()
14    if forest.find(u) != forest.find(v):
15      T.addEdge(u, v)
16      forest.union( forest.find(u),
17                  forest.find(v) )
18
19  return T

```

Kruskal's Algorithm

Priority Queue:	Heap	Sorted Array
Building :7-9		
Each removeMin :13		

```
1 KruskalMST(G) :
2   DisjointSets forest
3   foreach (Vertex v : G) :
4     forest.makeSet(v)
5
6   PriorityQueue Q    // min edge weight
7   foreach (Edge e : G) :
8     Q.insert(e)
9
10  Graph T = (V, {})
11
12  while |T.edges()| < n-1:
13    Vertex (u, v) = Q.removeMin()
14    if forest.find(u) != forest.find(v) :
15      T.addEdge(u, v)
16      forest.union( forest.find(u),
17                  forest.find(v) )
18
19  return T
```

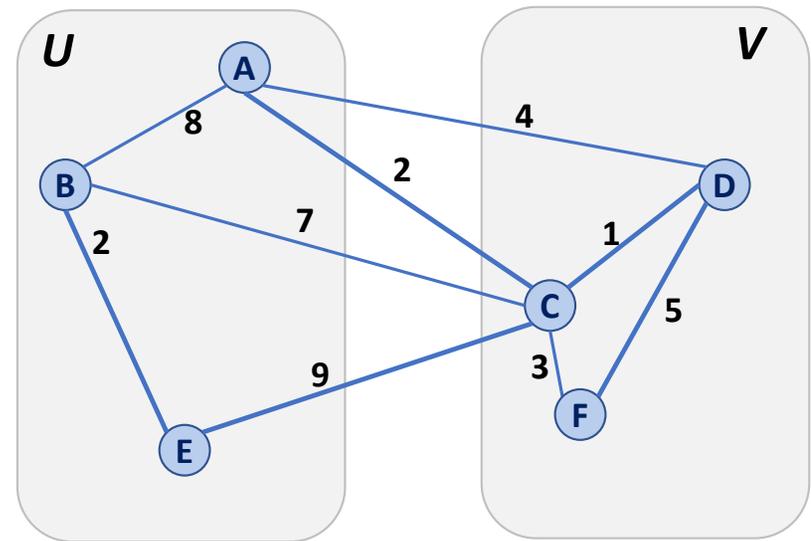
Kruskal's Algorithm

Priority Queue:	Total Running Time
Heap	
Sorted Array	

```
1 KruskalMST(G) :
2   DisjointSets forest
3   foreach (Vertex v : G) :
4     forest.makeSet(v)
5
6   PriorityQueue Q    // min edge weight
7   foreach (Edge e : G) :
8     Q.insert(e)
9
10  Graph T = (V, {})
11
12  while |T.edges()| < n-1:
13    Vertex (u, v) = Q.removeMin()
14    if forest.find(u) != forest.find(v) :
15      T.addEdge(u, v)
16      forest.union( forest.find(u) ,
17                  forest.find(v) )
18
19  return T
```

Partition Property

Consider an arbitrary partition of the vertices on \mathbf{G} into two subsets \mathbf{U} and \mathbf{V} .

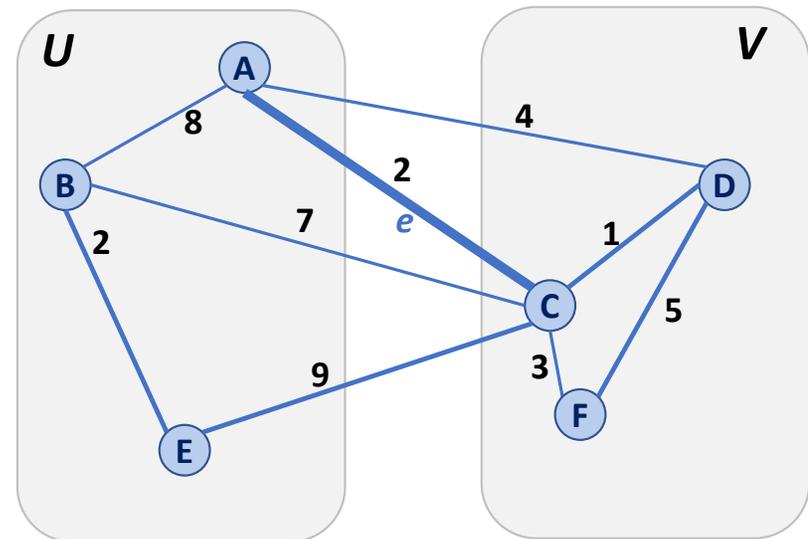


Partition Property

Consider an arbitrary partition of the vertices on \mathbf{G} into two subsets \mathbf{U} and \mathbf{V} .

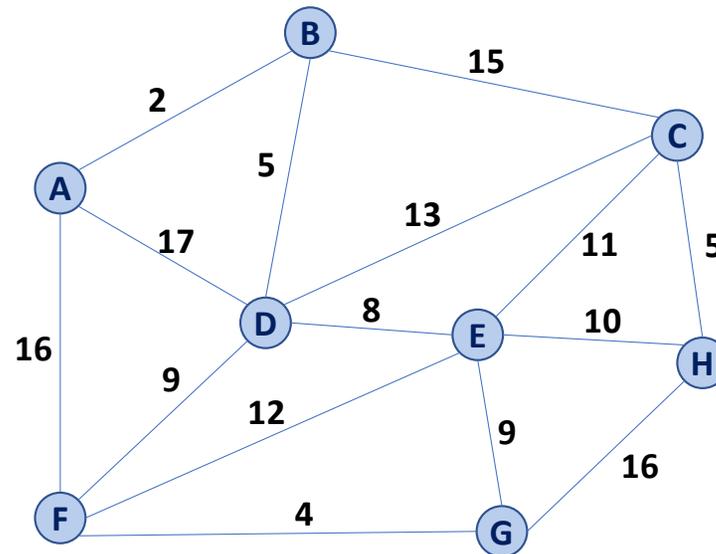
Let \mathbf{e} be an edge of minimum weight across the partition.

Then \mathbf{e} is part of some minimum spanning tree.

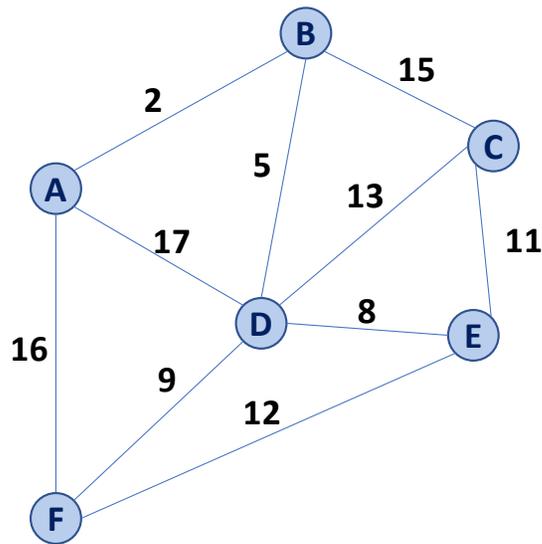


Partition Property

The partition property suggests an algorithm:



Prim's Algorithm



```
1 PrimMST(G, s):
2   Input: G, Graph;
3         s, vertex in G, starting vertex
4   Output: T, a minimum spanning tree (MST) of G
5
6   foreach (Vertex v : G):
7     d[v] = +inf
8     p[v] = NULL
9   d[s] = 0
10
11  PriorityQueue Q // min distance, defined by d[v]
12  Q.buildHeap(G.vertices())
13  Graph T // "labeled set"
14
15  repeat n times:
16    Vertex m = Q.removeMin()
17    T.add(m)
18    foreach (Vertex v : neighbors of m not in T):
19      if cost(v, m) < d[v]:
20        d[v] = cost(v, m)
21        p[v] = m
22
23  return T
```

Prim's Algorithm

```
6 PrimMST(G, s):
7   foreach (Vertex v : G):
8     d[v] = +inf
9     p[v] = NULL
10  d[s] = 0
11
12  PriorityQueue Q // min distance, defined by d[v]
13  Q.buildHeap(G.vertices())
14  Graph T        // "labeled set"
15
16  repeat n times:
17    Vertex m = Q.removeMin()
18    T.add(m)
19    foreach (Vertex v : neighbors of m not in T):
20      if cost(v, m) < d[v]:
21        d[v] = cost(v, m)
22        p[v] = m
```

	Adj. Matrix	Adj. List
Heap		
Unsorted Array		

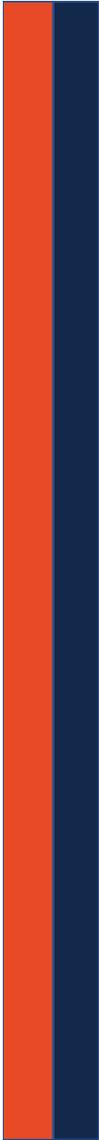
Prim's Algorithm

Sparse Graph:

Dense Graph:

```
6 PrimMST(G, s):
7   foreach (Vertex v : G):
8     d[v] = +inf
9     p[v] = NULL
10  d[s] = 0
11
12  PriorityQueue Q // min distance, defined by d[v]
13  Q.buildHeap(G.vertices())
14  Graph T          // "labeled set"
15
16  repeat n times:
17    Vertex m = Q.removeMin()
18    T.add(m)
19    foreach (Vertex v : neighbors of m not in T):
20      if cost(v, m) < d[v]:
21        d[v] = cost(v, m)
22        p[v] = m
```

	Adj. Matrix	Adj. List
Heap	$O(n^2 + m \lg(n))$	$O(n \lg(n) + m \lg(n))$
Unsorted Array	$O(n^2)$	$O(n^2)$



MST Algorithm Runtime:

- Kruskal's Algorithm:

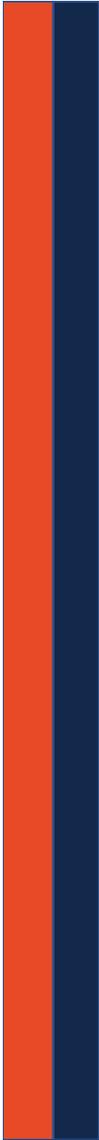
$$O(n + m \lg(n))$$

- Prim's Algorithm:

$$O(n \lg(n) + m \lg(n))$$

- What must be true about the connectivity of a graph when running an MST algorithm?

- How does n and m relate?



MST Algorithm Runtime:

- Kruskal's Algorithm:
 $O(n + m \lg(n))$

- Prim's Algorithm:
 $O(n \lg(n) + m \lg(n))$