

# Natural Deduction Rules for Quantifiers

$$\frac{\Lambda x. P \ x}{\forall x. P \ x} \text{allI}$$

$$\frac{\forall x. P \ x \quad P \ ?x \implies R}{R} \text{allE}$$

$$\frac{P \ ?x}{\exists x. P \ x} \text{exI}$$

$$\frac{\exists x. P \ x \quad \Lambda x. P \ x \implies R}{R} \text{exE}$$

- **allI** and **exE** introduce new parameters ( $\Lambda x$ )
- **allE** and **exI** introduce new unknowns ( $?x$ )

# Safe and Unsafe Rules

**Safe:** `allI`, `exE`

**Unsafe:** `allE`, `exI`

Create parameters first, unknowns later

# Instantiating Variables in Rules

```
proof (rule_tac x = "term" in rule)
```

Like `rule`, but `?x` in `rule` is instantiated with `term` before application.  
`?x` must be schematic variable occurring in statement of `rule`.

Similar: `erule_tac`

! `x` is in *rule*, not in goal !

# Two Apply-Style Successful Proofs

```
1.  $\forall x. \exists y. x = y$   
  apply (rule allI)  
1.  $\Lambda x. \exists y. x = y$ 
```

Better practice:

```
apply (rule exI)  
1.  $\Lambda x. x = ?yx$   
  apply (rule refl)
```

$?y \mapsto \lambda u. u$

simpler & cleaner

Exploration:

```
apply(rule_tac x = "x" in exI)  
1.  $\Lambda x. x = x$   
  apply (rule refl)
```

shorter & trickier

# Successful Attempt in Isar

```
lemma shows " $\forall (x::'a). \exists y. x = y$ "  
proof (rule allI)  
  fix x::'a  
  show " $\exists y. x = y$ "  
  proof (rule exI)  
    show " $x = x$ " by (rule refl)  
  qed  
qed
```

# Two Unsuccessful Apply-Style Proof Attempts

1.  $\exists y. \forall x. x = y$

```
apply(rule_tac  
      x = ??? in exI)
```

```
apply (rule exI)  
1.  $\forall x. x = ?y$   
apply(rule allI)  
1.  $\Lambda x. x = ?y$   
apply(rule refl)  
 $?y \mapsto x$  yields  $\Lambda x'. x' = x$ 
```

Principles:  $?f\ x_1 \dots x_n$  can only be replaced by term  $t$  if  
 $params(t) \subseteq \{x_1, \dots, x_n\}$

# Parameter Names

Parameter names are chosen by Isabelle

1.  $\forall x. \exists y. x = y$

`apply(rule allI)`

1.  $\wedge x. \exists y. x = y$

`apply(rule_tac x = "x" in exI)`

Works, but is brittle!!

Better to use Isar, where you choose the name.

# Forward Proofs: frule and drule

“Forward” rule:  $A_1 \implies A$

Subgoal: 1.  $\llbracket B_1; \dots; B_n \rrbracket \implies C$

Substitution:  $\sigma(B_i) \equiv \sigma(A_1)$

New subgoal: 1.  $\sigma(\llbracket B_1; \dots; B_n; A \rrbracket \implies C)$

Command:

`apply(frule < rulename >)`

Like `frule` but also deletes  $B_i$ :

`apply(drule < rulename >)`



# frule and drule: The General Case

Rule:  $\llbracket A_1; \dots; A_m \rrbracket \Longrightarrow A$

Creates additional subgoals:

1.  $\sigma(\llbracket B_1; \dots; B_n \rrbracket \Longrightarrow A_2)$
- $\vdots$
- $m - 1$ .  $\sigma(\llbracket B_1; \dots; B_n \rrbracket \Longrightarrow A_m)$
- $m$ .  $\sigma(\llbracket B_1; \dots; B_n; A \rrbracket \Longrightarrow C)$

In Isar style, use **have**

# Forward Proofs: OF and THEN

$$r \text{ [OF } r_1 \dots r_n]$$

Prove assumption 1 of theorem  $r$  with theorem  $r_1$ , and assumption 2 with theorem  $r_2$ , etc.

$$\text{Rule } r \quad \llbracket A_1; \dots; A_m \rrbracket \implies A$$

$$\text{Rule } r_1 \quad \llbracket B_1; \dots; B_n \rrbracket \implies B$$

$$\text{Substitution} \quad \sigma(B) \equiv \sigma(A_1)$$

$$r \text{ [OF } r_1] \quad \sigma(\llbracket B_1; \dots; B_n; A_2; \dots; A_m \rrbracket \implies A)$$

$$r_1 \text{ [THEN } r_2] \quad \text{means} \quad r_2 \text{ [OF } r_1]$$

# Forward Proofs: of

Given a theorem like `gcd_mult_distrib2`:

$$?k * \text{gcd } (?m, ?n) = \text{gcd } (?k * ?m, ?k * ?n)$$

- We want to replace `?m` by 1.
- `of` instantiates variables left to right
- In above the order is `?k`, `?m`, and `?n`
- `[of k 1]` replaces `?k` by `k`, and `?m` by 1.
- `gcd_mult_distrib2 [of k 1]` yields

$$k * \text{gcd } (1, ?n) = \text{gcd } (k * 1, k * ?n)$$

# Forward Proofs: where

Alternately, with `where` you can specify the variable to get the term:

`gcd_mult_distrib2 [where m = "1"] yields`

$$?k * \text{gcd } (1, ?n) = \text{gcd } (?k * 1, ?k * ?n)$$

Same result given by `gcd_mult_distrib2 [of _ 1]`

`gcd_mult_distrib2 [where m = "1" and k = "k"] yields`

$$k * \text{gcd } (1, ?n) = \text{gcd } (k * 1, k * ?n)$$

Caution: `of` and `where` cannot use goal parameters

# Forward Proofs: lemmas

- Can use `lemmas` to capture result of forward proof:

```
lemmas gcd_mult0 = gcd_mult_distrib2 [of k 1]
```

- Can follow on with more forward reasoning:

```
lemmas gcd_mult1 = gcd_mult0 [simplified] yields  
k = gcd (k, k * ?n)
```

- `[simplified]` applies `simp` to theorem

# Forward Proofs: lemmas

Can combine multiple steps together:

```
lemmas gcd_mult =  
gcd_mult_distrib2 [of _ 1, simplified, THEN sym]  
  
yields  
  
gcd (?k, ?k * ?n) = ?k
```

# Adding Assumptions to Goals

- `cut_tac thm` insert *thm* as new assumption to current subgoal

```
lemma relprime_dvd_mult:
```

```
"[gcd(k,n) = 1; k dvd m * n]  $\implies$  k dvd m"
```

```
apply (cut_tac gcd_mult_distrib2 [of m k n])
```

yields:

```
 $[gcd(k,n) = 1; k \text{ dvd } m * n; m * gcd(k,n) = gcd(m * k, m * n)] \implies$   
 $k \text{ dvd } m$ 
```

# Adding Assumptions to Goals

**Note:** `of` and `where` can use only original user variables, but **not Isabelle generated parameters**

`cut_tac k="m" and m="k" and n="n" in gcd_mult_distrib2` yields same result as above

`cut_tac` can use parameters



# Adding Assumptions to Goals: `subgoal_tac`

- Can always add assumption *asm* to current subgoal with  
`apply (subgoal_tac "asm")`
- Statement can use Isabelle parameters
- Adds new subgoal *asm* with same assumptions as current subgoal

# Adding Assumptions to Goals: `subgoal_tac`

1.  $\llbracket A_1; \dots; A_n \rrbracket \Rightarrow A$   
`apply (subgoal_tac "asm")`

yields

1.  $\llbracket A_1; \dots; A_n; \text{asm} \rrbracket \Rightarrow A$
2.  $\llbracket A_1; \dots; A_n \rrbracket \Rightarrow \text{asm}$

# Removing Assumptions: `thin_tac`

- Can remove unwanted assumption *asm* from current subgoal with `apply (thin_tac "asm")`

1.  $\llbracket A_1; \dots; A_{i-1}; A_i; A_{i+1}; \dots; A_n \rrbracket \implies A$   
`apply (thin_tac "A_i")`

yields

1.  $\llbracket A_1; \dots; A_{i-1}; A_{i+1}; \dots; A_n; \text{asm} \rrbracket \implies A$

# “Clarifying” the Goal

- `proof (intro ... )`

Repeated application of intro rules

**Example:** `proof (intro allI)`

- `proof (elim ... )`

Repeated application of elim rules

**Example:** `proof (elim conjE)`

- `proof (clarify)`

Repeated application of safe rules without splitting goal

- `proof (clarsimp simp add: ... )`

Combination of `clarify` and `simp`

# Other Automated Proof Methods

- **blast** Isabelle's most powerful classical reasoner.  
Useful for goals stated using only predicate logic and set theory  
Can be extended with rules (with **[iff]** attribute) to handle broader classes of goals
- **auto**  
Applies to all subgoals.  
Combines classical reasoning with simplification  
Does what it can; leaves unfinished subgoals  
Splits subgoals
- **force**  
Similar to **auto**, but only applies to one goal, and either finishes or fails.
- **safe**  
Like **clarify** but also splits goals

# Demo: Proof Methods