### CS 498ABD: Algorithms for Big Data

# Subspace Embeddings for Regression

Lecture 12 October 1, 2020

### Subspace Embedding

**Question:** Suppose we have linear subspace E of  $\mathbb{R}^n$  of dimension d. Can we find a projection  $\Pi : \mathbb{R}^d \to \mathbb{R}^k$  such that for *every*  $x \in E$ ,  $\|\Pi x\|_2 = (1 \pm \epsilon) \|x\|_2$ ?

- Not possible if k < d.
- Possible if k = ℓ. Pick Π to be an orthonormal basis for E.
  Disadvantage: This requires knowing E and computing orthonormal basis which is slow.

What we really want: *Oblivious* subspace embedding ala JL based on random projections

### **Oblivious Supspace Embedding**

#### Theorem

Suppose E is a linear subspace of  $\mathbb{R}^n$  of dimension d. Let  $\Pi$  be a DJL matrix  $\Pi \in \mathbb{R}^{k \times d}$  with  $k = O(\frac{d}{\epsilon^2} \log(1/\delta))$  rows. Then with probability  $(1 - \delta)$  for every  $x \in E$ ,

$$\|rac{1}{\sqrt{k}}\Pi x\|_2 = (1\pm\epsilon)\|x\|_2.$$

In other words JL Lemma extends from one dimension to arbitrary number of dimensions in a graceful way.

### Part I

# Faster algorithms via subspace embeddings

### Linear model fitting

An important problem in data analysis

- *n* data points
- Each data point a<sub>i</sub> ∈ ℝ<sup>d</sup> and real value b<sub>i</sub>. We think of a<sub>i</sub> = (a<sub>i,1</sub>, a<sub>i,2</sub>, ..., a<sub>i,d</sub>). Interesting special case is when d = 1.
- What model should one use to explain the data?

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- What model should one use to explain the data?

Simplest model? Affine fitting.  $b_i = \alpha_0 + \sum_{j=1}^d \alpha_j a_{i,j}$  for some real numbers  $\alpha_0, \alpha_1, \ldots, \alpha_d$ . Can restrict to  $\alpha_0 = 0$  by lifting to d + 1 dimensions and hence linear model.

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But data is noisy so we won't be able to satisfy all data points even if true model is a linear model. How do we find a good linear model?

### Regression

- n data points
- Each data point  $\mathbf{a}_i \in \mathbb{R}^d$  and real value  $b_i$ . We think of  $\mathbf{a}_i = (a_{i,1}, a_{i,2}, \dots, a_{i,d})$ .

Linear model fitting: Find real numbers  $\alpha_1, \ldots, \alpha_d$  such that  $b_i \simeq \sum_{j=1}^d \alpha_j a_{i,j}$  for all points.

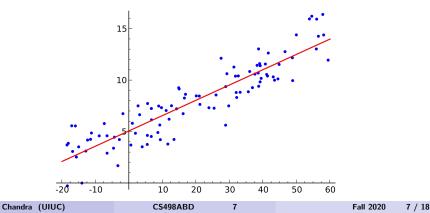
Let A be matrix with one row per data point  $a_i$ . We write  $x_1, x_2, \ldots, x_d$  as variables for finding  $\alpha_1, \ldots, \alpha_d$ .

**Ideally:** Find  $x \in \mathbb{R}^d$  such that Ax = b**Best fit:** Find  $x \in \mathbb{R}^d$  to minimize Ax - b under some norm.

•  $||Ax - b||_{\infty}$ ,  $||Ax - b||_2$ ,  $||Ax - b||_1$ 

**Linear least squares:** Given  $A \in \mathbb{R}^{n \times d}$  and  $b \in \mathbb{R}^d$  find x to minimize  $||Ax - b||_2$ . Optimal estimator for certain noise models

Interesting when  $n \gg d$  the over constrained case when there is no solution to Ax = b and want to find best fit.



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Geometrically Ax is a linear combination of columns of A. Hence we are asking what is the vector z in the column space of A that is closest to vector b in  $\ell_2$  norm.

Closest vector to  $\boldsymbol{b}$  is the projection of  $\boldsymbol{b}$  into the column space of  $\boldsymbol{A}$  so it is "obvious" geometrically. How do we find it?

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- Find an orthonormal basis  $z_1, z_2, \ldots, z_r$  for the columns of A.
- Compute projection c of b to column space of A as c = ∑<sub>j=1</sub><sup>r</sup> ⟨b, z<sub>j</sub>⟩z<sub>j</sub> and output answer as ||b c||<sub>2</sub>.
  What is x?

**Linear least squares:** Given  $A \in \mathbb{R}^{n \times d}$  and  $b \in \mathbb{R}^{d}$  find x to minimize  $||Ax - b||_2$ .

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- Find an orthonormal basis  $z_1, z_2, \ldots, z_r$  for the columns of A.
- Compute projection c of b to column space of A as  $c = \sum_{j=1}^{r} \langle b, z_j \rangle z_j$  and output answer as  $||b c||_2$ .
- What is x? We know that Ax = c. Solve linear system. Can combine both steps via SVD and other methods.

## Linear least square: Optimization perspective

**Linear least squares:** Given  $A \in \mathbb{R}^{n \times d}$  and  $b \in \mathbb{R}^{d}$  find x to minimize  $||Ax - b||_2$ .

Optimization: Find  $x \in \mathbb{R}^d$  to minimize  $||Ax - b||_2^2$ 

$$||Ax - b||_2^2 = x^T A^T A x - 2b^T A x + b^t b$$

The quadratic function  $f(x) = x^T A^T A x - 2b^T A x + b^t b$  is a convex function since the matrix  $A^T A$  is positive semi-definite.  $\nabla f(x) = 2A^T A x - 2b^T A$  and hence optimum solution  $x^*$  is given by  $x^* = (A^T A)^{-1} b^T A$ .

### **Computational perspective**

*n* large (number of data points), *d* smaller so *A* is tall and skinny.

Exact solution requires SVD or other methods. Worst case time  $nd^2$ .

Can we speed up computation with some potential approximation?

## Linear least squares via Subspace embeddings

Let  $A^{(1)}, A^{(2)}, \ldots, A^{(d)}$  be the columns of A and let E be the subspace spanned by  $\{A^{(1)}, A^{(2)}, \ldots, A^{(d)}, b\}$ Note columns are in  $\mathbb{R}^n$  corresponding to n data points

**E** has dimension at most d + 1.

Use subspace embedding on *E*. Applying JL matrix  $\Pi$  with  $k = O(\frac{d}{\epsilon^2})$  rows we reduce  $\{A^{(1)}, A^{(2)}, \dots, A^{(d)}, b\}$  to  $\{A^{\prime(1)}, A^{\prime(2)}, \dots, A^{\prime(d)}, b'\}$  which are vectors in  $\mathbb{R}^k$ .

Solve  $\min_{x' \in \mathbb{R}^d} \|A'x' - b'\|_2$ 

#### Lemma

With probability  $(1 - \delta)$ ,

$$(1-\epsilon)\min_{x\in\mathbb{R}^d} \|Ax-b\| \leq \min_{x'\in\mathbb{R}^d} \|A'x'-b'\|_2 \leq (1+\epsilon)\min_{x\in\mathbb{R}^d} \|Ax-b\|$$

#### Lemma

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With probability  $(1 - \delta)$  via the subpsace embedding guarantee, for all  $z \in E$ ,

$$(1-\epsilon)\|z\|_2 \le \|\Pi z\|_2 \le (1+\epsilon)\|z\|_2$$

Now prove two inequalities in lemma separately using above.

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Suppose  $x^*$  is an optimum solution to  $\min_x ||Ax - b||_2$ .

Let  $z = Ax^* - b$ . We have  $\|\Pi z\|_2 \leq (1 + \epsilon) \|z\|_2$  since  $z \in E$ .

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Since  $x^*$  is a feasible solution to  $\min_{x'} ||A'x' - b'||$ ,

 $\min_{x'} \|A'x'-b'\|_2 \le \|A'x^*-b'\|_2 = \|\Pi(Ax^*-b)\|_2 \le (1+\epsilon)\|Ax^*-b\|_2$ 

For any  $y \in \mathbb{R}^d$ ,  $\|\Pi Ay - \Pi b\|_2 \ge (1 - \epsilon) \|Ay - b\|_2$  because Ay - b is a vector in E and  $\Pi$  preserves all of them.

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Let  $y^*$  be optimum solution to  $\min_{x'} ||A'x' - b'||_2$ . Then  $||\Pi(Ay^* - b)||_2 \ge (1 - \epsilon) ||Ay^* - b||_2 \ge (1 - \epsilon) ||Ax^* - b||_2$ 

### **Running time**

Reduce problem for d vectors in  $\mathbb{R}^n$  to d vectors in  $\mathbb{R}^k$  where  $k = O(d/\epsilon^2)$ .

Computing  $\Pi A$ ,  $\Pi b$  can be done in nnz(A) via sparse/fast JL (input sparsity time).

Need to solve least squares on A', b' which can be done in  $O(d^3/\epsilon^2)$  time.

Essentially reduce n to  $d/\epsilon^2$ . Useful when  $n \gg d/\epsilon^2$  (for this  $\epsilon$  should not be too small)

### **Further improvement**

Reduced dimension of vectors from  $\mathbb{R}^n$  to  $\mathbb{R}^k$  where  $k = O(d/\epsilon^2)$ .

For small  $\epsilon$  a dependence of  $1/\epsilon^2$  is not so good. Can we improve?

Can use  $\Pi$  with  $k = O(d/\epsilon)$ .

- Suffices if **Π** has 1/10-approximate subspace embedding property and property of preserving matrix multiplication
- $(\Pi A)^{T}(\Pi A)$  has small condition number
- Use  $\Pi$  that has 1/10-approximate subspace embedding property and then use gradient descent whose convergence depends on condition number of A.

## Other uses of JL/subspace embeddings in numerical linear algebra

- Approximate matrix multiplication
- Low rank approximation and SVD
- Compressed Sensing