

# ECE 598HH: Advanced Wireless Networks and Sensing Systems

## Lecture 8: Localization Part 1

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# Wireless Localization / Positioning

**The process of obtaining a human or object's location using wireless signals**

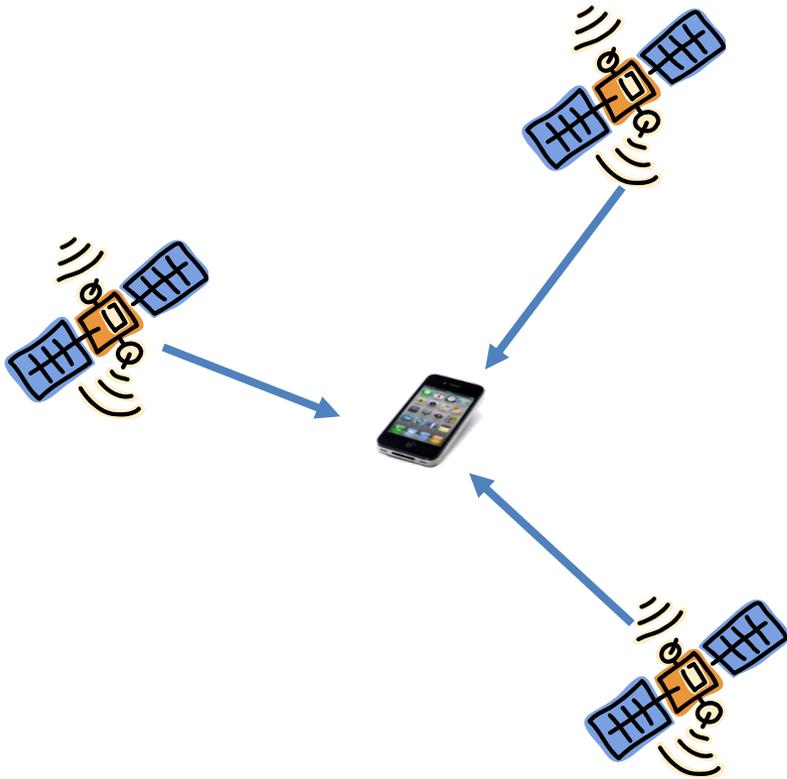
## Applications:

- Navigation: outdoors (GPS) and indoors (e.g., museum)
- Location based services: Tagging, Reminder, Ads
- Virtual Reality and Motion Capture
- Gestures, writing in the air
- Behavioral Analytics (Health, activities, etc.)
- Locating misplaced items (keys)
- Location based security
- Delivery drones

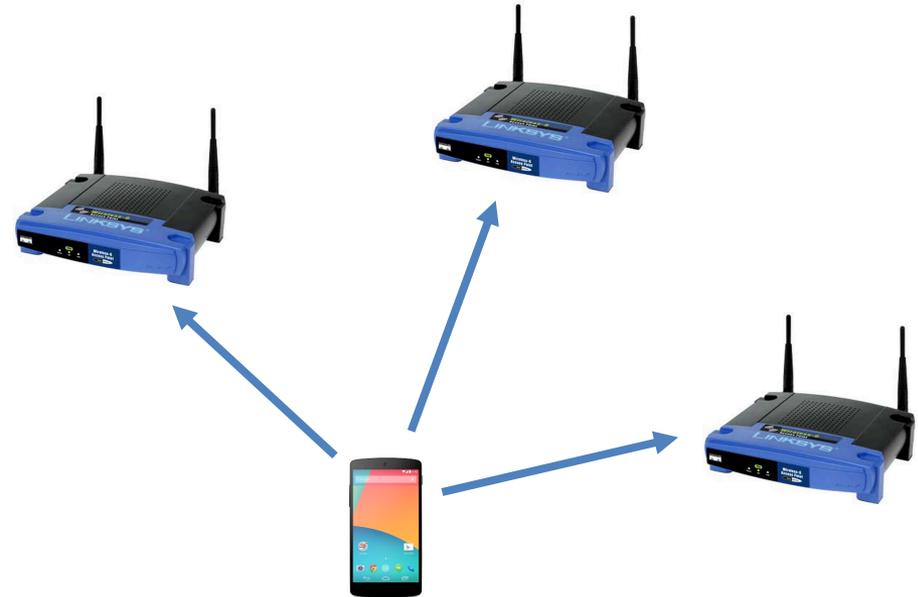


# Wireless Localization Architecture.

- Device based: A device uses incoming signal from one or more “anchors” to determine its own location



- Network based: Anchors (or Access points) use the signal coming from device to determine its location



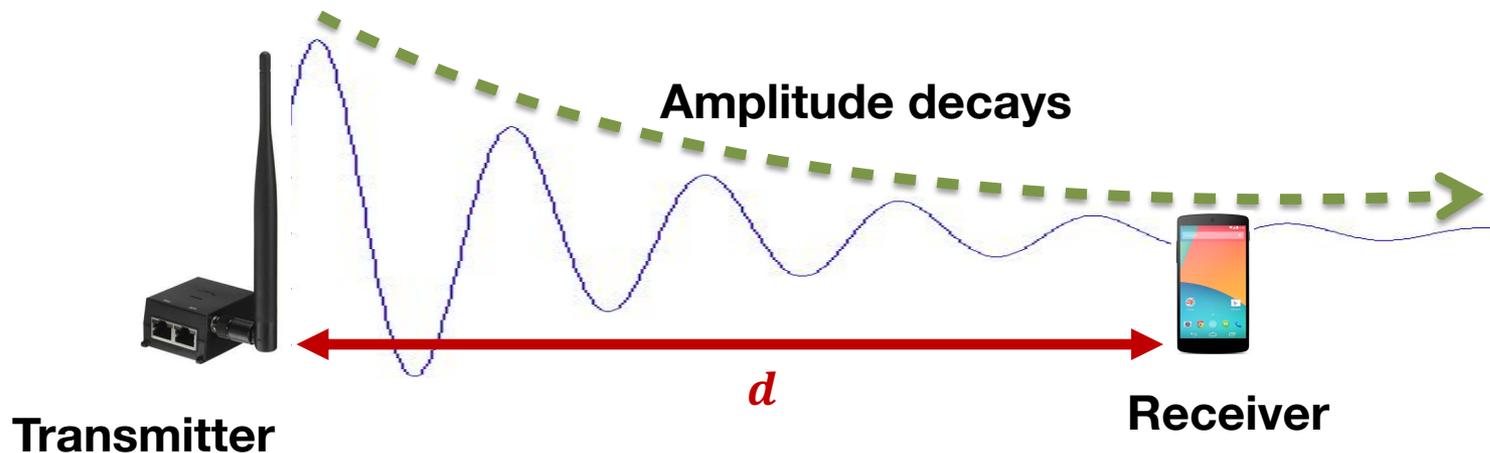
# Wireless Localization

This Lecture: Focus on WiFi Localization

Future Lectures: Other wireless technologies

# Method 1: RSSI Based Localization

- Higher received power → Closer
- Lower received power → Farther

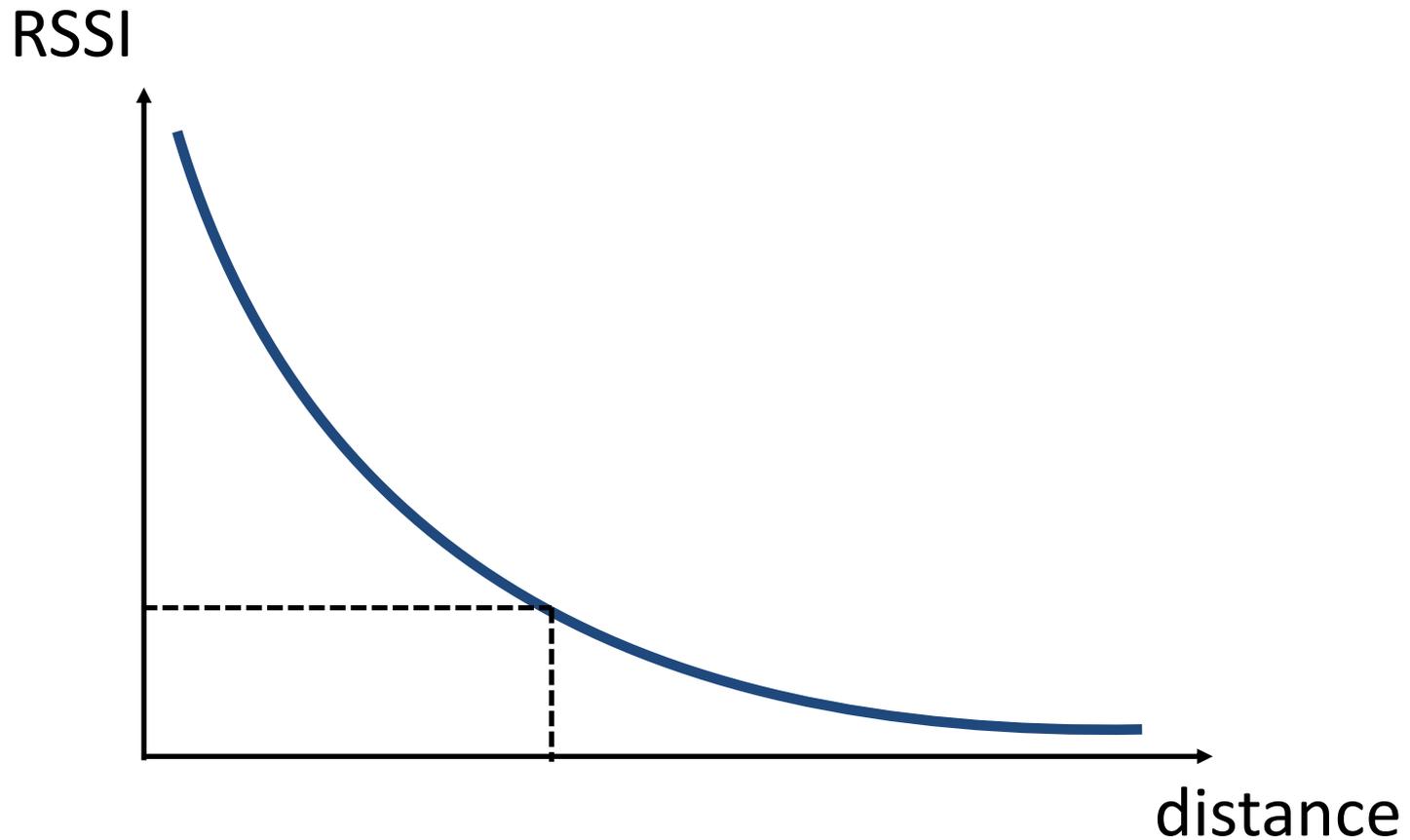


$$P_{Rx} = \frac{G_{Tx} G_{Rx} \lambda^2}{(4\pi d)^2} P_{Tx} \quad \Rightarrow \quad RSSI \propto \frac{1}{d^2}$$

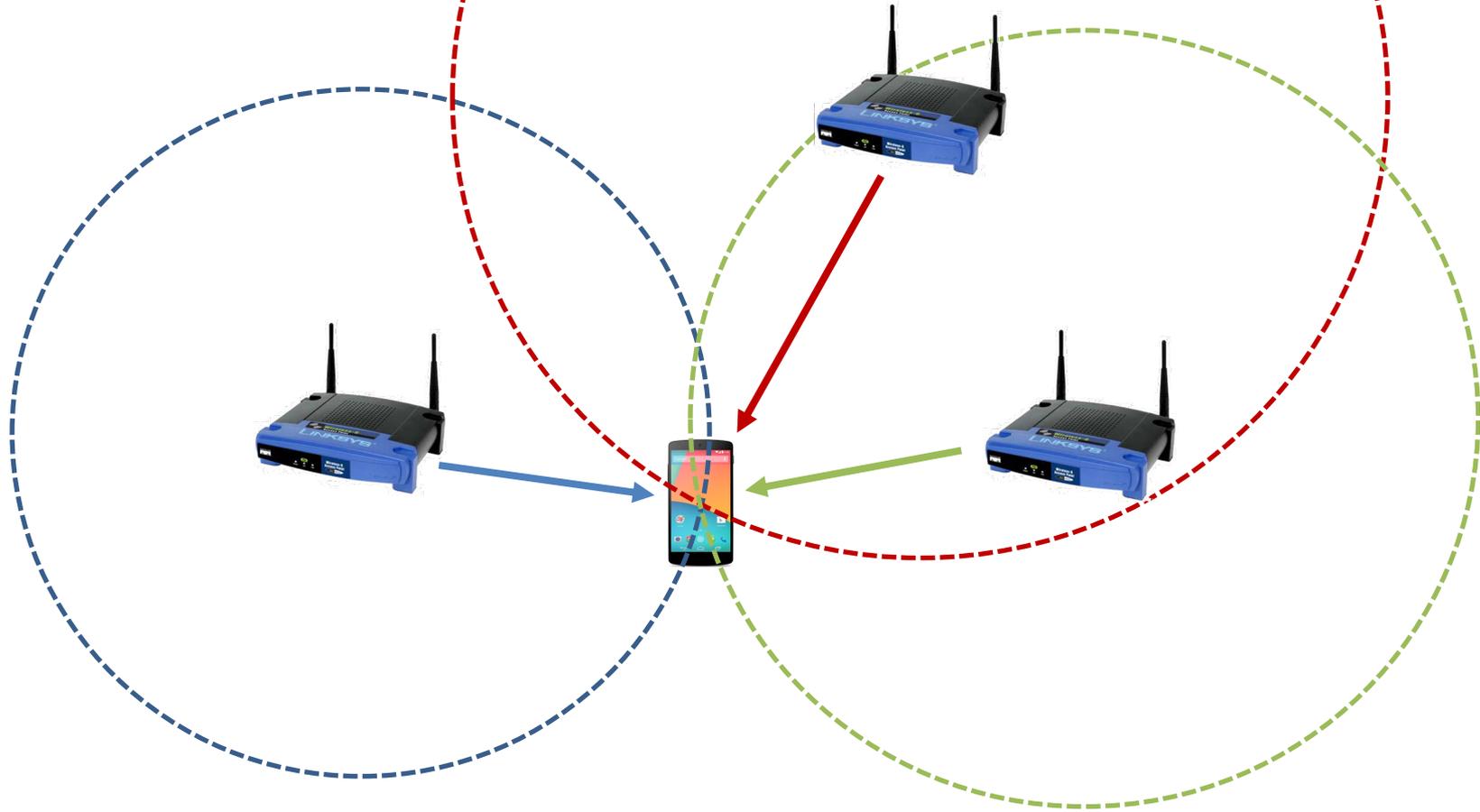
Use RSSI to estimate distance from APs!

# Method 1: RSSI Based Localization

$$RSSI \propto \frac{1}{d^2}$$



# Method 1: RSSI Based Localization

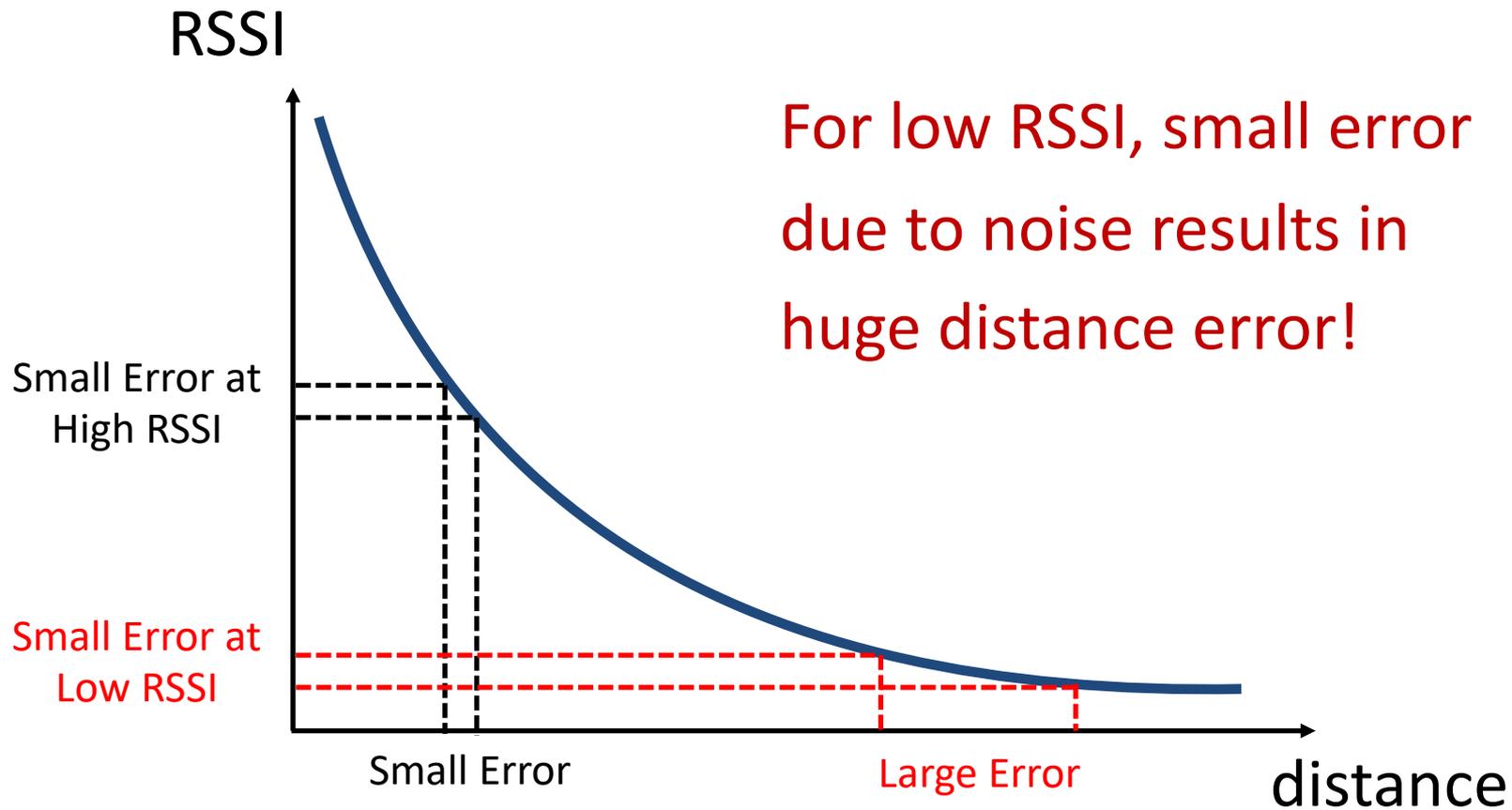


**Trilateration**

# Method 1: RSSI Based Localization

**Pros:** Very simple, no hardware modifications

**Cons:** Highly inaccurate!

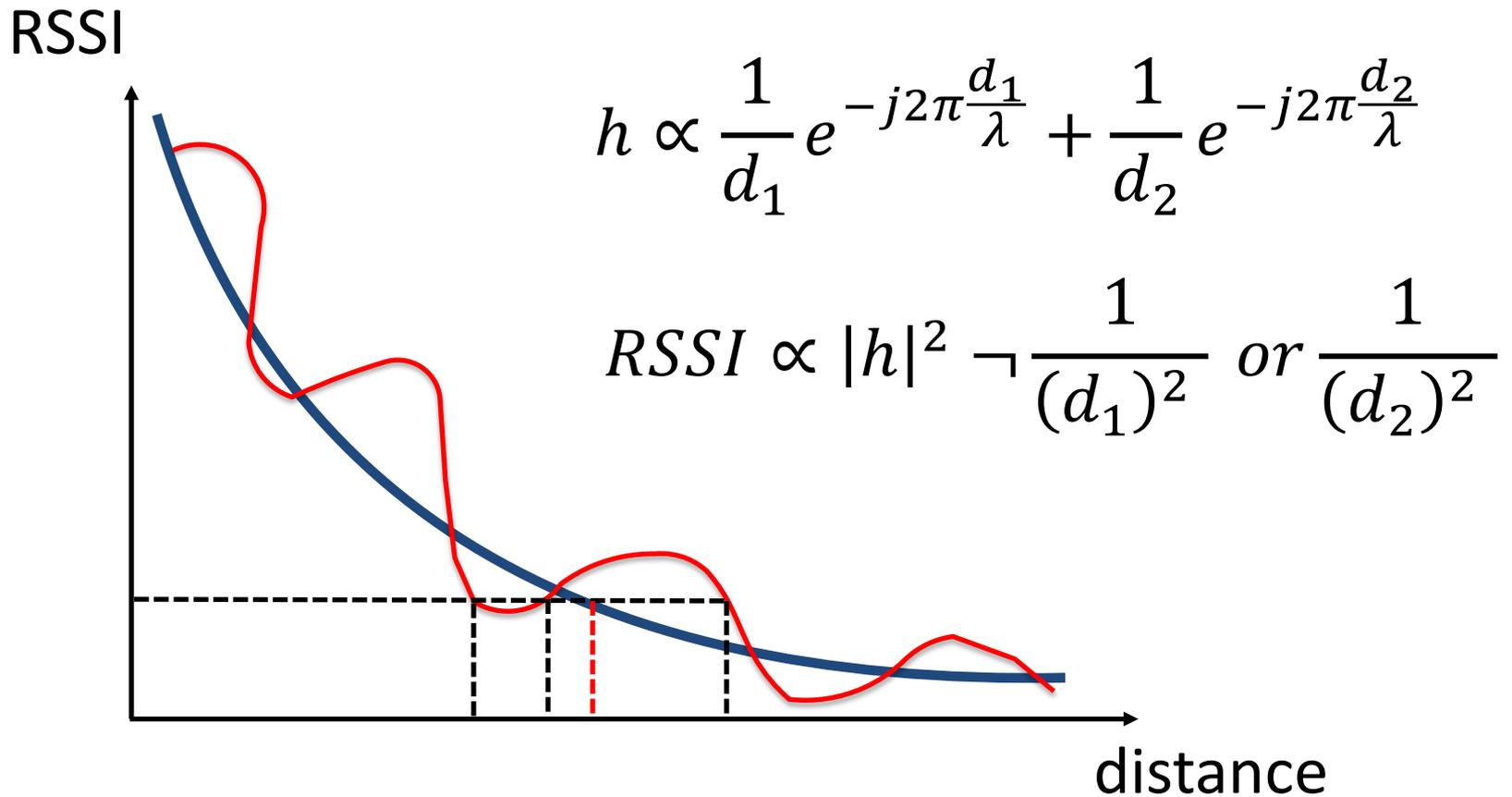


# Method 1: RSSI Based Localization

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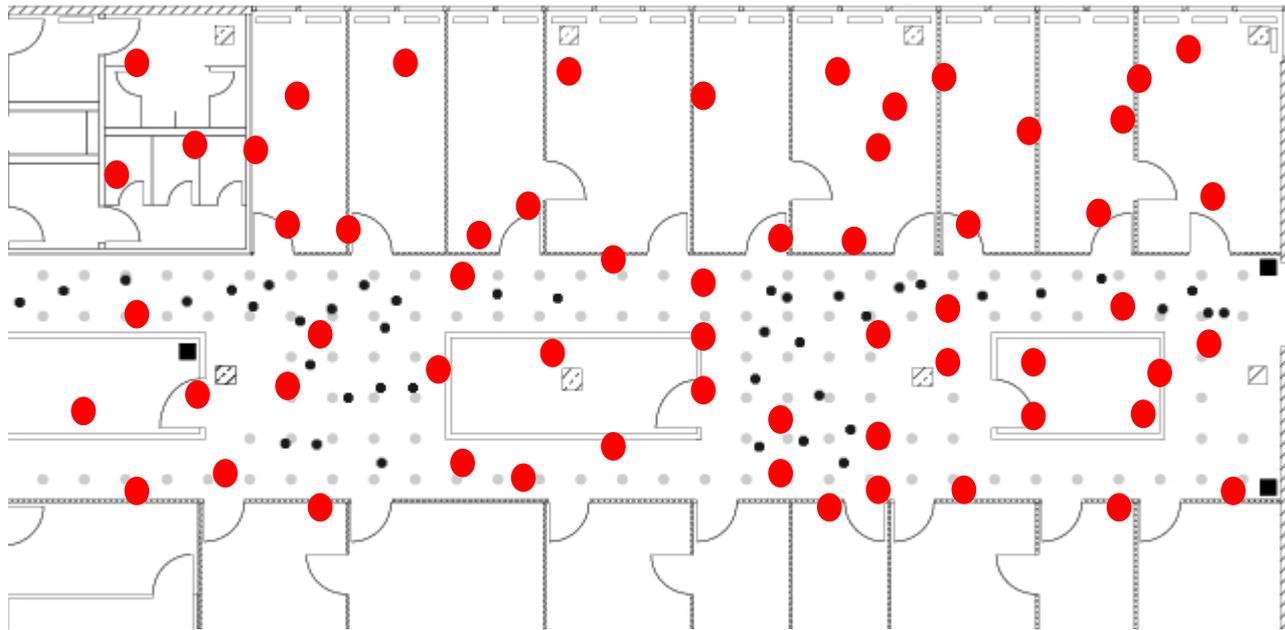
Does not work with multipath!



# Method 1: RSSI Based Localization

## **Solution:** Fingerprinting

Measure and records RSSI fingerprints at each location (war-driving)

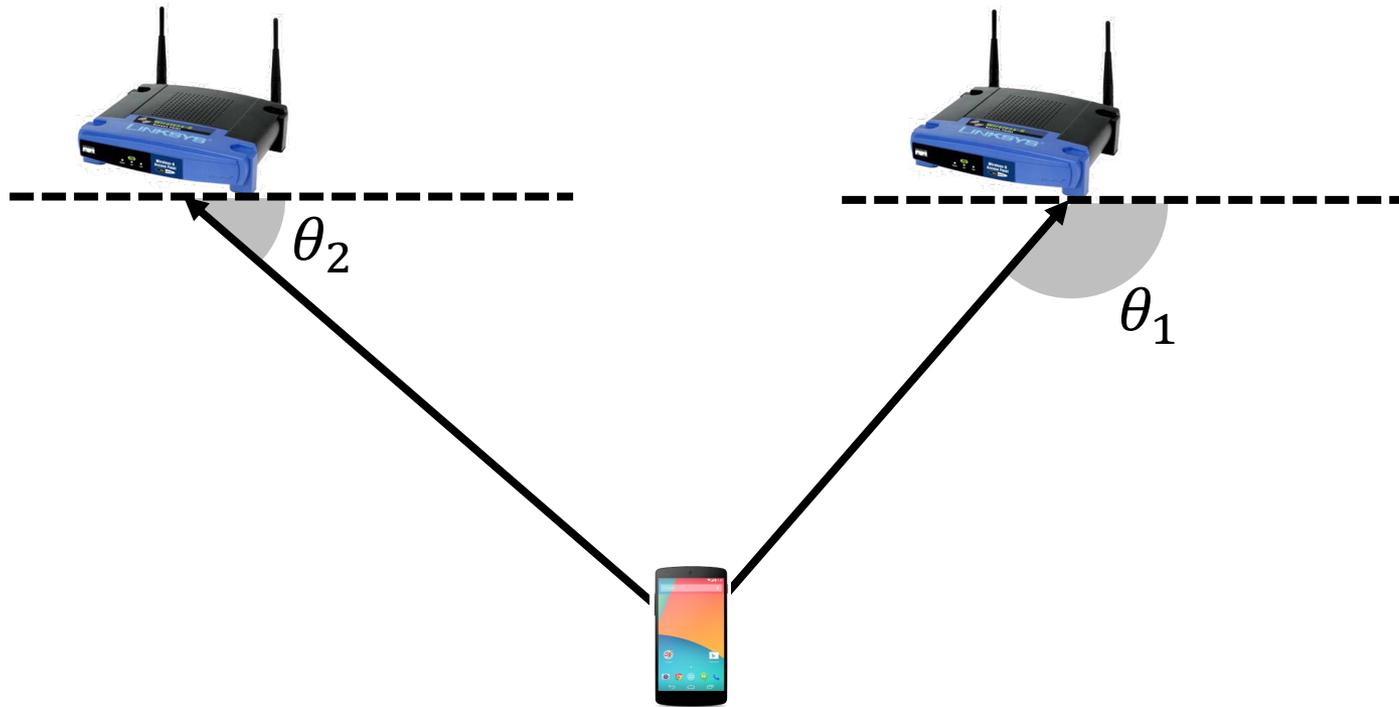


**Pros:** Works with multipath, No need to know AP locations!

**Cons:** Changes in environment/movement → change RSSI!  
Continuous training is needed. Lots of effort!

# Method 2: AoA Based Localization

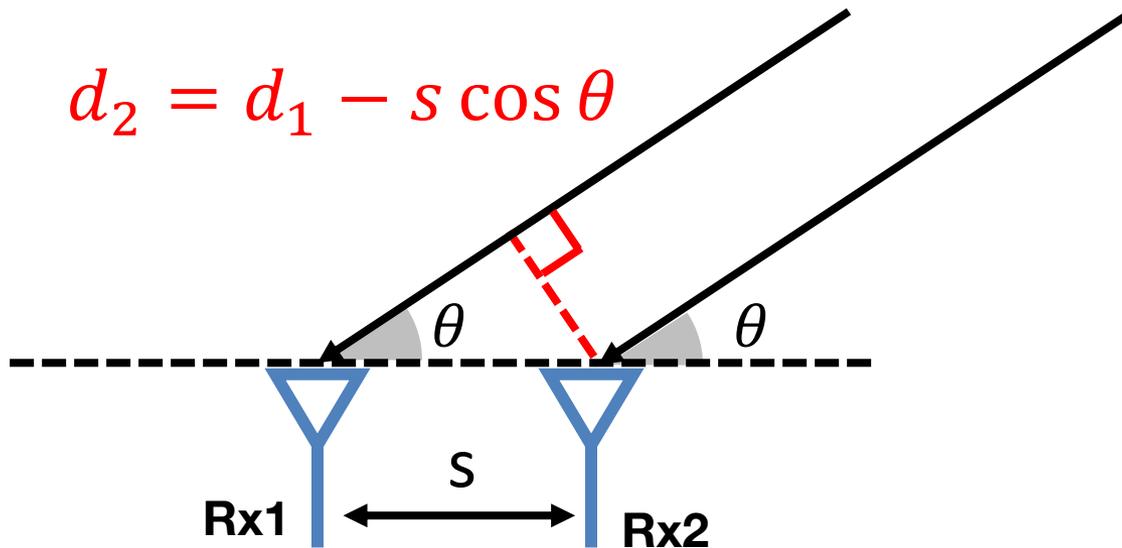
Measure Angle of Arrival (AoA) from device to each AP



**Triangulation**

# Method 2: AoA Based Localization

Measure Angle of Arrival (AoA) from device to each AP

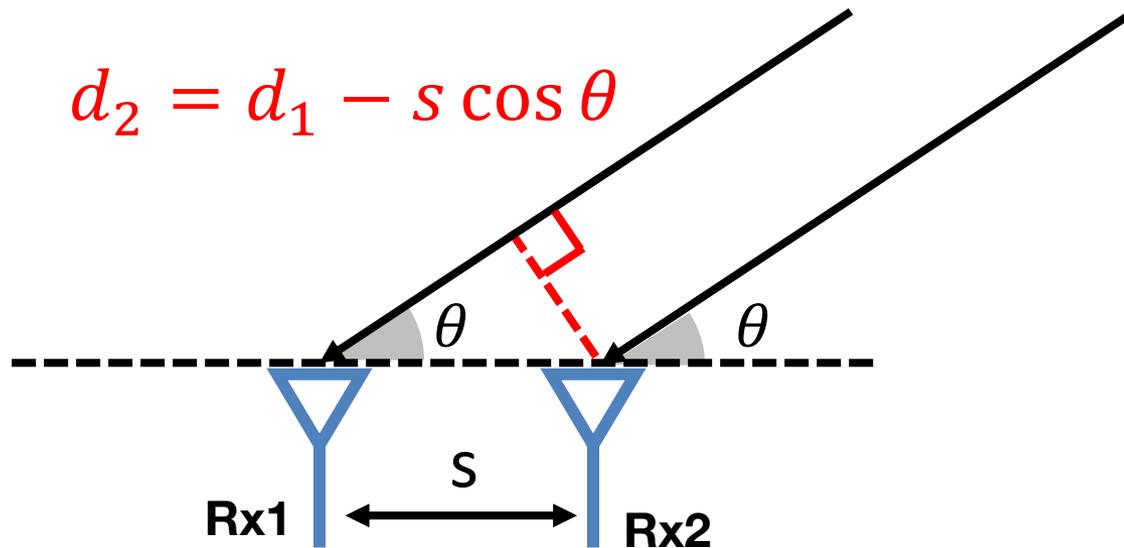


$$h_1 \propto e^{-j2\pi \frac{d_1}{\lambda}} \quad h_2 \propto e^{-j2\pi \frac{d_2}{\lambda}} = e^{-j2\pi \frac{d_1 - s \cos \theta}{\lambda}}$$

$$\Delta\Phi = \angle h_2 - \angle h_1 = 2\pi s \cos \theta / \lambda \text{ mod } 2\pi$$

# Method 2: AoA Based Localization

Measure Angle of Arrival (AoA) from device to each AP



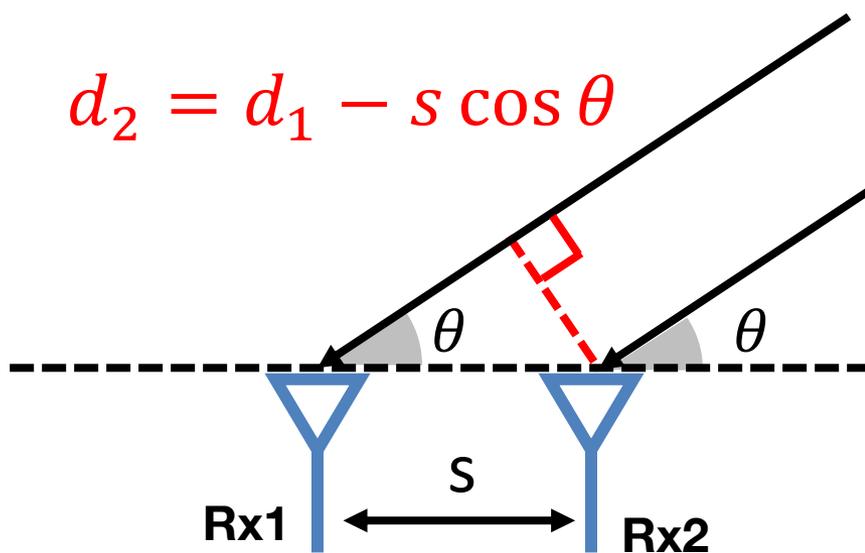
$$\Delta\Phi = \angle h_2 - \angle h_1 = 2\pi s \cos \theta / \lambda \text{ mod } 2\pi$$

**Ambiguity:**  $\exists \theta_1 \neq \theta_2 \mid \Delta\Phi_1 = \Delta\Phi_2 \text{ mod } 2\pi$

**To avoid ambiguity, we want:**  $-\pi \leq \Delta\Phi \leq \pi$

# Method 2: AoA Based Localization

Measure Angle of Arrival (AoA) from device to each AP



**We want:**

$$-\pi \leq \Delta\Phi \leq \pi$$

**We have:**

$$-1 \leq \cos \theta \leq 1$$

$$-2\pi \frac{s}{\lambda} \leq 2\pi \frac{s}{\lambda} \cos \theta \leq 2\pi \frac{s}{\lambda}$$

$$-2\pi \frac{s}{\lambda} \leq \Delta\Phi \leq 2\pi \frac{s}{\lambda}$$

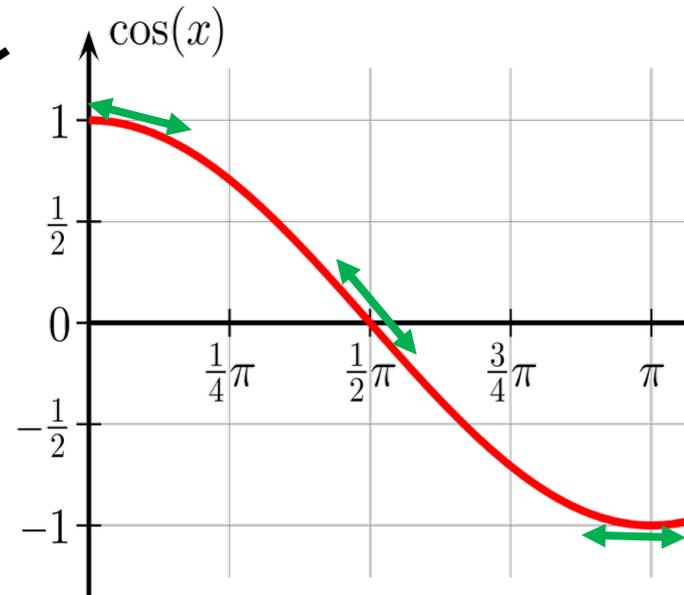
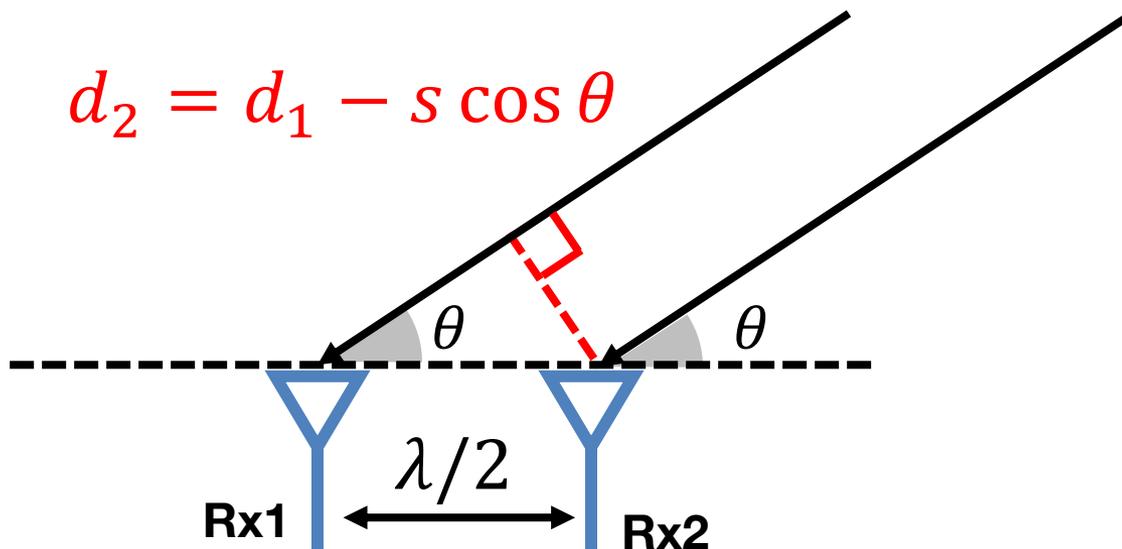
**Set:  $s = \lambda/2$**

$$-\pi \leq \Delta\Phi \leq \pi$$

# Method 2: AoA Based Localization

Measure Angle of Arrival (AoA) from device to each AP

$$d_2 = d_1 - s \cos \theta$$



**Pros:** More accurate than RSSI, Simple!

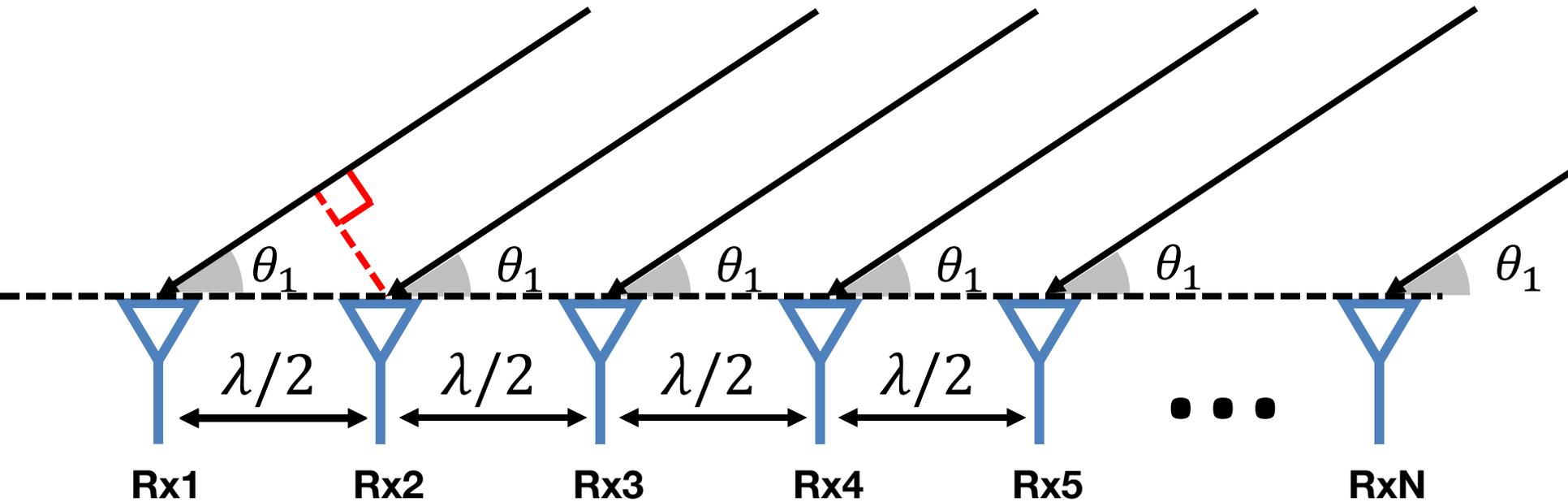
**Cons:** Ambiguity:  $\cos \theta = \cos(-\theta)$

Error not linear with  $\theta$  due to  $\cos \theta$

Requires 2 Antennas separated  $\lambda/2$

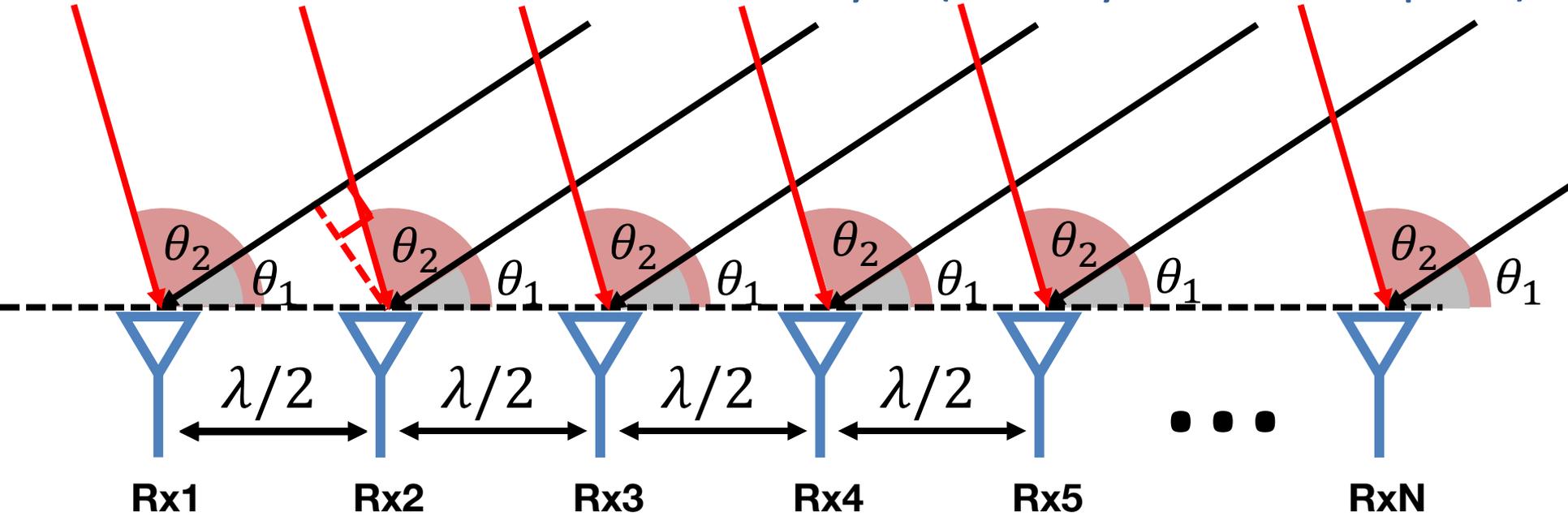
Does not work with multipath!

# Method 3: Antenna Arrays (ArrayTrack Paper)



$$h_k = \alpha_1 e^{-j2\pi \frac{d_1 - k s \cos \theta_1}{\lambda}} = \alpha_1 e^{-j\phi_1 + k\pi \cos \theta_1}$$

# Method 3: Antenna Arrays (ArrayTrack Paper)



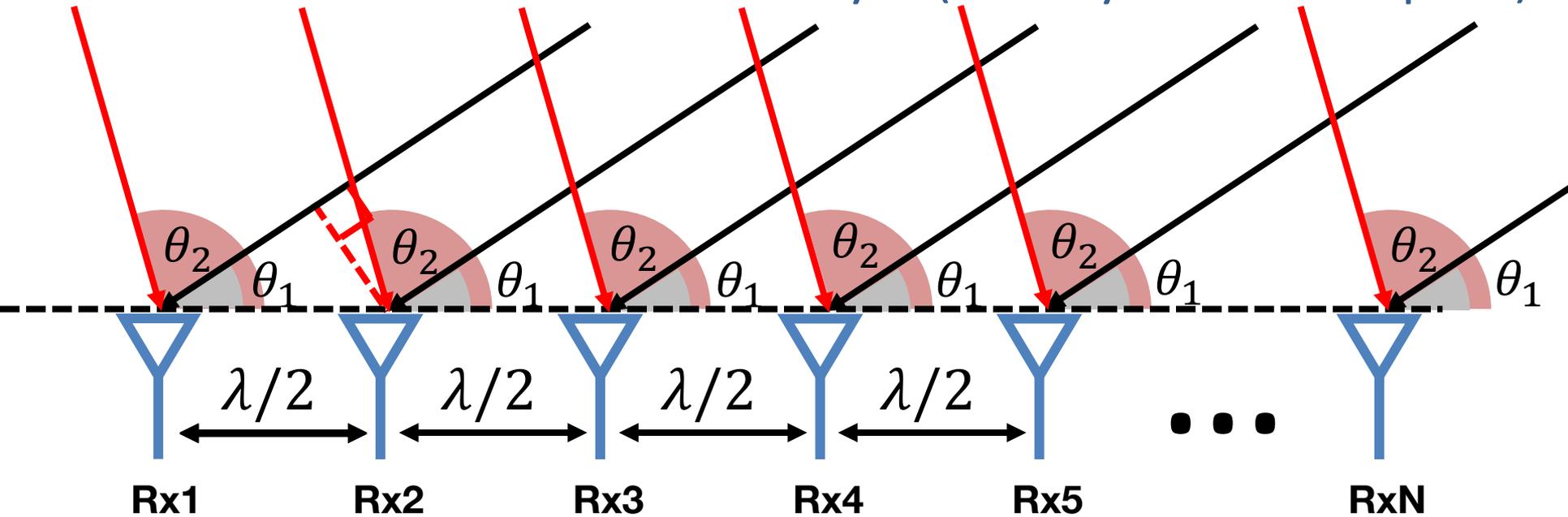
$$h_k = \alpha_1 e^{-j2\pi \frac{d_1 - k s \cos \theta_1}{\lambda}} = \alpha_1 e^{-j\phi_1 + k\pi \cos \theta_1}$$

$$+ \alpha_2 e^{-j2\pi \frac{d_2 - k s \cos \theta_2}{\lambda}} + \alpha_2 e^{-j\phi_2 + k\pi \cos \theta_2}$$

For L paths  $\rightarrow$

$$h_k = \sum_{l=1}^L \alpha_l e^{jk\pi \cos \theta_l - j\phi_l}$$

# Method 3: Antenna Arrays (ArrayTrack Paper)



$$h_k = \sum_{l=1}^L \alpha_l e^{jk\pi \cos \theta_l - j\phi_l}$$

Multipath Profile: 
$$P(\theta) = \left| \sum_{k=1}^N h_k e^{-jk\pi \cos \theta} \right|^2$$

# Method 3: Antenna Arrays (ArrayTrack Paper)

$$P(\theta) = \left| \sum_{k=1}^N h_k e^{-jk\pi \cos \theta} \right|^2 \quad h_k = \sum_{l=1}^L \alpha_l e^{jk\pi \cos \theta_l - j\phi_l}$$

$$P(\theta_1) = \left| \sum_{k=1}^N h_k e^{-jk\pi \cos \theta_1} \right|^2$$

$$= \left| \sum_{k=1}^N \left( \sum_{l=1}^L \alpha_l e^{jk\pi \cos \theta_l - j\phi_l} \right) e^{-jk\pi \cos \theta_1} \right|^2$$

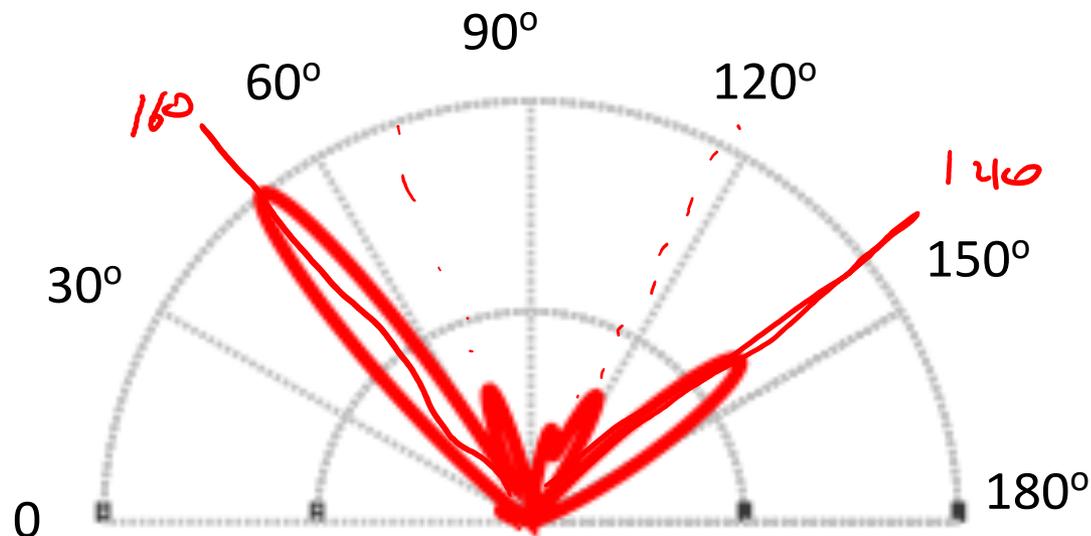
$$= \left| \sum_{k=1}^N \alpha_1 e^{-j\phi_1} + \sum_{k=1}^N \left( \sum_{l=2}^L \alpha_l e^{jk\pi(\cos \theta_l - \cos \theta_1) - j\phi_l} \right) \right|^2$$

$$= \left| N\alpha_1 e^{-j\phi_1} + \sum_{l=2}^L \alpha_l e^{-j\phi_l} \left( \sum_{k=1}^N e^{jk\pi(\cos \theta_l - \cos \theta_1)} \right) \right|^2 \approx N^2 \alpha_1^2$$

# Method 3: Antenna Arrays (ArrayTrack Paper)

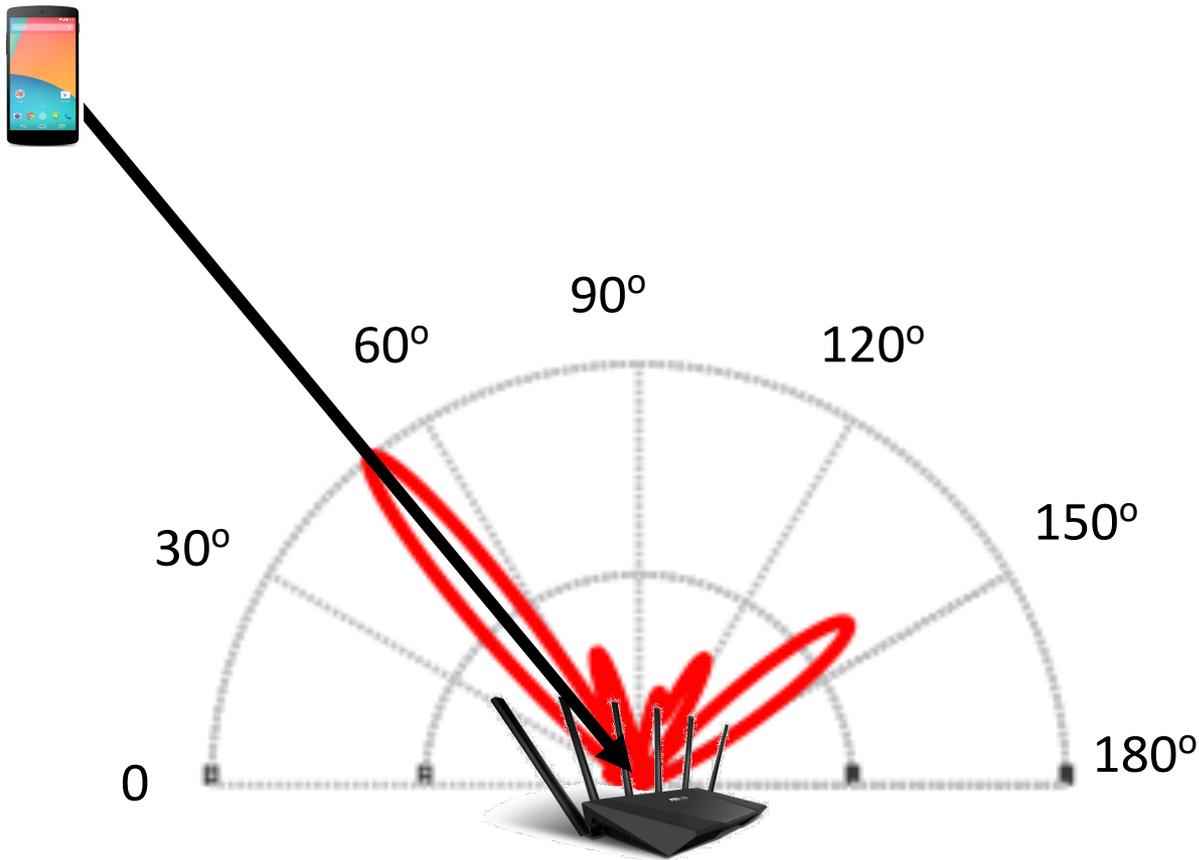
$$h_k = \sum_{l=1}^L \alpha_l e^{jk\pi \cos \theta_l - j\phi_l}$$

$$\text{Multipath Profile: } P(\theta) = \left| \sum_{k=1}^N h_k e^{-jk\pi \cos \theta} \right|^2$$



# Method 3: Antenna Arrays (ArrayTrack Paper)

Which is the Line-of-Sight Path (Direct Path)?  
Strongest Path!

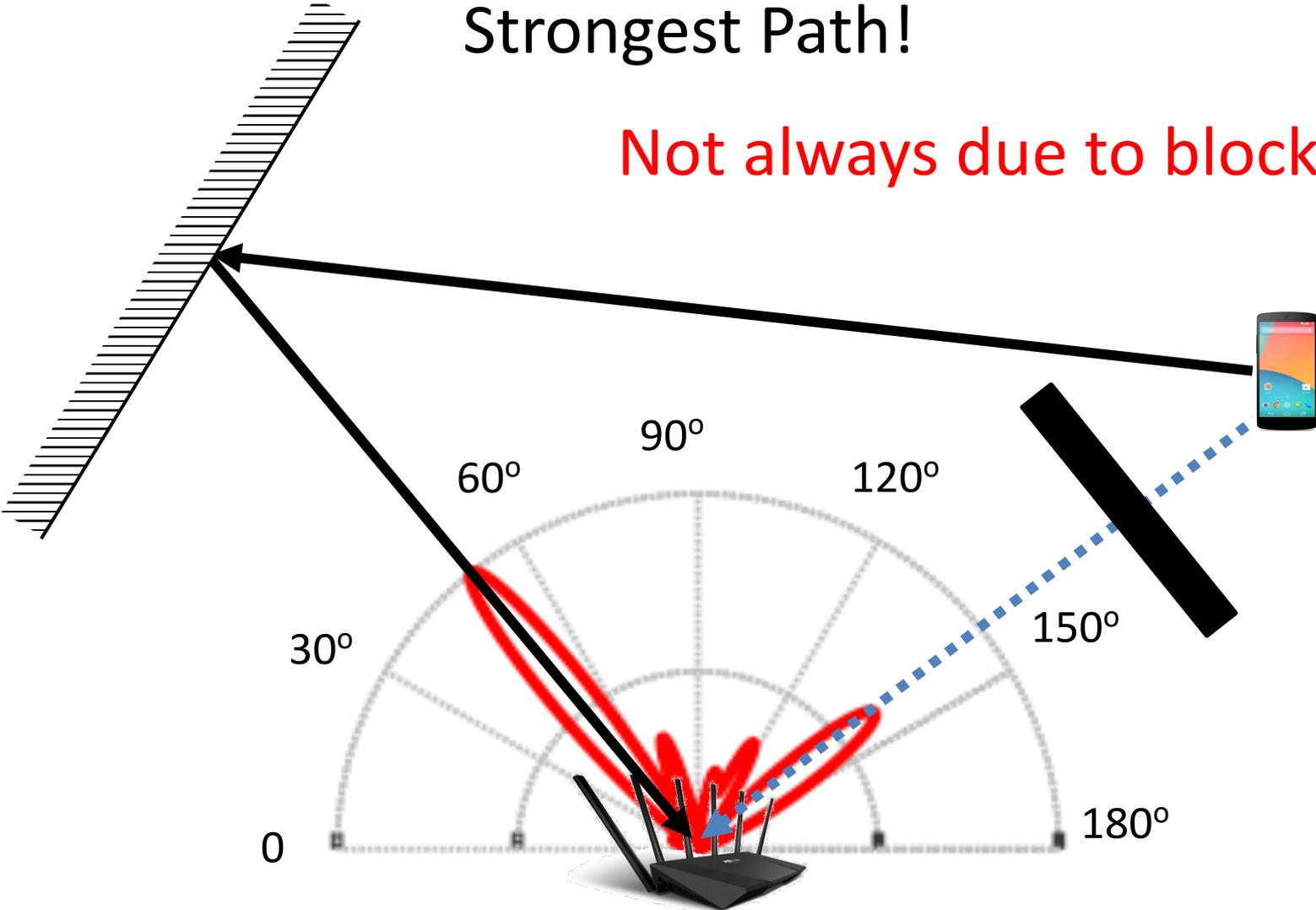


# Method 3: Antenna Arrays (ArrayTrack Paper)

Which is the Line-of-Sight Path (Direct Path)?

Strongest Path!

Not always due to blockage!

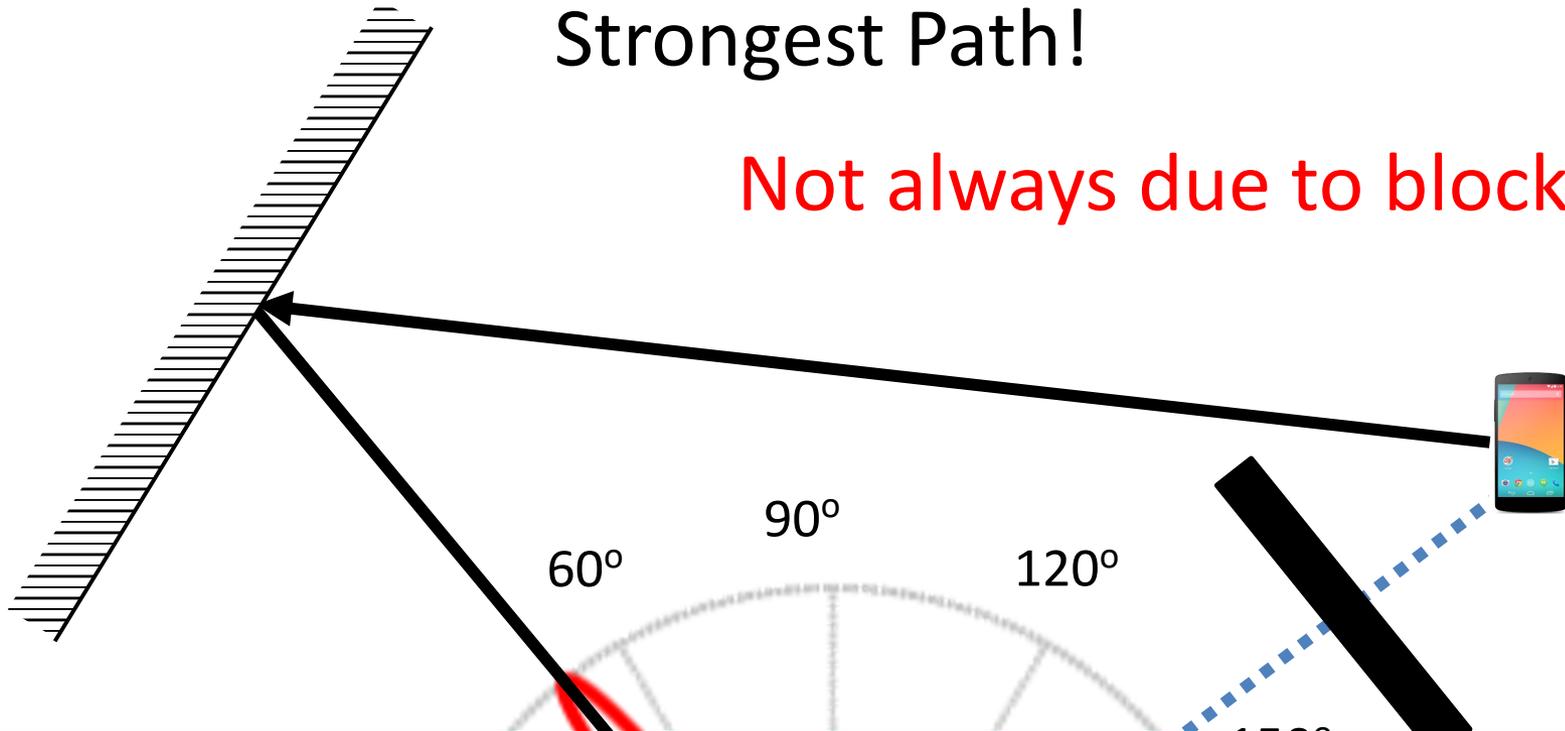


# Method 3: Antenna Arrays (ArrayTrack Paper)

Which is the Line-of-Sight Path (Direct Path)?

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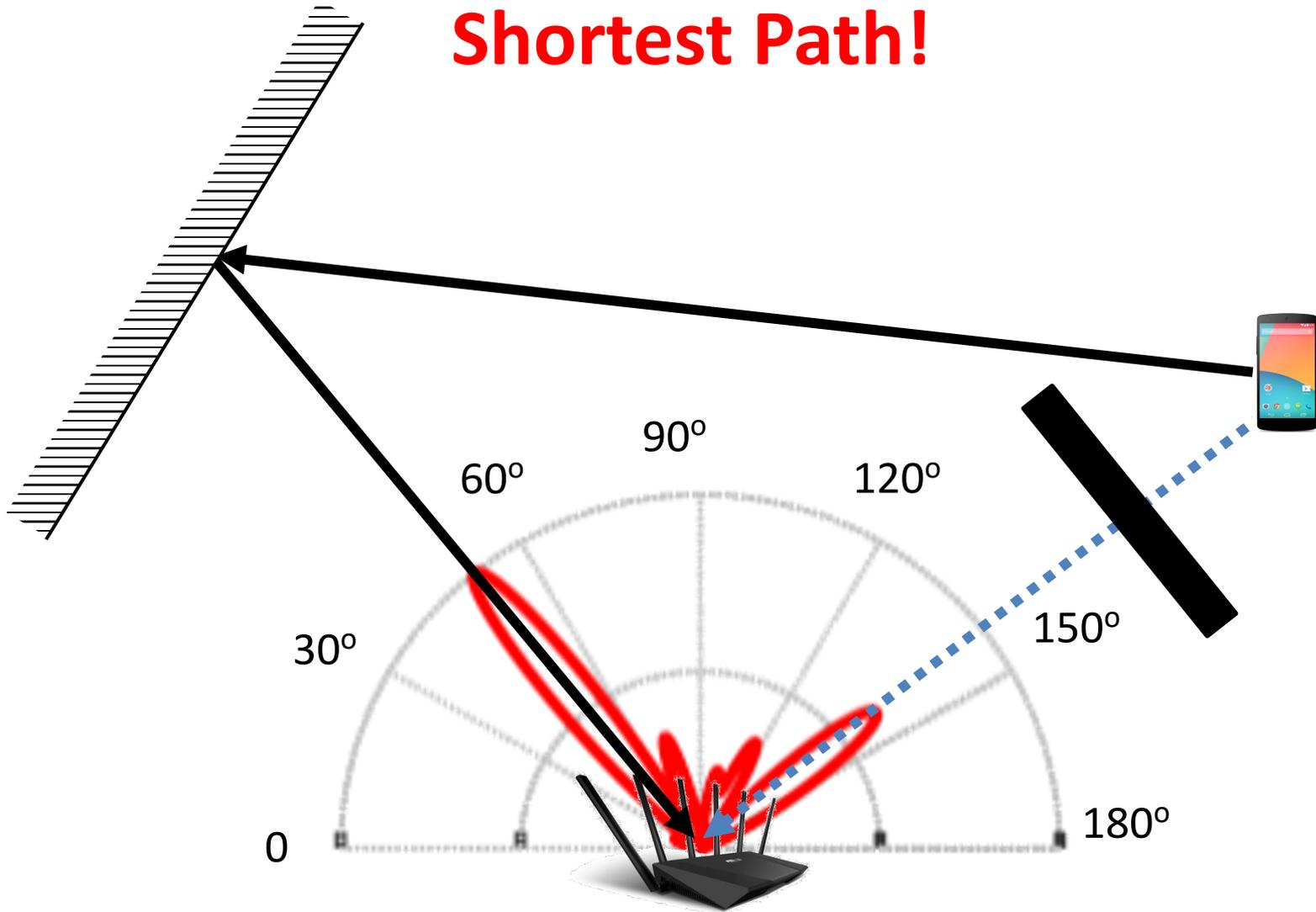
## ArrayTrack: Leverage Mobility

- Line of sight path relatively stable with mobility
- Multipath reflection changes faster with mobility

# Method 3: Antenna Arrays

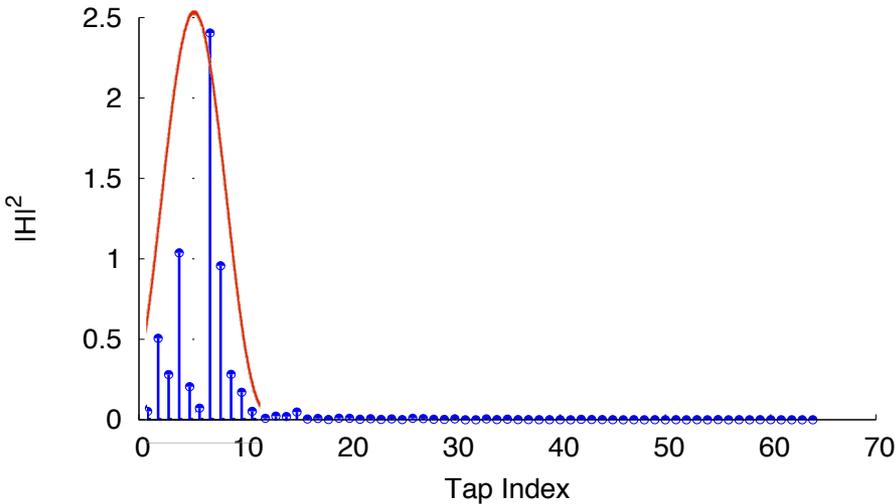
Which is the Line-of-Sight Path (Direct Path)?

**Shortest Path!**



# Method 3: Antenna Arrays

Which is the Shortest Path (Direct Path)?



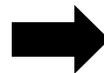
Multipath Profile vs Time

$$\Delta\tau = \frac{\Delta d}{c}$$

$$\Delta d = 1m$$

$$c = 3 \times 10^8 m/s$$

$$\Delta\tau = 3.3ns$$



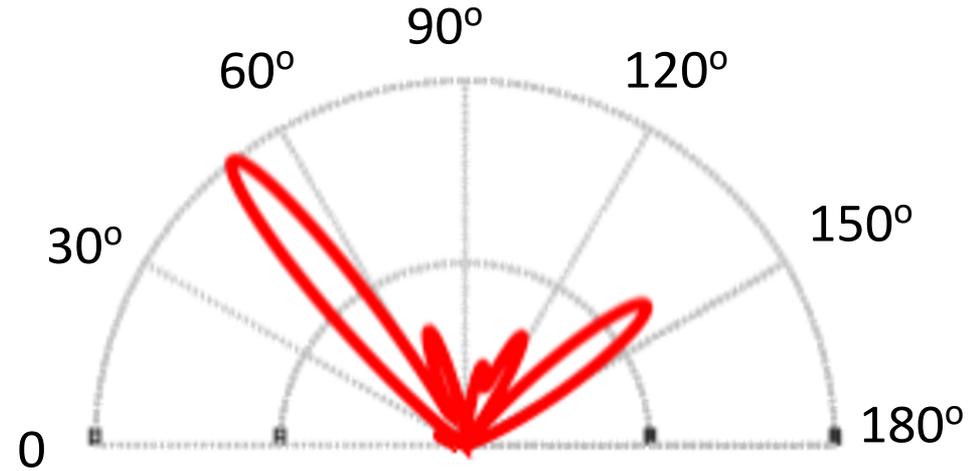
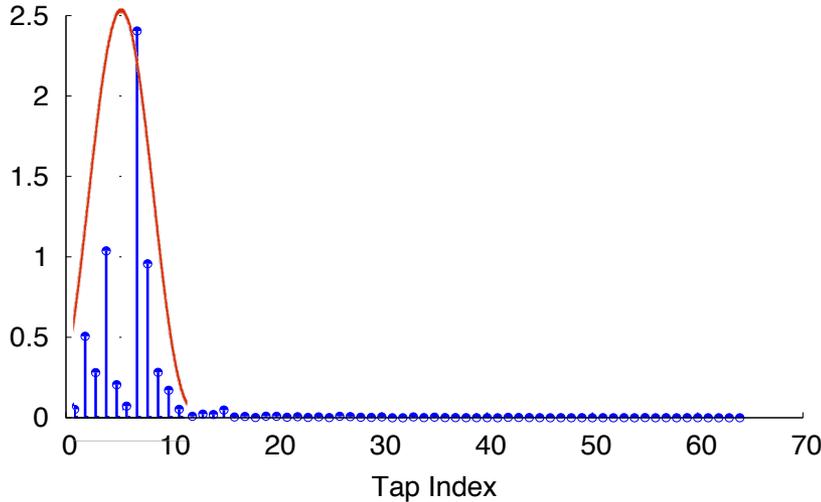
Requires a sampling rate

$$1/\Delta\tau = 300MHz$$

802.11n bandwidth = 40MHz

# Method 3: Antenna Arrays

## Which is the Shortest Path (Direct Path)?



### Multipath Profile vs Time

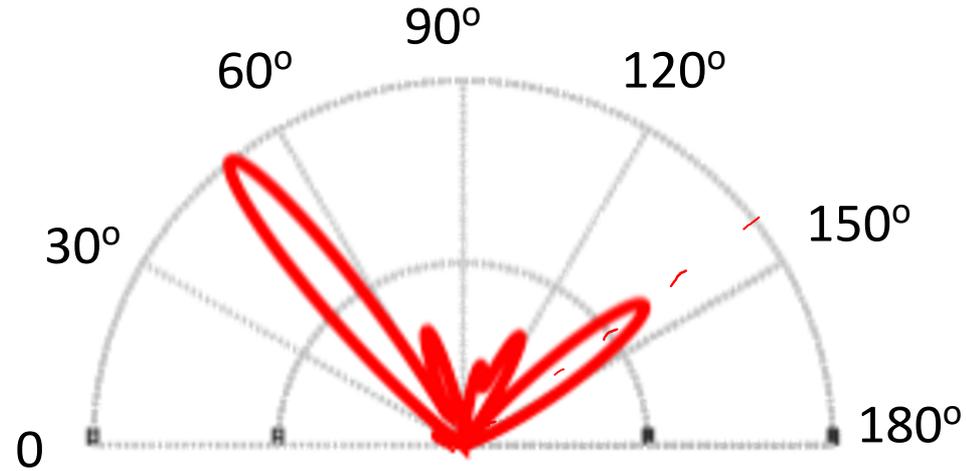
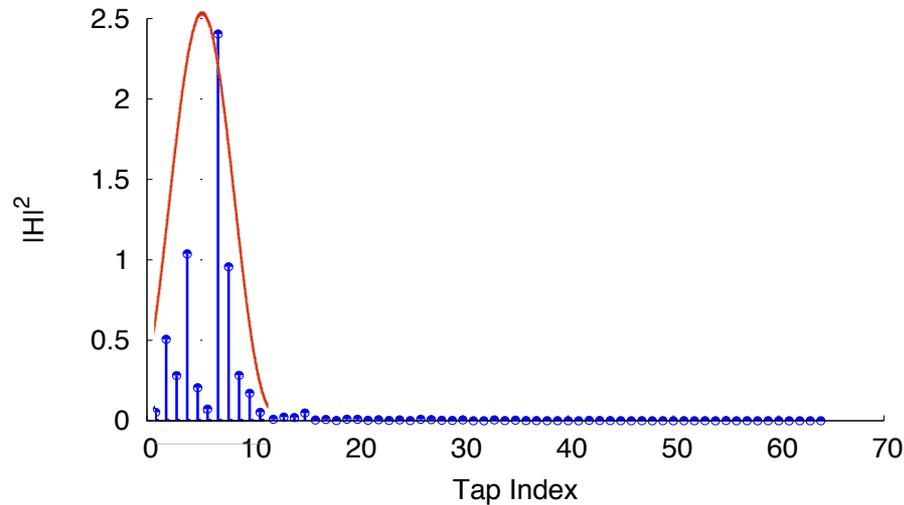
### Multipath Profile vs AoA

1. Use multipath profile as a filter to separate different paths
2. Estimate time of arrival of each path
3. Find the shortest path

**But How?**

# Method 3: Antenna Arrays

Which is the Shortest Path (Direct Path)?



Multipath Profile vs Time

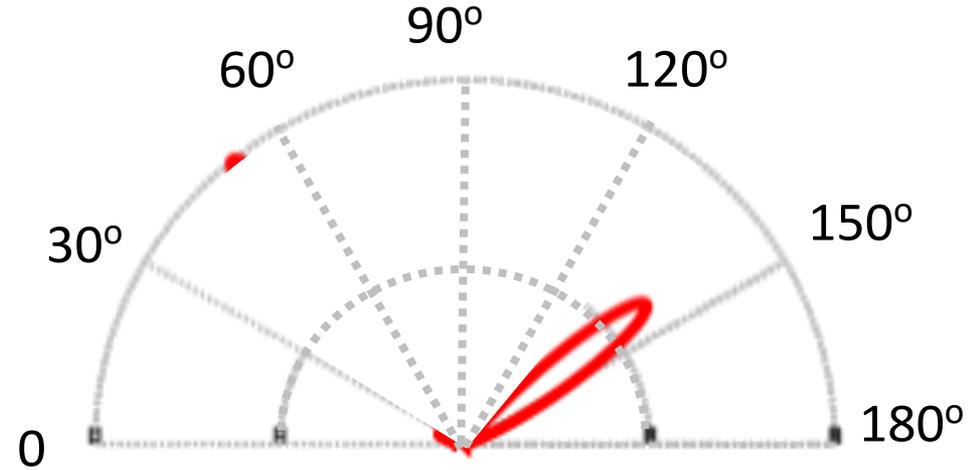
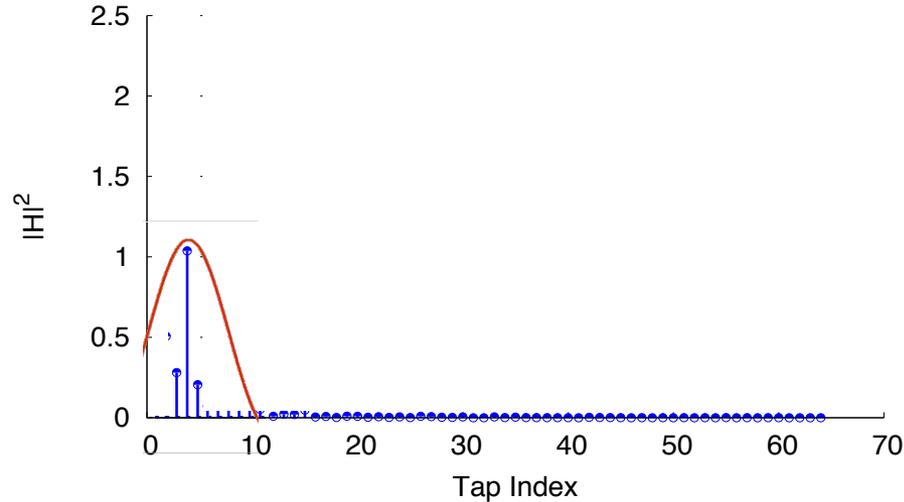
Multipath Profile vs AoA

1. Use multipath profile as a filter to separate different paths

$$y_{\theta_1}(t) = \sum_{k=1}^N y(t) e^{-jk\pi \cos \theta_1}$$

# Method 3: Antenna Arrays

Which is the Shortest Path (Direct Path)?



Multipath Profile vs Time

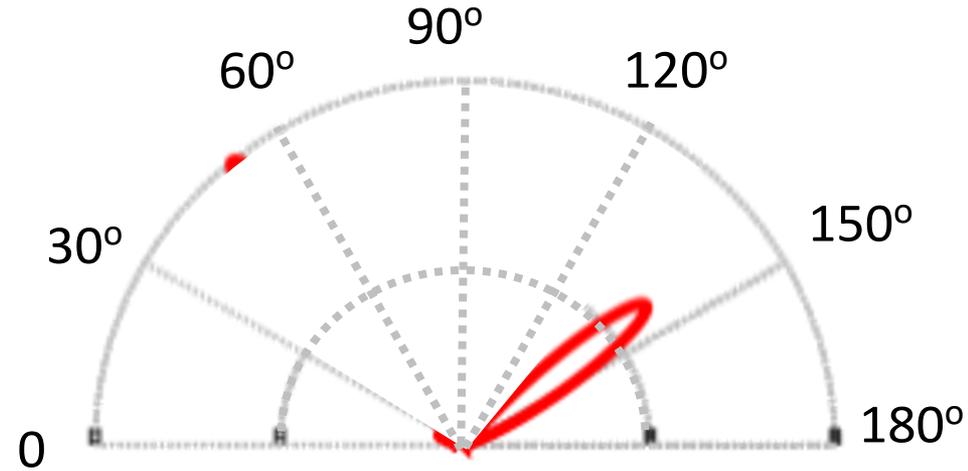
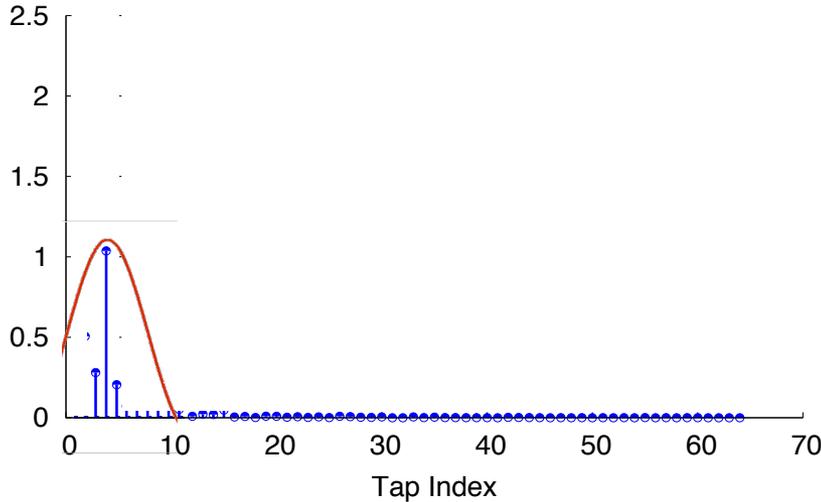
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# Method 3: Antenna Arrays

## Which is the Shortest Path (Direct Path)?



**Multipath Profile vs Time**

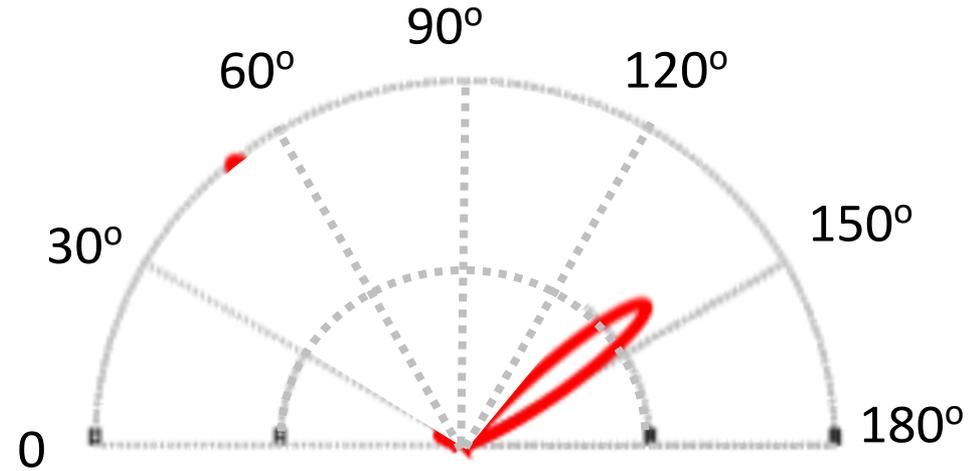
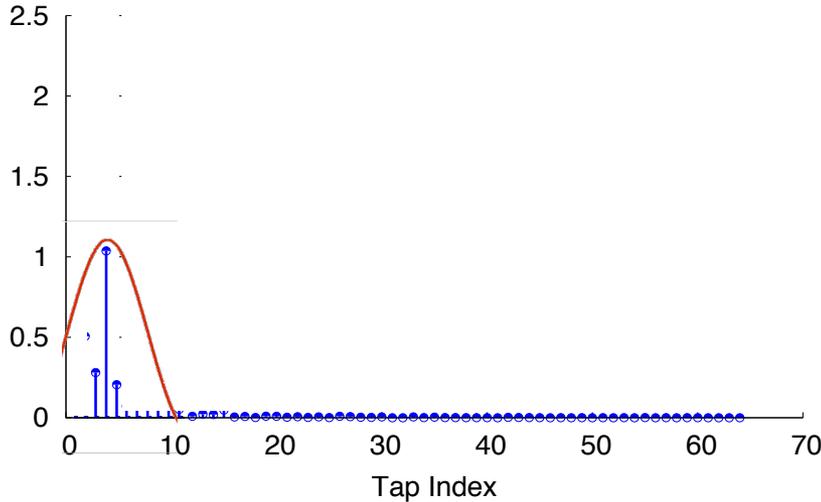
**Multipath Profile vs AoA**

1. Use multipath profile as a filter to separate different paths
2. Estimate time of arrival of each path

**Time Resolution still not enough ➡ Use OFDM**

# Method 3: Antenna Arrays

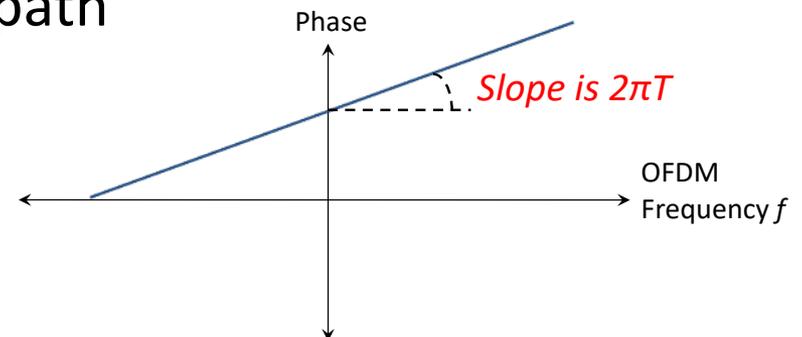
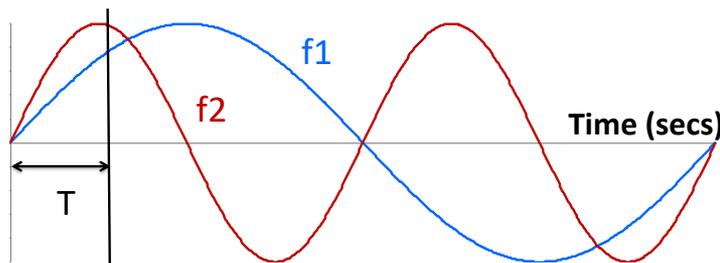
## Which is the Shortest Path (Direct Path)?



### Multipath Profile vs Time

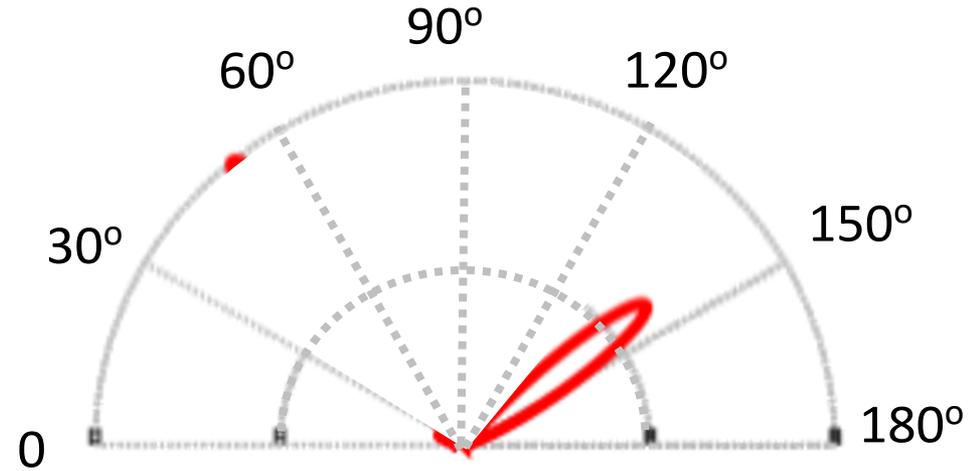
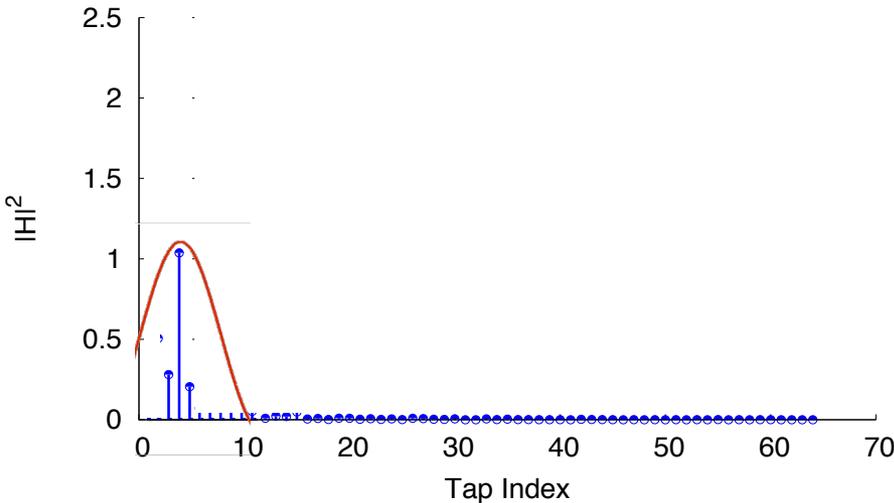
### Multipath Profile vs AoA

1. Use multipath profile as a filter to separate different paths
2. Estimate time of arrival of each path



# Method 3: Antenna Arrays

## Which is the Shortest Path (Direct Path)?



**Multipath Profile vs Time**

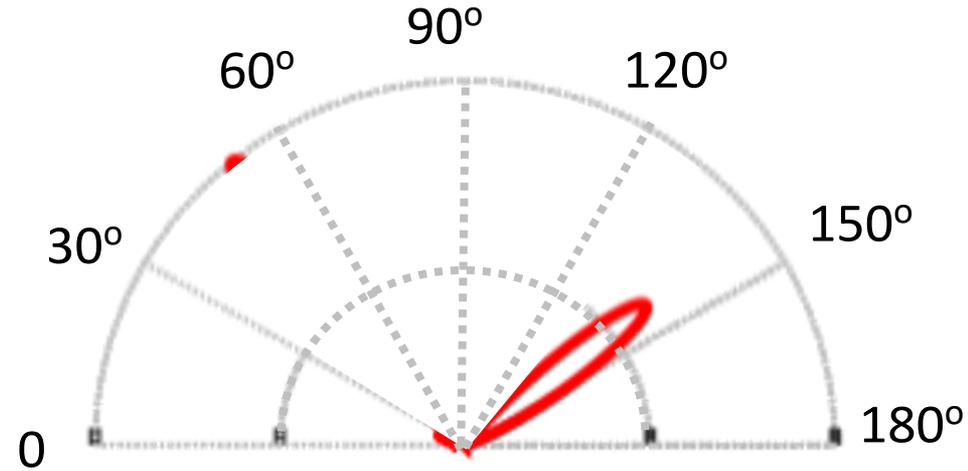
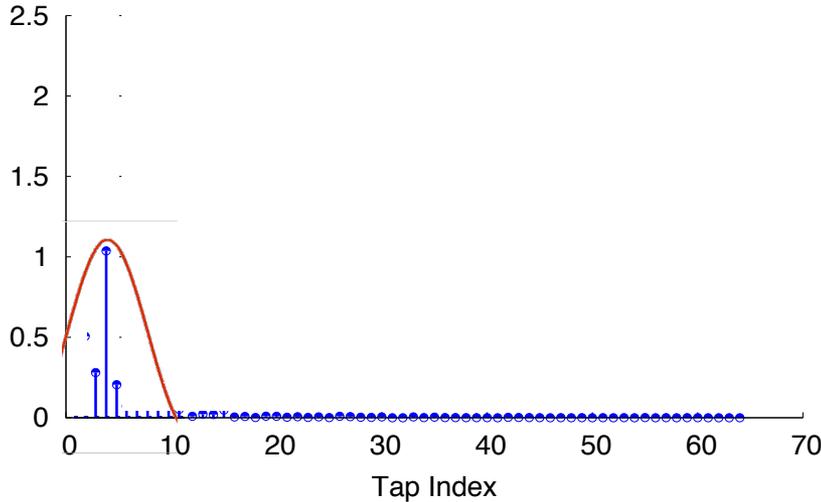
**Multipath Profile vs AoA**

1. Use multipath profile as a filter to separate different paths
2. Estimate time of arrival of each path
  - Use OFDM to estimate delay from slope of phase vs freq.

**But this delay includes packet detection delay & processing delay, not just propagation delay!**

# Method 3: Antenna Arrays

## Which is the Shortest Path (Direct Path)?



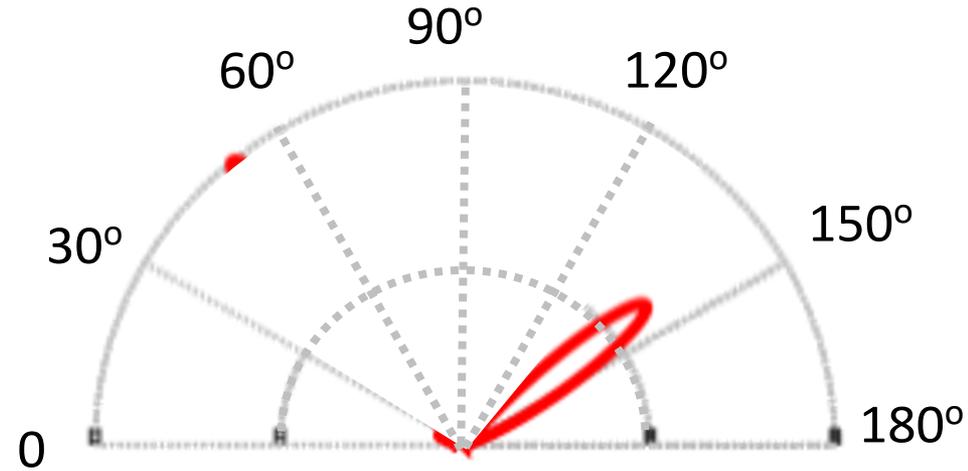
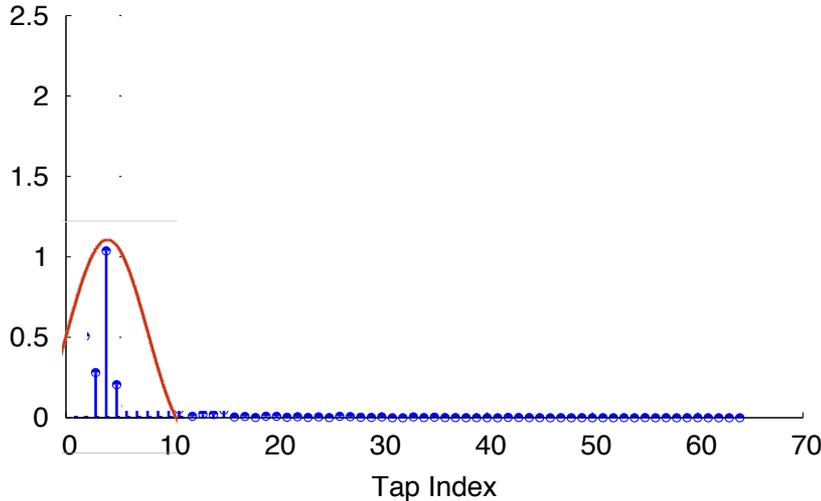
### Multipath Profile vs Time

### Multipath Profile vs AoA

1. Use multipath profile as a filter to separate different paths
2. Estimate time of arrival of each path
  - Use OFDM to estimate delay from slope of phase vs freq.
  - Compute relative delay for different paths!

# Method 3: Antenna Arrays

## Which is the Shortest Path (Direct Path)?

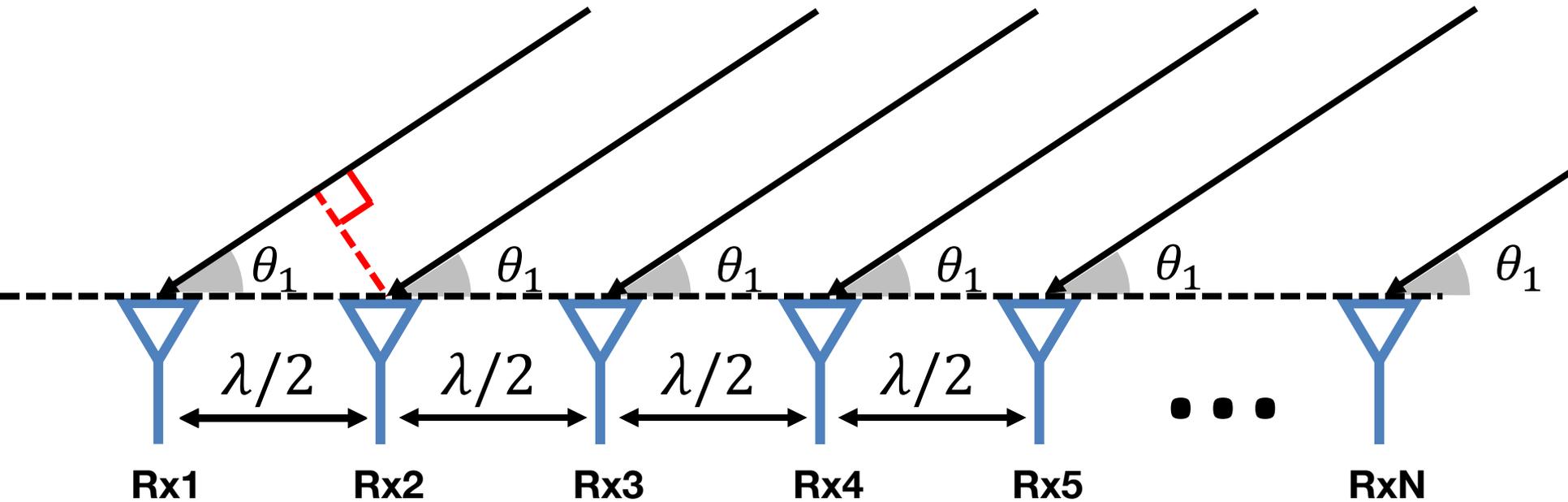


### Multipath Profile vs Time

### Multipath Profile vs AoA

1. Use multipath profile as a filter to separate different paths
2. Estimate time of arrival of each path
  - Use OFDM to estimate delay from slope of phase vs freq.
  - Compute relative delay for different paths!
3. Compare relative delays to find the shortest path

# Method 3: Antenna Arrays



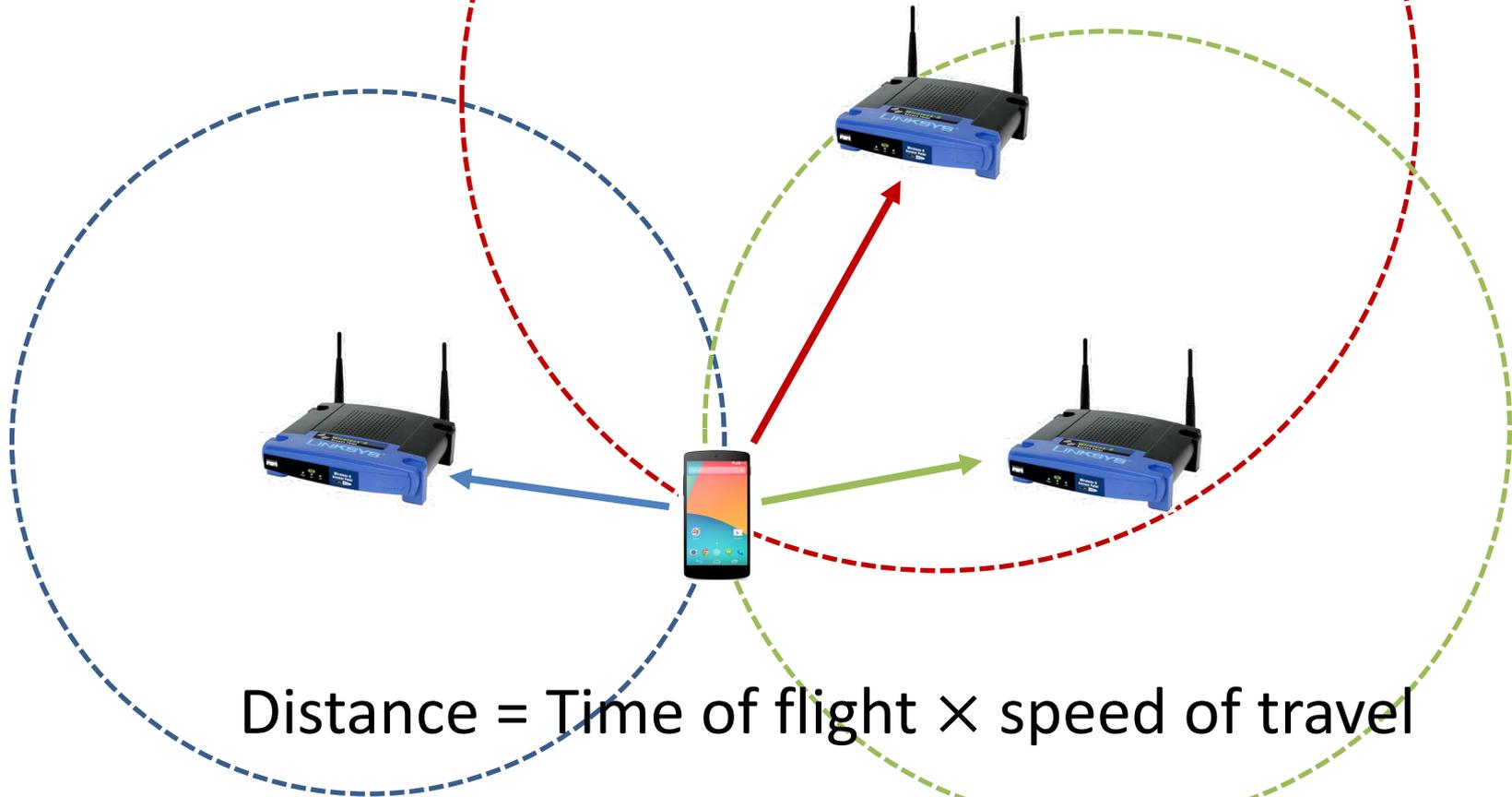
**Pros:** Works with multipath, No need for fingerprinting

**Cons:** Requires more hardware!

Assumes device is sufficiently far such that wavefront is parallel

# Method 4: ToF Based Localization

Measure Time of Flight (ToF) from device to each AP



Measure ToF  $\rightarrow$  Get distance  $\rightarrow$  Trilateration

# Method 4: ToF Based Localization

Measure Time of Flight (ToF) from device to each AP

## Challenges:

- How do you know when signal was transmitted?



Measure Round Trip

- How about packet detection delay & processing delay?
  - Use OFDM to correct for packet detection delay
  - Estimate and calibrate for processing delay

**Not Practical!**

# Method 4: ToF Based Localization

Measure Time of Flight (ToF) from device to each AP

## Challenges:

- Accuracy limited by sampling rate (bandwidth)!

$$\Delta d = \Delta \tau \times c$$

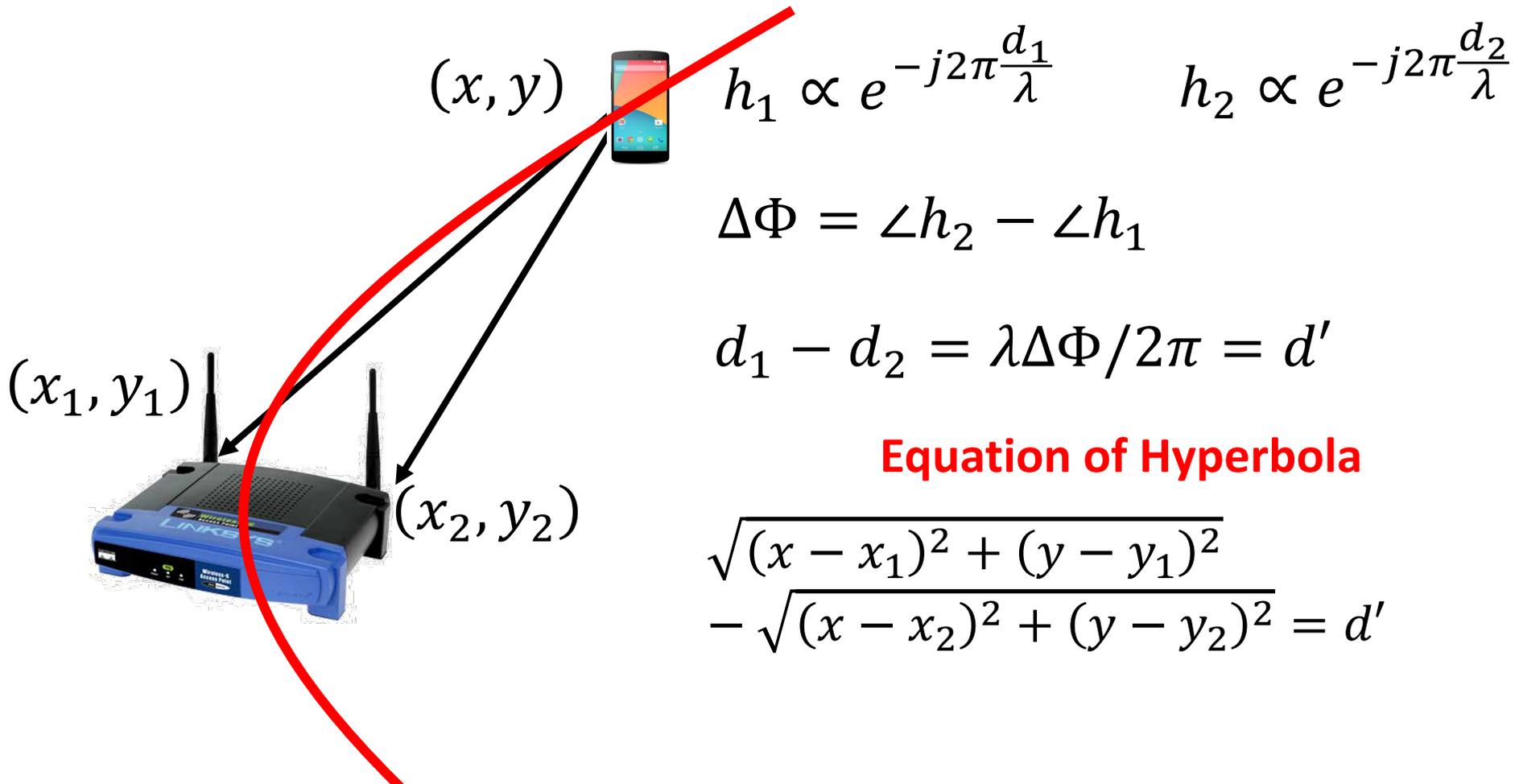
802.11n bandwidth =  $40MHz$   $\Rightarrow$   $\Delta \tau = 25ns$   $\Rightarrow$   $\Delta d = 12.5 m$

- Other systems than WiFi can get accurate ToF:
  - UWB: Ultra-Wide Band
  - FMCW: Frequency Modulated Carrier Wave

**Not Supported in WiFi**  
**(Will discuss in future lectures)**

# Method 5: TDoA Based Localization

Measure Time Difference of Arrival (TDoA) from device to AP's antennas



$$(x, y) \quad h_1 \propto e^{-j2\pi\frac{d_1}{\lambda}} \quad h_2 \propto e^{-j2\pi\frac{d_2}{\lambda}}$$

$$\Delta\Phi = \angle h_2 - \angle h_1$$

$$d_1 - d_2 = \lambda\Delta\Phi/2\pi = d'$$

**Equation of Hyperbola**

$$\sqrt{(x - x_1)^2 + (y - y_1)^2} - \sqrt{(x - x_2)^2 + (y - y_2)^2} = d'$$

# Method 5: TDoA Based Localization

Measure Time Difference of Arrival (TDoA) from device to AP's antennas

