

# Lectures 6&7



# What will I learn in this lecture?

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**Dynamics, two examples of the use of `ode45`.**

**Numeric Integration using `trapz` and `quad/quadl` functions.**

**Readings: Matlab by Pratap Chapter 5.4,5.5**



# Dynamics: time evolution of physical processes

## 1. Problem Definition

Use Matlab to plot the velocity of a free-falling object. Assume that the object is near the earth's surface, so that the force due to gravity is given by mass \* g where  $9.8 \text{ m/s}^2$ . Further assume that air friction is present and that the force due to air friction satisfies  $F_{\text{air friction}} = b * v^2$ , where b is constant and v is the velocity of the falling object (downward is negative velocity).

## 2. Refine, Generalize, Decompose the problem definition (i.e., identify sub-problems, I/O, etc.)

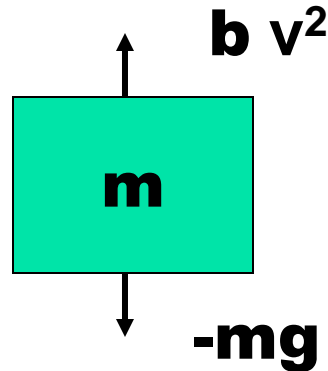
Mass of object is 70Kg , acceleration due to gravity is  $-9.8 \text{ m/s}^2$  and the coefficient of air friction  $b = .25 \text{ Kg/s}$ . At time = 0 assume  $v=0$ , that is,

$$v(0) = 0 \quad (\text{initial condition})$$

# Falling object

## 2. (continued)

From Newton's 2<sup>nd</sup> law, the sum of the forces on the falling object equal it's mass times acceleration:



$$m * \frac{dv(t)}{dt} = -m * g + b * v^2(t)$$

$$\frac{dv(t)}{dt} = -g + (b/m) * v^2(t)$$

# Falling object

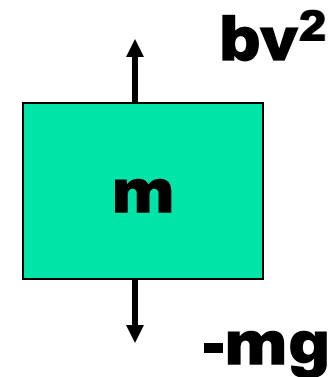
## 2. (continued)

Using calculus we can rewrite the differential equation in the form:

$$dv = \left( -g + \frac{b}{m} * v^2(t) \right) dt$$

and integration of both sides gives,

$$v(t) = -\sqrt{\frac{mg}{b}} \tanh\left( \frac{gt}{\sqrt{\frac{mg}{b}}} \right)$$



# Falling object

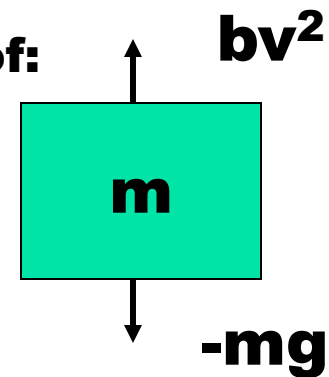
## 2. (continued)

Since we can write  $\tanh(x)$  as:

$$\tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}} = \frac{1 - e^{-2x}}{1 + e^{-2x}}$$

when  $x \rightarrow \text{infinity}$   $\tanh(x) \rightarrow 1$  and so  
the falling body has a terminal velocity of:

$$v(\infty) = -\sqrt{\frac{mg}{b}}$$





# Matlab ode45 function

## 3. Develop Algorithm (processing steps to solve problem)

Rather than using calculus to solve this problem we can use a built-in Matlab function... ode45. The format of this function is:

**[t, v] = ode45(@aux\_function, time, initial\_condition);**

**aux\_function:** user created function that computes the derivate

**time:** a vector [start, stop] for the range of time of the solution

**initial\_condition:** initial value v(start)

**t:** solution column vector of time values on range [start, stop]

**v:** solution column vector velocity values at times t



# Falling object

## 4. Write the “Function” (Code)

(instruction sequence to be carried out by the computer)

Use the Matlab editor to create a file `vprime.m` .

```
function vp = vprime(t,v)
```

```
% function vp = vprime(t,v)
```

```
% compute dv/dt
```

```
m = 70;
```

```
g = 9.8;
```

```
b = .25;
```

```
vp = -g +(b/m)*v.^2;
```

$$\frac{dv(t)}{dt} = -g + (b/m) * v^2(t)$$





# Falling object

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## 5. Test and Debug the Code

To test our program in Matlab, we will plot velocity versus time for  $t=0$  seconds to  $t=10$  seconds,

```
plot(t,v)
```

## 6. Run Code

To run our program we will use 'ode45' as follows:

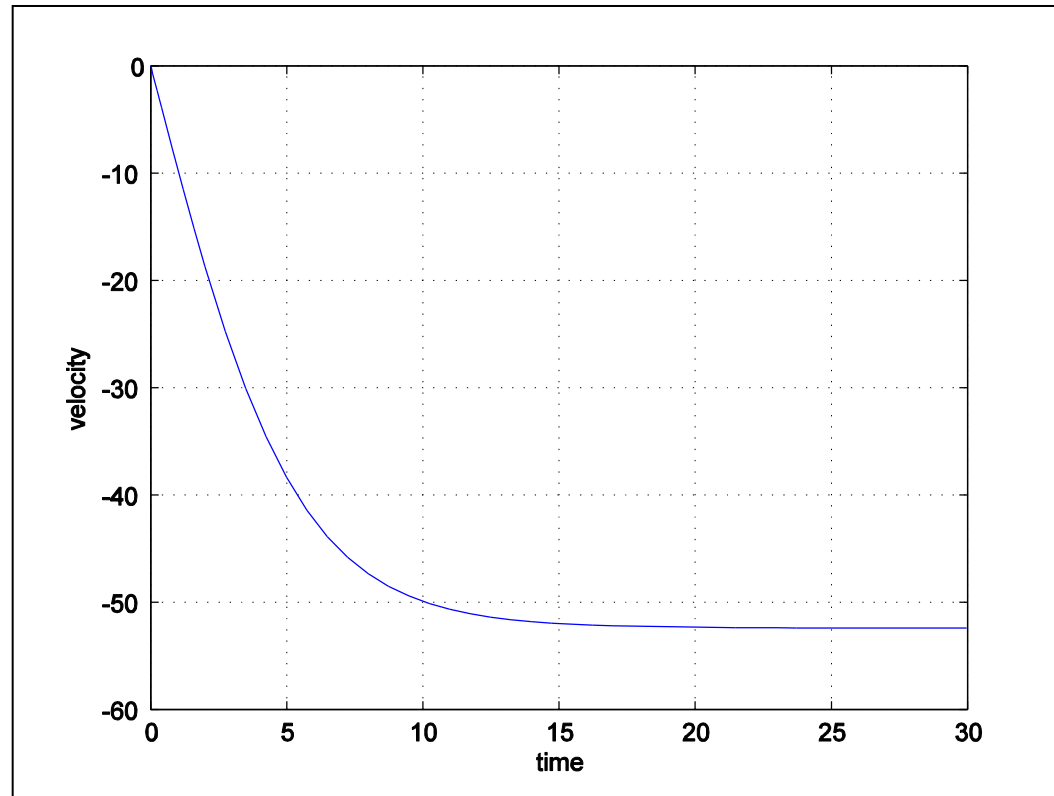
```
[t, v] = ode45(@aux_function, time, initial_condition);
```

```
>> [t, v] = ode45(@vprime, [0,30], 0);
```

```
>> plot(t,v)
```

**(See plot on next slide.)**

# Falling object



**As time increases the velocity levels out around -52.3818 m/s. This velocity is called the terminal velocity of the object. This agrees with the solution since  $v(\text{infinity}) = -\text{sqrt}(m \cdot g/b) = -52.3832$**



# Use Matlab to solve 2nd order ODE's.

## 1. Problem Definition

Use Matlab to plot both the velocity and position(height) of a free-falling object.

## 2. Refine, Generalize, Decompose the problem definition (i.e., identify sub-problems, I/O, etc.)

Mass of object is 70Kg , acceleration due to gravity is  $9.8 \text{ m/s}^2$  and the coefficient of air friction  $b = .25 \text{ Kg/s}$ .

Initial conditions: at time = 0 assume  $v=0$  and  $y = 2000\text{m}$ .

Plot the height  $y$  and the velocity  $v$  versus time for  $t = 0$  to  $t = 30$  seconds.

# Falling object2

## 3. Develop Algorithm (processing steps to solve problem)

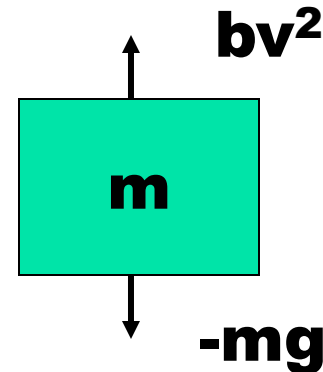
The ODE describing the motion of a falling object is:

$$m \frac{d^2 y}{dt^2} = -mg + b \left( \frac{dy}{dt} \right)^2$$

which is equivalent to the following system of ODEs:

$$\frac{dy}{dt} = v$$

$$\frac{dv}{dt} = -g + \frac{b}{m} v^2$$



# Falling object2

## 4. Write the “Function” (Code)

(instruction sequence to be carried out by the computer)

Use the Matlab editor to create a file `yvprime.m` .

Function `yvprime` has two inputs:

`t`: a scalar value for time

`yv`: a vector containing `[y , v]` values at time = `t`

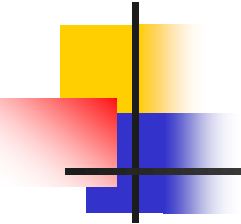
Function `yvprime` has one output:

`yvp`: a vector containing `[ dy/dt ; dv/dt]`

```
function yvp = yvprime(t, yv)
% function yvp = yvprime(t, yv)
m = 70;
g = 9.8;
b = .25;
y = yv(1);
v = yv(2);
yvp = [v ; (-g +(b/m)*v.^2)];
```

$$\frac{dy}{dt} = v$$

$$\frac{dv}{dt} = -g + \frac{b}{m} v^2$$



# Falling object2

## 6. Run Code

To run our program we will use 'ode45' in a slightly different way as follows:

```
[t, yv] = ode45(@yvprime, [0,30], [2000;0]);
```

```
[t, yv] = ode45(@aux_function, time, initial_conditions);
```

**aux\_function:** user created function that computes the derivatives

**time:** a vector [start stop] for the range of time of the solution.

**initial\_condition:** initial value(s) [ y(start) ; v(start) ]

**t:** solution column vector of time values from [start, stop]

**yv:** solution matrix with two columns [ y , v ] representing values y in the first column and v in the second at time t

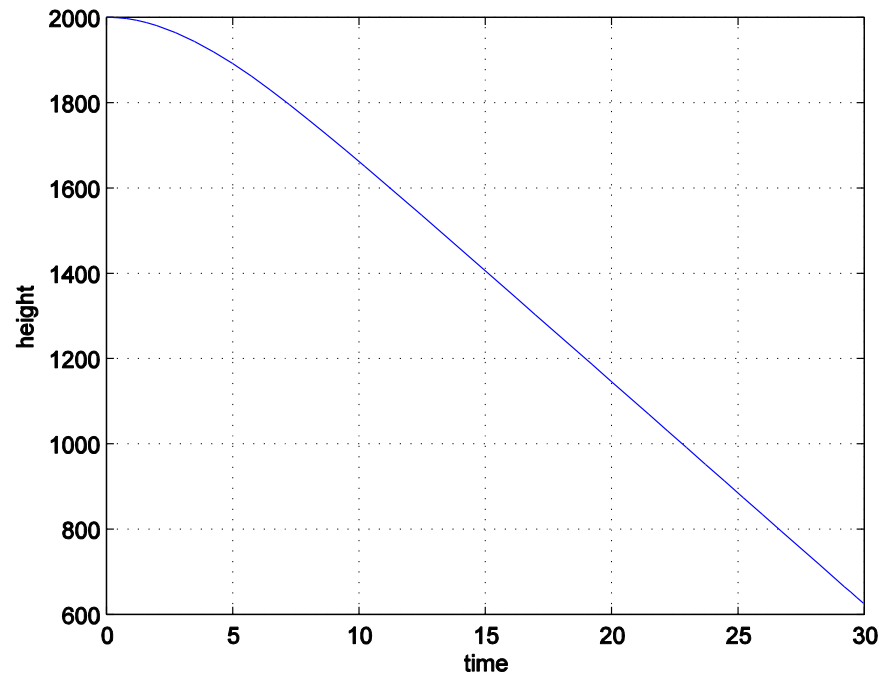
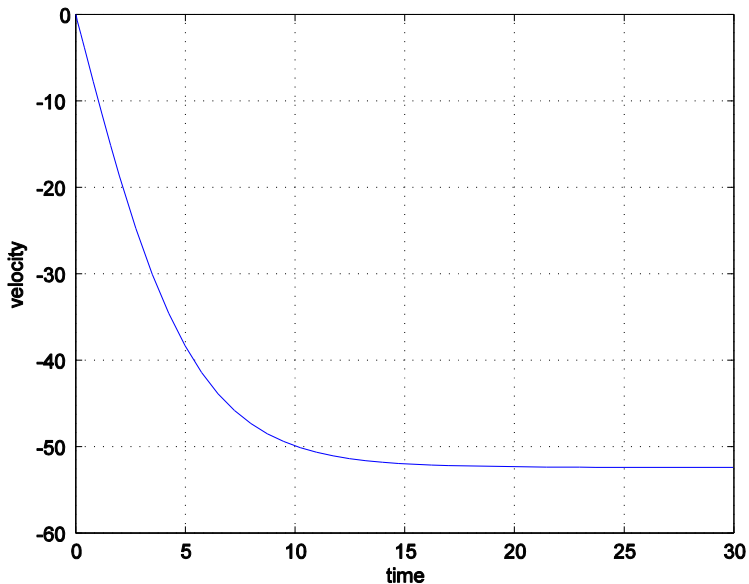
# Falling object2

## 5. Test and Debug the Code

To test our program in Matlab, we will plot velocity versus time

**>> plot(t,yv( : , 2 ))**  
and we will plot y versus time,

**>> plot(t,yv( : , 1))**



# Falling object2

## 5. Test and Debug the Code

Matlab produces a discretized solution

```
>> yv
```

```
>> t
```

```
>> t
t =
    0
    0.000005126298840
    0.000010252597680
    0.000015378896519
    0.000020505195359
    0.000046136689558
    0.000071768183757
    0.000097399677956
    0.000123031172156
    0.000251188643151
    0.000379346114146
    0.000507503585142
    0.000635661056137
```

```
>> yv
yv =
    1.0e+003 *
    2.0000000000000000    0
    1.999999999999871   -0.000000050237729
    1.999999999999485   -0.000000100475457
    1.999999999998841   -0.000000150713186
    1.999999999997940   -0.000000200950915
    1.9999999999969570  -0.000000452139558
    1.999999999974762   -0.000000703328201
    1.999999999953515   -0.000000954516844
    1.999999999925830   -0.000001205705487
    1.999999999690831   -0.000002461648701
    1.999999999294873   -0.000003717591912
```





# Matlab ODE solvers

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**Matlab offers a family of ODE solvers that use different methods to solve ODEs:**

**ode45, ode15i, ode15s, ode23, ode23s, ode23t,  
ode23tb, ode113**

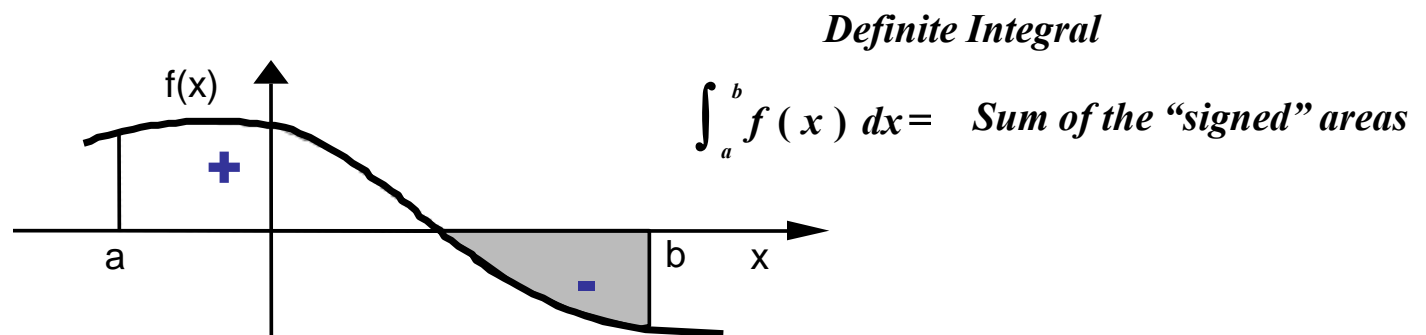
**Matlab does NOT guarantee that the solution any of the solvers produces is accurate.**

**Knowledge that a particular solver will produce an accurate solution for a given ODE is beyond the scope of this course. CS 357 / CS 457 are courses in numerical analysis that cover methods of solving ODEs.**

# Numerical Integration

Most integrals arising from solutions of problems in engineering and the physical sciences cannot be represented in "closed form"- they must be evaluated numerically.

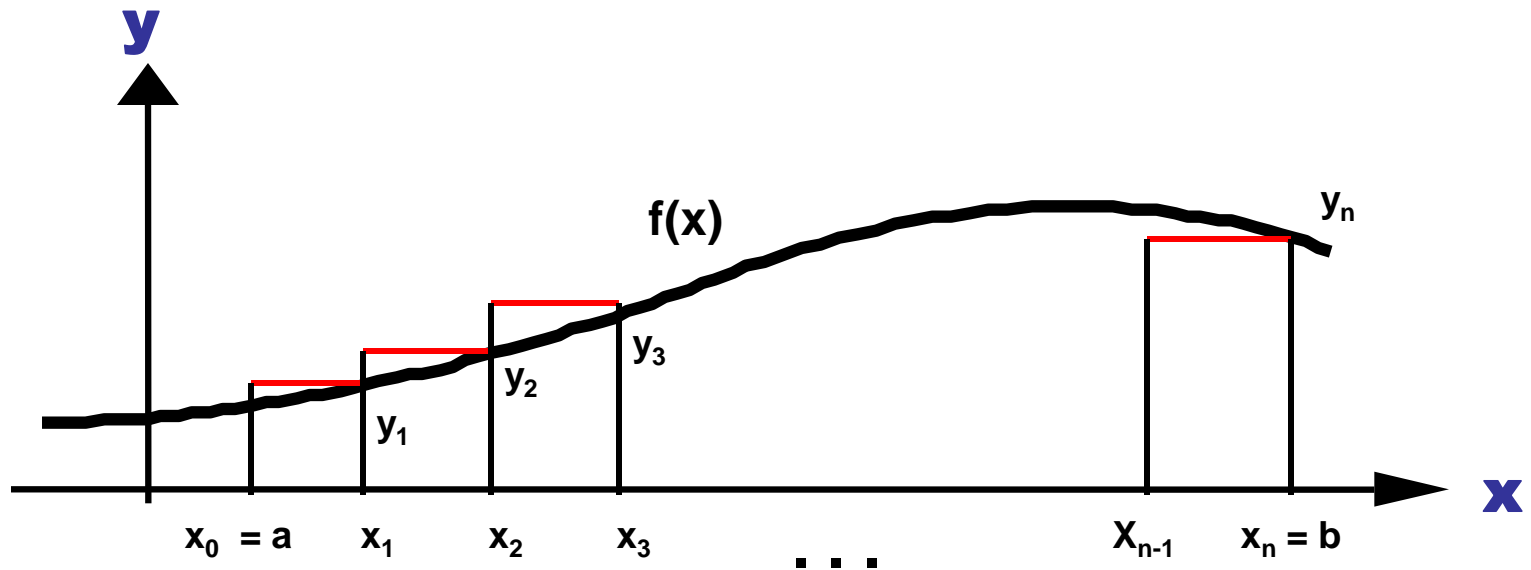
- For a function of a single variable, we seek an approximation to the area "under" the curve:



The Matlab functions: `quad` (`quad8`) and `trapz` only apply to continuous functions  $f(x)$  of one variable -  $x$  ( a scalar).

# Integration - Using Rectangles

Approximation of  $f(x)$  by using constant functions on the intervals  $[x_{k-1}, x_k]$  (not a good approximation).

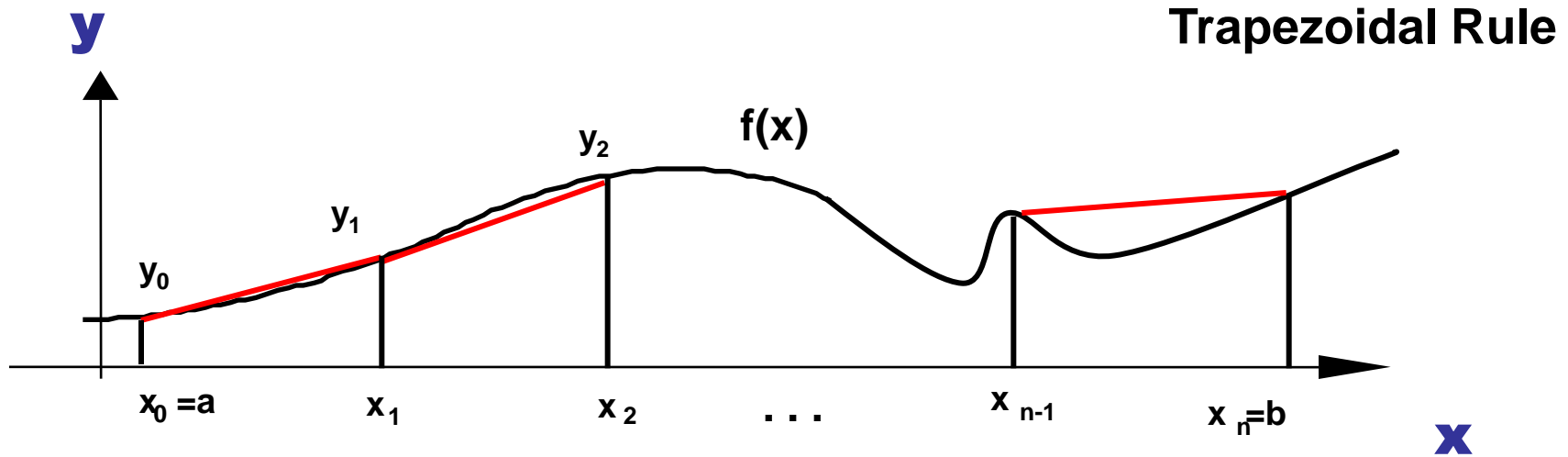


In this case, we approximate the integral by adding the areas of a set of approximating **rectangles**.

$$f(x) \approx f(x_k) \quad x_{k-1} \leq x \leq x_k, \quad k = 1, 2, \dots, n$$

# Integration - Using Trapezoids

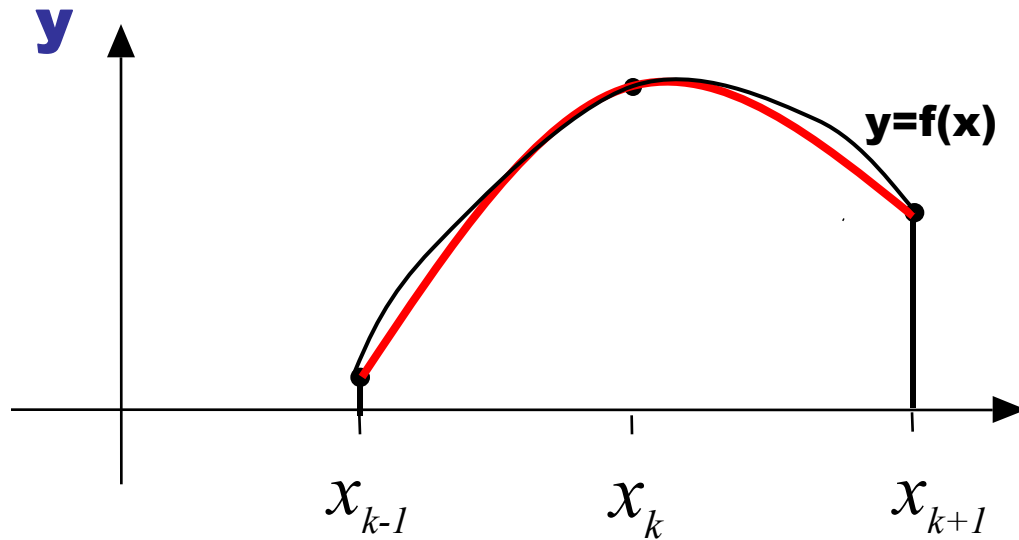
Approximation of  $f(x)$  by using a linear function on the intervals  $[x_{k-1}, x_k]$  (a better approximation).



In this case, we approximate the integral by adding the areas of a set of approximating **trapezoids**.

# Integration - Using Parabolas

Approximation of  $f(x)$  by using a quadratic function on the intervals  $[x_{k-1}, x_{k+1}]$  (better approximation).



Simpson's Rule  
(parabola)

In this case, we approximate the integral by adding the areas under a set of approximating **parabolas**.



# trapez and quadl - Matlab functions

The two built-in Matlab functions (we will use in CS101) for integration are **trapez** and **quad**.

- The function **trapez** trapezoidal rule (Pratap p. 152) is used when we don't know  $f(x)$  explicitly but we have a vector  $x$  which is a partition of the interval  $[a,b]$  and a vector  $y = f(x)$ . That is, we know the  $y$  values of  $f(x)$  only for some discrete set of  $x$  values.
- We can use **quad** (Pratap 5.4 adaptive Simpson's Rule) or **quadl** (Pratap 5.4 adaptive Lobatto) when we know the function  $f(x)$ . That is,  $f(x)$  is a built-in Matlab function or a user defined function.



# Function - trapz

**Example:**

**Use Matlab to compute the integral:**

$$\int_a^b f(x) dx$$

**where  $f(x) = \sin(x)$  and  $a = 0$  ,  $b = \pi$ .**

```
>> format long
```

```
>> x = linspace(0,pi,1000);
```

```
>> y = sin(x);
```

```
>> trapz(x,y)
```

```
ans =
```

```
1.99999989714020
```



# Function - quadl

**Example:**

**Use Matlab to compute the integral:**

$$\int_a^b f(x) dx$$

**where  $f(x) = \sin(x)$  and  $a = 0$  ,  $b = \pi$ .**

```
>> quadl(@sin,0,pi)
```

```
ans =  
1.99999997747113
```





# What have I learned in this lecture?

We can use the Matlab function **ode45** to solve a system of ordinary (not partial) differential equations.

For numeric integration we can use **quadl** when we know the function  $f(x)$ . The function **trapz** is used when we don't know  $f(x)$  explicitly.