ECE 417 Multimedia Signal Processing Solutions to Homework 6

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Assigned: Tuesday, 11/7/2023; Due: Tuesday, 11/28/2023

Problem 6.1

Suppose you have a recurrent neural network with input x[n], target $y[n] \in \{0,1\}$, output h[n], and loss function:

$$\mathcal{L} = -\frac{1}{N} \sum_{n=0}^{N-1} (y[n] \ln h[n] + (1 - y[n]) \ln(1 - h[n]))$$

where

$$h[n] = \sigma(\xi[n]),$$

$$\xi[n] = x[n] + \sum_{m=1}^{M-1} w[m]h[n-m],$$

and where $\sigma(\cdot)$ is the logistic sigmoid. Write $d\mathcal{L}/dw[3]$ in terms of the signals y[n] and h[m]. You may assume that h[n] = 0 for n < 0.

Solution: First step: forward-prop. Assume that h[n] has been calculated. Second step: partial derivatives:

$$\begin{split} \frac{\partial \mathcal{L}}{\partial h[n]} &= \frac{1}{N} \left(\frac{y[n]}{h[n]} - \frac{1 - y[n]}{1 - h[n]} \right) \\ &= \begin{cases} \frac{1}{N} \frac{1}{h[n]} & y[n] = 1\\ \frac{1}{N} \frac{1}{h[n] - 1} & y[n] = 0 \end{cases} \\ &= \frac{1}{N} \frac{h[n] - y[n]}{h[n](h[n] - 1)} \end{split}$$

Third step: total derivatives:

$$\begin{split} \frac{d\mathcal{L}}{dh[n]} &= \frac{\partial \mathcal{L}}{\partial h[n]} + \sum_{m=1}^{M-1} \frac{d\mathcal{L}}{dh[n+m]} \frac{\partial h[n+m]}{\partial h[n]} \\ &= \frac{\partial \mathcal{L}}{\partial h[n]} + \sum_{m=1}^{M-1} \frac{d\mathcal{L}}{dh[n+m]} \dot{\sigma} \left(\xi[n+m] \right) w[m] \\ &= \frac{1}{N} \frac{h[n] - y[n]}{h[n](h[n] - 1)} + \sum_{m=1}^{M-1} \frac{d\mathcal{L}}{dh[n+m]} h[n+m] (1 - h[n+m]) w[m] \end{split}$$

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Fourth step: weight gradient:

$$\begin{split} \frac{d\mathcal{L}}{dw[3]} &= \sum_{n=0}^{N-1} \frac{d\mathcal{L}}{dh[n]} \frac{\partial h[n]}{\partial w[3]} \\ &= \frac{1}{N} \frac{h[n] - y[n]}{h[n](h[n] - 1)} \dot{\sigma}(\xi[n]) h[n - 3] + \sum_{m=1}^{M-1} \frac{d\mathcal{L}}{dh[n + m]} h[n + m] (1 - h[n + m]) w[m] \dot{\sigma}(\xi[n]) h[n - 3] \\ &= \frac{1}{N} (h[n] - y[n]) h[n - 3] + \sum_{m=1}^{M-1} \frac{d\mathcal{L}}{dh[n + m]} h[n + m] (1 - h[n + m]) w[m] h[n] (1 - h[n]) h[n - 3] \end{split}$$

Problem 6.2

Suppose that

$$h_0 = x^3$$

$$h_1 = \cos(x) + \sin(h_0)$$

$$\hat{y} = \frac{1}{2} (h_1^2 + h_0^2)$$

What is $d\hat{y}/dx$? Express your answer as a function of x only, without the variables h_0 or h_1 in your answer.

Solution:

$$\frac{dh_0}{dx} = 3x^2$$

$$\frac{dh_1}{dx} = \frac{\partial h_1}{dx} + \frac{dh_0}{dx} \frac{\partial h_1}{\partial h_0}$$

$$= -\sin(x) + 3x^2 \cos(x^3)$$

$$\frac{d\hat{y}}{dx} = \frac{dh_0}{dx} \frac{\partial \hat{y}}{\partial h_0} + \frac{dh_1}{dx} \frac{\partial \hat{y}}{\partial h_1}$$

$$= h_0 (3x^2) + h_1 (-\sin(x) + 3x^2 \cos(x^3))$$

$$= 3x^5 + (\cos(x) + \sin(x^3)) (-\sin(x) + 3x^2 \cos(x^3))$$

Problem 6.3

Consider a one-gate recurrent neural net, defined as follows:

$$c[n] = c[n-1] + w_c x[n] + u_c h[n-1] + b_c$$

$$h[n] = o[n]c[n]$$

$$o[n] = \sigma(w_o x[n] + u_o h[n-1] + b_o)$$

where $\sigma(\cdot)$ is the logistic sigmoid, x[n] is the network input, c[n] is the cell, o[n] is the output gate, and and h[n] is the output. Suppose that you've already completed synchronous back-prop, which has given you the following quantity:

$$\epsilon[n] = \frac{\partial \mathcal{L}}{\partial h[n]}$$

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Find asynchronous back-prop formulas, i.e., find formulas for the following quantities, in terms of one another, and/or in terms of the other quantities defined above:

$$\delta_h[n] = \frac{d\mathcal{L}}{dh[n]}$$

$$\delta_o[n] = \frac{d\mathcal{L}}{do[n]}$$

$$\delta_c[n] = \frac{d\mathcal{L}}{dc[n]}$$

Solution:

$$\begin{split} \delta_h[n] &= \epsilon[n] + \delta_c[n+1] u_c + \delta_o[n+1] \dot{\sigma}(w_o x[n+1] + u_o h[n] + b_1) u_o \\ &= \epsilon[n] + \delta_c[n+1] u_c + \delta_o[n+1] o[n+1] (1 - o[n+1]) u_o \\ \delta_o[n] &= \delta_h[n] c[n] \\ \delta_c[n] &= \delta_c[n+1] + \delta_h[n+1] o[n] \end{split}$$

Problem 6.4

Remember that in lecture we defined a super-simplified nonlinearity called the clipped ReLU or CReLU, which is:

$$CReLU(x) = \max(0, \min(1, x))$$

Using the CReLU nonlinearity for both σ_h and σ_q in an LSTM, choose weights and biases,

$$\{b_c, u_c, w_c, b_f, u_f, w_f, b_i, u_i, w_i, b_o, u_o, w_o\},\$$

that will cause an LSTM to count the number of nonzero inputs, and output the tally only when the input is zero:

$$h[n] = \begin{cases} \sum_{m=0}^{n} \mathbf{1}[x[m] \ge 1] & x[n] = 0\\ 0 & x[n] \ge 1 \end{cases}$$

where $\mathbf{1}[\cdot]$ is the unit indicator function, and you may assume that x[n] is always a non-negative integer.

Solution: First, we only want to generate output when x[n] = 0, so

$$o[n] = \text{CReLU}(x[n]), \quad \Rightarrow \quad b_o = 1, w_o = -1, u_o = 0$$

Second, we want c[n] to increase by exactly 1, every time $x[n] \ge 1$, and otherwise to keep its previous value, i.e.,

$$c[n] = c[n-1] + CReLU(x[n]),$$

but we know that c[n] is defined to be

$$c[n] = f[n]c[n-1] + i[n]CReLU(w_cx[n] + u_ch[n-1] + b_c)$$

so we want f[n] = 1 always, and i[n] = 1 whenever $x[n] \ge 0$, so

$$b_f = 1, w_f \ge 0, u_f \ge 0, (w_i \ge 1 \text{ or } b_i \ge 1), u_i \ge 0, w_c = 1, u_c = 0, b_c = 0$$

Putting it all together, we have

$$\{b_c = 0, u_c = 0, w_c = 1, b_f = 1, u_f \ge 0, w_f \ge 0, (b_i \ge 1 \text{ or } w_i \ge 1), u_i \ge 0, b_o = 1, u_o = 0, w_o = 1\}$$