

1 a) Plugging $\Psi(\vec{r}) = R(r)Y(\theta, \phi)$ into the equation

$$\left(\hat{p}_r^2 + \frac{\hat{L}^2}{r^2} + 2mV\right)\Psi = 2mE\Psi, \text{ and noting that } \hat{p}_r$$

only acts on R , while \hat{L} only acts on Y , we get

$$\left(\hat{p}_r^2 + \frac{\hat{L}^2}{r^2} + 2mV\right)RY = 2mERY, \text{ or}$$

$$Y\hat{p}_r^2 R + R\frac{\hat{L}^2 Y}{r^2} = 2m(E-V)RY, \text{ or dividing by } RY$$

$$\frac{\hat{p}_r^2 R}{R} + \frac{\hat{L}^2 Y}{r^2 Y} = 2m(E-V). \text{ Multiplying by } r^2 \text{ gives}$$

$$r^2 \frac{\hat{p}_r^2 R}{R} + \frac{\hat{L}^2 Y}{Y} = 2m(E-V)r^2, \text{ or}$$

$$\underbrace{\left[r^2 \frac{\hat{p}_r^2 R}{R} - 2m(E-V)r^2 \right]}_{\text{only depends on } r} + \underbrace{\frac{\hat{L}^2 Y}{Y}}_{\text{only depends on } \theta, \phi} = 0$$

We can then set each term equal to a constant.

I'll call the constant for the Y -equation $\hbar^2 \lambda^2$.

Then

$$\frac{\hat{L}^2 Y}{Y} = \hbar^2 \lambda^2, \text{ or } \frac{\hat{L}^2 Y}{\hbar^2} = \lambda^2 Y$$

The constant for the R -equation must then be $-\hbar^2 \lambda^2$,
so the R -equation is

$$r^2 \frac{\hat{p}_r^2 R}{R} - 2m(E-V)r^2 = -\hbar^2 \lambda^2$$

b) The units of h are $\text{kg} \frac{\text{m}^2}{\text{s}}$. The units of L are also $\text{kg} \frac{\text{m}^2}{\text{s}}$. Thus, L^2/h^2 is unitless, and so λ is unitless.

c) This equation becomes

$$-\left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T F}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2 T F}{\partial \phi^2} \right] = \lambda^2 T F, \text{ or}$$

$$-\frac{F}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T}{\partial \theta} \right) - \frac{T}{\sin^2 \theta} \frac{\partial^2 F}{\partial \phi^2} = \lambda^2 T F. \text{ Dividing by } T F,$$

$$-\frac{1}{T \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T}{\partial \theta} \right) - \frac{1}{F \sin^2 \theta} \frac{\partial^2 F}{\partial \phi^2} = \lambda^2. \text{ Multiplying by } \sin^2 \theta,$$

$$-\frac{\sin \theta}{T} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T}{\partial \theta} \right) - \frac{1}{F} \frac{\partial^2 F}{\partial \phi^2} = \lambda^2 \sin^2 \theta, \text{ or}$$

$$0 = \underbrace{\left[\frac{\sin \theta}{T} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T}{\partial \theta} \right) + \lambda^2 \sin^2 \theta \right]}_{\text{only depends on } \theta} + \underbrace{\left[\frac{1}{F} \frac{\partial^2 F}{\partial \phi^2} \right]}_{\text{only depends on } \phi}$$

We can then separate these into two equations:

$$\frac{\sin \theta}{T} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T}{\partial \theta} \right) + \lambda^2 \sin^2 \theta = -\mu$$

$$\frac{1}{F} \frac{\partial^2 F}{\partial \phi^2} = \mu$$

d) This equation is $F'' = \mu F$. We have two possibilities. If $\mu < 0$, then we have solutions

$$F(\phi) = e^{ik\phi}, \text{ where } k = \pm\sqrt{-\mu}$$

If $\mu > 0$, we have solutions

$$F(\phi) = e^{K\phi}, \text{ where } K = \pm\sqrt{\mu}$$

e) If $\mu > 0$, our most general solution is

$$F(\phi) = Ae^{\sqrt{\mu}\phi} + Be^{-\sqrt{\mu}\phi}$$

We need $F(\phi + 2\pi n) = F(\phi)$. This clearly can't happen. As $n \rightarrow \infty$, the first term $\rightarrow \infty$, while the second $\rightarrow 0$. So we can't come back to $F(\phi)$.

If $\mu < 0$, we have $F(\phi) = Ae^{ik\phi} + Be^{-ik\phi}$.

In this case, $F(\phi + 2\pi n) = F(\phi)$ provided $e^{i2\pi nk}$ and $e^{-i2\pi nk}$ are both 1. This happens iff k is an integer, call it m .

Thus, we see that μ is negative and $\sqrt{-\mu} = m$, or $\mu = -m^2$.

f) We now get $F(\phi) = e^{im\phi}$, $m = 0, \pm 1, \pm 2, \dots$

Note the \pm means we're getting both the $e^{ik\phi}$ and the $e^{-ik\phi}$ solutions.

g) Plugging in $\mu = -m^2$ to our T-equation from (c),

$$\sin\theta \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial T}{\partial\theta} \right) = (m^2 - \lambda^2 \sin^2\theta) T$$

~~The~~ The original equation for Y was

$$\frac{\hat{L}^2 Y}{\hbar^2} = \lambda^2 Y, \quad \text{or} \quad \hat{L}^2 Y = \hbar^2 \lambda^2 Y.$$

Now we know $\lambda^2 = l(l+1)$, so

$\hat{L}^2 Y = \hbar^2 l(l+1)Y$, so Y is an eigenfun of \hat{L}^2 w/ eigenvalue $\hbar^2 l(l+1)$.

h)

$\hat{L}_z = \hat{z} \cdot \hat{L}$

$$= \frac{\hbar}{i} \left(\hat{z} \cdot \hat{\phi} \frac{\partial}{\partial \theta} - \frac{\hat{z} \cdot \hat{\theta}}{\sin \theta} \frac{\partial}{\partial \phi} \right)$$

Note $\hat{z} \cdot \hat{\phi} = 0$, b/c these are always perpendicular. Meanwhile, $\hat{z} \cdot \hat{\theta} = -\sin \theta$. Thus,

$$\hat{L}_z = \frac{\hbar}{i} \frac{\partial}{\partial \phi}$$

$$\begin{aligned} \text{i) } \hat{L}_z P_l^m(\cos \theta) e^{im\phi} &= \frac{\hbar}{i} \frac{\partial}{\partial \phi} P_l^m(\cos \theta) e^{im\phi} \\ &= P_l^m(\cos \theta) \frac{\hbar}{i} \frac{\partial}{\partial \phi} e^{im\phi} \\ &= P_l^m(\cos \theta) i m e^{im\phi} \end{aligned}$$

So $\hat{L}_z Y_l^m = i m Y_l^m$, and Y_l^m is an eigenfun of

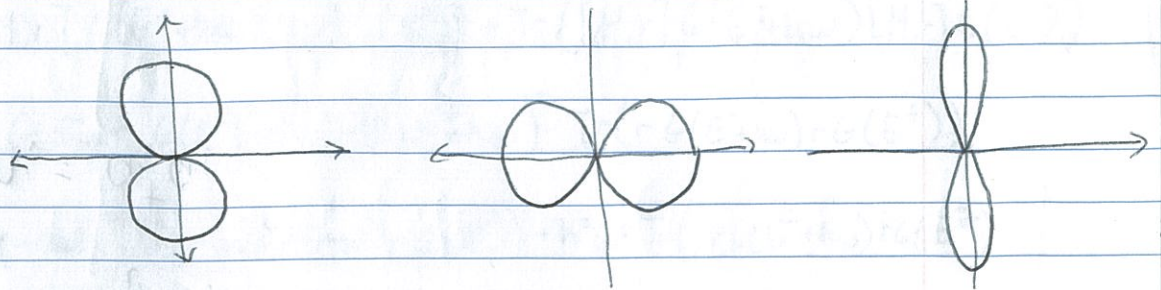
\hat{L}_z w/ eigenvalue $i m$.

$$Y_1^{1*} Y_1^1 = \sin^2 \theta$$

$$Y_1^{0*} Y_1^0 = \cos^2 \theta$$

$$Y_2^{2*} Y_2^2 = \sin^4 \theta$$

j)



$$k) \vec{j}_1^0 = \text{Re} \left[\cos \theta \frac{\vec{\nabla}}{im} \cos \theta \right] = \text{Re} \left[\cos \theta \frac{\hat{\theta}}{im} \frac{\partial}{\partial \theta} \cos \theta \right] = 0$$

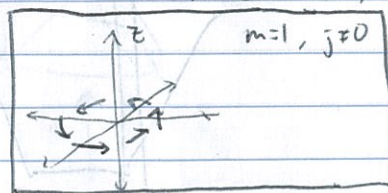
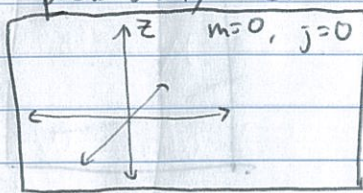
$$\vec{j}_1^1 = \text{Re} \left[\sin \theta e^{-i\phi} \frac{\vec{\nabla}}{im} \sin \theta e^{i\phi} \right]$$

$$= \text{Re} \left[\sin \theta e^{-i\phi} \frac{1}{im} \left(\frac{\hat{\theta}}{r} \frac{\partial}{\partial \theta} + \frac{\hat{\phi}}{r \sin \theta} \frac{\partial}{\partial \phi} \right) \sin \theta e^{i\phi} \right]$$

$$= \text{Re} \left[\sin \theta e^{-i\phi} \frac{1}{im} \left(\hat{\theta} \frac{\cos \theta e^{i\phi}}{r} + \hat{\phi} \frac{i}{r} e^{i\phi} \right) \right]$$

$$= \text{Re} \left[\hat{\theta} \frac{1}{imr} \cos \theta \sin \theta + \hat{\phi} \frac{\sin \theta}{mr} \right] = \frac{\sin \theta}{mr} \hat{\phi}$$

So when $L_z = 0$, no \vec{j} . But when $L_z = \hbar$, we have a probability current in the $\hat{\phi}$ direction, around \hat{z}



$$l) \hat{L}^2 \hat{L}_z \psi = \frac{1}{r^2} \left[-\frac{\hbar^2}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \left(\frac{\hbar}{i} \frac{\partial \psi}{\partial \phi} \right) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\hbar^2}{i} \frac{\partial^3 \psi}{\partial \phi^3} \right]$$

$$= \frac{\hbar}{i} \frac{\partial}{\partial \phi} \left[\frac{1}{r^2} \left[-\frac{\hbar^2}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \psi}{\partial \theta} \right) \right] + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 \psi}{\partial \phi^2} \right]$$

$$= \hat{L}_z \hat{L}^2 \psi, \text{ so } [\hat{L}_z, \hat{L}^2] = 0$$