

Section (Check One) MWF 10am _____ MWF 2pm _____

1. 25 / 25 2. 25 / 25

3. 25 / 25 4. 25 / 25

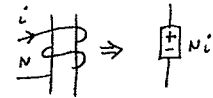
Total 100 / 100

Useful information

$$\sin(x) = \cos(x - 90^\circ) \quad \bar{V} = \overline{ZI} \quad \bar{S} = \overline{VI}^* \quad \mu_0 = 4\pi \cdot 10^{-7} \text{ H/m}$$

$$\int_C \mathbf{H} \cdot d\mathbf{l} = \int_S \mathbf{J} \cdot \mathbf{n} da \quad \int_C \mathbf{E} \cdot d\mathbf{l} = -\frac{\partial}{\partial t} \int_S \mathbf{B} \cdot \mathbf{n} da \quad MMF = Ni = \phi \mathcal{R}$$

$$\mathcal{R} = \frac{l}{\mu A} \quad B = \mu H \quad \phi = BA \quad \lambda = N\phi \quad \lambda = Li \text{ (if linear)}$$



$$W_m = \int_0^\lambda i d\hat{\lambda} \quad W_m' = \int_0^i \lambda d\hat{i} \quad W_m + W_m' = \lambda i \quad f^e = \frac{\partial W_m'}{\partial x} = -\frac{\partial W_m}{\partial x} \quad x \rightarrow \theta$$

$$f^e \rightarrow T^e$$

$$EFE_{a \rightarrow b} = \int_a^b i d\lambda \quad EFM_{a \rightarrow b} = -\int_a^b f^e dx \quad EFE_{a \rightarrow b} + EFM_{a \rightarrow b} = W_{mb} - W_{ma} \quad \lambda = \frac{\partial W_m'}{\partial i} \quad i = \frac{\partial W_m}{\partial \lambda}$$

$$M \frac{dv}{dt} = \sum \text{forces in } +x \text{ direction}$$

$$\dot{\underline{x}} = \underline{f}(\underline{x}, \underline{u})$$

$$\text{Equilibrium: } \underline{f}(\underline{x}_{eq}, \underline{u}_{eq}) = 0$$

$$\underline{x}(t_{n+1}) = \underline{x}(t_n) + \Delta t \cdot \underline{f}(\underline{x}(t_n), \underline{u}(t_n))$$

$$\text{Linearization: } \Delta \dot{x}_1 = \frac{\partial f_1}{\partial x_1} \Delta x_1 + \frac{\partial f_1}{\partial x_2} \Delta x_2 + \dots + \frac{\partial f_1}{\partial u} \Delta u$$

$$\Delta \dot{x}_2 = \frac{\partial f_2}{\partial x_1} \Delta x_1 + \frac{\partial f_2}{\partial x_2} \Delta x_2 + \dots + \frac{\partial f_2}{\partial u} \Delta u$$

$$\text{Stability: } A = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{bmatrix}$$

$$|\lambda I - A| = 0$$

$$\text{stable if } \text{Re}\{\lambda\} < 0$$

Problem 1. (25 points)

In class, generally we treated mutual inductances to be sinusoidal in rotational devices. In the system below, we have added a third harmonic (the 3θ terms). This gives the mutual inductance a more trapezoidal shape, which is common in some actual machines.

$$\begin{bmatrix} \lambda_a \\ \lambda_b \\ \lambda_r \end{bmatrix} = \begin{bmatrix} L_s & 0 & M(\cos\theta - 0.1\cos(3\theta)) \\ 0 & L_s & M(\sin\theta + 0.1\sin(3\theta)) \\ M(\cos\theta - 0.1\cos(3\theta)) & M(\sin\theta + 0.1\sin(3\theta)) & L_r \end{bmatrix} \begin{bmatrix} i_a \\ i_b \\ i_r \end{bmatrix}$$

- Find the co-energy in terms of the currents.
- Find an expression for the energy stored in the coupling field in terms of currents.
- Find the torque of electric origin T^e in terms of the currents.
- Suppose $i_a = i_b = i_r = 1$ A, $L_s = L_r = 1$ H, $M = 0.9$ H, and $\theta = 60^\circ$. What is the contribution to the torque due to including the third harmonic (3θ) mutual inductance terms?

$$a) w'_m = \left(\frac{1}{2}L_s i_a^2\right) + \left(0 + \frac{1}{2}L_s i_b^2\right) + \left(m(\cos\theta - 0.1\cos 3\theta) i_a i_r + m(\sin\theta + 0.1\sin 3\theta) i_b i_r + \frac{1}{2}L_r i_r^2\right)$$

$$b) w_m = w'_m$$

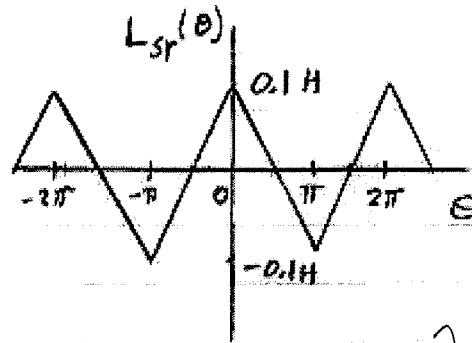
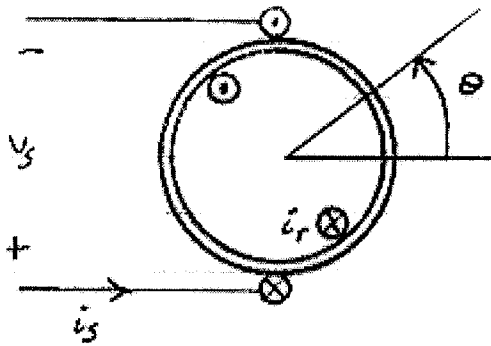
$$c) T^e = -m\sin\theta i_a i_r + 0.3m\sin 3\theta i_a i_r + m\cos\theta i_b i_r + 0.3m\cos 3\theta i_b i_r$$

$$d) T_{3\theta}^e = 0.3 \times 0.9 \sin 180^\circ \times 1 \times 1 + 0.3 \times 0.9 \cos 180^\circ \times 1 \times 1$$

$$= \underline{\underline{-0.27 \text{ NM}}}$$

Problem 2. (25 points.)

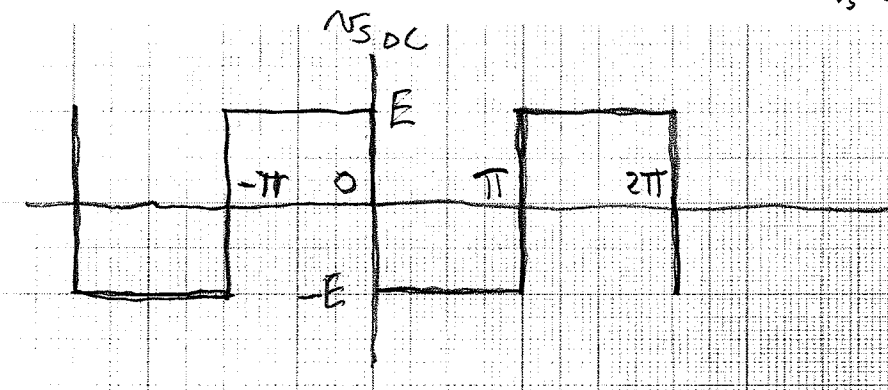
A single-phase generator consists of a coil on the stator and a coil on the rotor with a mutual inductance variation with θ as shown in the figure below. The rotor is being driven at a constant speed of 377 radians per second and the rotor coil has a constant dc current $i_r = 5$ A. The self inductances are constants and you may assume a linear magnetic core.



$$v_s = \frac{d\lambda_s}{dt}$$

$$\lambda_s = L_{s1} i_s + L_{sr}(\theta) i_r$$

a) Plot the open-circuit stator voltage ($i_s = 0$) as a function of θ (label all points)



$$\begin{aligned} E &= \frac{dL_{sr}(\theta) i_r}{dt} \\ i_s &= 0 \\ &= \frac{dL_{sr}}{d\theta} \times 377 \times 5 \\ &= \frac{0.2}{\pi} 377 \times 5 \\ &= 24 \times 5 \\ &= 120 \text{ V} \end{aligned}$$

b) What is the torque of electrical origin when $i_s = 10$ Amps and $\theta = 45^\circ$?

$$w'_m = \frac{1}{2} L_{s1} i_s^2 + L_{sr}(\theta) i_s i_r$$

$$\begin{aligned} T_e &= \frac{dw'_m}{d\theta} = \frac{dL_{sr}(\theta)}{d\theta} i_s i_r = -\frac{0.2}{\pi} \times 10 \times 5 \text{ Nm} \\ &= -3.18 \text{ Nm} \end{aligned}$$

Problem 3. (25 points.)

An electric machine (1 = stator, 2 = rotor) has the following linear flux linkage vs current characteristic:

$$\lambda_1 = 0.2i_1 + 0.1\sin\theta i_2$$

$$\lambda_2 = 0.1\sin\theta i_1 + 0.3 i_2$$

- What is the energy stored in the coupling field when $\theta = 90$ degrees, $i_1 = 3$ Amps, and $i_2 = 5$ Amps?
- How much energy is given to the coupling field by the mechanical system if θ is changed from 90 degrees to 60 degrees while the two currents remain constant?
- How much energy is given to the coupling field by the electrical system during that same path from θ equals 90 degrees to 60 degrees while the two currents remain constant?

$$a) w_m = w'_m = 0.1i_1^2 + 0.1\sin\theta i_1 i_2 + \frac{0.3i_2^2}{2}$$

$$w_m \Big|_{\theta=90} = 0.9 + 1.5 + 3.75 = 6.15 \text{ J}$$

$$i_1 = 3$$

$$i_2 = 5$$

$$.2 \times 3 + .1 \sin 60 \times 5$$

$$.1 \sin 60 \times 3 + .3 \times 5$$

$$1.633$$

$$1.76$$

$$c) EPE = \int_{90^\circ-60^\circ} 3 d\lambda_1 + \int 5 d\lambda_2 = \int 3 d\lambda_1 + \int 5 d\lambda_2 = -.2 -.2 = -.4 \text{ J}$$

$$b) w_m \Big|_{\theta=60} = 0.9 + 1.3 + 3.75 = 5.95 \text{ J}$$

$$\theta = 60$$

$$i_1 = 3$$

$$i_2 = 5$$

$$EFM = w_m 60 - w_m 90 - EPE = 5.95 - 6.15 + .4 \text{ J}$$

$$= 0.2 \text{ J}$$

$$\text{OR } T^e = \frac{2w'_m}{2\theta} = 0.1 \cos\theta i_1 i_2$$

$$EFM = - \int_{90-60}^{60} 0.1 \cos\theta \times 3 \times 5 d\theta = -1.55 \Big|_{90}^{60} = -1.3 - (-1.5)$$

$$= 0.2 \text{ J}$$

Problem 4. (25 points.)

Consider the following nonlinear equations

$$\begin{aligned}\dot{x}_1 &= x_1 - x_1 x_2 \\ \dot{x}_2 &= 0.5 x_1 x_2 - 2 x_2\end{aligned}$$

Assume the initial conditions for this system are

$$\mathbf{x}(0) = \begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} 2 \\ 0.5 \end{bmatrix}$$

- Using Euler's method with a time step $\Delta t = 0.1$ sec, determine the value of $\mathbf{x}(0.1)$ and $\mathbf{x}(0.2)$.
- Determine all of the equilibrium points for this system.
- Find the eigenvalues for each of these equilibrium points
- Are these points stable or unstable or neither? Explain why.

a)

$$x_1(0.1) = 2 + (2 - 2 \times 0.5) \cdot 0.1 = 2.1$$

$$x_2(0.1) = 0.5 + (0.5 \times 2 \times 0.5 - 2 \times 0.5) \cdot 0.1 = 0.45$$

$$x_1(0.2) = 2.1 + (2.1 - 2.1 \times 0.45) \cdot 0.1 = 2.22$$

$$x_2(0.2) = 0.45 + (0.5 \times 2.1 \times 0.45 - 2 \times 0.45) \cdot 0.1 = 0.407$$

b)

$$x_1 = 0, \quad x_2 = 0$$

$$x_1 = 4, \quad x_2 = 1$$

c)

$$J = \begin{bmatrix} 1-x_2 & -x_1 \\ 0.5x_2 & 0.5x_1-2 \end{bmatrix} \quad J_1 = \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix}$$

d)

$$\begin{vmatrix} \lambda - 1 & 0 \\ 0 & \lambda + 2 \end{vmatrix} = (\lambda - 1)(\lambda + 2) = 0$$

$\lambda = 1, -2$
↑
unstable

$$J_2 = \begin{bmatrix} 0 & -4 \\ 0.5 & 0 \end{bmatrix} \quad \begin{vmatrix} \lambda & 4 \\ -0.5 & \lambda \end{vmatrix} = \lambda^2 + 2 = 0$$

$\lambda = \pm j\sqrt{2}$
neither

