

# Lecture 21: Lovász Local Lemma

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## 1 Lovász Local Lemma

LLL is a powerful tool in the probabilistic method and has found several highly non-trivial applications in algorithms.

In the probabilistic method we prove the existence of some object by running a probabilistic experiment and arguing that the object property holds with non-zero probability.

### 1.1 First Moment Method

We use expectation analysis. As an example, we showed that in any graph  $G = (V, E)$  there exists a max cut of value  $\frac{|E|}{2}$  by picking a random cut whose expectation is  $\frac{|E|}{2}$ .

### 1.2 Second Moment Method

Here we use variance analysis plus something like the Chebyshev bound.

**Example 1.** Let  $G(n, p)$  be a random graph on  $n$  vertices where each edge is chosen independently with probability  $p$ . At what value of  $p$  will  $G(n, p)$  have a clique of size 4?

Clearly when  $p = 0$ , the graph will be very sparse and there will not be a 4-clique. When  $p = 1$  there will be a 4-clique with high probability since the graph becomes dense.

Turns out that  $p = \frac{1}{n^3}$  is the threshold.

To see one direction we use first moment method. Let  $X$  be the number of 4-cliques.

$$\mathbb{E}[X] = \binom{n}{4} p^6$$

since if we fix a set of 4 vertices, it will be a clique iff all six edges are chosen.

If  $p \leq \frac{c}{n^3}$  for sufficiently small constant  $c$ , then  $\mathbb{E}[X] \leq 0.1$ .

For a non-negative integer random variable:

$$\Pr[X \geq 1] \leq \mathbb{E}[X]$$

So  $\Pr[X = 0] \geq 1 - \mathbb{E}[X] \geq 0.9$ .

We would like to compute the variance of  $X$ . Note that  $X = \sum_{S \in \mathcal{S}} X_S$  where  $S$  ranges over all  $\binom{n}{4}$  subsets of four vertices and  $X_S$  is an indicator for  $S$  being a clique.  $\Pr[X_S = 1] = p^6$ .

If  $S_i, S_j \in \mathcal{S}$ , then  $X_{S_i}$  and  $X_{S_j}$  are independent if  $S_i$  and  $S_j$  do not share any edges. Otherwise they are dependent.

To estimate  $\text{Var}(X)$  we write:

$$\mathbb{E}[X^2] = \mathbb{E} \left[ \left( \sum_S X_S \right)^2 \right] = \sum_S \mathbb{E}[X_S^2] + 2 \sum_{S \sim S'} \mathbb{E}[X_S \cdot X_{S'}]$$

where  $S \sim S'$  means  $S$  and  $S'$  are dependent and  $S \perp S'$  means independent.

Suppose we pretend all  $S$  and  $S'$  are independent. Then there are roughly  $n^8$  such pairs and in that case:

$$\text{Var}(X) = \sum_{S \in \mathcal{S}} \text{Var}(X_S) = n^4 p^6 (1 - p^6)$$

Then by Chebyshev:

$$\Pr[X = 0] \leq \Pr[|X - \mathbb{E}[X]| \geq \mathbb{E}[X]] \leq \frac{\text{Var}(X)}{(\mathbb{E}[X])^2} \leq \frac{n^4 p^6}{(n^4 p^6)^2} = \frac{1}{n^4 p^6}$$

One can check that if  $p \geq \frac{C}{n^{3/2}}$  for sufficiently large  $C$ , then  $\Pr[X = 0] \leq 0.1$ .

However,  $X_S$  and  $X_{S'}$  are not independent for all  $S_i$  and  $S_j \in \mathcal{S}$ . But if we calculate  $\text{Var}(X)$  more carefully we see that:

$$\begin{aligned} \mathbb{E}[X^2] &= \sum_{S_i \in \mathcal{S}} \mathbb{E}[X_{S_i}^2] + \sum_{S_i \sim S_j} \mathbb{E}[X_{S_i} X_{S_j}] \\ &= \sum_{S \in \mathcal{S}} \mathbb{E}[X_S] + \sum_{S \perp S'} \mathbb{E}[X_S] \mathbb{E}[X_{S'}] \end{aligned}$$

There are  $\binom{n}{4}^2 = O(n^8)$  total pairs. How many are not independent?  $S \sim S'$  if they share at least one edge. But the number of dependent pairs is  $O(n^7)$  while the number of independent pairs is  $\Theta(n^8)$ , which is close to all pairs. So  $\text{Var}(X)$  still behaves as if not all pairs are independent and one can show that  $p \geq \frac{C}{n^{3/2}}$  for sufficiently large constant ensures  $G(n, p)$  has a 4-clique with probability  $\geq 0.9$ .

### 1.3 Concentration plus Union Bound

We saw several examples of using concentration bounds plus union bound. The general strategy is to show that for some events  $A_1, A_2, \dots, A_n$ :

$$\Pr[A_i] \leq \frac{1}{n}$$

where  $A_i$  is a bad event.

Then by the union bound:

$$\Pr[A_1 \cup A_2 \cup \dots \cup A_n] \leq n \cdot \frac{1}{n} = 1$$

$$\Pr[\overline{A_1} \cap \overline{A_2} \cap \dots \cap \overline{A_n}] > 0$$

Thus we have all good events happening with non-zero probability, and if we can express the property we want in those terms then we are done.

**Example 2** (Routing paths). We saw that we can convert fractional solution to integral solution by randomized rounding. We get  $O(\log n / \log \log n)$  congestion by using Chernoff bounds on each single edge and then union bound over all edges.

## 1.4 Local Phenomena

There are many situations where we cannot use union bound because the individual bad event probability is not that small.

If  $A_i$  are independent this does not matter because we have:

$$\Pr[\overline{A_1} \cap \overline{A_2} \cap \dots \cap \overline{A_n}] = \prod_{i=1}^n (1 - \Pr[A_i])$$

and hence all we need is  $\Pr[A_i] < 1$ .

However, independence is rarely possible in complex events.

LLL considers a local setting where the events  $A_1, \dots, A_n$  are not completely independent but there is some limited dependence.

How can one capture such a scenario? For that we use a **dependency graph** on the events. The vertices are the events and we have an edge  $(A_i, A_j)$  if  $A_i$  and  $A_j$  are dependent. No edge means that  $A_i$  and  $A_j$  are conditionally independent. That is,  $\Pr[A_i \mid A_j] = \Pr[A_i]$ .

Note that  $A_i$  is conditionally independent of all events that it has no edges to. We define it formally:

**Definition 1.** An event  $A$  is conditionally independent with respect to  $B_1, B_2, \dots, B_k$  if:

$$\forall S \subseteq \{1, 2, \dots, k\} : \Pr \left[ A \mid \bigcap_{i \in S} B_i \right] = \Pr[A]$$

**When can we easily identify conditional independence?**

**Claim 1.** Suppose  $X_1, X_2, \dots, X_n$  are independent random variables. Suppose event  $A_i$  is completely determined by a subset  $S_i \subseteq \{X_1, X_2, \dots, X_n\}$ . If  $S_i \cap S_j = \emptyset$  for  $j \in \{j_1, j_2, \dots, j_k\}$  then  $A_i$  is mutually independent of  $A_{j_1}, A_{j_2}, \dots, A_{j_k}$ .

With this in place we state the Symmetric version of the LLL:

**Theorem 1** (Symmetric LLL). Suppose  $A_1, A_2, \dots, A_n$  are events in an underlying probability space and let  $d$  be the max degree of the dependency graph and  $\Pr[A_i] \leq p$  for all  $i$ . Then if  $ep(d+1) \leq 1$ , i.e., if  $pd \leq \frac{1}{e}$ , then:

$$\Pr \left[ \bigcap_{i=1}^n \overline{A_i} \right] \geq (1 - 2p)^n > 0$$

so in particular if  $pd \leq \frac{1}{e}$  then  $\Pr[\bigcap_i \overline{A_i}] > 0$ .

A more general version of the LLL called asymmetric or lopsided LLL is the following:

**Theorem 2** (LLL). Suppose  $A_1, \dots, A_n$  are events in a probability space and let  $H$  be the dependency graph. Suppose there exist numbers  $x_1, x_2, \dots, x_n \in (0, 1)$  such that:

$$\Pr[A_i] \leq x_i \prod_{j \in N(i)} (1 - x_j)$$

Then:

$$\Pr \left[ \bigcap_i \overline{A_i} \right] \geq \prod_{i=1}^n (1 - x_i)$$

Here  $N(i)$  is the set of dependent neighbors of  $A_i$ .

## 1.5 Proof of Symmetric Version

The heart of the proof is the following lemma:

**Lemma 1.** *For any  $S \subseteq \{1, 2, \dots, n\}$  and  $i \notin S$ :*

$$\Pr \left[ A_i \mid \bigcap_{j \in S} \overline{A_j} \right] \leq 2p$$

Assuming the lemma above, the symmetric LLL follows as below:

$$\begin{aligned} \Pr[\overline{A_1} \cap \overline{A_2} \cap \dots \cap \overline{A_n}] &= \Pr[\overline{A_1}] \cdot \Pr[\overline{A_2} \mid \overline{A_1}] \cdot \Pr[\overline{A_3} \mid \overline{A_1} \cap \overline{A_2}] \dots \\ &\quad \cdot \Pr[\overline{A_n} \mid \overline{A_1} \cap \overline{A_2} \cap \dots \cap \overline{A_{n-1}}] \\ &= (1 - \Pr[A_1]) \cdot (1 - \Pr[A_2 \mid \overline{A_1}]) \\ &\quad \cdot (1 - \Pr[A_3 \mid \overline{A_1} \cap \overline{A_2}]) \dots \\ &\geq (1 - 2p)^n > 0 \end{aligned}$$

Now we prove the lemma by induction on  $|S|$ .

Suppose  $|S| = 0$ . Then  $\Pr[A_i] \leq p \leq 2p$ .

Assume true for  $|S| = k$ . Consider  $|S| = k + 1$ ,  $i \notin S$ . Want to prove  $\Pr[A_i \mid \bigcap_{j \in S} \overline{A_j}] \leq 2p$ .

Let  $S_{dep} = S \cap N(i)$  be the set of events in  $S$  that  $A_i$  is dependent on, and  $S_{ind} = S \setminus S_{dep}$ . Thus  $S = S_{dep} \cup S_{ind}$ .

If  $|S_{ind}| = k + 1$  then  $S_{dep} = \emptyset$  and:

$$\Pr[A_i \mid \bigcap_{j \in S} \overline{A_j}] = \Pr[A_i] \leq p \leq 2p$$

Thus we now consider  $|S_{ind}| \leq k$ .

We now use conditional probability or Bayes theorem. For events  $X, Y$ :

$$\Pr[X \mid Y] = \frac{\Pr[X \cap Y]}{\Pr[Y]}$$

and for events  $X, Y, Z$ :

$$\Pr[X \mid Y \cap Z] = \frac{\Pr[X \cap Y \mid Z]}{\Pr[Y \mid Z]}$$

Applying with  $X = A_i$ ,  $Y = \bigcap_{j \in S_{dep}} \overline{A_j}$  and  $Z = \bigcap_{j \in S_{ind}} \overline{A_j}$ , we have:

$$\Pr \left[ A_i \mid \bigcap_{j \in S} \overline{A_j} \right] = \frac{\Pr \left[ A_i \cap \left( \bigcap_{j \in S_{dep}} \overline{A_j} \right) \mid \bigcap_{j \in S_{ind}} \overline{A_j} \right]}{\Pr \left[ \bigcap_{j \in S_{dep}} \overline{A_j} \mid \bigcap_{j \in S_{ind}} \overline{A_j} \right]}$$

Consider denominator. Via union bound:

$$\begin{aligned} \Pr \left[ \bigcap_{j \in S_{dep}} \overline{A_j} \mid \bigcap_{j \in S_{ind}} \overline{A_j} \right] &= 1 - \Pr \left[ \bigcup_{j \in S_{dep}} A_j \mid \bigcap_{j \in S_{ind}} \overline{A_j} \right] \\ &\geq 1 - \sum_{j \in S_{dep}} \Pr \left[ A_j \mid \bigcap_{j \in S_{ind}} \overline{A_j} \right] \end{aligned}$$

By induction hypothesis, since  $|S_{ind}| \leq k$ :

$$\Pr \left[ A_j \mid \bigcap_{\ell \in S_{ind}} \overline{A_\ell} \right] \leq 2p$$

and  $|S_{dep}| \leq d$ .

Hence:

$$\Pr \left[ \bigcup_{j \in S_{dep}} A_j \mid \bigcap_{j \in S_{ind}} \overline{A_j} \right] \geq 1 - 2pd$$

Numerator is:

$$\begin{aligned} \Pr \left[ A_i \cap \left( \bigcap_{j \in S_{dep}} \overline{A_j} \right) \mid \bigcap_{j \in S_{ind}} \overline{A_j} \right] &\leq \Pr \left[ A_i \mid \bigcap_{j \in S_{ind}} \overline{A_j} \right] \\ &= \Pr[A_i] \leq p \end{aligned}$$

Hence:

$$\Pr \left[ A_i \mid \bigcap_{j \in S} \overline{A_j} \right] \leq \frac{p}{1 - 2pd} \leq 2p$$

## 2 Application of LLL

### 2.1 k-SAT

Recall that a  $k$ -SAT formula is a Boolean formula in CNF form with each clause having exactly  $k$  literals over distinct variables.

**Theorem 3.** *Let  $\Phi$  be a  $k$ -SAT formula in which each variable occurs in at most  $\frac{2^k}{k}$  clauses. Then  $\Phi$  is satisfiable.*

Note that there is no limitation on number of variables or clauses.

**Example 3.** If  $k = 10$  then it is requiring each variable to be in at most  $\frac{2^{10}}{10} \approx 102$  clauses.

The theorem may not be interesting from a SAT perspective but is mainly to showcase the power of LLL and a setting in which it applies.

We prove this by considering a random assignment to the variables. Let  $A_i$  be the event that a clause  $C_i$  is not satisfiable (bad event), then  $\Pr[A_i] = \frac{1}{2^k}$ .

What does  $A_i$  depend on?  $C_i$  has  $k$  variables. Each variable that is in  $C_i$  is in at most  $\frac{2^k}{k} - 1$  other clauses. So  $C_i$  shares a variable with at most  $k \cdot \left( \frac{2^k}{k} - 1 \right) = 2^k - k$  other clauses.

If  $C_i$  and  $C_j$  do not share variables then  $A_i$  and  $A_j$  are mutually independent.

Thus we can apply symmetric LLL with  $p = \frac{1}{2^k}$  and  $d = 2^k - k$ .

Since  $pd = \frac{2^k - k}{2^k} < \frac{1}{e}$ :

$$\Pr \left[ \bigcap_i \overline{A_i} \right] > 0$$

where  $m$  is the number of clauses.

Therefore  $\Pr[\Phi \text{ is satisfiable}] > 0$ .

## 2.2 Routing for Congestion Minimization

Recall that we saw the congestion minimization problem:

- $G = (V, E)$  directed graph
- $(s_1, t_1), \dots, (s_k, t_k)$ :  $k$  pairs that we want to connect by paths  $P_1, P_2, \dots, P_k$
- Minimize  $\max_{e \in E} |\{i : e \in P_i\}|$  (congestion on  $e$ )

We used an LP relaxation and found a fractional routing that minimizes max fractional congestion.

A fractional routing for a pair  $(s_i, t_i)$  is a probability distribution over paths  $p \in \mathcal{P}_i$  where  $\mathcal{P}_i$  is the set of all  $s_i$ - $t_i$  paths. We let  $x_p$ ,  $p \in \mathcal{P}$ , be the amount of flow routed along  $p$ . We have  $\sum_{p \in \mathcal{P}_i} x_p = 1$ .

Suppose:

$$\sum_{i: p \in \mathcal{P}_i} \sum_{p \in \mathcal{P}_i: e \in p} x_p \leq 1$$

i.e., the max fractional congestion is at most 1.

Randomized rounding picks a path for each  $i$  independently according to the distribution  $\{x_p : p \in \mathcal{P}_i\}$ .

Then we used Chernoff bounds to show that  $\Pr[\ell_e \geq c \log m]$  is at most  $\frac{1}{m^2}$  for some sufficiently large constant  $c$ . Here  $\ell_e$  is the load on  $e$  (the number of paths that use  $e$ ).

Then via the union bound we see that with high probability  $\max_{e \in E} \ell_e = O(\log m)$ .

### 2.2.1 Better bound when paths are short

Now we will prove a better bound when paths are short.

Suppose  $x_p = 0$  or  $|p| \leq h$  where  $h$  is some parameter. In many applications  $h$  is a small constant independent of  $m, n$ . This implies locality because even if the graph is large, paths along which flow is routed are short.

**Theorem 4.** *There exists an integral routing where max congestion is  $O(h \log h)$ .*

Note: the bound does not depend on graph size.

In order to apply LLL we do some preprocessing. By discretization tricks we will assume that all  $x_p$  values that are non-zero have same value  $\frac{1}{L}$  for some  $L$ . We may duplicate paths to achieve this. Thus each pair now has exactly  $L$  paths.

Then we do randomized rounding as before but with the discretized paths. So we pick one of the  $L$  paths for each pair.

**How can we apply LLL here?** Need to set up the events carefully.

Let  $C$  be the threshold of congestion we want to avoid. For edge  $e$ , let  $S_e$  be the set of all paths that use  $e$ .

Define  $A_{e,S}$  for  $e \in E$ ,  $S \subseteq S_e$ ,  $|S| = C$  to be the event that  $S$  is the set of paths chosen.

**Claim 2.** *If  $S$  contains two paths from path collection of same pair, then  $\Pr[A_{e,S}] = 0$ . Otherwise it is equal to  $\frac{1}{L^C}$ .*

We use notation  $S = \{(i_1, j_1), (i_2, j_2), \dots, (i_C, j_C)\}$  where  $i_\ell \in \{1, 2, \dots, K\}$  indicates the pair and  $j_\ell \in \{1, 2, \dots, L\}$  to denote the index of the path in the  $L$  paths for the pair. We order the paths in some fashion for each pair. We let  $P_i^j$  denote the  $j$ -th path for pair  $i$ .

**Dependencies:** Fix two events  $A_{e,S}$  and  $A_{e',S'}$  where  $S$  has paths from distinct pairs and similarly  $S'$ .

Suppose  $S = \{(i_1, j_1), (i_2, j_2), \dots, (i_C, j_C)\}$  and  $S' = \{(i'_1, j'_1), (i'_2, j'_2), \dots, (i'_C, j'_C)\}$ .

If  $\{i_1, i_2, \dots, i_C\} \cap \{i'_1, i'_2, \dots, i'_C\} = \emptyset$ , i.e., the pairs don't overlap, then  $A_{e,S}$  is independent of  $A_{e',S'}$ .

We need to understand how many other events does  $A_{e,S}$  depend on. Suppose  $e' \in E$ ,  $S' \subseteq S_{e'}$ , and  $|S'| = C$  with  $\{i_1, i_2, \dots, i_C\} \cap \{i'_1, i'_2, \dots, i'_C\} \neq \emptyset$ . Say  $i_1 = i'_1$ .

How many choices of  $e'$ ,  $\{i'_2, \dots, i'_C\}$  and  $\{j'_1, j'_2, \dots, j'_C\}$  do we have?

$L$  choices for  $j'_1$ . Fix one such  $j'_1$ .

Then we have path  $P_{i_1}^{j'_1}$  and this path has at most  $h$  edges.

So  $e'$  has  $h$  choices. For each such edge, at most  $L$  paths use the edge (since total flow on each edge  $\leq 1$ ). And we can choose any  $C - 1$  paths from those  $L$ .

Thus for fixed choice of  $j'_1$  there are  $h \cdot \binom{L}{C-1}$  choices.

Hence total is  $L \cdot h \cdot \binom{L}{C-1}$ .

There are  $C$  choices of pair overlap between  $S$  and  $S'$ .

Hence the neighborhood size of  $A_{e,S}$  in the dependency graph is at most  $C \cdot L \cdot h \cdot \binom{L}{C-1}$ .

To apply LLL we have  $\Pr[A_{e,S}] = \frac{1}{L^C} = p$  and  $d = C \cdot L \cdot h \cdot \binom{L}{C-1}$ .

To ensure  $pd \leq \frac{1}{e}$  we need:

$$\frac{1}{L^C} \cdot C \cdot L \cdot h \cdot \binom{L}{C-1} \leq \frac{1}{e}$$

It suffices to have  $C = O(h \log h)$ .

Note that if no bad event  $A_{e,S}$  happens, then congestion is at most  $C - 1$ .