

Program Verification: Lecture 24

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Constructor Pattern Predicates

Recall from Lecture 18 that for an executable rewrite theory $\mathcal{R} = (\Sigma, E \cup B, R)$ with constructor subsignature Ω and state sort St , an expressive set Π of **state predicate names** to specify modal properties of $\mathbb{C}_{\mathcal{R}}$ is the set of **constrained constructor patterns** $u|\varphi$,

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DNF Theorem. Any $p \in PCPattF$ has a **disjunctive normal form**, $dnf(p)$, which is either \perp or has the form $u_1 \vee \dots \vee u_n$, with $u_i \in T_{\Omega}(X)_{St}$, $1 \leq i \leq n$, $n \geq 1$, and is such that $\llbracket p \rrbracket = \llbracket dnf(p) \rrbracket$.

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Definition. For $\mathcal{R} = (\Omega, B, R)$ topmost with state sort St , the set $\mathcal{R}^*[I]$ of \mathcal{R} -**reachable states** from a set $I \subseteq T_{\Omega/B, St}$ of initial states is, by definition, the set $\rightarrow_{R/B}^*[I]$ (recall STACS). That is, $\mathcal{R}^*[I] = \{[v] \in T_{\Omega/B, St} \mid \exists [u] \in I \text{ s.t. } [u] \rightarrow_{R/B}^* [v]\}$. Likewise, by definition, $\mathcal{R}[I] =_{\text{def}} \rightarrow_{R/B}[I]$, $\mathcal{R}^n[I] =_{\text{def}} \rightarrow_{R/B}^n[I]$, and $\mathcal{R}^{\leq n}[I] =_{\text{def}} I \cup \mathcal{R}[I] \cup \dots \cup \mathcal{R}^n[I]$, $n \in \mathbb{N}$.

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Ex.24.1: Prove that: (1) Q is \mathcal{R} -transition-closed iff $\mathcal{R}^*[Q] = Q$, and (2) the smallest invariant from a set of initial states $I \subseteq T_{\Omega/B, St}$, namely, $\mathcal{R}^*[I]$, is inductive.

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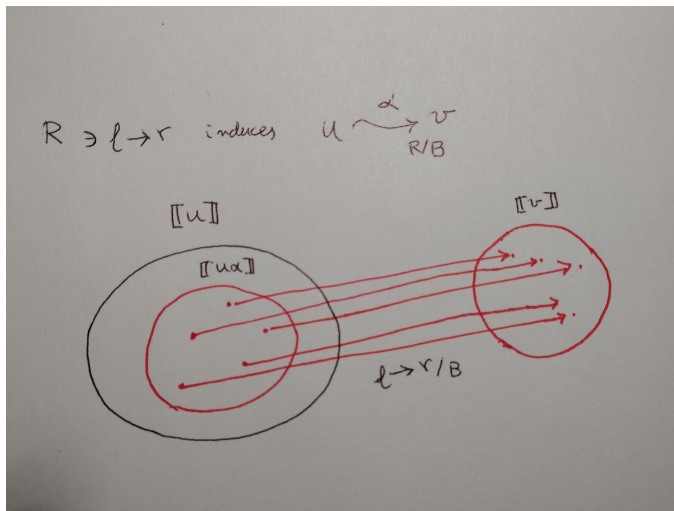
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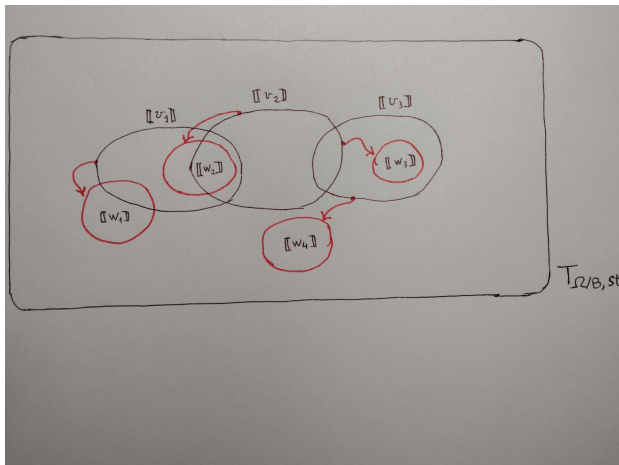
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The Set-Theoretic Meaning of Narrowing



The Set-Theoretic Meaning of Folding Narrowing

For $F_d = v_1 \vee v_2 \vee v_3$, then $F_{d+1} = w_1 \vee w_2 \vee w_4$. w_3 folded into v_3 .



Completeness of Folding Narrowing

Completeness Theorem of Folding Narrowing. Let (Ω, B, R) be a topmost rewrite theory with state sort St , and $u_1 \vee \dots \vee u_n$ an initial state. For each depth $d \in \mathbb{N}$, $\llbracket P_d \rrbracket = \mathcal{R}^{\leq d} \llbracket u_1 \vee \dots \vee u_n \rrbracket$.

If it exists, let d be the smallest depth such that $F_{d+1} = \perp$. Then, $P_{d+1} = P_d \vee F_{d+1} = P_d \vee \perp$, which implies $\llbracket P_d \rrbracket = \llbracket P_{d+1} \rrbracket$. I.e., $\mathcal{R}^{\leq d} \llbracket u_1 \vee \dots \vee u_n \rrbracket = \llbracket P_d \rrbracket = \llbracket P_{d+1} \rrbracket = \mathcal{R}^{\leq d+1} \llbracket u_1 \vee \dots \vee u_n \rrbracket = \mathcal{R}[\mathcal{R}^{\leq d} \llbracket u_1 \vee \dots \vee u_n \rrbracket] \cup \mathcal{R}^{\leq d} \llbracket u_1 \vee \dots \vee u_n \rrbracket$, so that $\llbracket P_d \rrbracket$ is **transition-closed**. Therefore, by **Ex.24.1** we have $\llbracket P_d \rrbracket = \mathcal{R}^* \llbracket P_d \rrbracket$. But then $\llbracket P_d \rrbracket = \mathcal{R}^* \llbracket u_1 \vee \dots \vee u_n \rrbracket$ follows from the inclusions:

$$\mathcal{R}^* \llbracket u_1 \vee \dots \vee u_n \rrbracket \subseteq \mathcal{R}^* \llbracket P_d \rrbracket = \llbracket P_d \rrbracket \subseteq \mathcal{R}^* \llbracket u_1 \vee \dots \vee u_n \rrbracket.$$

That is, we get a **finite**, symbolic description of all reachable states $\mathcal{R}^* \llbracket u_1 \vee \dots \vee u_n \rrbracket$ as the pattern disjunction P_d .

Four Methods to Symbolically Verify Invariants

For $\mathcal{R} = (\Omega, B, R)$ a topmost rewrite theory with state sort St , $u_1 \vee \dots \vee u_n$ an initial state, and $Q \subseteq T_{\Omega/B, St}$, the following four methods can verify $(\dagger) \mathbb{C}_{\mathcal{R}}, \llbracket u_1 \vee \dots \vee u_n \rrbracket \models_{S4} \square Q$.

A. If Q is specifiable as $Q = \llbracket n \rrbracket$ for n a **negative pattern formula** different from \top (if $n = \top$, (\dagger) holds trivially). W.L.O.G. we may assume $n = ncnf(n) = \neg v_1 \wedge \dots \wedge \neg v_m$.

Method 1. (\dagger) holds if $\mathbb{C}_{\mathcal{R}}, \llbracket u_1 \vee \dots \vee u_n \rrbracket \not\models_{S4} \diamond \llbracket v_1 \vee \dots \vee v_m \rrbracket$. A **sufficient condition** to automatically verify (\dagger) is that the m commands $\{\text{fold}\} \text{vu-narrow } u_1 \vee \dots \vee u_n \Rightarrow^* v_j, 1 \leq j \leq m$ return: No solution.

If this succeeds, Maude can return the positive pattern disjunction P_d such that $\llbracket P_d \rrbracket = \mathcal{R}^* \llbracket u_1 \vee \dots \vee u_n \rrbracket$, which enables **Method 2**.

Four Methods to Symbolically Verify Invariants (II)

Method 2. If we have found $P_d = w_1 \vee \dots \vee w_k$ s.t.
 $\llbracket P_d \rrbracket = \mathcal{R}^* \llbracket u_1 \vee \dots \vee u_n \rrbracket$, then (\dagger) holds for **any** Q of the form,
 $Q = \llbracket \neg v_1 \wedge \dots \wedge \neg v_m \rrbracket$ iff $\forall 1 \leq i \leq k, \forall 1 \leq j \leq m, w_i \wedge v_j = \perp$,
 i.e., (see Appendix 1), iff $Unif_B(w_i = v_j) = \emptyset$ for all i, j (we
 assume $vars(w_i) = vars(v_j)$). Note that **no search is needed!**

B. If Q is specifiable as $Q = \llbracket p \rrbracket$ for p a **positive pattern formula**
 different from \perp (if $p = \perp$, (\dagger) cannot hold). W.L.O.G. we may
 assume $p = dnf(p) = v_1 \vee \dots \vee v_m$.

Method 3. If we have found $P_d = w_1 \vee \dots \vee w_k$ s.t.
 $\llbracket P_d \rrbracket = \mathcal{R}^* \llbracket u_1 \vee \dots \vee u_n \rrbracket$, then (\dagger) holds for any Q of the form,
 $Q = \llbracket v_1 \vee \dots \vee v_m \rrbracket$ iff $w_1 \vee \dots \vee w_k \subseteq_B v_1 \vee \dots \vee v_m$. A decidable
 sufficient condition is $w_1 \vee \dots \vee w_k \sqsubseteq_B v_1 \vee \dots \vee v_m$.

Four Methods to Symbolically Verify Invariants (III)

Method 4. (\dagger) holds for $Q = \llbracket v_1 \vee \dots \vee v_m \rrbracket$ if: (1) Q is **transition-closed**; this holds iff a $@\text{fold}$ vu -narrow $v_1 \vee \dots \vee v_m \Rightarrow 1$ $\$$ command, where $\$$ is a fresh (and therefore unreachable) constant added to \mathcal{R} , generates an $F_1(v_1 \vee \dots \vee v_m)$ s.t. either $F_1(v_1 \vee \dots \vee v_m) = \perp$, or $F_1(v_1 \vee \dots \vee v_m) \subset_B v_1 \vee \dots \vee v_m$. (2) $u_1 \vee \dots \vee u_n \subset_B v_1 \vee \dots \vee v_m$. A decidable sufficient condition is $u_1 \vee \dots \vee u_n \sqsubseteq_B v_1 \vee \dots \vee v_m$.