# ECE 537 Practice Exam 1 

## UNIVERSITY OF ILLINOIS

Department of Electrical and Computer Engineering
The real exam will be October 24, 2022 in class

- This is a closed-book exam.
- You are allowed to bring one $8.5 \times 11$ sheet of handwritten notes (front and back).
- No calculators are allowed. Please do not simplify explicit numerical expressions.
- There are 100 points in the exam. Points for each problem are specified by the problem number.

Name: $\qquad$

NetID:

## Possibly Useful Charts and Formulas

## Dynamic Time Warping

$$
A_{i, k}=\max \left(A_{i+1, k}, A_{i, k+1}, a_{i, k}+A_{i+1, k+1}\right)
$$

## Linear Prediction

$$
\begin{gathered}
s[n]=G e[n]+\sum_{m=1}^{p} a_{m} s[n-m]=h[n] * x[n] \\
H(z)=\frac{G}{1-\sum_{m=1}^{N} a_{m} z^{-m}}=\frac{G}{\prod_{k=1}^{N}\left(1-p_{k} z^{-1}\right)} \\
\mathcal{E}=\sum_{n=0}^{N-1} e^{2}[n]=\sum_{n=0}^{N-1}\left(s[n]-\sum_{m=1}^{p} a_{m} s[n-m]\right)^{2} \\
0=\sum_{n=0}^{N-1}\left(s[n]-\sum_{m=1}^{p} a_{m} s[n-m]\right) s[n-k], \quad 1 \leq k \leq p \\
\vec{c}=\Phi \vec{a}
\end{gathered}
$$

## Hidden Markov Models

$$
\begin{gathered}
\alpha_{t}(j)=\sum_{i=1}^{N} \alpha_{t-1}(i) a_{i j} b_{j}\left(\vec{o}_{t}\right), \quad 1 \leq j \leq N, 2 \leq t \leq T \\
\beta_{t}(i)=\sum_{j=1}^{N} a_{i j} b_{j}\left(\vec{o}_{t+1}\right) \beta_{t+1}(j), \quad 1 \leq i \leq N, 1 \leq t \leq T-1 \\
\gamma_{t}(i)=\frac{\alpha_{t}(i) \beta_{t}(i)}{\sum_{k=1}^{N} \alpha_{t}(k) \beta_{t}(k)} \\
\xi_{t}(i, j)=\frac{\alpha_{t}(i) a_{i j} b_{j}\left(\vec{o}_{t+1}\right) \beta_{t+1}(j)}{\sum_{k=1}^{N} \sum_{\ell=1}^{N} \alpha_{t}(k) a_{k \ell} b_{\ell}\left(\partial_{t+1}\right) \beta_{t+1}(\ell)} \\
\tilde{\alpha}_{t}(j)=\sum_{i=1}^{N} \hat{\alpha}_{t-1}(i) a_{i j} b_{j}\left(\vec{x}_{t}\right) \\
c_{t}=\sum_{j=1}^{N} \tilde{\alpha}_{t}(j) \\
\hat{\alpha}_{t}(j)=\frac{1}{g_{t}} \tilde{a}_{t}(j) \\
\bar{a}_{i j}=\frac{\sum_{t=1}^{T-1} \xi_{t}(i, j)}{\sum_{j=1}^{N} \sum_{t=1}^{T-1} \xi_{t}(i, j)} \\
\bar{U}_{i}=\frac{\sum_{t=1}^{T} \gamma_{t}(i)\left(\vec{o}_{t}-\vec{\mu}_{i}\right)\left(\vec{x}_{t}-\vec{\mu}_{i}\right)^{T}}{\sum_{t=1}^{T} \gamma_{t}(i)} \\
\bar{\mu}_{i}=\frac{\sum_{t=1}^{T} \gamma_{t}(i) \vec{o}_{t}}{\sum_{t=1}^{T} \gamma_{t}(i)}
\end{gathered}
$$

1. (20 points) In (Velichko \& Zagoruyko, 1970), the best time alignment was defined to be the one that maximized the sum of similarities. Consider, instead, an alignment that minimizes the sum of distances. Consider the problem of finding a sequence of alignments $I=[i(1), \ldots, i(T)]$ and $J=[j(1), \ldots, j(T)]$ where $I, J$, and $T$ are chosen to maximize

$$
D=\max _{i(t), j(t) \forall 1 \leq t} d(i(t-1), j(t-1), i(t), j(t))
$$

where

$$
d(i(t-1), j(t-1), i(t), j(t))= \begin{cases}C & i(t)=i(t-1), j(t)=j(t-1)+1 \\ C & i(t)=i(t-1)+1, j(t)=j(t-1) \\ d_{i(t), j(t)} & i(t)=i(t-1)+1, j(t)=j(t-1)+1 \\ \infty & \text { otherwise }\end{cases}
$$

In other words, the cost of any horizontal or vertical move in the alignment matrix is a constant $(C)$, the cost of a diagonal move is dependent on $i(t)$ and $j(t)$, and no other moves are possible. Suppose that the lengths of the two utterances are the same, i.e., $i(T)=j(T)=N$. What is the smallest value of $C$ that is guaranteed to find an alignment with $N$ diagonal moves?
2. (20 points) Suppose we have the following model of pitch prediction:

$$
e[n]=d[n]-\beta_{1} d[n-P+1]-\beta_{2} d[n-P]-\beta_{3}[n-P-1],
$$

and we wish to find the values of $\vec{\beta}=\left[\beta_{1}, \beta_{2}, \beta_{3}\right]^{T}$ that minimizes

$$
\mathcal{E}=\sum_{n=0}^{N-1}(e[n])^{2}
$$

What value of the vector $\vec{\beta}$ minimizes $\mathcal{E}$ ? If you write your answer in terms of any other vectors, matrices, or covariance functions, be sure to define them.
3. (20 points) An LPC-based speech coder generates every $N$-sample frame of a synthetic speech signal, $\hat{s}[n]$, from a synthetic quantized residual, $\hat{q}[n]$. There are two ways this may be done. First, the synthesis may be done using IIR filters, as shown in Equations (1) and (2):

$$
\begin{align*}
& \hat{d}[n]=\hat{q}[n]+\sum_{m=1}^{3} \beta_{m} \hat{d}[n-P+2-m]  \tag{1}\\
& \hat{s}[n]=\hat{d}[n]+\sum_{m=1}^{10} a_{k} \hat{s}[n-m] \tag{2}
\end{align*}
$$

Second, the synthesis may be performed using FIR filters, as shown in Equation (3):

$$
\begin{equation*}
\hat{s}[n]=\sum_{m=0}^{n} h[n-m] \hat{q}[m], \tag{3}
\end{equation*}
$$

where

$$
H(z)=\left(\frac{1}{1-\sum_{m=1}^{3} \beta_{m} z^{-P+2-m}}\right)\left(\frac{1}{1-\sum_{m=1}^{10} a_{k} z^{-m}}\right)
$$

Suppose that most of the samples of $\hat{q}[n]$ are zero; only $M$ samples per frame, on average, are non-zero, where $M \ll N$. Suppose that $h[n]$, $a_{m}$, and $\beta_{m}$ have already been computed, and your only task now is to decide whether the FIR or the IIR synthesis method is more computationally efficient. For what values of $M$ is the FIR synthesis more computationally efficient (fewer multiply operations) than the IIR synthesis method?
4. (20 points) Consider a two-state HMM with parameters. Suppose that all of the parameters of this HMM have the value of 0.5 . In other words, suppose that:

$$
\begin{aligned}
& \pi_{i}=P\left(q_{1}=i\right)=0.5 \quad \forall i \in\{1,2\} \\
& a_{i, j}=P\left(q_{t}=j \mid q_{t-1}=i\right)=0.5 \quad \forall i, j \in\{1,2\} \\
& b_{j}(k)=P\left(o_{t}=k \mid q_{t}=j\right)=0.5 \forall j, k
\end{aligned}
$$

Define

$$
\hat{\alpha}_{t}(i)=P\left(q_{t}=i \mid o_{1}, \ldots, o_{t}, \lambda\right)
$$

Find the value of $\hat{\alpha}_{300}(1)$.
5. (20 points) Recall that Baum's auxiliary can be written as

$$
Q(\lambda, \bar{\lambda})=\sum_{Q} P(Q \mid O, \lambda) \ln P(O, Q \mid \bar{\lambda})
$$

and that the part related to the observation pdf can be simplified to

$$
Q_{b}(\lambda, \bar{\lambda})=\sum_{t=1}^{T} \sum_{i=1}^{N} \gamma_{t}(i) \ln \bar{b}_{i}\left(o_{t}\right)
$$

where the terms are defined as

$$
\left.\left.\begin{array}{rl}
\gamma_{t}(i) & =P\left(q_{t}=i \mid O, \lambda\right) \\
\bar{b}_{i}\left(o_{t}\right) & =P\left(o_{t}\right.
\end{array}=o_{t} \right\rvert\, q_{t}=i, \bar{\lambda}\right) \text { 位 }
$$

Suppose that we have a sequence of scalar observations, $O=\left[o_{1}, \ldots, o_{T}\right]$, modeled by state-dependent Gaussian pdfs,

$$
\bar{b}_{i}\left(o_{t}\right)=\frac{1}{\sqrt{2 \pi \bar{\rho}_{i}}} e^{-\frac{\left(o_{t}-\bar{\mu}_{i}\right)^{2}}{2 \bar{p}_{i}}},
$$

where $\bar{\mu}_{i}$ and $\bar{\rho}_{i}$ are the state-dependent mean and variance, respectively. As you know, the variance terms in a Gaussian need to be non-negative. We can force $\bar{\rho}_{i}$ to be non-negative by maximing a Lagrangian term of the form

$$
\mathcal{L}(\bar{\lambda})=Q_{b}(\lambda, \bar{\lambda})-\sum_{i=1}^{N} \kappa_{i} \bar{\rho}_{i}
$$

Simplify $\mathcal{L}(\bar{\lambda})$ so that it is a function of only $\gamma_{t}(i), o_{t}, \bar{\mu}_{i}, \bar{\rho}_{i}$, and $\kappa_{i}$ for $1 \leq t \leq T, 1 \leq i \leq N$.

