

# ECE 417 Multimedia Signal Processing

## Solutions to Homework 3

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Assigned: Tuesday, 9/28/2021; Due: Tuesday, 10/5/2021  
Reading: , Sections 1-3

### Problem 3.1

Suppose  $\vec{X} = [X_1, X_2]^T$  is a Gaussian random vector with mean and covariance given by

$$\vec{\mu} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad \Sigma = \begin{bmatrix} 9 & 0 \\ 0 & 4 \end{bmatrix}$$

Sketch the set of points such that  $f_{\vec{X}}(\vec{x}) = \frac{1}{12\pi} e^{-\frac{1}{8}}$ , where  $f_{\vec{X}}(\vec{x})$  is the pdf of  $\vec{X}$ .

**Solution:** Your sketch should be an ellipse, centered at the point  $\vec{\mu} = [1, 0]^T$ , with a radius of  $\frac{\sigma_1}{2} = \frac{3}{2}$  in the  $x_1$  direction, and with a radius of  $\frac{\sigma_2}{2} = 1$  in the  $x_2$  direction.

### Problem 3.2

Suppose  $\vec{X} = [X_1, X_2]^T$  is a Gaussian random vector with mean and covariance given by

$$\vec{\mu} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad \Sigma = \begin{bmatrix} 9 & 0 \\ 0 & 4 \end{bmatrix}$$

Define  $\Phi(z)$  as follows:

$$\Phi(z) = \int_{-\infty}^z \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}u^2} du$$

In terms of  $\Phi(z)$ , find the probability  $\Pr\{-1 < X_1 < 1, -1 < X_2 < 1\}$ .

**Solution:**

$$\begin{aligned} \Pr\{-1 < X_1 < 1, -1 < X_2 < 1\} &= \Pr\{-1 < X_1 < 1\} \Pr\{-1 < X_2 < 1\} \\ &= \left( \Phi\left(\frac{1-1}{3}\right) - \Phi\left(\frac{-1-1}{3}\right) \right) \left( \Phi\left(\frac{1-0}{2}\right) - \Phi\left(\frac{-1-0}{2}\right) \right) \end{aligned}$$

### Problem 3.3

Suppose that, for a particular classification problem, the observations are  $\vec{x} \in \mathfrak{R}^2$ , and the labels are  $y \in \{0, 1\}$ . It just so happens that the correct label of every data point is as follows:

$$y^*(\vec{x}) = \begin{cases} 1 & \|\vec{x}\|_2 > 1.5 \\ 0 & \|\vec{x}\|_2 < 1.5 \end{cases} \quad (3.3-1)$$

Unfortunately, you aren't allowed to use the correct labeling function. Instead, are required to learn a Gaussian classifier with the following form:

$$\hat{y}(\vec{x}) = \begin{cases} 1 & \frac{p_{\vec{X}|Y}(\vec{x}|1)}{p_{\vec{X}|Y}(\vec{x}|0)} > \eta \\ 0 & \frac{p_{\vec{X}|Y}(\vec{x}|1)}{p_{\vec{X}|Y}(\vec{x}|0)} < \eta \end{cases} \quad (3.3-2)$$

where  $\eta$  is a parameter called the likelihood ratio threshold, and where the probability models for for both classes are zero-mean Gaussians, with different covariance matrices  $\Sigma_0$  and  $\Sigma_1$ :

$$p_{\vec{X}|Y}(\vec{x}|y) = \mathcal{N}\left(\vec{x}|\vec{\mu} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \Sigma_y\right) \quad (3.3-3)$$

Suppose that  $\Sigma_0$  and  $\Sigma_1$  are known to be the identity matrix, and the scaled identity matrix, respectively:

$$\Sigma_0 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad \Sigma_1 = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

Find a value of  $\eta$  so that the Gaussian classifier (Eq. (3.3-2)) gives exactly the same decision boundary as the correct decision rule (Eq. (3.3-1)).

**Solution:** The Gaussian classifier chooses  $\hat{y} = 1$  under any of the following conditions, all of which are equivalent:

$$\begin{aligned} p_{\vec{X}|Y}(\vec{x}|1) &> \eta p_{\vec{X}|Y}(\vec{x}|0) \\ \ln p_{\vec{X}|Y}(\vec{x}|1) &> \ln p_{\vec{X}|Y}(\vec{x}|0) + \ln \eta \\ -\frac{1}{2} \ln |\Sigma_1| - \frac{1}{2} d_{\Sigma_1}(\vec{x}, \vec{0}) &> -\frac{1}{2} \ln |\Sigma_0| - \frac{1}{2} d_{\Sigma_0}(\vec{x}, \vec{0}) + \ln \eta \\ -\frac{1}{2} \ln(4) - \frac{1}{2} \left( \frac{x_1^2 + x_2^2}{2} \right) &> -\frac{1}{2} (x_1^2 + x_2^2) + \ln \eta \\ \|\vec{x}\|^2 \left( \frac{1}{2} - \frac{1}{4} \right) &> \ln \eta + \frac{1}{2} \ln(4) \\ \|\vec{x}\| &> \sqrt{4 \ln \eta + 2 \ln(4)} \end{aligned}$$

This is exactly the same as Eq. (3.3-2) if  $\sqrt{4 \ln \eta + 2 \ln(4)} = 1.5$ , i.e.,

$$\eta = e^{\frac{(1.5)^2 - 2 \ln(4)}{4}}$$

### Problem 3.4

Suppose you have a scalar random variable  $X$ , with training examples  $[x_1, x_2, x_3, x_4] = [-1, 0, 1, 2]$ . You want to try to model these data using a Gaussian mixture model, with the form

$$p_X(x) = \sum_{k=0}^1 c_k \mathcal{N}(x|\mu_k, \sigma_k^2) \quad (3.4-1)$$

You have initial parameter estimates  $\mu_0 = 0$ ,  $\mu_1 = 1$ ,  $\sigma_0^2 = \sigma_1^2 = 1$ , and  $c_0 = c_1 = 0.5$ . Perform one iteration of EM training. What are the new values of  $\mu_0$ ,  $\mu_1$ ,  $\Sigma_0$  and  $\Sigma_1$ , after one round of EM training? Write your answer in terms of the normal probability density functions  $\mathcal{N}(x|\mu, \sigma^2)$ , for numerical values of  $x, \mu$  and  $\sigma^2$ .

**Solution:** The gamma probabilities are

$$\gamma_1(1) = \frac{0.5\mathcal{N}(-1|1, 1)}{0.5\mathcal{N}(-1|0, 1) + 0.5\mathcal{N}(-1|1, 1)}$$

$$\gamma_2(1) = \frac{0.5\mathcal{N}(0|1, 1)}{0.5\mathcal{N}(0|0, 1) + 0.5\mathcal{N}(0|1, 1)}$$

$$\gamma_3(1) = \frac{0.5\mathcal{N}(1|1, 1)}{0.5\mathcal{N}(1|0, 1) + 0.5\mathcal{N}(1|1, 1)}$$

$$\gamma_4(1) = \frac{0.5\mathcal{N}(2|1, 1)}{0.5\mathcal{N}(2|0, 1) + 0.5\mathcal{N}(2|1, 1)}$$

and similarly for  $\gamma_0$ . The re-estimated parameters are written in terms of the gamma probabilities, so they will be

$$\begin{aligned} \mu_0 &= - \left( \frac{\mathcal{N}(-1|0, 1)}{\mathcal{N}(-1|0, 1) + \mathcal{N}(-1|1, 1)} \right) + \left( \frac{\mathcal{N}(1|0, 1)}{\mathcal{N}(1|0, 1) + \mathcal{N}(1|1, 1)} \right) + 2 \left( \frac{\mathcal{N}(2|0, 1)}{\mathcal{N}(2|0, 1) + \mathcal{N}(2|1, 1)} \right) \\ \mu_1 &= - \left( \frac{\mathcal{N}(-1|1, 1)}{\mathcal{N}(-1|0, 1) + \mathcal{N}(-1|1, 1)} \right) + \left( \frac{\mathcal{N}(1|1, 1)}{\mathcal{N}(1|0, 1) + \mathcal{N}(1|1, 1)} \right) + 2 \left( \frac{\mathcal{N}(2|1, 1)}{\mathcal{N}(2|0, 1) + \mathcal{N}(2|1, 1)} \right) \\ \sigma_0^2 &= \left( \frac{\mathcal{N}(-1|0, 1)}{\mathcal{N}(-1|0, 1) + \mathcal{N}(-1|1, 1)} \right) + \left( \frac{\mathcal{N}(1|0, 1)}{\mathcal{N}(1|0, 1) + \mathcal{N}(1|1, 1)} \right) + 4 \left( \frac{\mathcal{N}(2|0, 1)}{\mathcal{N}(2|0, 1) + \mathcal{N}(2|1, 1)} \right) \\ \sigma_1^2 &= 4 \left( \frac{\mathcal{N}(-1|1, 1)}{\mathcal{N}(-1|0, 1) + \mathcal{N}(-1|1, 1)} \right) + \left( \frac{\mathcal{N}(0|1, 1)}{\mathcal{N}(0|0, 1) + \mathcal{N}(0|1, 1)} \right) + \left( \frac{\mathcal{N}(2|1, 1)}{\mathcal{N}(2|0, 1) + \mathcal{N}(2|1, 1)} \right) \end{aligned}$$