

1. We are interested in determining the rates for the following transitions:

$$\underline{|n \ell m\rangle} \rightarrow \underline{|n' \ell' m'\rangle}$$

$$\underline{|200\rangle} \rightarrow |100\rangle$$

(2s \rightarrow 1s transition)

$$\left\{ \underline{|21-1\rangle} \rightarrow |100\rangle \right.$$

$$\left\{ \underline{|210\rangle} \rightarrow |100\rangle \right.$$

$$\left\{ \underline{|211\rangle} \rightarrow |100\rangle \right.$$

(2p \rightarrow 1s transitions)

($n=1,2,\dots$)

$$E_n = - \left[\frac{m_e}{2\hbar^2} \left(\frac{e^2}{4\pi\epsilon_0} \right)^2 \right] \frac{1}{n^2} = - \frac{13.6 \text{ eV}}{n^2}$$

$$A_{2s \rightarrow 1s} = \frac{\omega_{12}^3 q^2}{3\pi\epsilon_0 \hbar c^3} \left| \langle 100 | \hat{r} | 200 \rangle \right|^2$$

$$A^{(1)}_{2p \rightarrow 1s} = \frac{\omega_{12}^3 q^2}{3\pi\epsilon_0 \hbar c^3} \left| \langle 100 | \hat{r} | 21-1 \rangle \right|^2$$

$$A^{(2)}_{2p \rightarrow 1s} = \frac{\omega_{12}^3 q^2}{3\pi\epsilon_0 \hbar c^3} \left| \langle 100 | \hat{r} | 210 \rangle \right|^2$$

$$A^{(3)}_{2p \rightarrow 1s} = \frac{\omega_{12}^3 q^2}{3\pi\epsilon_0 \hbar c^3} \left| \langle 100 | \hat{r} | 211 \rangle \right|^2$$

$$(i) \langle 100 | \vec{r} | 200 \rangle$$

$$= \langle 100 | x | 200 \rangle \hat{i} + \langle 100 | y | 200 \rangle \hat{j} + \langle 100 | z | 200 \rangle \hat{k}$$

$$\langle 100 | x | 200 \rangle = \langle 100 | r \sin \theta \cos \phi | 200 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^\pi \underbrace{|Y_{00}(\theta, \phi)|^2}_{\frac{1}{4\pi}} \sin^2 \theta \cos \phi \, d\theta \, d\phi \right) \left(\int_0^{6a} r^3 R_{20}(r) R_{10}(r) \, dr \right)$$

$$= 0 \quad \left(\int_0^{2\pi} \cos \phi \, d\phi = 0 \text{ and } Y_{00}(\theta, \phi) = \frac{1}{\sqrt{4\pi}} \right)$$

Similarly, $\langle 100 | y | 200 \rangle = 0$.

$$\langle 100 | z | 200 \rangle = \langle 100 | r \cos \theta | 200 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^\pi |Y_{00}(\theta, \phi)|^2 \sin\theta \cos\theta \, d\theta \, d\phi \right) \left(\int_0^{6a} r^3 R_{20}(r) R_{10}(r) \, dr \right)$$

$$= 0 \quad \left(\int_0^\pi \sin\theta \cos\theta \, d\theta = \int_{-1}^1 u \, du = 0 \right)$$

$$\therefore \langle 200 | \vec{r} | 100 \rangle = \vec{0} \quad \text{which}$$

means $A_{2s \rightarrow 1s} = 0$. So the

lifetime $\tau_{2s \rightarrow 1s} = \frac{1}{A_{2s \rightarrow 1s}} = \infty$ for

the $2s \rightarrow 1s$ transition.

Of course using selection rules it's
 a no-brainer that $\langle 100 | \vec{r} | 200 \rangle = 0$.

$$(ii) \langle 100 | \vec{r} | 21-1 \rangle$$

$$= \langle 100 | x | 21-1 \rangle \hat{i} + \langle 100 | y | 21-1 \rangle \hat{j} \\ + \langle 100 | z | 21-1 \rangle \hat{k}$$

$$\langle 100 | x | 21-1 \rangle = \langle 100 | r \sin \theta \cos \phi | 21-1 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^{\pi} (Y_{1,-1}(\theta, \phi))^* (Y_{2,0}(\theta, \phi)) \sin^2 \theta \cos \phi \, d\theta \, d\phi \right) \left(\int_0^{\infty} r^3 R_{21}(r) R_{10}(r) \, dr \right)$$

$$= \left(\sqrt{\frac{3}{32\pi^2}} \int_0^{2\pi} \int_0^{\pi} \sin^3 \theta e^{i\phi} \cos \phi \, d\theta \, d\phi \right) \left(\int_0^{\infty} r^3 R_{21}(r) R_{10}(r) \, dr \right)$$

$$\int_0^{\pi} \sin^2 \theta \, d\theta = \int_0^{\pi} \sin \theta (1 - \cos^2 \theta) \, d\theta$$

$$= \int_{-1}^1 (1 - u^2) \, du = \left(u - \frac{u^3}{3} \right) \Big|_{-1}^1 = \frac{4}{3}$$

$$\int_0^{2\pi} e^{i\phi} \cos \phi \, d\phi = \frac{1}{2} \int_0^{2\pi} e^{2i\phi} \, d\phi + \frac{1}{2} \int_0^{2\pi} d\phi$$

$$= \pi$$

$$\int_0^{\infty} r^3 R_{21}(r) R_{10}(r) \, dr = \frac{1}{a^3 \sqrt{b}} \int_0^{\infty} \left(\frac{r^4}{a} \right) e^{-3r/2a} \, dr$$

$$= \frac{1}{a^4 \sqrt{6}} \int_0^{\infty} r^4 e^{-3r/2a} dr = \frac{1}{a^4 \sqrt{6}} \left(4! \left(\frac{2a}{3} \right)^5 \right)$$

$$= \frac{2^3 \cdot 3}{2^{4/2} 3^{4/2}} \left(\frac{2}{3} \right)^5 a = \frac{2^{15/2}}{3^{9/2}} a$$

$$\Rightarrow \langle 100 | x | 21 - 1 \rangle$$

$$= \left(\frac{3^{4/2}}{2^{5/2}} \right) \left(\frac{2^2}{3} \right) \left(\frac{2^{15/2}}{3^{9/2}} a \right) = \frac{2^7}{3^5} a$$

$$\langle 100 | y | 21 - 1 \rangle$$

$$= \langle 1 \ 0 \ 0 \mid r \sin \theta \sin \phi \mid 2 \ 1 \ -1 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^\pi (Y_{1,-1}(\theta, \phi)) (Y_{00}(\theta, \phi))^* \sin^2 \theta \sin \phi \, d\theta \, d\phi \right) \left(\int_0^\infty r^3 R_{21}(r) R_{00}(r) \, dr \right)$$

$$= \left(\sqrt{\frac{3}{32\pi^2}} \int_0^{2\pi} \int_0^\pi \sin^2 \theta e^{i\phi} \sin \phi \, d\theta \, d\phi \right) \left(\int_0^\infty r^3 R_{21}(r) R_{00}(r) \, dr \right)$$

$$= \left(\frac{3^{1/2}}{2^{5/2}\pi} \right) \left(\frac{2^2}{3} \right) (-i\pi) \left(\frac{2^{15/2}}{3^{9/2}} a \right)$$

$$= -i \frac{2^7}{3^5} a$$

$$\langle 100 | z | 21-1 \rangle$$

$$= \langle 100 | r \cos \theta | 21-1 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^\pi (Y_{1,-1}(\theta, \phi))^* (Y_{20}(\theta, \phi)) \sin \theta \cos \theta d\theta d\phi \right) \left(\int_0^\infty r^3 R_{21}(r) R_{10}(r) dr \right)$$

$$= 0 \quad \left(\int_0^\pi \sin \theta \cos \theta d\theta = \int_{-1}^1 u du = 0 \right)$$

$$\therefore \langle 100 | \vec{r} | 21-1 \rangle$$

$$= \frac{2^7}{3^5} (\hat{i} - i\hat{j}) a$$

which means

$$A_{2p \rightarrow 1s}^{(1)} = \frac{\omega_{12}^3 q^2}{3\pi\epsilon_0 \hbar c^3} \left| \langle 100 | \hat{r} | 21-1 \rangle \right|^2$$

$$= \frac{\omega_{21}^3 q^2}{3\pi\epsilon_0 \hbar c^3} \left(\frac{2^{15}}{3^{10}} \right) a^2$$

$$\Rightarrow \tau_{2p \rightarrow 1s}^{(1)} = \frac{1}{A_{2p \rightarrow 1s}^{(1)}} = \frac{3\pi\epsilon_0 \hbar c^3}{\omega_{12}^3 q^2} \frac{3^{10}}{2^{15} a^2}$$

(iii) $\langle 100 | \vec{r} | 211 \rangle$ involves
basically the same integrals as (ii).

$$\Rightarrow \langle 100 | \vec{r} | 211 \rangle \\ = -\frac{2^7}{3^5} a (\hat{i} + i\hat{j})$$

$$\therefore |\langle 211 | \vec{r} | 100 \rangle|^2 = \\ |\langle 21-1 | \vec{r} | 100 \rangle|^2$$

$$\Rightarrow \tau_{2p \rightarrow 1s}^{(3)} = \tau_{2p \rightarrow 1s}^{(1)}$$

$$= \frac{3\pi\epsilon_0\hbar c^3}{\omega_{12}^3 a^2} \frac{3^{10}}{2^{15} a^2}$$

$$(iv) \langle 100 | \hat{r} | 210 \rangle$$

$$= \langle 100 | x | 210 \rangle \hat{i}$$

$$+ \langle 100 | y | 210 \rangle \hat{j}$$

$$+ \langle 100 | z | 210 \rangle \hat{k}$$

$$\langle 100 | x | 210 \rangle$$

$$= \langle 100 | r \sin \theta \cos \phi | 210 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^{\pi} (Y_{10}(\theta, \phi)) (Y_{20}(\theta, \phi))^* \sin^2 \theta \cos \phi \, d\theta \, d\phi \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{10}(r) \, dr \right)$$

$$= 0 = \langle 100 | y | 210 \rangle$$

$$\left(Y_{10}(\theta, \phi) = \sqrt{\frac{3}{4\pi}} \cos \theta \text{ and} \right.$$

$$\int_0^{2\pi} \cos \phi \, d\phi = \int_0^{2\pi} \sin \phi \, d\phi = 0$$

$$\langle 100 | z | 210 \rangle$$

$$= \langle 100 | r \cos \theta | 210 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^{\pi} (Y_{10}(\theta, \phi)) (Y_{20}(\theta, \phi))^* \sin \theta \cos \theta \, d\theta \, d\phi \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{10}(r) \, dr \right)$$

$$= \left(\frac{\sqrt{3}}{2} \int_0^{\pi} \sin\theta \cos^2\theta d\theta \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{10}(r) dr \right)$$

$$= \left(\frac{1}{3^{3/2}} \right) \left(\frac{2^{15/2}}{3^{9/2}} a \right) = \frac{2^{15/2}}{3^5} a$$

$$\therefore \langle 100 | \hat{r} | 210 \rangle$$

$$= \frac{2^{15/2}}{3^5} a \hat{k}$$

$$\Rightarrow A_{2p \rightarrow 1s}^{(2)} = \frac{\omega_{12}^3 q^2}{3\pi\epsilon_0 \hbar c^3} |\langle 100 | r | 210 \rangle|^2$$

$$= \frac{\omega_{12}^3 q^2}{3\pi\epsilon_0 \hbar c^3} \frac{2^{15}}{3^{10}} a^2$$

$$\Rightarrow \gamma_{2p \rightarrow 1s}^{(2)} = \frac{1}{A_{2p \rightarrow 1s}^{(2)}}$$

$$= \frac{3\pi\epsilon_0 \hbar c^3}{\omega_{12}^3 q^2} \frac{3^{10}}{2^{15} a^2}$$

We see that all the transition rates (and therefore lifetimes) are the same for all $2p \rightarrow 1s$ transitions

$$\begin{aligned} \tau_{2p \rightarrow 1s}^{(1)} &= \tau_{2p \rightarrow 1s}^{(2)} = \tau_{2p \rightarrow 1s}^{(3)} \\ &= \frac{3\pi\epsilon_0 \hbar c^3}{\omega_{12}^3 a^2} = \tau \end{aligned}$$

Note that $\omega_{12} = \frac{E_1 - E_2}{\hbar}$

$$= \frac{E_1}{\hbar} \left(1 - \frac{1}{4}\right) = \frac{3E_1}{4\hbar} = \frac{3(13.6 \text{ eV})}{4\hbar}$$

$$\therefore \tau = \frac{3\pi\epsilon_0\hbar c^3}{q^2} \left(\frac{4\hbar}{3E_1}\right)^3 \frac{3^{10}}{2^{15}a^2}$$

$\approx \boxed{1.6 \text{ ns}}$ for the $2p \rightarrow 1s$ transitions

Whereas the $2s \rightarrow 1s$ transition has

$\boxed{\tau = \infty}$ lifetime.

2. (a) Determining the allowed decay routes means applying the selection rules at each step that allow us to identify the nonzero matrix elements.

$$|300\rangle \xrightarrow{\text{(i)}} |nlm\rangle \xrightarrow{\text{(ii)}} |100\rangle$$

$$(i) \langle nlm | \vec{r} | 300 \rangle \begin{pmatrix} n=2 \\ l=0,1 \\ m=-1,0,1 \end{pmatrix}$$

$$\Delta l = \pm 1 \quad \text{and} \quad \Delta m_l = 0, \pm 1$$

Thus, $\langle 21-1 | \hat{T} | 300 \rangle$,

$\langle 210 | \hat{T} | 300 \rangle$, and

$\langle 211 | \hat{T} | 300 \rangle$ are all

non-zero, meaning

$$|300\rangle \xrightarrow{(i)} \left\{ \begin{array}{l} |211\rangle \\ |210\rangle \\ |21-1\rangle \end{array} \right\}$$

are all allowed transitions.

(Notice that $\langle 200 | \hat{T} | 300 \rangle = 0$)

so that isn't allowed. Also,

$$\langle 100 | \vec{r} | 300 \rangle = 0 \text{ so we}$$

can't just go directly to the

ground state either.

$$|300\rangle \xrightarrow[\text{(i)}]{\cancel{\rightarrow}} |200\rangle$$

$$(ii) \langle 100 | \vec{r} | n \ell m \rangle \neq 0$$

$$\text{iff } \Delta \ell = \pm 1 \text{ and$$

$$\Delta m_\ell = 0, \pm 1$$

This means $\langle 100 | \hat{r} | 21-1 \rangle$,

$\langle 100 | \hat{r} | 211 \rangle$, and

$\langle 100 | \hat{r} | 210 \rangle$ are all non-zero.

Therefore,

$$\left. \begin{array}{l} | 211 \rangle \\ | 210 \rangle \\ | 21-1 \rangle \end{array} \right\} \xrightarrow{(ii)} | 100 \rangle$$

are all allowed transitions

(Of course, $\langle 100 | \hat{T} | 200 \rangle = 0$

so this transition isn't allowed.)

Thus, all possible decay routes are shown below.

$$|300\rangle \rightarrow \left\{ \begin{array}{l} |211\rangle \\ |210\rangle \\ |21-1\rangle \end{array} \right\} \rightarrow |100\rangle$$

$$(b) |300\rangle \rightarrow \left\{ \begin{array}{l} |211\rangle \\ |210\rangle \\ |21-1\rangle \end{array} \right\}$$

$$\langle 211 | \vec{r} | 300 \rangle$$

$$= \langle 211 | x | 300 \rangle \hat{i}$$

$$+ \langle 211 | y | 300 \rangle \hat{j}$$

$$+ \langle 211 | z | 300 \rangle \hat{k}$$

$$\langle 211 | x | 300 \rangle$$

$$= \langle 211 | r \sin \theta \cos \phi | 300 \rangle$$

$$= \left(\int_0^{2\bar{u}} \int_0^{\pi} (Y_{11}(\theta, \phi))^* (Y_{00}(\theta, \phi)) \sin^2 \theta \cos \phi \, d\theta \, d\phi \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{30}(r) \, dr \right)$$

$$= \left(-\sqrt{\frac{3}{32\bar{u}^2}} \int_0^{2\bar{u}} \int_0^{\pi} \sin^2 \theta e^{-i\phi} \cos \phi \, d\theta \, d\phi \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{30}(r) \, dr \right)$$

$$= \left(-\frac{1}{\pi} \sqrt{\frac{3}{32}} \left(\frac{4}{3} \right) (\pi) \right) \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr$$

$$= -\frac{1}{\sqrt{6}} \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr$$

$$\langle 211 | y | 300 \rangle$$

$$= \langle 211 | r \sin \theta \sin \phi | 300 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^{\pi} (Y_{11}(\theta, \phi))^* (Y_{30}(\theta, \phi)) \sin^2 \theta \sin \phi d\theta d\phi \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr \right)$$

$$= \left(-\sqrt{\frac{3}{32\pi^2}} \int_0^{2\pi} \int_0^\pi \sin^3 \theta e^{-i\phi} \sin \phi \, d\theta \, d\phi \right)$$

$$\times \left(\int_0^\infty r^3 R_{21}(r) R_{20}(r) \, dr \right)$$

$$= \left(-\sqrt{\frac{3}{32\pi^2}} \left(\frac{4}{3} \right) (-i\pi) \right) \int_0^\infty r^3 R_{21}(r) R_{20}(r) \, dr$$

$$= \frac{i}{\sqrt{6}} \int_0^\infty r^3 R_{21}(r) R_{20}(r) \, dr$$

$$\langle 211 | 210 \rangle$$

$$= \langle 211 | r \cos \theta | 100 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^{\pi} (Y_{11}(\theta, \phi))^* (Y_{00}(\theta, \phi)) \sin \theta \cos \theta \, d\theta \, d\phi \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{10}(r) \, dr \right)$$

$$= \left(-\sqrt{\frac{3}{32\pi^2}} \int_0^{2\pi} \int_0^{\pi} \sin^2 \theta \cos \theta e^{-i\phi} \, d\phi \right) \left(\int_0^{\infty} r^3 R_{21}(r) R_{10}(r) \, dr \right)$$

$$= 0$$

$$\langle 211 | \hat{r} | 300 \rangle$$

$$= \left(-\frac{1}{\sqrt{6}} \hat{i} + \frac{i}{\sqrt{6}} \hat{j} \right) \left(\int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr \right)$$

In the same vein,

$$\langle 21-1 | \hat{r} | 300 \rangle$$

$$= \langle 21-1 | x | 300 \rangle \hat{i}$$

$$+ \langle 21-1 | y | 300 \rangle \hat{j}$$

$$+ \langle 21-1 | z | 300 \rangle \hat{k}$$

$$\langle 21-1 | x | 300 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^{\pi} (Y_{1,-1}(\theta, \phi))^* (Y_{00}(\theta, \phi)) \sin^2 \theta \cos \phi \, d\theta \, d\phi \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{30}(r) \, dr \right)$$

$$= \left(\sqrt{\frac{3}{32\pi^2}} \int_0^{2\pi} \int_0^{\pi} \sin^3 \theta e^{i\phi} \cos \phi \, d\theta \, d\phi \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr \right)$$

$$= \left(\sqrt{\frac{3}{32\pi^2}} \right) \left(\frac{4}{3} \right) \left(\frac{\pi}{11} \right) \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr$$

$$= \frac{1}{\sqrt{6}} \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr$$

$$\langle 21-1 | y | 300 \rangle$$

$$= \langle 21-1 | r \sin \theta \sin \phi | 300 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^{\pi} (Y_{1,-1}(\theta, \phi))^* (Y_{0,0}(\theta, \phi)) \sin^2 \theta \sin \phi \, d\theta \, d\phi \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{30}(r) \, dr \right)$$

$$= \left(\sqrt{\frac{3}{32\pi^2}} \int_0^{2\pi} \int_0^{\pi} \sin^3 \theta e^{i\phi} \sin \phi \, d\theta \, d\phi \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{30}(r) \, dr \right)$$

$$= \left(\sqrt{\frac{3}{32\pi^2}} \right) \left(\frac{4}{3} \right) (-i\sqrt{2}) \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) \, dr$$

$$= -\frac{i}{\sqrt{6}} \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr$$

$$\langle 21-1 | \hat{z} | 300 \rangle = 0$$

$$\langle 21-1 | \hat{r} | 300 \rangle$$

$$= \left(\frac{1}{\sqrt{6}} \hat{i} - \frac{i}{\sqrt{6}} \hat{j} \right) \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr$$

$$\langle 210 | \hat{r} | 300 \rangle$$

$$= \langle 210 | x | 300 \rangle \hat{i}$$

$$+ \langle 210 | y | 300 \rangle \hat{j}$$

$$+ \langle 210 | z | 300 \rangle \hat{k}$$

$$\langle 210 | x | 300 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^{\pi} (Y_{10}(\theta, \phi))^* (Y_{30}(\theta, \phi)) \sin^2 \theta \cos \phi \, d\theta \, d\phi \right) \\ \times \left(\int_0^{\infty} r^3 R_{21}(r) R_{30}(r) \, dr \right)$$

$$= 0 = \langle 210 | y | 300 \rangle$$

$$\langle 210 | z | 300 \rangle$$

$$= \left(\int_0^{2\pi} \int_0^{\pi} (Y_{10}(\theta, \phi))^* (Y_{30}(\theta, \phi)) \sin \theta \cos \theta \, d\theta \, d\phi \right)$$

$$\times \left(\int_0^{\infty} r^3 R_{21}(r) R_{30}(r) \, dr \right)$$

$$= \left(\frac{\sqrt{3}}{2} \int_0^{\pi} \cos^2 \theta \sin \theta \, d\theta \right) \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) \, dr$$

$$= \frac{1}{\sqrt{3}} \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) \, dr$$

$$\Rightarrow \langle 210 | \hat{L}_z | 300 \rangle$$

$$= \left(\frac{1}{\sqrt{3}} \hat{L}_z \right) \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr$$

$$\therefore |\langle 211 | \hat{L}_z | 300 \rangle|^2$$

$$= |\langle 21-1 | \hat{L}_z | 300 \rangle|^2$$

$$= |\langle 210 | \hat{L}_z | 300 \rangle|^2$$

$$= \frac{1}{3} \left| \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr \right|^2$$

$$A^{(1)}_{3s \rightarrow 2p} = A^{(2)}_{3s \rightarrow 2p} = A^{(3)}_{3s \rightarrow 2p}$$

$$\equiv A_{3s \rightarrow 2p} = \frac{\omega_{23}^3 q^2}{3\pi\epsilon_0 \hbar c^3} \left(\frac{1}{3} \right) \left| \int_0^\infty r^3 R_{21}(r) R_{30}(r) dr \right|^2$$

All of the three $3s \rightarrow 2p$ transitions are equal, so they must go by $\boxed{1/3}$ via each route.

$$c) \text{ Total decay rate} = 3 A_{3s \rightarrow 2p}$$

$$= \frac{\omega_{23}^3 q^2}{3\pi\epsilon_0 \hbar c^3} \left| \int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr \right|^2$$

$$\omega_{23} = \frac{E_2 - E_3}{\hbar} = \frac{E_1}{\hbar} \left(\frac{1}{4} - \frac{1}{9} \right)$$

$$\Rightarrow \omega_{23} = \frac{5E_1}{36\hbar}$$

$$\int_0^{\infty} r^3 R_{21}(r) R_{30}(r) dr$$

$$= \left(\frac{1}{9a^3\sqrt{2}} \right) \int_0^{\infty} r^3 \left(\frac{r}{a} \right) \left(1 - \frac{2}{3} \frac{r}{a} + \frac{2}{27} \left(\frac{r}{a} \right)^2 \right) e^{-\frac{r}{6a}} dr$$

$$= \frac{1}{9a^4\sqrt{2}} \int_0^{\infty} r^4 e^{-\frac{r}{6a}} dr - \frac{\sqrt{2}}{27a^5} \int_0^{\infty} r^5 e^{-\frac{r}{6a}} dr$$

$$+ \frac{\sqrt{2}}{243a^6} \int_0^{\infty} r^6 e^{-\frac{r}{6a}} dr$$

$$= \frac{1}{9a^4\sqrt{2}} \left(4! \left(\frac{6a}{5} \right)^5 \right) - \frac{\sqrt{2}}{27a^5} \left(5! \left(\frac{6a}{5} \right)^6 \right)$$

$$+ \frac{\sqrt{2}}{243a^6} \left(6! \left(\frac{6a}{5} \right)^7 \right)$$

$$= \frac{a}{9\sqrt{2}} \left(4! \left(\frac{6}{5}\right)^5 - \frac{2}{3} 5! \left(\frac{6}{5}\right)^6 + \frac{2}{27} 6! \left(\frac{6}{5}\right)^7 \right)$$

$$= \frac{a}{9\sqrt{2}} (4!) \left(\frac{6}{5}\right)^5 \left(1 - \frac{2}{3} (120) \left(\frac{6}{5}\right) + \frac{2}{27} (720) \left(\frac{6}{5}\right)^2 \right)$$

$$= \frac{a}{9\sqrt{2}} \left(\frac{4! 6^5}{5^6} \right) = \frac{2^7 3^4}{5^6} \sqrt{2} a$$

$$\therefore 3A_{3s \rightarrow 2p} = \frac{\omega_{23}^3 q^2}{3\pi\epsilon_0 \hbar c^3} \left| \int_0^\infty r^3 R_{21}(r) R_{30}(r) dr \right|^2$$

$$= \frac{q^2}{3\pi\epsilon_0 \hbar c^3} \left(\frac{5E_1}{36\hbar} \right)^3 \left(\frac{2^{15} 3^8}{5^{12}} a^2 \right)$$

$$\tau = \frac{1}{3A_{3s \rightarrow 2p}} = \frac{3\pi \epsilon_0 \hbar c^3}{9^2} \left(\frac{36\hbar}{5E_1} \right)^3 \left(\frac{5^{12}}{2^{15} 3^8} a^2 \right)$$

$$\Rightarrow \boxed{\tau \approx 0.158 \mu\text{s}}$$