

Lecture 3

- Announcements:
- HW 1 will be posted on Thursday (due 9/18)
 - Office hrs start next week
Tuesdays 2-3pm (Zoom link on course website)

Recap: Normal subgroup $H \trianglelefteq G$

H is a subgroup and $gH = Hg$
 $gHg^{-1} = H$ for all $g \in G$

G/H quotient group

Group Homomorphism $\phi: G \rightarrow K$

$$\phi(g_1 g_2) = \phi(g_1) \cdot \phi(g_2)$$

$$K \supseteq \text{Im } \phi = \{ \phi(g) \mid g \in G \}$$

$$G \supseteq \text{Ker } \phi = \{ g \in G \mid \phi(g) = E_K \}$$

① $\text{Im } \phi \leq K$ is a subgroup of K

$$\phi(E_G) = \phi(g \cdot g^{-1})$$

a) $E_K = \phi(E_G)$ $E_K \subseteq \text{Im } \phi$

$$= \phi(g) \cdot \phi(g^{-1})$$

b) $k_1, k_2 \in \text{Im } \phi$

$$= \phi(g) \cdot [\phi(g)]^{-1}$$

$$k_1 = \phi(g_1), k_2 = \phi(g_2)$$

$$= E_K$$

$$k_1, k_2 = \phi(g_1) \cdot \phi(g_2) = \phi(g_1 \cdot g_2) \in \text{Im } \phi$$

c) $k_1 \in \text{Im } \phi$

$$k_1 = \phi(g_1) \Rightarrow k_1^{-1} = [\phi(g_1)]^{-1} = \phi(g_1^{-1}) \in \text{Im } \phi$$

④ $\text{Ker } \phi \trianglelefteq G$ is a normal subgroup of G

a) $\phi(E_G) = E_K \Rightarrow E_G \subseteq \text{Ker } \phi$

b) $g_1, g_2 \in \text{Ker } \phi \quad \phi(g_1) = E_K, \phi(g_2) = E_K$

$$\phi(g_1 \cdot g_2) = \phi(g_1) \cdot \phi(g_2) = E_K \cdot E_K = E_K$$

$$\Rightarrow g_1 \cdot g_2 \in \text{Ker } \phi$$

$$c) g_1 \in \ker \phi \quad \phi(g_1) \cdot \phi(g_1^{-1}) = \phi(g_1^{-1})$$

$$\phi(E_G) = E_K$$

$$g_1^{-1} \in \ker \phi$$

$$d) g \in \ker \phi \quad g' \in G$$

$$g'gg'^{-1} \in \ker \phi$$

$$\phi(g'gg'^{-1}) = \phi(g') \cdot \cancel{\phi(g)} \cdot \phi(g'^{-1})$$

$$= \phi(g') \cdot \phi(g'^{-1}) = \phi(g'g'^{-1}) = E_K$$

$$g' \ker \phi g'^{-1} = \ker \phi \rightarrow \ker \phi \leq G$$

First isomorphism theorem: let G, K be groups,
 $\underline{\varphi: G \rightarrow K}$ a group homomorphism

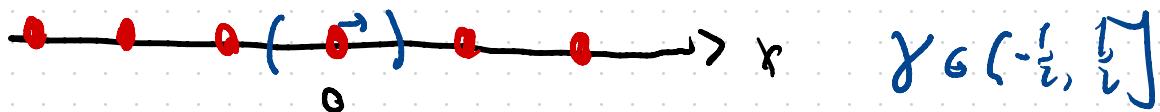
$\frac{G}{\ker \varphi}$ is isomorphic to $\text{Im } \varphi$

There is an invertible
homomorphism

$$\text{Example: } R' = \{ \beta ax \mid \beta \in R \}$$

$$T = \{ nax \mid n \in \mathbb{Z} \}$$

$$\begin{aligned} & (\Phi(g^{-1}) \cdot [\Phi(g)])^{-1} \\ & \Phi(E_G) = E_K \\ & [\Phi(\alpha)]^{-1} \Phi(g) = E_K \\ & = \Phi(g^{-1}) \Phi(g) \end{aligned}$$



Claim: $\mathbb{R}^1/\mathbb{T} \cong U(1)$ the unit circle

Pf: look for a homomorphism w/ $\text{Im} \subseteq U(1)$, $\text{Ker} = \mathbb{T}$

$$\varphi(\beta a \hat{x}) = e^{i2\pi\beta}$$

is a homomorphism $\varphi(\beta_1 a \hat{x} + \beta_2 a \hat{x}) = e^{i2\pi\beta_1} e^{i2\pi\beta_2} = \varphi(\beta_1 a \hat{x}) \varphi(\beta_2 a \hat{x})$

✓

$$\text{Ker } \varphi : \left\{ \beta a \hat{x} \mid e^{i2\pi\beta} = 1 \right\} = \left\{ n a \hat{x} \mid n \in \mathbb{Z} \right\} = \mathbb{T}$$

$\text{Im } \varphi$: entire unit circle

First isomorphism theorem

$\mathbb{R}^1/\mathbb{T} \cong U(1)$ the unit cell of the Bravais lattice

One last thing about quotient groups:

Let $H \trianglelefteq G$ be a normal subgroup

$$G = H \cup Hg_1 \cup \dots \cup Hg_{n-1} \quad n = |G:H|$$

$G/H = \{H, Hg_1, \dots, Hg_{n-1}\}$ is a group

In some cases we can identify elements of G/H to elements of G

$$\iota: G/H \rightarrow G \quad \text{"inclusion"}$$

$$\iota(Hg_i) = \bar{g}_i \in Hg_i$$

$$\iota(H) = E$$

If ι exists, $\text{Im } \iota = \{\bar{g}_1, \bar{g}_2, \dots, \bar{g}_{n-1}\} \leq G$

$$G/H \cong \text{Im } i$$

$G = \bigcup_{i=0}^{n-1} H\bar{g}_i$, every element of G can
be written uniquely as $g = h k$

$$\begin{matrix} h \in H \\ k \in \text{Im } i \end{matrix}$$

$$G = H(\text{Im } i)$$

If this is possible G is a semidirect product

$$G = H \rtimes \text{Im } i$$

Example: Rigid transformations of 3D space
Euclidean group $E(3)$ - translations

- rotations
- < reflections

elements $g \in E(3)$ using a "Sexte symbol"

$$g = \{R | \vec{v}\} \quad R \in O(3) \text{ rotation or reflection}$$

$\vec{v} \in \mathbb{R}^3$ is a translation

$$\{R | \vec{v}\} \cdot \vec{x} = [R] \vec{x} + \vec{v} \quad [R] = 3 \times 3 \text{ matrix}$$

that implements R

multiplication: $g_1 = \{R_1 | \vec{v}_1\}$ $g_2 = \{R_2 | \vec{v}_2\}$

$$\begin{aligned} g_1 \cdot g_2 \vec{x} &= g_1 \cdot (g_2 \vec{x}) = g_1 \cdot ([R_2] \vec{x} + \vec{v}_2) \\ &= [R_1] \cdot ([R_2] \vec{x} + \vec{v}_2) + \vec{v}_1 \end{aligned}$$

$$= [R_1 R_2] \vec{x} + (v_1 + [R_1] v_2)$$

$$g \cdot g_2 = \{R_1 R_2 | v_1 + R_1 \vec{v}_2\}$$

$$\text{inverses: } \{R_1 | v\}^{-1} = \{R^{-1} | -R^{-1} \vec{v}\}$$

$$\text{identity: } \{E | \vec{0}\}$$

$$\textcircled{1} \quad O(\mathbb{R}) < E(\mathbb{R})$$

$$\{\{R | \vec{0}\}, R \in O(\mathbb{R})\}$$

$$\textcircled{2} \quad R^3 = \{\{E | \vec{v}\} | v \in R^3\} \triangleleft E(\mathbb{R}) \text{ is a normal subgroup}$$

$$\{\{R | \vec{0}\} \{E | \vec{v}\} \{R | \vec{0}\}^{-1} = \{R | \vec{j} + R \vec{v}\} \{R^{-1} | -R^{-1} \vec{j}\}\}$$

$$= \{E | \vec{r} + R\vec{v} - \vec{r}_0\} = \{E | R\vec{v}\}$$

$$\{R|\vec{v}\} = \{E|\vec{v}\} \{R|0\}$$

$$EF(3) = \mathbb{R}^3 \rtimes O(3)$$

$$EF(3) = \bigcup_{R \in O(3)} (\mathbb{R}^3)_R$$

$EF(3)$ is a semi-direct product

V = Hilbert space of states $|\Psi\rangle$

G group of symmetries of our Hamiltonian

$\rho: G \rightarrow U(V)$ ← group of unitary operators on V

$$g \mapsto \rho(g) \quad \rho(g)|\psi\rangle = |\psi'\rangle$$
$$\rho(g)^* \hat{O} \rho(g) = \hat{O}' \quad \text{give transformed states and operators}$$

$$\rho(g_1 g_2) = \rho(g_1) \rho(g_2) \quad \text{so } \rho \text{ should be a homomorphism}$$

Def a vector space V and a homomorphism $\rho: G \rightarrow U(V)$
is called a unitary representation of G on V

V - the representation space

$\rho(g)$ - the representative of g

Ex: representation of translations \mathbb{R}^3 on Hilbert space

$V = \{\psi(\vec{x}) \text{ square-integrable wavefunctions}\}$

$$\mathbb{R}^3 \ni \vec{v} \rightarrow \rho(\vec{v}) = e^{-\frac{i}{\hbar} \vec{p} \cdot \vec{v}} \in U(V)$$

$$\rho(v_1 + v_2) = \rho(v_1)\rho(v_2)$$

$$\rho(\vec{v})^\dagger \hat{x} \rho(\vec{v}) = e^{\frac{i}{\hbar} \vec{p} \cdot \vec{v}} \hat{x} e^{-\frac{i}{\hbar} \vec{p} \cdot \vec{v}} = \hat{x} + \vec{v}$$

More complicated example: $SU(2) \subset$ special unitary group in \mathbb{C}^2

$$\left\{ (\hat{n}, \theta) \mid \begin{matrix} \hat{n} \\ \theta \end{matrix} \in (-2\pi, 2\pi) \right\}$$

\uparrow
3D unit vectors

$$(\hat{n}, \theta=0) = E$$

$$(\hat{n}, \theta \approx 2\pi) \approx \vec{E}$$

Spin- $\frac{1}{2}$ representation: $R_{\frac{1}{2}}((\hat{n}, \theta)) = \cos \frac{\theta}{2} \hat{\sigma}_z + i \sin \frac{\theta}{2} \hat{n} \cdot \vec{\sigma}$

$\begin{matrix} \text{1} \\ -i \frac{\theta}{2} \hat{n} \cdot \vec{\sigma} \\ e \end{matrix}$
 $\begin{matrix} \text{2x2 identity} \\ \uparrow \end{matrix}$
 $\begin{matrix} \text{Vector of} \\ \text{Pauli matrices} \\ \uparrow \end{matrix}$

defining representation

$$\text{Ker } R_{\frac{1}{2}} = \{E\}$$

$$\text{Im } R_{\frac{1}{2}} = SU(2)$$

Other representations: Spin $\ell=1$

$$L_x = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$R_1((\hat{n}, \theta)) = e^{-i \hat{n} \cdot \vec{L} \theta}$$

$$L_y = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & i \end{pmatrix}$$

$$L_z = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\text{Ker } P_1 = \{E, \bar{E}\}$$

$$\text{Im } P_1 = SO(3) = \frac{SU(2)}{\{E, \bar{E}\}}$$

" $SU(2)$ is a double cover $SO(3)$)

" Z_2 rotat."