# CS 498ABD: Algorithms for Big Data

# Applications of CountMin and Count Sketches

Lecture 10 September 22, 2022

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### CountMin Sketch

```
\begin{aligned} & \textbf{CountMin-Sketch}(w,d) \colon \\ & \textbf{$h_1,h_2,\dots,h_d$} \text{ are pair-wise independent hash functions} \\ & \text{from } [\textbf{$n$}] \rightarrow [\textbf{$w$}] . \\ & \text{While (stream is not empty) do} \\ & \textbf{$e_t = (i_t,\Delta_t)$ is current item} \\ & \text{for } \ell = 1 \text{ to } \textbf{$d$ do} \\ & \textbf{$C[\ell,h_\ell(i_j)]} \leftarrow \textbf{$C[\ell,h_\ell(i_j)]} + \Delta_t$ \\ & \text{endWhile} \\ & \text{For } \textbf{$i \in [n]$ set $\tilde{x_i} = \min_{\ell=1}^d \textbf{$C[\ell,h_\ell(i)]$}.} \end{aligned}
```

Counter  $C[\ell, j]$  simply counts the sum of all  $x_i$  such that  $h_{\ell}(i) = j$ . That is.

$$C[\ell,j] = \sum_{i:h_{\ell}(i)=j} x_i.$$

# **Summarizing**

#### Lemma

Let  $d = \Omega(\log \frac{1}{\delta})$  and  $w > \frac{2}{\epsilon}$ . Then for any fixed  $i \in [n]$ ,  $x_i \leq \tilde{x}_i$  and

$$\Pr[\tilde{x}_i \geq x_i + \epsilon ||x||_1] \leq \delta.$$

#### **Corollary**

With  $d = \Omega(\ln n)$  and  $w = 2/\epsilon$ , with probability  $(1 - \frac{1}{n})$  for all  $i \in [n]$ :

$$\tilde{x}_i \leq x_i + \epsilon ||x||_1$$
.

Total space:  $O(\frac{1}{\epsilon} \log n)$  counters and hence  $O(\frac{1}{\epsilon} \log n \log m)$  bits.

### **Count Sketch**

```
Count-Sketch(w, d):
      h_1, h_2, \dots, h_d are pair-wise independent hash functions
            from [n] \rightarrow [w].
      g_1, g_2, \dots, g_d are pair-wise independent hash functions
             from [n] \to \{-1, 1\}.
      While (stream is not empty) do
             e_t = (i_t, \Delta_t) is current item
            for \ell = 1 to d do
                   C[\ell, h_{\ell}(i_i)] \leftarrow C[\ell, h_{\ell}(i_i)] + g(i_t)\Delta_t
      endWhile
      For i \in [n]
             set \tilde{\mathbf{x}}_i = \text{median}\{\mathbf{g}_1(i)\mathbf{C}[1,\mathbf{h}_1(i)],\ldots,\mathbf{g}_{\ell}(i)\mathbf{C}[\ell,\mathbf{h}_{\ell}(i)]\}.
```

# Summarizing

#### Lemma

Let  $d \ge 4 \log \frac{1}{\delta}$  and  $w > \frac{3}{\epsilon^2}$ . Then for any fixed  $i \in [n]$ ,  $E[\tilde{x}_i] = x_i$  and  $Pr[|\tilde{x}_i - x_i| \ge \epsilon ||x||_2] \le \delta$ .

#### **Corollary**

With  $\mathbf{d} = \Omega(\ln \mathbf{n})$  and  $\mathbf{w} = 3/\epsilon^2$ , with probability  $(1 - \frac{1}{\mathbf{n}})$  for all  $\mathbf{i} \in [\mathbf{n}]$ :

$$|\tilde{x}_i - x_i| \leq \epsilon ||x||_2.$$

Total space  $O(\frac{1}{\epsilon^2} \log n)$  counters and hence  $O(\frac{1}{\epsilon^2} \log n \log m)$  bits.

# Part I

# **Applications**

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**Heavy Hitters Problem:** Find all items i such that  $x_i > \alpha ||x||_1$  for some fixed  $\alpha \in (0, 1]$ .

Approximate version: output any i such that  $x_i \geq (\alpha - \epsilon) \|x\|_1$ 

The sketches give us a data structure such that for any  $i \in [n]$  we get an estimate  $\tilde{x}_i$  of  $x_i$  with additive error.

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Go over each *i* and check if  $\tilde{x}_i > (\alpha - \epsilon) ||x||_1$ .

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Additional data structures to speed up above computation and reduce time/space to be proportional to  $O(\frac{1}{\alpha} \operatorname{polylog}(n))$ . More tricky for Count Sketch. See notes and references

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Range query: given  $i, j \in [n]$  want to know  $\sum_{i \le \ell \le i} x[i, j]$ 

#### Examples:

- [n] corresponds to IP address space in network routing and [i, i] corresponds to addresses in a range
- [n] corresponds to some numerical attribute in a database and we want to know number of records within a range
- [n] corresponds to the discretization of a signal value

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Want to create a sketch data structure that can answer range queries for any given range that is chosen *after* the sketch is done.  $\Omega(n^2)$  potential queries

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**Simple idea:** imagine a binary tree over [n] and any interval [i,j] can be broken up into  $O(\log n)$  disjoint "dyadic" intervals

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Create one sketch data structure per level of binary tree

Output estimate  $\tilde{x}[i,j]$  by adding estimates for  $O(\log n)$  dyadic intervals that [i,j] decomposes into

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Create one sketch data structure per level of binary tree

Output estimate  $\tilde{x}[i,j]$  by adding estimates for  $O(\log n)$  dyadic intervals that [i,j] decomposes into

To manage error choose  $\epsilon' = \epsilon/\log n$ : total space is  $O(\alpha \log n/\epsilon)$  where  $\alpha$  is the space for single level sketch

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### Part II

# **Sparse Recovery**

### **Sparse Recovery**

**Sparsity** is an important theme in optimization/algorithms/modeling

- Data is often *explicitly* sparse. Examples: graphs, matrices, vectors, documents (as word vectors)
- Data is often *implicitly* sparse in a different representation the data is explicitly sparse. Examples: signals/images, topics, etc

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# **Sparse Recovery**

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### **Algorithmic goals**

- Take advantage of sparsity to improve performance (speed, quality, memory etc)
- Find implicit sparse representation to reveal information about data. Example: topics in documents, frequencies in Fourier analysis

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# **Sparse Recovery**

**Problem:** Given vector/signal  $x \in \mathbb{R}^n$  find a sparse vector z such that z approximates x

More concretely: given x and integer  $k \ge 1$ , find z such that z has at most k non-zeroes  $(\|z\|_0 \le k)$  such that  $\|x - z\|_p$  is minimized for some  $p \ge 1$ .

**Optimum offline solution:** z picks the largest k coordinates of x (in absolute value)

Want to do it in streaming setting: turnstile streams and p=2 and want to use  $\tilde{O}(k)$  space proportional to output

# Sparse Recovery under $\ell_2$ norm

Formal objective function:

$$\operatorname{err}_{2}^{k}(x) = \min_{z:||z||_{0} \leq k} ||x - z||_{2}$$

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# Sparse Recovery under $\ell_2$ norm

Formal objective function:

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 $\operatorname{err}_2^{\pmb{k}}(\pmb{x})$  is interesting only when it is small compared to  $\|\pmb{x}\|_2$ 

For instance when x is uniform, say  $x_i = 1$  for all i then  $||x||_2 = \sqrt{n}$  but  $\operatorname{err}_2^k(x) = \sqrt{n-k}$ 

 $\operatorname{err}_2^{\mathbf{k}}(\mathbf{x}) = 0$  iff  $\|\mathbf{x}\|_0 \leq \mathbf{k}$  and hence related to distinct element detection

# Sparse Recovery under $\ell_2$ norm

#### **Theorem**

There is a linear sketch with size  $O(\frac{k}{\epsilon^2} polylog(n))$  that returns z such that  $||z||_0 \le k$  and with high probability  $||x-z||_2 \le (1+\epsilon) err_2^k(x)$ .

Hence space is proportional to desired output. Assumption k is typically quite small compared to n, the dimension of x.

Note that if x is k-sparse vector is exactly reconstructed

Based on CountSketch

# **Algorithm**

- Use Count Sketch with  $w = 3k/\epsilon^2$  and  $d = \Omega(\log n)$ .
- Count Sketch gives estimages  $\tilde{x_i}$  for each  $i \in n$
- Output the **k** coordinates with the largest estimates

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### Intuition for analysis

- With  $w = ck/\epsilon^2$  the k biggest coordinates will be spread out in their own buckets
- rest of small coordinates will be spread out evenly
- refine the analysis of Count-Sketch to carefully analyze the two scenarios

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# **Analysis Outline**

#### Lemma

Count-Sketch with  $\mathbf{w} = 3\mathbf{k}/\epsilon^2$  and  $\mathbf{d} = \mathbf{O}(\log \mathbf{n})$  ensures that

$$\forall i \in [n], \quad |\tilde{x}_i - x_i| \leq \frac{\epsilon}{\sqrt{k}} err_2^k(x)$$

with high probability (at least (1 - 1/n)).

#### Lemma

Let  $x, y \in \mathbb{R}^n$  such that  $||x - y||_{\infty} \leq \frac{\epsilon}{\sqrt{k}} err_2^k(x)$ . Then,  $||x - z||_2 \leq (1 + 5\epsilon) err_2^k(x)$ , where z is the vector obtained as follows:  $z_i = y_i$  for  $i \in T$  where T is the set of k largest (in absolute value) indices of y and  $z_i = 0$  for  $i \notin T$ .

Lemmas combined prove the correctness of algorithm.

### **Count Sketch**

```
Count-Sketch(w, d):
      h_1, h_2, \dots, h_d are pair-wise independent hash functions
            from [n] \rightarrow [w].
      g_1, g_2, \dots, g_d are pair-wise independent hash functions
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      While (stream is not empty) do
            e_t = (i_t, \Delta_t) is current item
            for \ell = 1 to d do
                   C[\ell, h_{\ell}(i_i)] \leftarrow C[\ell, h_{\ell}(i_i)] + g(i_t)\Delta_t
      endWhile
      For i \in [n]
            set \tilde{\mathbf{x}}_i = \text{median}\{\mathbf{g}_1(i)\mathbf{C}[1,\mathbf{h}_1(i)],\ldots,\mathbf{g}_d(i)\mathbf{C}[\mathbf{d},\mathbf{h}_d(i)]\}.
```

# **Recap of Analysis**

Fix an  $i \in [n]$ . Let  $Z_{\ell} = g_{\ell}(i)C[\ell,h_{\ell}(i)]$ .

For  $i' \in [n]$  let  $Y_{i'}$  be the indicator random variable that is 1 if  $h_{\ell}(i) = h_{\ell}(i')$ ; that is i and i' collide in  $h_{\ell}$ .  $E[Y_{i'}] = E[Y_{i'}^2] = 1/w$  from pairwise independence of  $h_{\ell}$ .

$$Z_\ell = g_\ell(i)C[\ell,h_\ell(i)] = g_\ell(i)\sum_{i'}g_\ell(i')x_{i'}Y_{i'}$$

Therefore,

$$m{E}[m{Z}_\ell] = m{x}_i + \sum_{i' 
eq i} m{E}[m{g}_\ell(i)m{g}_\ell(i')m{Y}_{i'}]m{x}_{i'} = m{x}_i,$$

because  $E[g_{\ell}(i)g_{\ell}(i')] = 0$  for  $i \neq i'$  from pairwise independence of  $g_{\ell}$  and  $Y_{i'}$  is independent of  $g_{\ell}(i)$  and  $g_{\ell}(i')$ .

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# **Recap of Analysis**

$$Z_{\ell} = g_{\ell}(i)C[\ell, h_{\ell}(i)]$$
. And  $E[Z_{\ell}] = x_i$ .

$$\begin{aligned} Var(Z_{\ell}) &= \mathbb{E} \big[ (Z_{\ell} - x_{i})^{2} \big] \\ &= \mathbb{E} \left[ (\sum_{i' \neq i} g_{\ell}(i) g_{\ell}(i') Y_{i'} x_{i'})^{2} \right] \\ &= \mathbb{E} \left[ \sum_{i' \neq i} x_{i'}^{2} Y_{i'}^{2} + \sum_{i' \neq i''} x_{i'} x_{i''} g_{\ell}(i') g_{\ell}(i'') Y_{i'} Y_{i''} x_{i''} x_{i''} \right] \\ &= \sum_{i' \neq i} x_{i'}^{2} \mathbb{E} \big[ Y_{i'}^{2} \big] \\ &\leq \|x\|_{2}^{2} / w. \end{aligned}$$

# **Refining Analysis**

 $T_{\text{big}} = \{i' \mid i' \text{ is one of the } k \text{ biggest coordinates in } x\}$ 

$$T_{\mathsf{small}} = [n] \setminus T$$

$$\sum_{i' \in T_{\text{small}}} x_{i'}^2 = (\text{err}_2^k(x))^2$$

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$$\sum_{i' \in T_{\text{small}}} x_{i'}^2 = (\operatorname{err}_2^k(x))^2$$

What is 
$$\Pr\left[|Z_{\ell} - x_i| \ge \frac{\epsilon}{\sqrt{k}} \operatorname{err}_2^k(x)\right]$$
?

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What is 
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#### Lemma

$$\Pr\left[|Z_{\ell}-x_{i}| \geq \frac{\epsilon}{\sqrt{k}}err_{2}^{k}(x)\right] \leq 2/5.$$

$$Z_{\ell} = g_{\ell}(i)C[\ell,h_{\ell}(i)].$$

Let  $A_\ell$  be event that  $h_\ell(i') = h_\ell(i)$  for some  $i' \in \mathcal{T}_{\text{big}}, i' \neq i$ 

#### Lemma

 $\Pr[\mathbf{A}_{\ell}] \leq \epsilon^2/3$ . In other words with  $1 - \epsilon^2/3$  probability no big coordinates collide with  $\mathbf{i}$  under  $\mathbf{h}_{\ell}$ .

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- $Y_{i'}$  indicator for  $i' \neq i$  colliding with i.  $\Pr[Y_{i'}] \leq 1/w \leq \epsilon^2/(3k)$ .
- Let  $Y = \sum_{i' \in T_{\text{hig}}} Y_{i'}$ .  $E[Y] \le \epsilon^2/3$  by linearity of expectation.
- Hence  $\Pr[\mathbf{A}_{\ell}] = \Pr[\mathbf{Y} \geq 1] \leq \epsilon^2/3$  by Markov

$$\begin{array}{l} Z_{\ell} = g_{\ell}(i)C[\ell,h_{\ell}(i)] \\ = x_{i} + \sum_{i' \in T_{\text{big}}} g_{\ell}(i)g_{\ell}(i')Y_{i'}x_{i'} + \sum_{i' \in T_{\text{small}}} g_{\ell}(i)g_{\ell}(i')Y_{i'}x_{i'} \end{array}$$

Let 
$$Z'_\ell = \sum_{i' \in \mathcal{T}_{\mathsf{small}}} g_\ell(i) g_\ell(i') Y_{i'}$$

#### Lemma

$$\Pr\left[|Z'_{\ell}| \geq \frac{\epsilon}{\sqrt{k}} err_2^k(x)\right] \leq 1/3.$$

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#### Lemma

$$\Pr\Big[|Z'_\ell| \geq \frac{\epsilon}{\sqrt{k}} err_2^k(x)\Big] \leq 1/3.$$

- $E[Z'_{\ell}] = 0$
- $Var(Z'_{\ell}) \leq \mathbb{E}[(Z'_{\ell})^2] = \sum_{i' \in T_{\text{small}}} x_{i'}^2 / w \leq \frac{\epsilon^2}{3k} (\text{err}_2^k(x))^2$
- By Cheybyshev  $\Pr\left[|Z'_{\ell}| \geq \frac{\epsilon}{\sqrt{k}} \operatorname{err}_2^k(x)\right] \leq 1/3.$

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Want to show:

### Lemma

$$\Pr\Big[|Z_{\ell}-x_i|\geq \frac{\epsilon}{\sqrt{k}}err_2^k(x)\Big]\leq 2/5.$$

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$$\Pr\left[|Z_{\ell}-x_{i}| \geq \frac{\epsilon}{\sqrt{k}}err_{2}^{k}(x)\right] \leq 2/5.$$

We have 
$$Z_{\ell} = g_{\ell}(i)C[\ell, h_{\ell}(i)]$$
  
=  $x_i + \sum_{i' \in T_{\text{big}}} g_{\ell}(i)g_{\ell}(i')Y_{i'}x_{i'} + \sum_{i' \in T_{\text{small}}} g_{\ell}(i)g_{\ell}(i')Y_{i'}x_{i'}$ 

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We saw:

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 $\Pr[\mathbf{A}_{\ell}] \leq \epsilon^2/3$ . In other words with  $1 - \epsilon^2/3$  probability no big coordinates collide with  $\mathbf{i}$  under  $\mathbf{h}_{\ell}$ .

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$$|Z_{\ell} - x_i| \ge \frac{\epsilon}{\sqrt{k}} \operatorname{err}_2^k(x)$$
 implies

- ullet  $A_\ell$  happens (that is some big coordinate collides with i in  $h_\ell$  or
- $|Z'_{\ell}| \geq \frac{\epsilon}{\sqrt{k}} \operatorname{err}_2^k(x)$

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Therefore, by union bound,

$$\Pr\left[|\mathbf{Z}_{\ell} - \mathbf{x}_{i}| \geq \frac{\epsilon}{\sqrt{k}} \operatorname{err}_{2}^{k}(\mathbf{x})\right] \leq \epsilon^{2}/3 + 1/3 \leq 2/5$$
 if  $\epsilon$  is sufficiently small.

# High probability estimate

### Lemma

$$\Pr\Big[|Z_{\ell}-x_{i}|\geq \frac{\epsilon}{\sqrt{k}}err_{2}^{k}(x)\Big]\leq 2/5.$$

Recall  $\tilde{x}_i = \text{median}\{g_1(i)C[1,h_1(i)],\ldots,g_d(i)C[d,h_d(i)]\}.$ 

- Hence by Chernoff bounds with  $d = \Omega(\log n)$ ,  $\Pr\left[|\tilde{x}_i x_i| \ge \frac{\epsilon}{\sqrt{k}} \operatorname{err}_2^k(x)\right] \le 1/n^2$
- By union bound, with probability at least (1-1/n),  $|\tilde{x}_i x_i| \leq \frac{\epsilon}{\sqrt{k}} \operatorname{err}_2^k(x)$  for all  $i \in [n]$ .

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### Lemma

Count-Sketch with  $\mathbf{w} = 3\mathbf{k}/\epsilon^2$  and  $\mathbf{d} = \mathbf{O}(\log \mathbf{n})$  ensures that  $\forall \mathbf{i} \in [\mathbf{n}], \quad |\tilde{\mathbf{x}}_{\mathbf{i}} - \mathbf{x}_{\mathbf{i}}| \leq \frac{\epsilon}{\sqrt{\mathbf{k}}} err_2^{\mathbf{k}}(\mathbf{x})$  with high probability (at least  $(1 - 1/\mathbf{n})$ ).

### Second lemma of outline

### Lemma

Let  $x, y \in \mathbb{R}^n$  such that  $||x - y||_{\infty} \leq \frac{\epsilon}{\sqrt{k}} err_2^k(x)$ . Then,  $||x - z||_2 \leq (1 + 5\epsilon) err_2^k(x)$ , where z is the vector obtained as follows:  $z_i = y_i$  for  $i \in T$  where T is the set of k largest (in absolute value) indices of y and  $z_i = 0$  for  $i \notin T$ .

### What the lemma is saying:

- $\bullet$   $\tilde{x}$  the estimated vector of Count-Sketch approximates x very closely in each coordinate
- Algorithm picks the top k coordinates of  $\tilde{x}$  to create z
- Then z approximates x well

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What the lemma is saying:

- $m{\tilde{x}}$  the estimated vector of Count-Sketch approximates  $m{x}$  very closely in each coordinate
- ullet Algorithm picks the top k coordinates of ilde x to create z
- Then z approximates x well

Proof is basically follows the intuition of triangle inequality

### Proof of lemma

**S** (previously  $T_{\text{big}}$ ) is set of **k** biggest coordinates in **x T** is the set of **k** biggest coordinates in  $\mathbf{y} = \tilde{\mathbf{x}}$ Let  $E = \frac{1}{\sqrt{k}} \operatorname{err}_2^k(x)$  for ease of notation.

$$(\operatorname{err}_2^{\mathbf{k}}(\mathbf{x}))^2 = \mathbf{k}\mathbf{E}^2 = \sum_{\mathbf{i} \in [\mathbf{n}] \setminus \mathbf{S}} \mathbf{x}_{\mathbf{i}}^2 = \sum_{\mathbf{i} \in \mathbf{T} \setminus \mathbf{S}} \mathbf{x}_{\mathbf{i}}^2 + \sum_{\mathbf{i} \in [\mathbf{n}] \setminus (\mathbf{S} \cup \mathbf{T})} \mathbf{x}_{\mathbf{i}}^2.$$

Want to bound

$$||x - z||_{2}^{2} = \sum_{i \in T} |x_{i} - z_{i}|^{2} + \sum_{i \in S \setminus T} |x_{i} - z_{i}|^{2} + \sum_{i \in [n] \setminus (S \cup T)} x_{i}^{2}$$

$$= \sum_{i \in T} |x_{i} - y_{i}|^{2} + \sum_{i \in S \setminus T} x_{i}^{2} + \sum_{i \in [n] \setminus (S \cup T)} x_{i}^{2}.$$

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## **Analysis continued**

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First term:  $\sum_{i \in T} |x_i - \tilde{x}_i|^2 \le k \epsilon^2 E^2 \le \epsilon^2 (\text{err}_2^k(x))^2$ 

## **Analysis continued**

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Third term: common to expression for  $(err_2^k(x))^2$ 

## **Analysis continued**

Want to bound

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First term: 
$$\sum_{i \in T} |x_i - \tilde{x}_i|^2 \le k \epsilon^2 E^2 \le \epsilon^2 (\text{err}_2^k(x))^2$$

Third term: common to expression for  $(err_2^k(x))^2$ 

Second term: needs more care

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Want to bound  $\sum_{i \in S \setminus T} x_i^2$ 

Let 
$$\ell = |S \setminus T| \le k$$
. Since  $|S| = |T| = k$ ,  $|T \setminus S| = \ell$ 

Coordinates in  $S \setminus T$  and  $T \setminus S$  must be close: within  $\frac{\epsilon}{\sqrt{k}} \operatorname{err}_2^k(x)$ 

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Claim: Let  $a = \max_{i \in S \setminus T} |x_i|$  and  $b = \min_{i \in T \setminus S} |x_i|$ . Then  $a \le b + 2 \frac{\epsilon}{\sqrt{k}} \operatorname{err}_2^k(x)$ .

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Therefore

$$\begin{split} \sum_{i \in S \setminus T} x_i^2 & \leq \ell a^2 \leq \ell (b + 2 \frac{\epsilon}{\sqrt{k}} \mathrm{err}_2^k(x))^2 \\ & \leq \ell b^2 + 4 k \frac{\epsilon^2}{k} (\mathrm{err}_2^k(x))^2 + 4 k b \frac{\epsilon}{\sqrt{k}} \mathrm{err}_2^k(x). \end{split}$$

$$\sum_{i \in S \setminus T} x_i^2 \leq \ell a^2 \leq \ell (b + 2 \frac{\epsilon}{\sqrt{k}} \operatorname{err}_2^k(x))^2 
\leq \ell b^2 + 4k \frac{\epsilon^2}{k} (\operatorname{err}_2^k(x))^2 + 4kb \frac{\epsilon}{\sqrt{k}} \operatorname{err}_2^k(x) 
\leq \ell b^2 + 4\epsilon^2 (\operatorname{err}_2^k(x))^2 + 4\epsilon (\sqrt{k}b) \operatorname{err}_2^k(x) 
\leq \ell b^2 + 8\epsilon (\operatorname{err}_2^k(x))^2 
\leq \sum_{i \in T \setminus S} x_i^2 + 8\epsilon (\operatorname{err}_2^k(x))^2.$$

**Exercise:** Why is  $\sqrt{k}b \le \operatorname{err}_2^k(x)$ ? (We used it above.)

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$$||x - z||_{2}^{2} = \sum_{i \in T} |x_{i} - z_{i}|^{2} + \sum_{i \in S \setminus T} |x_{i} - z_{i}|^{2} + \sum_{i \in [n] \setminus (S \cup T)} x_{i}^{2}$$

$$= \sum_{i \in T} |x_{i} - y_{i}|^{2} + \sum_{i \in S \setminus T} x_{i}^{2} + \sum_{i \in [n] \setminus (S \cup T)} x_{i}^{2}.$$

First term:  $\sum_{i \in T} |x_i - \tilde{x}_i|^2 \le k\epsilon^2 E^2 \le \epsilon^2 (\text{err}_2^k(x))^2$ 

Third term: common to expression for  $(err_2^k(x))^2$ 

Second term: at most  $\sum_{i \in T \setminus S} x_i^2 + 8\epsilon (\operatorname{err}_2^{\overline{k}}(x))^2$ 

Hence

$$||x - z||_2^2 \le (1 + 9\epsilon)(\operatorname{err}_2^k(x))^2$$

**Implies** 

$$\|x-z\|_2 \leq (\sqrt{1+9\epsilon})\mathrm{err}_2^{\pmb{k}}(\pmb{x}) \leq (1+5\epsilon)\mathrm{err}_2^{\pmb{k}}(\pmb{x})$$

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## Application to signal processing

Given signal x approximate it via small number of basis signals

- Fourier analysis and Wavelets
- Useful in compression of various kinds

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# Application to signal processing

Given signal x approximate it via small number of basis signals

- Fourier analysis and Wavelets
- Useful in compression of various kinds

Transform x into y = Bx where B is a transform and then approximate y by k-sparse vector z

To (approximately) reconstruct x, output  $x' = B^{-1}z$ 

If Bx can be computed in streaming fashion from stream for x, we can apply preceding algorithm to obtain z

# **Compressed Sensing**

We saw that given x in streaming fashion we can construct sketch that allows us to find k-sparse z that approximates x with high probability

**Compressed sensing:** we want to create projection matrix  $\Pi$  such that for any x we can create from  $\Pi x$  a good k-sparse approximation to x

Doable! With  $\Pi$  that has  $O(k \log(n/k))$  rows. Creating  $\Pi$  requires randomization but once found it can be used. Called RIP matrices. First due to Candes, Romberg, Tao and Donoho. Lot of work in signal processing and algorithms.