

UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN
CS440/ECE448 Artificial Intelligence
Conflict Exam 2
Spring 2022

Week of April 4, 2022

Your Name: _____

Your NetID: _____

Instructions

- Please write your NetID on the top of every page.
- This is a **CLOSED BOOK** exam. You will be permitted to bring one 8.5x11 page of handwritten notes (front & back).
- Calculators are not permitted. You need not simplify explicit numerical expressions.

Possibly Useful Formulas**Search:**

$$\text{Admissible Heuristic: } h(n) \leq d(n)$$

$$\text{Consistent Heuristic: } h(m) - h(n) \leq d(m) - d(n) \text{ if } d(m) - d(n) \geq 0$$

Belief Propagation:

$$P(A, B, C) = P(A)P(B|A)P(C|A, B)$$

$$P(A, C) = \sum_b P(A, B = b, C)$$

$$P(A|C) = \frac{P(A, C)}{P(C)}$$

Expectation Maximization:

$$P(B = b|A = a) \leftarrow \frac{E[\# \text{ times } A = a, B = b]}{E[\# \text{ times } A = a]}$$

$$E[\# \text{ times } A = a, B = b] = \sum_t P(A_t = a, B_t = b | \text{observations on day } t)$$

HMM:

$$P(Y_1, X_1, \dots, Y_T, X_T) = \prod_{t=1}^T P(Y_t|Y_{t-1})P(X_t|Y_t)$$

Viterbi Algorithm:

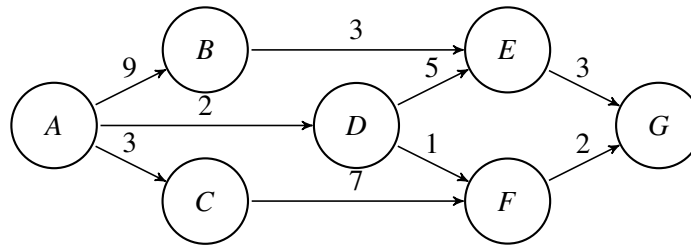
$$e_{i,j,t} = a_{j,i}b_{j,k}$$

$$v_{i,1} = \pi_i b_{i,x_1}$$

$$v_{j,t} = \max_i v_{i,t-1} e_{i,j,t}$$

Question 1 (7 points)

Consider the following search graph. The starting state is A, the goal state is G, and the cost of each possible action is shown on the corresponding edge:



Suppose that the states shown have the following heuristics:

	A	B	C	D	E	F	G
$h(n)$:	4	3	1	1	0	2	0

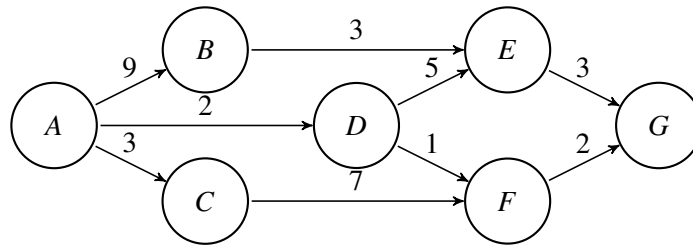
A* search (with repetitions avoided using an explored set) is applied to this graph to find the shortest path.

- What states are expanded, and
- what is the shortest path?

Solution: Expanded states: A,D,C,F,G
Shortest path: A,D,F,G

Question 2 (7 points)

Consider the following search graph. The starting state is A, the goal state is G, and the cost of each possible action is shown on the corresponding edge:



You are considering trying to implement A* search over this graph. You are trying to decide whether to use $h_1(n)$ or $h_2(n)$ as the heuristic, where $h_1(n)$ and $h_2(n)$ are as given in the following table:

	A	B	C	D	E	F	G
$h_1(n)$:	4	5	8	2	2	1	0
$h_2(n)$:	4	5	8	3	2	1	0

- (a) Suppose you are using an explored set to prevent repeated states, i.e., you will only expand a state if you have never expanded it before. Which of these two heuristics is better to use, and why?

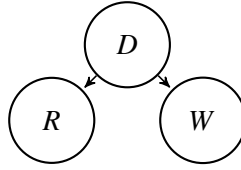
Solution: Use $h_1[n]$, because it is consistent.

- (b) Your friend convinces you to use an explored dict, i.e., you will only expand a state if you have never expanded it before with a smaller $g(n)$. Which of these two heuristics is better to use, and why?

Solution: Use $h_2(n)$, because it dominates $h_1(n)$.

Question 4 (7 points)

Consider the following Bayesian network. All variables are binary:



Suppose that the model parameters are as follows:

$$P(D = T) = 0.3$$

$$P(R = T|D) = \begin{cases} 0.8 & D = F \\ 0.1 & D = T \end{cases}$$

$$P(W = T|D) = \begin{cases} 0.1 & D = F \\ 0.6 & D = T \end{cases}$$

What is $P(D = T|W = T)$?

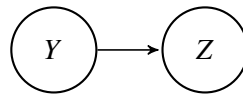
Solution:

$$\begin{aligned} P(D = T|W = T) &= \frac{\sum_{r=1}^2 P(D = T, W = T)}{\sum_{d=F}^T P(D = d, W = T)} \\ &= \frac{(0.3)(0.6)}{(0.3)(0.6) + (0.7)(0.1)} \end{aligned}$$

If you wish, you can simplify the last formula to $\frac{18}{25} = 0.72$, but it's not required.

Question 5 (7 points)

Consider the following Bayesian network, showing the relationship between two binary variables Y and Z :



Suppose that you've been given the following initial estimates of the model parameters, where a , b , and c are some arbitrary constants:

$$P(Y = T) = a, \quad P(Z = T|Y = F) = b, \quad P(Z = T|Y = T) = c$$

You are now trying to re-estimate the values of these model parameters. You have observed the values of the variables on five consecutive days, but on the fifth day, the value of Z was unobserved (labeled with a "?" in the table below:

	Day 1	Day 2	Day 3	Day 4	Day 5
Value of Y :	T	F	T	F	F
Value of Z :	F	F	F	T	?

For this table, in terms of the current model parameters a , b , and c , what is the expected number of days on which $Y = F$ and $Z = T$?

Solution:

$$\begin{aligned} E[\# \text{ days } Y = F, Z = T] &= 1 + P(Z = T|Y = F) \\ &= 1 + b \end{aligned}$$

Question 6 (7 points)

Suppose that you have a hidden Markov model in which the state variables (Y_t) and observation variables (X_t) are binary. The initial-state probability is $P(Y_1 = T) = 0.6$, and the other model parameters are as follows:

Y_{t-1}	$P(Y_t = T Y_{t-1})$
F	0.2
T	0.3

Y_t	$P(X_t = T Y_t)$
F	0.2
T	0.9

What is $P(Y_1 = T|X_1 = T, X_2 = T)$?

Solution:

$$P(Y_1 = T|X_1 = T, X_2 = T)$$

$$= \frac{P(Y_1 = T, X_1 = T, Y_2 = T, X_2 = T) + P(Y_1 = T, X_1 = T, Y_2 = F, X_2 = T)}{P(Y_1 = T, X_1 = T, Y_2 = T, X_2 = T) + P(Y_1 = T, X_1 = T, Y_2 = F, X_2 = T) + P(Y_1 = F, X_1 = T, Y_2 = T, X_2 = T) + P(Y_1 = F, X_1 = T, Y_2 = F, X_2 = T)}$$

$$= \frac{(0.6)(0.9)(0.3)(0.9) + (0.6)(0.9)(0.7)(0.2)}{(0.6)(0.9)(0.3)(0.9) + (0.6)(0.9)(0.7)(0.2) + (0.4)(0.2)(0.2)(0.9) + (0.4)(0.2)(0.8)(0.2)}$$

Question 7 (7 points)

Suppose that you have a hidden Markov model in which the state variables (Y_t) and observation variables (X_t) are binary. The initial-state probability is $P(Y_1 = T) = 0.6$, and the other model parameters are as follows:

Y_{t-1}	$P(Y_t = F Y_{t-1})$
F	0.0
T	1.0

Y_t	$P(X_t = T Y_t)$
F	0.9
T	0.3

Suppose that the observations are $X_1 = F, X_2 = T$. What is the most likely sequence of values Y_1, Y_2 ?

Solution: In this problem, the sequences (F,F) and (T,T) are impossible. The other two sequences have the probabilities:

$$P(Y_1 = T, X_1 = F, Y_2 = F, X_2 = T) = (0.6)(0.7)(1)(0.9)$$

$$P(Y_1 = F, X_1 = F, Y_2 = T, X_2 = T) = (0.4)(0.1)(1)(0.3)$$

The sequence (T,F) has higher probability.