# ECE 598HH: Advanced Wireless Networks and Sensing Systems

Lecture 11: Wireless Sensing Part 2
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### WiVi: Tracking People Through Walls with WiFi

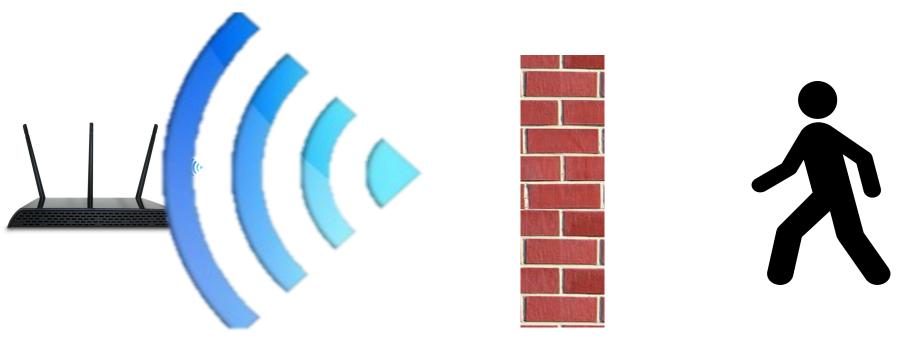
#### Key Idea







#### Challenges



Challenge #1: Wall reflection is 10,000x stronger than any reflections coming from behind the wall

Challenge #2: Tracking people from their reflections

## How Can We Eliminate the Wall's Reflection?

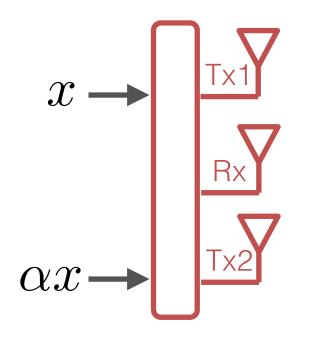
Idea: Transmit two waves that cancel each other when they reflect off static objects but not moving objects

Wall is static disappears

People tend detectable to move

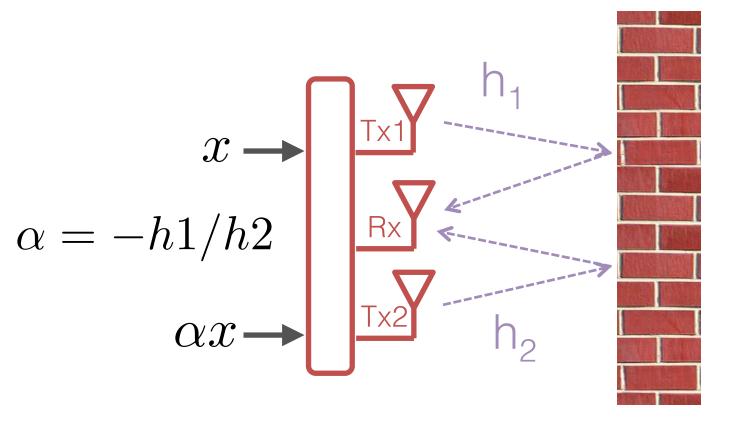
#### Eliminating the Wall's Reflection

Two transmit antennas and one receive antenna

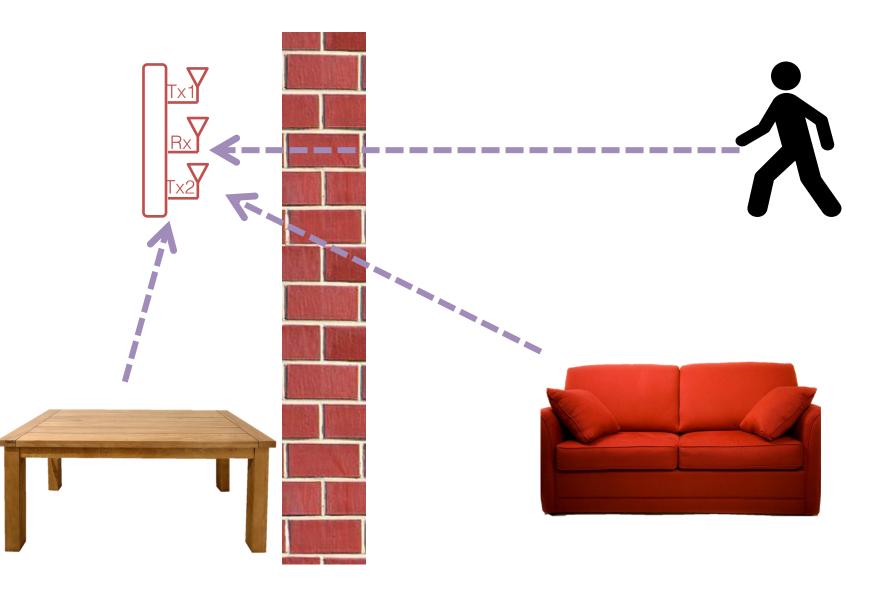


#### Eliminating the Wall's Reflection

Received signal:  $y = h_1 x + h_2 \alpha x$ 



#### Eliminating All Static Reflections



#### Eliminating All Static Reflections

$$y = h_1 x + h_2 \alpha x$$

Reflections linearly combine over the wireless medium

$$y = \left(\sum_{i} h_{1i}\right) x + \left(\sum_{i} h_{2i}\right) \alpha x$$
 reflector i

Static objects (wall, furniture, etc.) have constant channels

$$y_i = h_{11} x + h_{2i}(-h_{1i}/h_{2i})x$$
  $y_i = h_{1i} x + h_{2i}(-h_{1i}/h_{2i})x$ 

People move, therefore their channels change

$$y_i = h_{1i}' x + h_{2i}' (-h_{1i}/h_{2i}) x$$

Not Zero

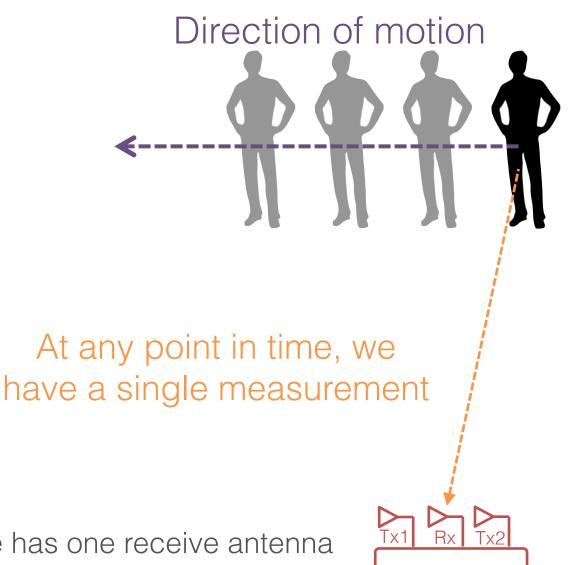
#### Eliminating All Static Reflections

- Noise leads to errors in estimating the channel
  - Limits ability to cancel static reflections and sense motion behind the wall
  - -Channel estimates ĥ≠h
- Refine channel estimates through an iterative nulling algorithm

How to extend to wideband WiFi channels?

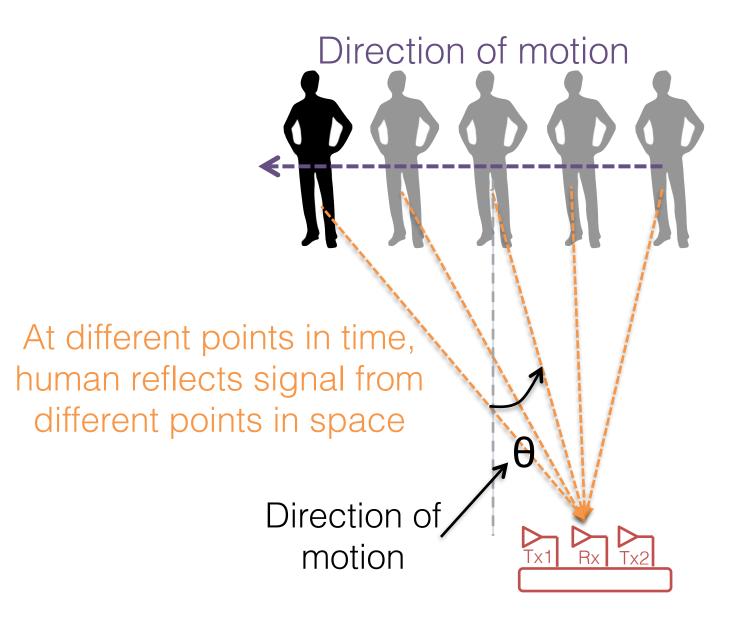
How Can We Track Using Reflections?

#### Tracking Motion

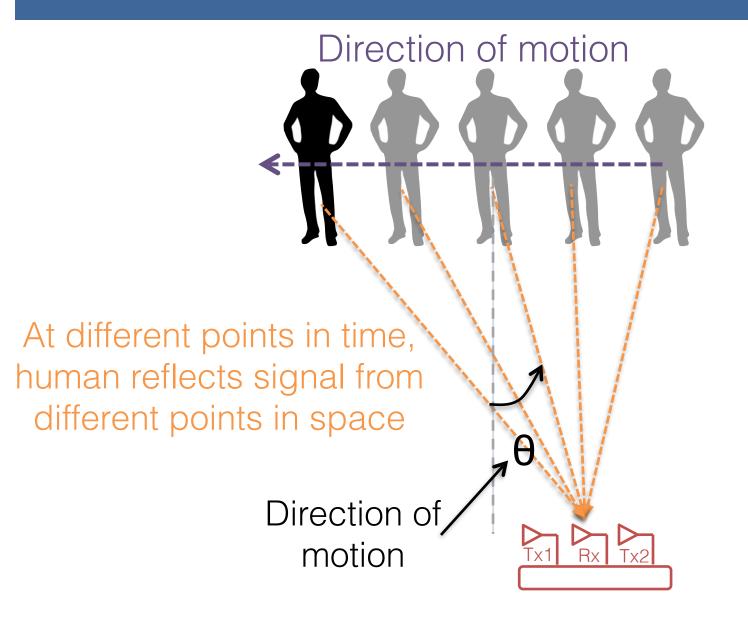


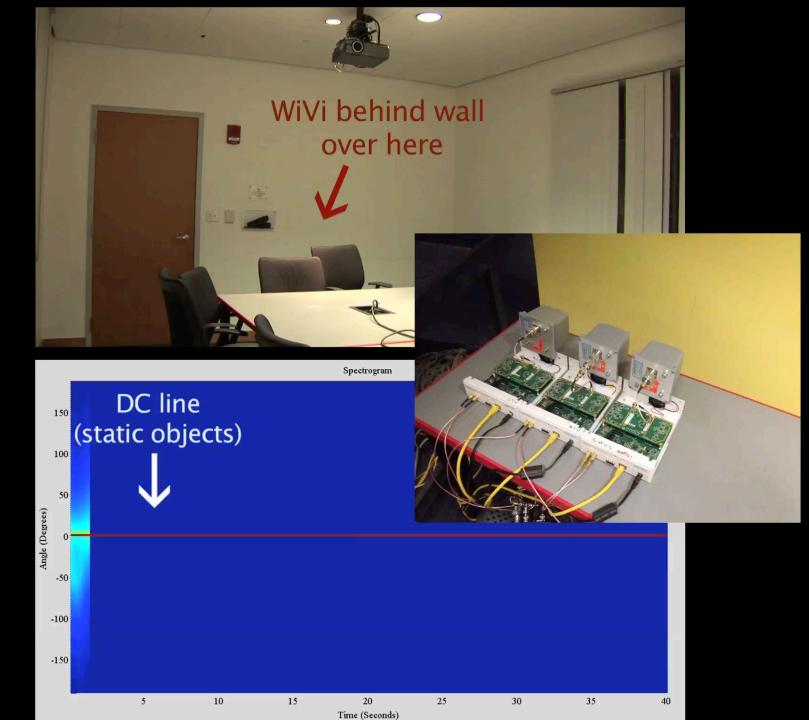
Device has one receive antenna

#### Tracking Motion



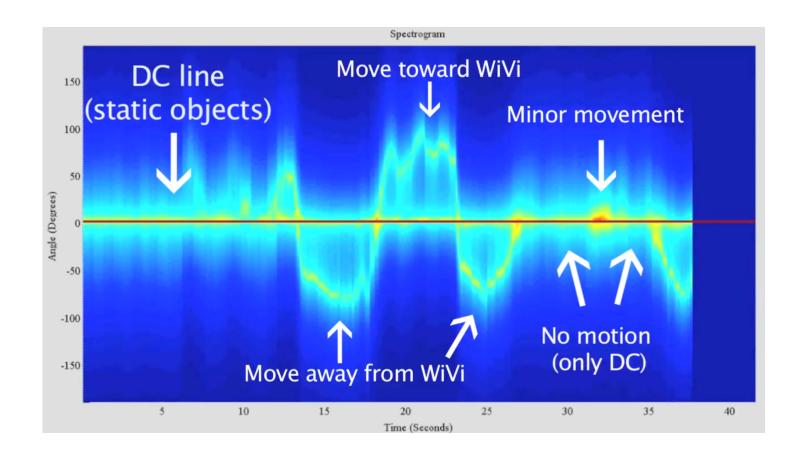
#### Human Motion Emulates an Antenna Array





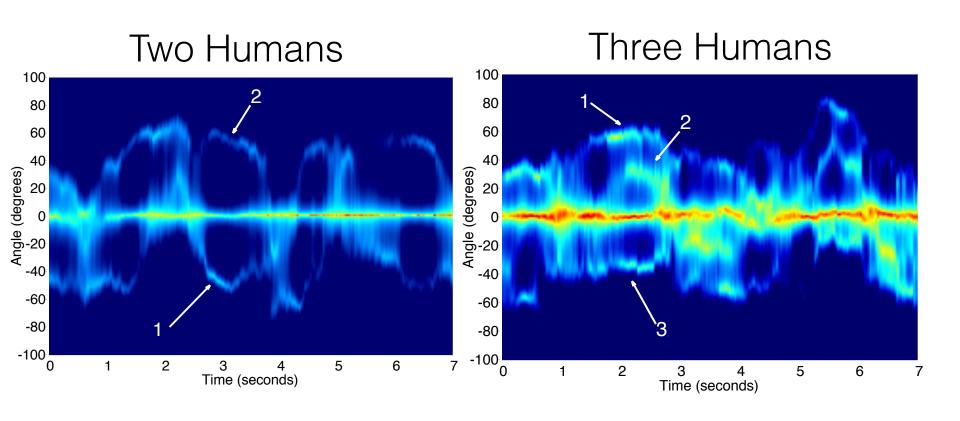
#### Tracking Multiple Humans

One moving person is indicated by a single curvy line



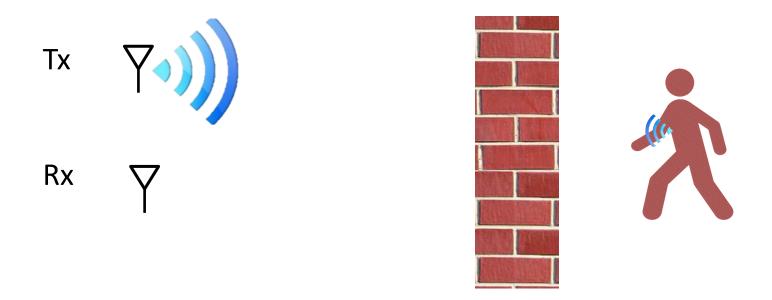
#### Tracking Multiple Humans

Number of distinct curves at the same time corresponds to the number of humans



#### WiTrack

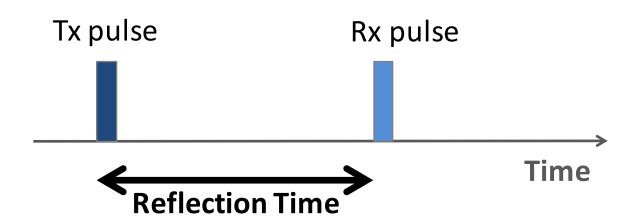
#### Measuring Distances



Distance = Reflection time x speed of light

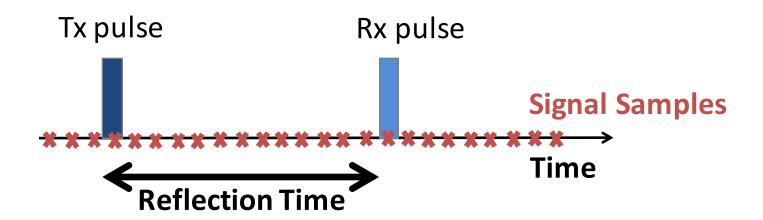
#### Measuring Reflection Time

 Option1: Transmit short pulse and listen for the echo.



#### Measuring Reflection Time

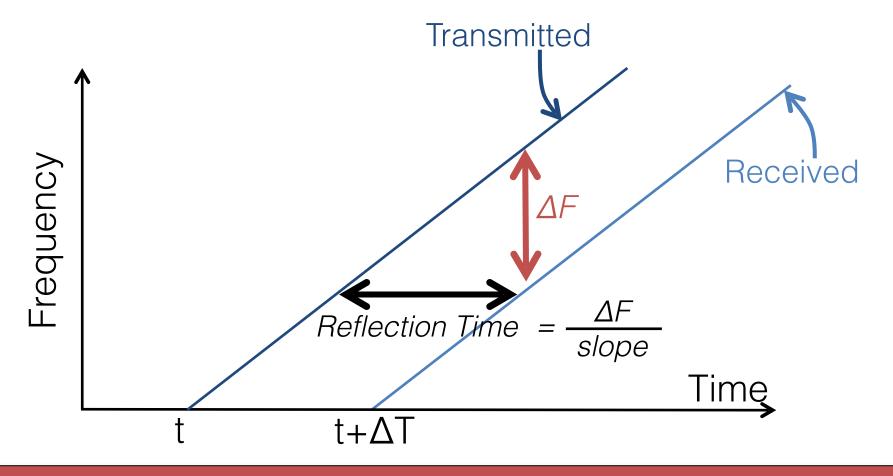
 Option1: Transmit short pulse and listen for the echo.



Need to sample at very high rate: UWB

Multi-GHz samplers are expensive and generate high noise: not suitable for this application

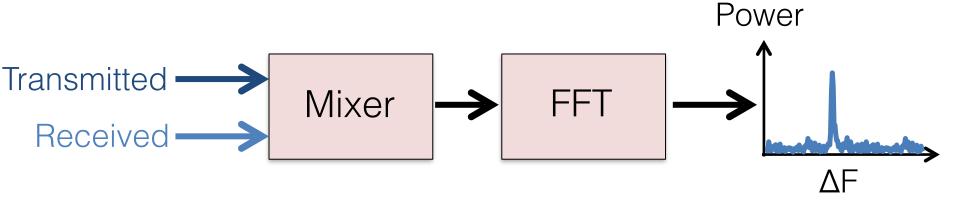
#### FMCW: Measure time by measuring frequency



How do we measure  $\Delta F$ ?

#### Measuring ΔF

- Subtracting frequencies is easy (e.g., removing carrier in WiFi)
- Done using a mixer (low-power; cheap)



Signal whose frequency is  $\Delta F$ 

 $\Delta F \rightarrow Reflection Time \rightarrow Distance$ 

#### **FMCW**

FMCW Transmitted Signal

Frequency is linear in time; hence phase is quadratic

$$x(t) = e^{j2\pi(\frac{k}{2}(t^2 + f_0 t))}$$

slope

FMCW Received Signal:

$$y(t) = \sum_{i} A_{i} e^{j2\pi(\frac{k}{2}((t-\tau_{i})^{2} + f_{0}(t-\tau_{i})))}$$

Reflections linearly combine over the wireless medium

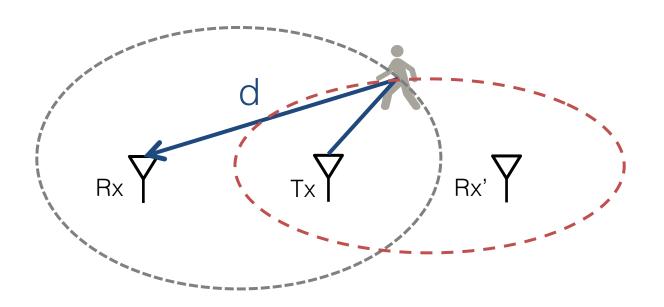
reflector i

hconversion:

$$y_b(t) = \sum_i A_i e^{j2\pi(k\tau_i t + f_0\tau_i)}$$
 frequency k  $\tau_i$ 

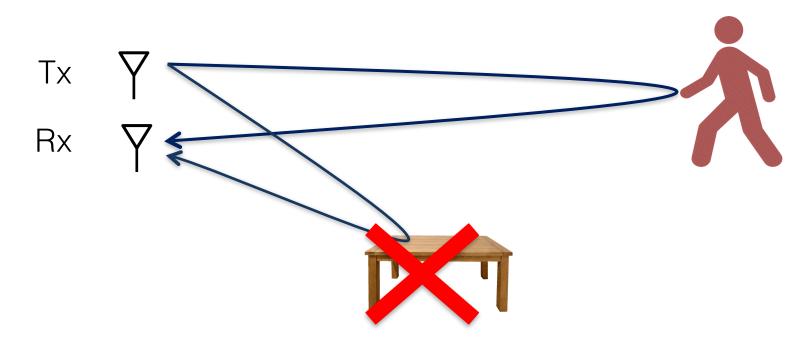
#### Mapping Distance to Location

Person can be anywhere on an ellipse whose foci are (Tx,Rx)



By adding another antenna and intersecting the ellipses, we can localize the person

### Dealing with multi-path when there is one moving user

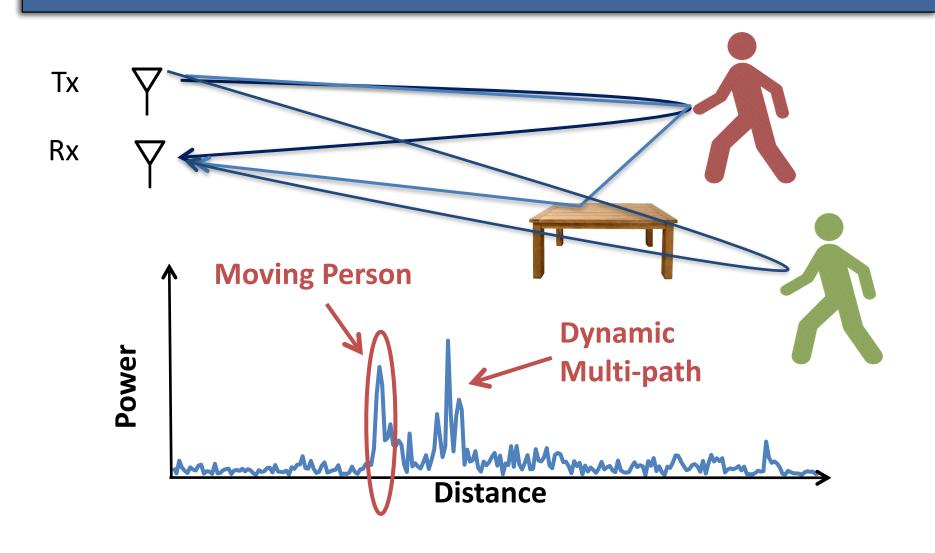


Direct furniture reflection:

eliminated by subtracting consecutive measurements

Needs User to Move

### Fails for multiple people in the environment, and we need a more comprehensive solution

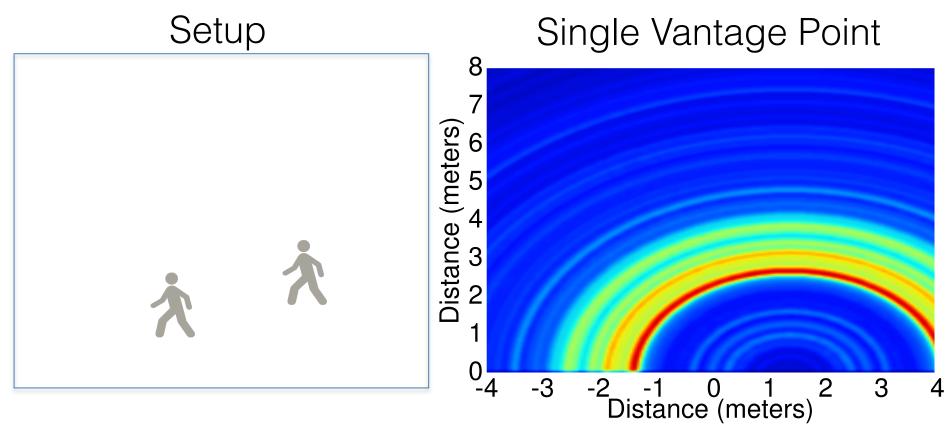


How can we deal with multi-path reflections when there are multiple persons in the environment?

Idea: Person is consistent across different vantage points while multi-path is different from different vantage points

#### Combining across Multiple Vantage Points

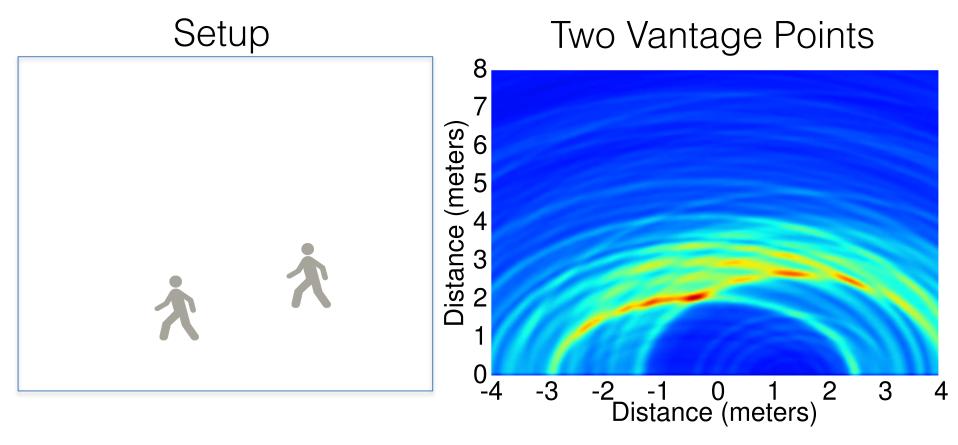
Experiment: Two users walking



Mathematically: each round-trip distance can be mapped to an ellipse whose foci are the transmitter and the receiver

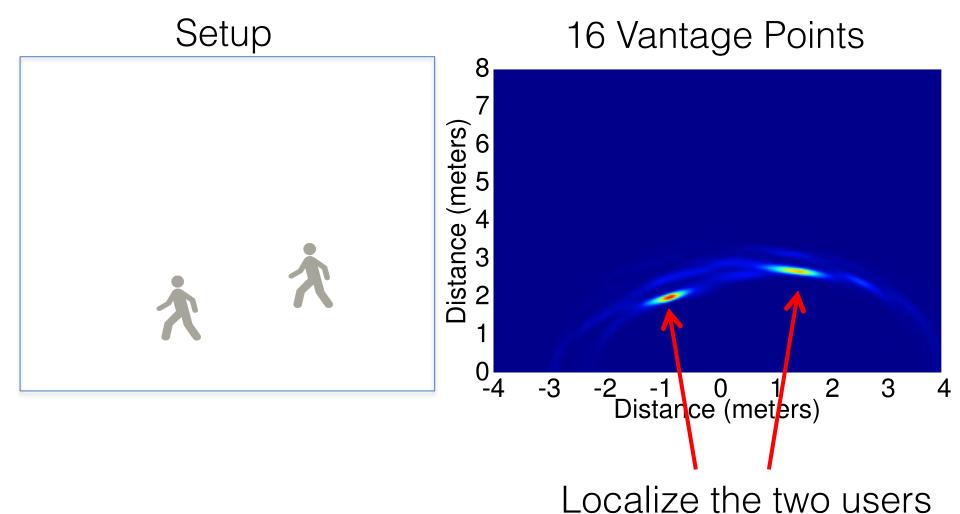
#### Combining across Multiple Vantage Points

**Experiment:** Two users walking



#### Combining across Multiple Vantage Points

Experiment: Two users walking



How can we obtain 16 vantage points?

#### Achieving 16 vantage points

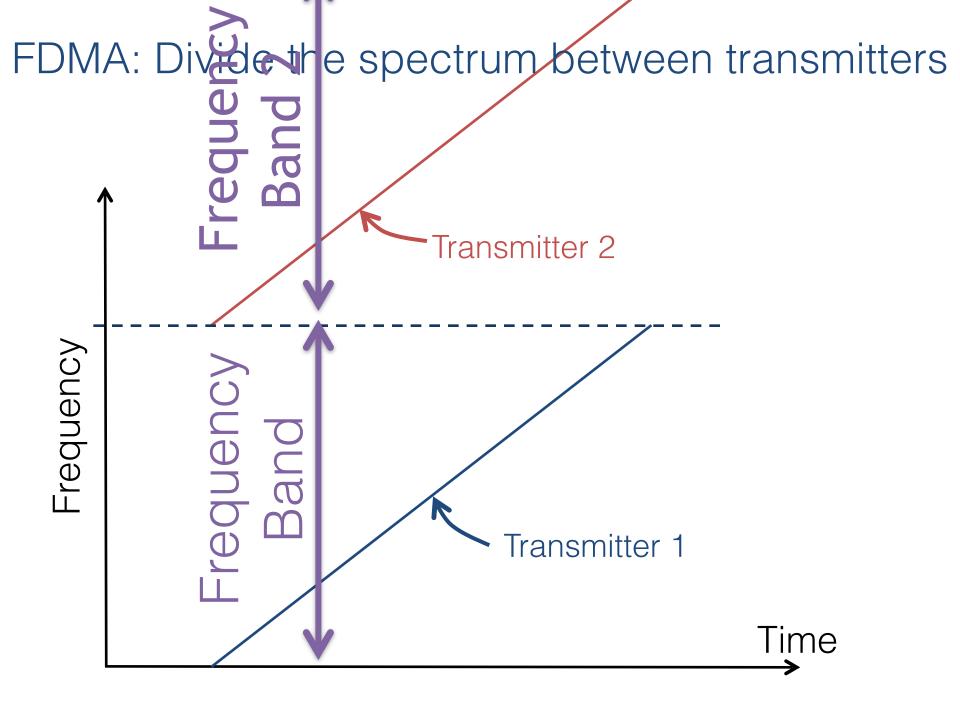
Naïve solution: 1 Transmitter and 16 Receivers

• Ideally: 4 Transmitters and 4 Receivers

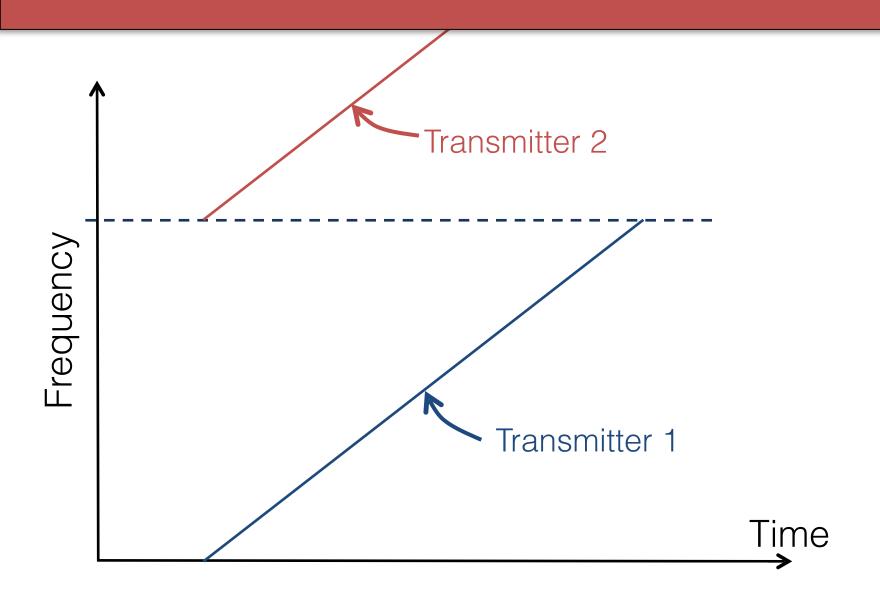
$$T_{X}$$
  $Y$   $T_{X}$   $Y$   $R_{X}$   $Y$   $R_{X}$   $Y$   $R_{X}$   $Y$   $R_{X}$   $Y$   $R_{X}$   $Y$   $R_{X}$   $Y$ 

Problem: Different transmitters interfere with each other!

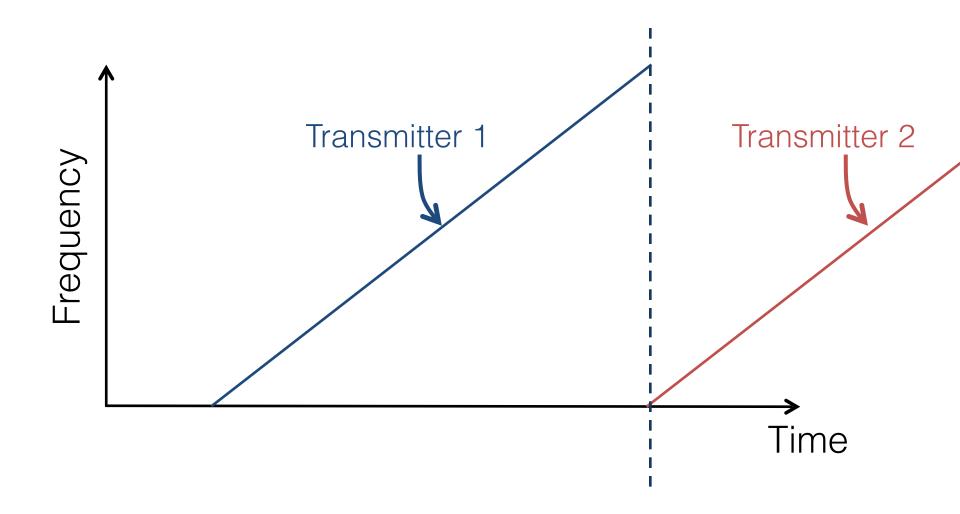
Let us look at standard mechanisms that are used to deal with interference



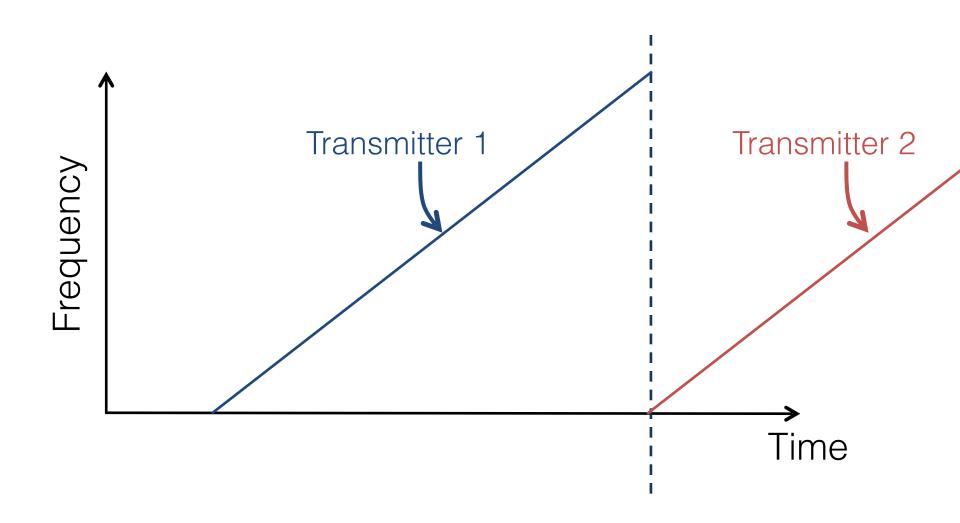
#### Would require N times the bandwidth!



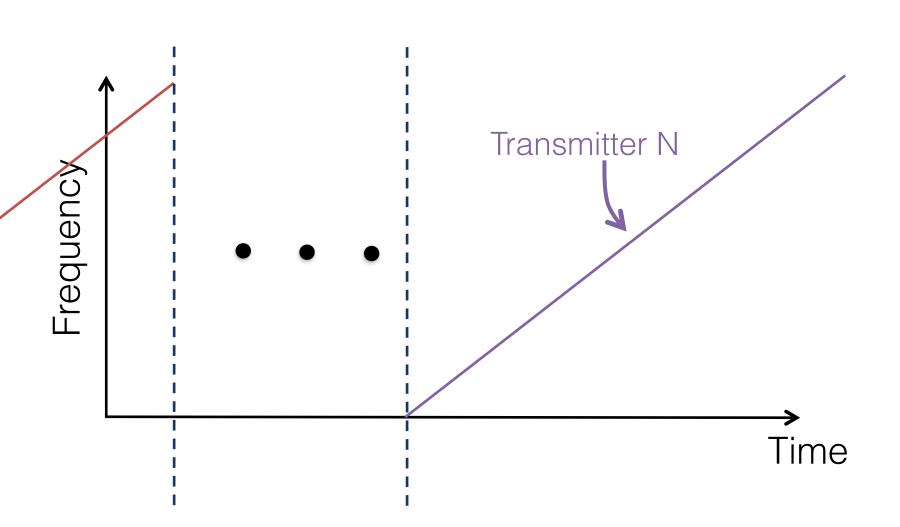
#### TDMA: Transmitters take turns transmitting



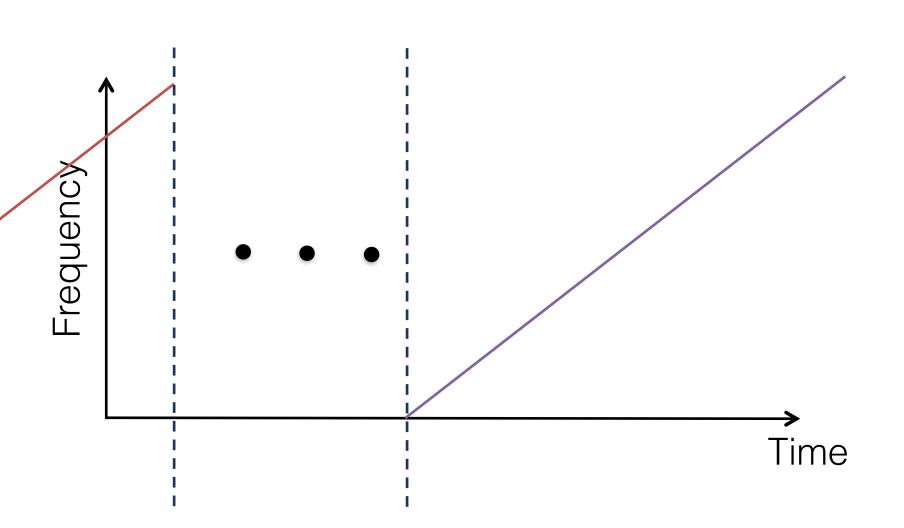
#### Would require N more time to localize



## Ideally: Transmit in the same time and in the same frequency band without interfering



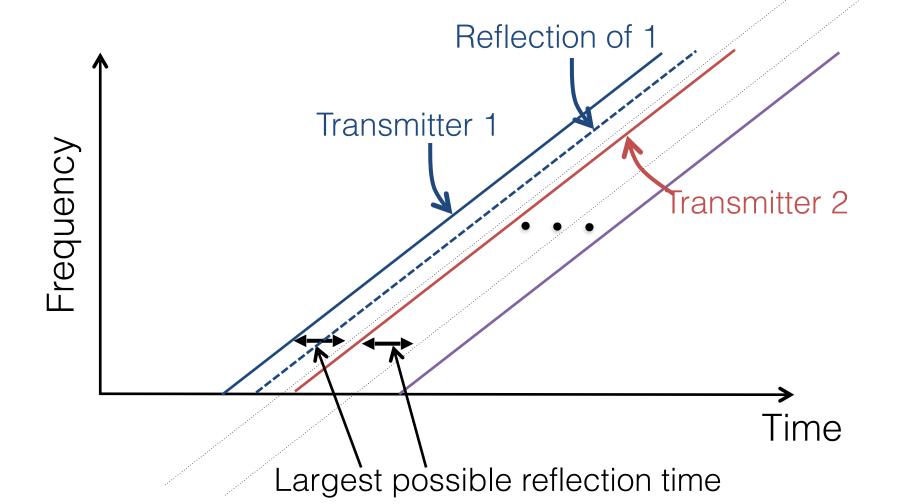
## Ideally: Transmit in the same time and in the same frequency band without interfering



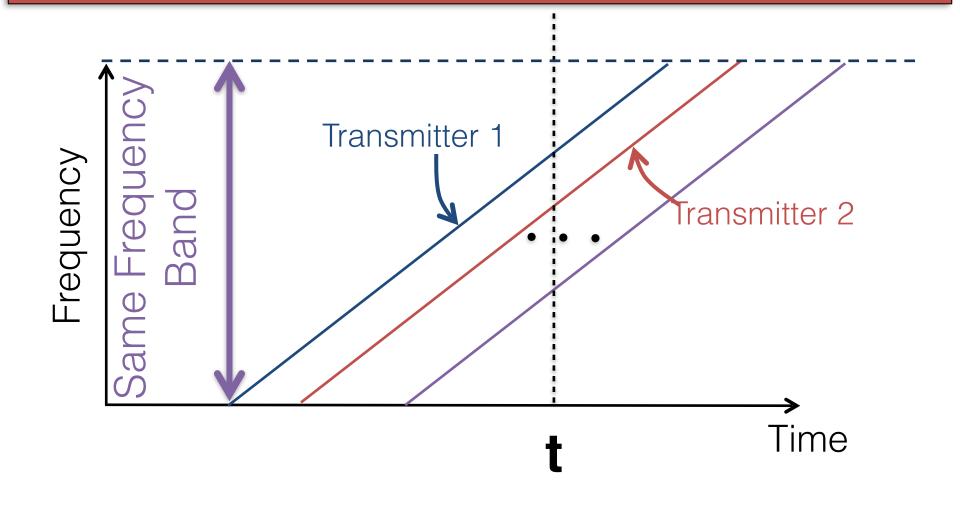
## Multi-shift FMCW: a new mechanism to divide resources between transmitters so that they don't suffer from interference

#### Objective: Transmit and Get Reflection

Largest reflection time indoors: 100ns



## Multi-shift FMCW enables multiple transmissions at the **same time** and in the **same frequency band** without interference

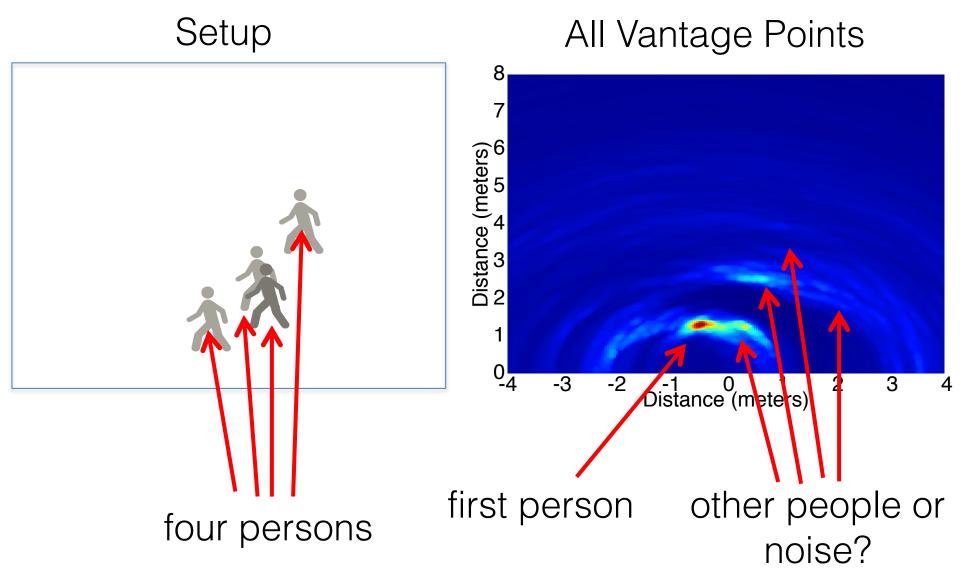


#### Multi-Person Localization

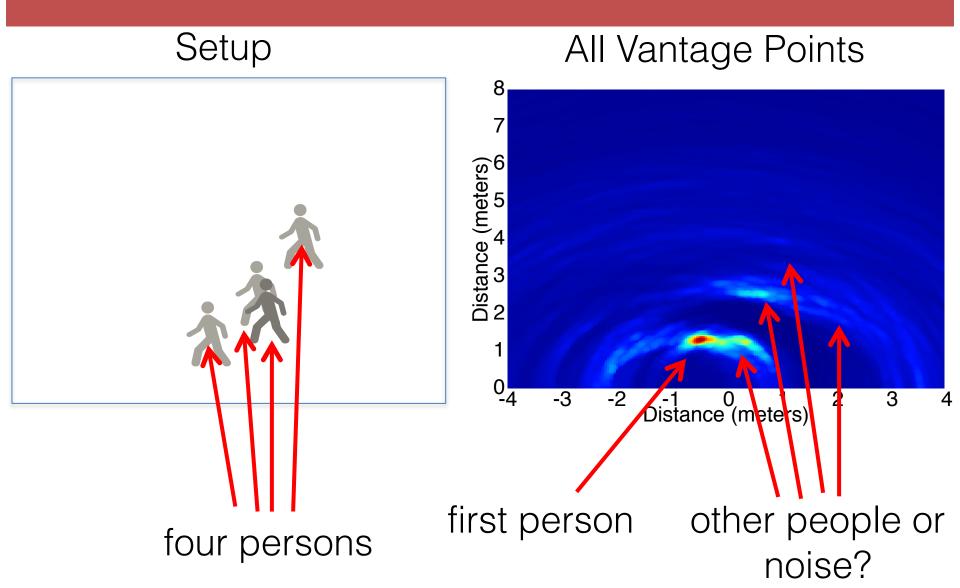
 Multi-shift FMCW enables a large number of vantage points for accurate localization of multiple subjects

#### Multi-User Localization

Experiment: Four persons walking



## Near-Far Problem: Nearby persons have more power than distance reflectors and can mask them



# Successive Silhouette Cancellation: a new algorithm that localizes multiple persons in the scene by addressing the near-far problem

Successive Silhouette Cancellation:
a new algorithm that localizes multiple
persons in the scene by addressing the
near-far problem

inspired by

Successive Interference Cancellation iteratively decode interfering transmissions by addressing the near-far problem

## Successive Interference Cancellation

Recover 0's and 1's

Decode 0's and 1's

Subtract

Reconstruct modulation & coding

## Successive Silhouette Cancellation

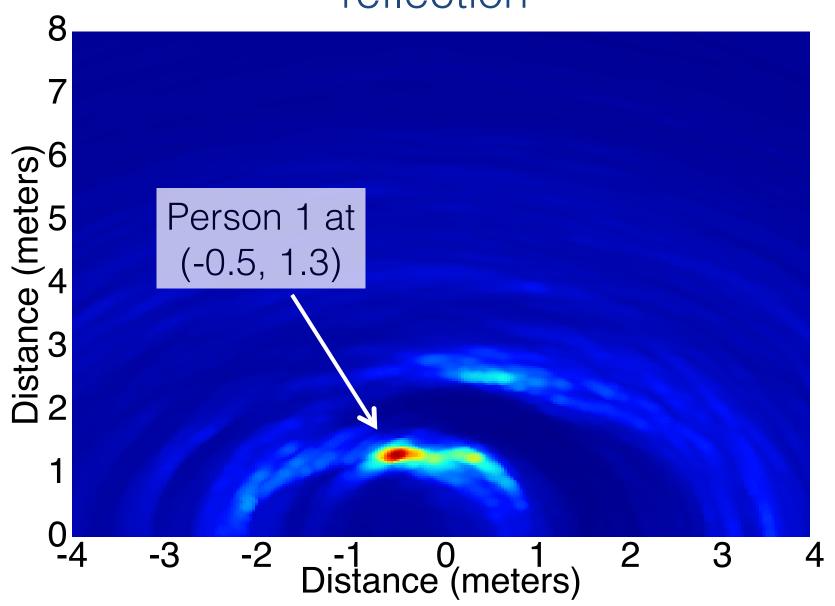
Recover human reflections

Decode human location

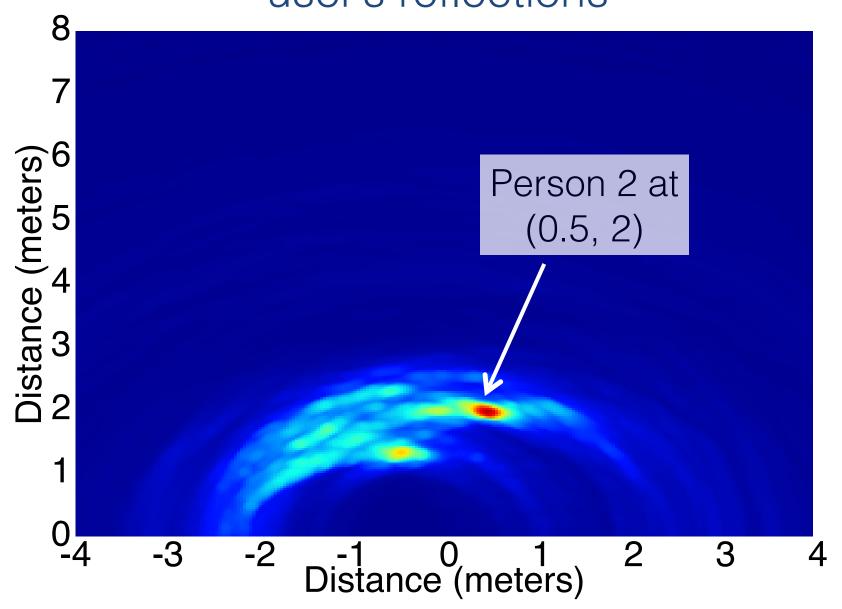
Subtract

Model human and reconstruct reflection patterns

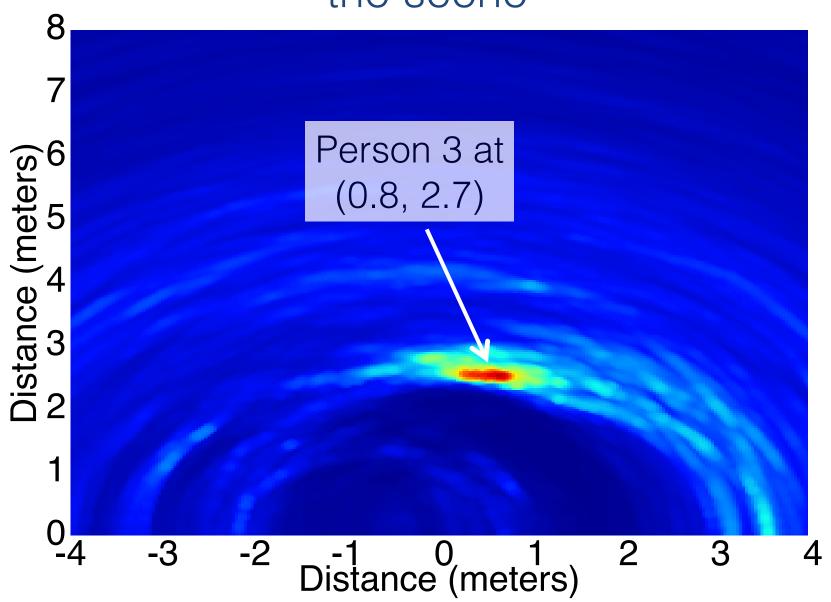
First localize the user with the strongest reflection



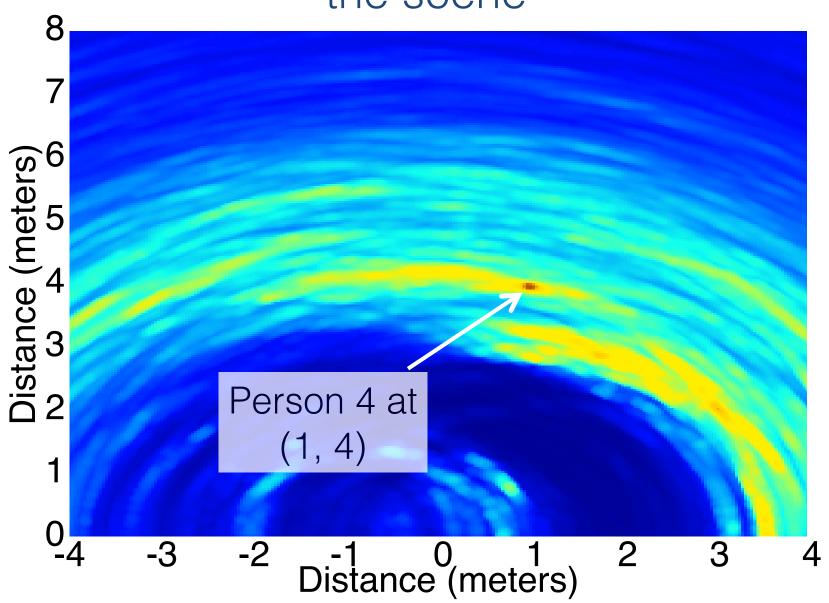
## After reconstructing and cancelling the first user's reflections



Iteratively localize the remaining users in the scene

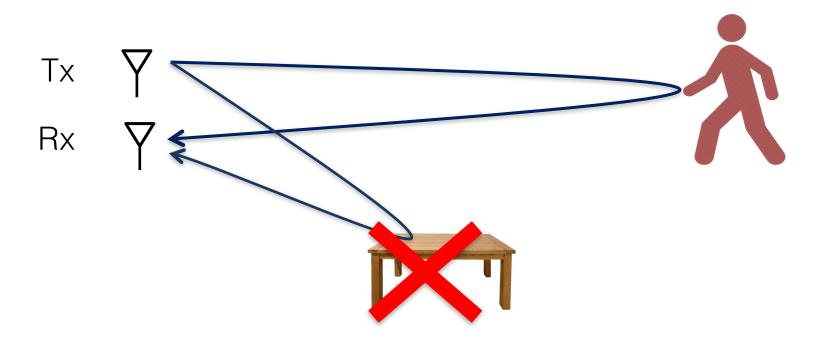


Iteratively localize the remaining users in the scene





## Dealing with multi-path when there is one moving user

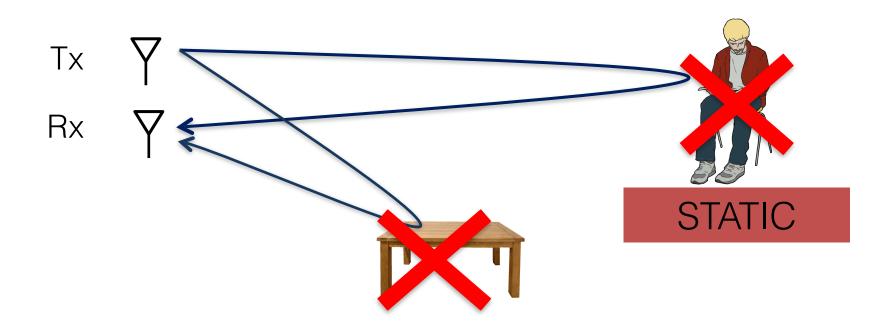


1. Direct furniture reflection:

eliminated by subtracting consecutive measurements

Needs User to Move

## Dealing with multi-path when there is one moving user



1. Direct furniture reflection:

eliminated by subtracting consecutive measurements

Needs User to Move

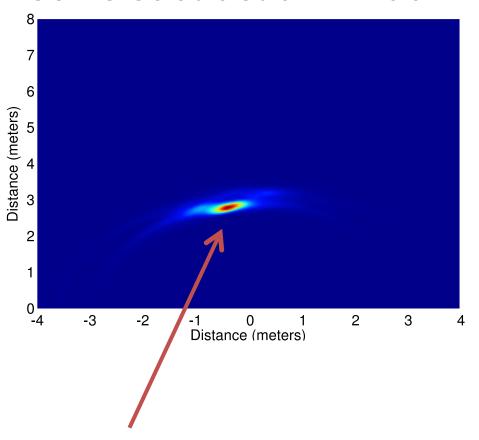
## Exploit breathing motion for localize static users

- Breathing and walking happen at different time scales
  - -A user that is pacing moves at 1m/s
  - -When you breathe, chest moves by few mm/s

 Cannot use the same subtraction window to eliminate multi-path

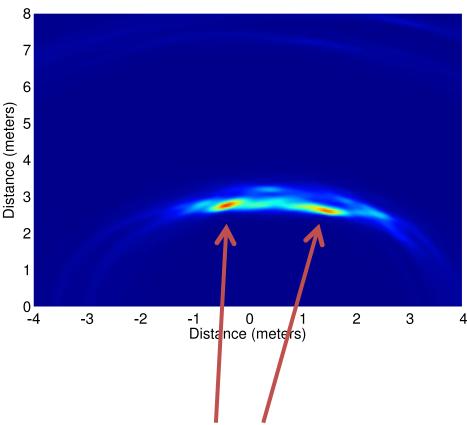
#### User Walking at 1m/s





Localize the person

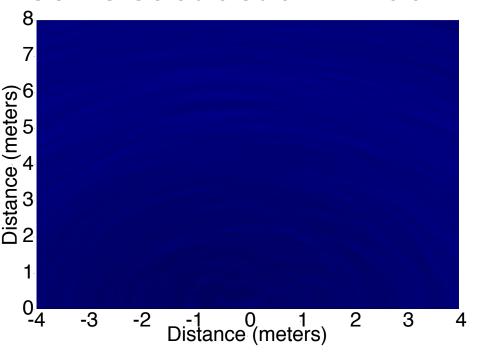
#### 3s subtraction window



Person appears in two locations

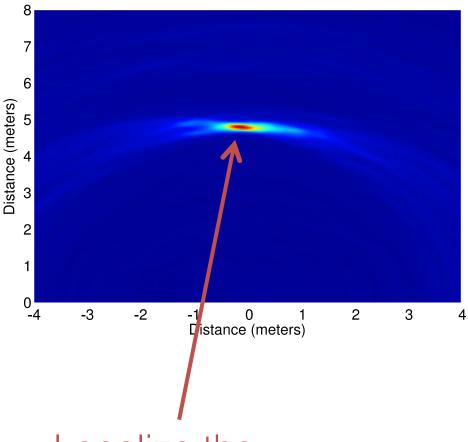
### User Sitting Still (Breathing)

30ms subtraction window



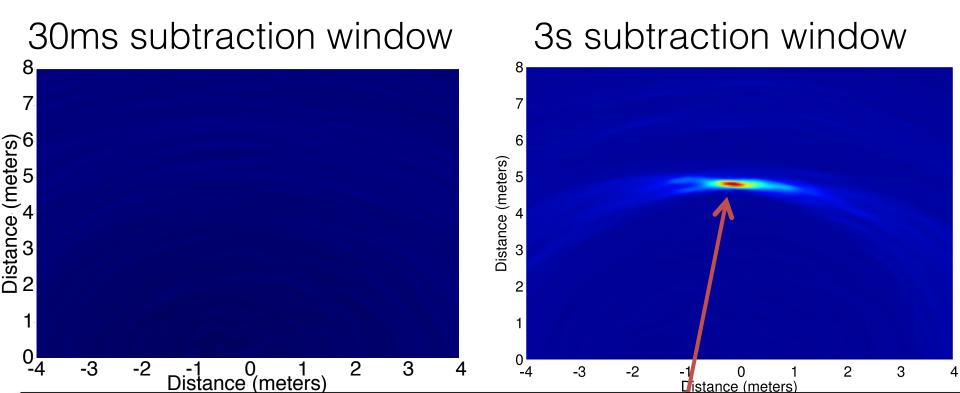
Cannot localize

3s subtraction window



Localize the person

#### User Sitting Still (Breathing)



Use multi-resolution subtraction window to eliminate multi-path while being able to localize both static and moving users

