CS 473: Algorithms, Spring 2021

Dynamic Programming on Trees

Lecture 4 Feb 4, 2021

Most slides are courtesy Prof. Chekuri

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What is Dynamic Programming?

Every recursion can be memoized. Automatic memoization does not help us understand whether the resulting algorithm is efficient or not.

Dynamic Programming:

A recursion that when memoized leads to an efficient algorithm.

Key Questions:

- Given a recursive algorithm, how do we analyze the complexity when it is memoized?
- How do we recognize whether a problem admits a (recursive) dynamic programming based efficient algorithm?
- How do we further optimize time and space of a dynamic programming based algorithm?

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Dynamic Programming Template

- Come up with a recursive algorithm to solve problem
- Understand the structure/number of the subproblems generated by recursion
- Memoize the recursion
 - set up compact notation for subproblems
 - set up a data structure for storing subproblems

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Dynamic Programming Template

- Come up with a recursive algorithm to solve problem
- Understand the structure/number of the subproblems generated by recursion
- Memoize the recursion
 - set up compact notation for subproblems
 - set up a data structure for storing subproblems
- Iterative algorithm
 - Understand dependency graph on subproblems
 - Pick an evaluation order (any topological sort of the dependency DAG)
- Analyze time and space
- Optimize

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Dynamic Programming on Trees

Fact: Many graph optimization problems are NP-Hard

Fact: The same graph optimization problems are in *P* on trees.

Why?

Dynamic Programming on Trees

Fact: Many graph optimization problems are NP-Hard

Fact: The same graph optimization problems are in *P* on trees.

Why?

A significant reason: DP algorithm based on decomposability

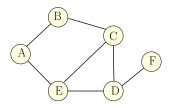
Powerful methodology for graph algorithms via a formal notion of decomposability called **treewidth** (beyond the scope of this class)

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Maximum Independent Set in a Graph

Definition

Given undirected graph G = (V, E) a subset of nodes $S \subseteq V$ is an independent set (also called a stable set) if for there are no edges between nodes in S. That is, if $u, v \in S$ then $(u, v) \not\in E$.

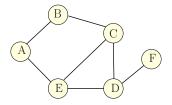


Some independent sets in graph above: $\{D\}, \{A, C\}, \{B, E, F\}$

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Maximum Independent Set Problem

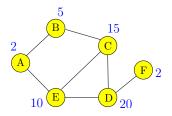
Input Graph G = (V, E)Goal Find maximum sized independent set in G



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Maximum Weight Independent Set Problem

Input Graph G = (V, E), weights $w(v) \ge 0$ for $v \in V$ Goal Find maximum weight independent set in G



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Maximum Weight Independent Set Problem

- No one knows an efficient (polynomial time) algorithm for this problem
- Problem is NP-Hard and it is believed that there is no polynomial time algorithm

Brute-force algorithm:

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Maximum Weight Independent Set Problem

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Brute-force algorithm:

Try all subsets of vertices.

Let $V = \{v_1, v_2, \dots, v_n\}$. For a vertex u let N(u) be its neighbors.

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For a vertex u let N(u) be its neighbors.

Observation

 v_1 : vertex in the graph.

One of the following two cases is true

Case 1 v_1 is in some maximum independent set.

Case 2 v_1 is in no maximum independent set.

We can try both cases to "reduce" the size of the problem

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 $G_1 = G - v_1$ obtained by removing v_1 and incident edges from G

$$G_2 = G - v_1 - N(v_1)$$
 obtained by removing $N(v_1) \cup v_1$ from G

$$MIS(G) = \max\{MIS(G_1), MIS(G_2) + w(v_1)\}\$$

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RecursiveMIS(G):

if G is empty then Output 0

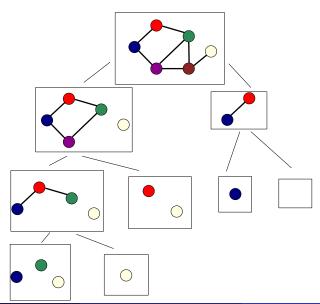
v \leftarrow a vertex of G

a = \text{RecursiveMIS}(G - v)

b = w(v) + \text{RecursiveMIS}(G - v - N(v))

Output \max(a, b)
```

Example



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..for Maximum Independent Set

Running time:

$$T(n) = T(n-1) + T(n-1 - deg(v)) + O(1 + deg(v))$$

where deg(v) is the degree of v. T(0) = T(1) = 1 is base case.

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where deg(v) is the degree of v. T(0) = T(1) = 1 is base case.

Worst case is when deg(v) = 0 when the recurrence becomes

$$T(n) = 2T(n-1) + O(1)$$

Solution to this is $T(n) = O(2^n)$.

We can memoize the recursive algorithm.

Question: Does it lead to an efficient algorithm?

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How many are they if G has n nodes to start with?

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Question: Does it lead to an efficient algorithm?

What are the sub-problems? Ans.: Subgraphs (subsets of nodes).

How many are they if G has n nodes to start with? A.: Exponential.

Exercise: Show that even when G is a cycle the number of subproblems is exponential in n.

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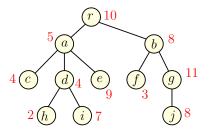
Part I

Maximum Weighted Independent Set in Trees

Maximum Weight Independent Set in a Tree

Input Tree T=(V,E) and weights $w(v)\geq 0$ for each $v\in V$

Goal Find maximum weight independent set in T



Maximum weight independent set in above tree: ??

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For an arbitrary graph **G**:

- 1 Number vertices as v_1, v_2, \ldots, v_n
- ② Find recursively optimum solutions without v_n (recurse on $G v_n$) and with v_n (recurse on $G v_n N(v_n)$ & include v_n).
- Saw that if graph G is arbitrary there was no good ordering that resulted in a small number of subproblems.

What about a tree?

For an arbitrary graph G:

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What about a tree? Natural candidate for v_n is root r of T?

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Natural candidate for v_n is root r of T? Let \mathcal{O} be an optimum solution to the whole problem.

Case $r \not\in \mathcal{O}$:

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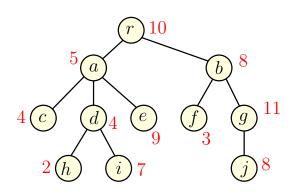
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Subproblems? Subtrees of *T* rooted at nodes in *T*.

How many of them? O(n)

Example



A Recursive Solution

T(u): subtree of T hanging at node u

OPT(u): max weighted independent set value in T(u)

$$OPT(u) =$$

A Recursive Solution

T(u): subtree of T hanging at node u

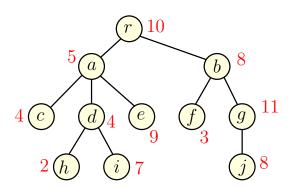
OPT(u): max weighted independent set value in T(u)

$$OPT(u) = \max \begin{cases} \sum_{v \text{ child of } u} OPT(v), \\ w(u) + \sum_{v \text{ grandchild of } u} OPT(v) \end{cases}$$

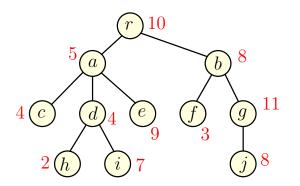
① To evaluate OPT(u) need to have computed values of all children and grandchildren of u. Compute OPT(u) bottom up.

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- **1** To evaluate OPT(u) need to have computed values of all children and grandchildren of u. Compute OPT(u) bottom up.
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Ans.: Post-order traversal of a tree.

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```
\begin{aligned} & \text{MIS-Tree}(T): \\ & \text{Let } v_1, v_2, \dots, v_n \text{ be a post-order traversal of nodes of } T \\ & \text{for } i = 1 \text{ to } n \text{ do} \\ & M[v_i] = \max \left( \begin{array}{c} \sum_{v_j \text{ child of } v_i} M[v_j], \\ w(v_i) + \sum_{v_j \text{ grandchild of } v_i} M[v_j] \end{array} \right) \\ & \text{return } M[v_n] \text{ (* Note: } v_n \text{ is the root of } T \text{ *)} \end{aligned}
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- ② Better bound: Value $M[v_j]$ is accessed by who all?

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Each node (including the root) is a *separator*!

Definition

Given a graph G = (V, E) a set of nodes $S \subset V$ is a *separator* for G if G - S has at least two connected components.

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Definition

Given a graph G = (V, E) a set of nodes $S \subset V$ is a *separator* for G if G - S has at least two connected components.

Definition

S is a *balanced* separator if each connected component of G - S has at most 2|V(G)|/3 nodes.

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Exercise: Prove that every tree T has a balanced separator consisting of a single node.

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Exercise: Prove that every tree *T* has a balanced separator consisting of a single node.

Aside: $O(2^{\sqrt{n}})$ algorithm to find MIS in planar graphs using, (i) balanced-separators, (ii) DP algorithm on trees.

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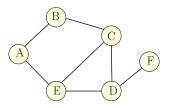
Part II

Minimum Dominating Set in Trees

Minimum Dominating Set in a Graph

Definition

Given undirected graph G = (V, E) a subset of nodes $S \subseteq V$ is a dominating set if for all $v \in V$, either $v \in S$ or a neighbor of v is in S.

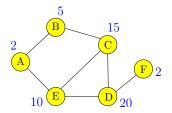


Some dominating sets in graph above: $\{A, B, C, D, E, F\}$,

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Minimum Weight Dominating Set Problem

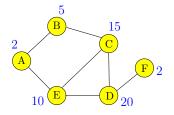
Input Graph G = (V, E), weights $w(v) \ge 0$ for $v \in V$ Goal Find minimum weight dominating set in G



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Minimum Weight Dominating Set Problem

Input Graph G = (V, E), weights $w(v) \ge 0$ for $v \in V$ Goal Find minimum weight dominating set in G



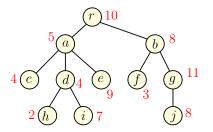
NP-Hard problem

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Minimum Weight Dominating Set in a Tree

Input Tree T=(V,E) and weights $w(v)\geq 0$ for each $v\in V$

Goal Find minimum weight dominating set in T



Minimum weight dominating set in above tree: ??

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r is root of T. Let \mathcal{O} be an optimum solution for T.

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Issue 1: In both cases it is not feasible to express $|\mathcal{O}|$ easily as optimum solution values of children or descendants of r.

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Issue 1: In both cases it is not feasible to express $|\mathcal{O}|$ easily as optimum solution values of children or descendants of r.

Issue 2: Removing r decomposes T into subtrees rooted at children of r. However, not easy to decompose problem structure recursively. Problems at children of r are dependent.

Need to introduce additional variable(s).

Recursive Algorithm: Understanding Dependence

Let u_1, u_2, \ldots, u_k be children of root r of T

What "information" do T_{u_1}, \ldots, T_{u_k} need to know about r's status in an optimum solution in order to become "independent"

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Recursive Algorithm: Understanding Dependence

Let u_1, u_2, \ldots, u_k be children of root r of T

What "information" do T_{u_1}, \ldots, T_{u_k} need to know about r's status in an optimum solution in order to become "independent"

- Whether r is included in the solution
- If r is not included then which of the children is going to cover it. Equivalently, T_{u_i} needs to know whether it should cover r or some other child will.

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Recursive Algorithm: Introducing Variables

- u: node in tree
- pi: boolean variable to indicate whether parent is in solution. pi = 0 means parent is not included. pi = 1 means it is included.
- cp: boolean variable to indicate whether node needed to cover parent. cp=1 means parent needs to be covered. cp=0 means not needed.

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OPT(u, pi, cp): value of minimum dominating set in T_u with booleans pi and cp with meaning above.

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OPT(r, 0, 0): value of minimum dominating set in T.

Recursive Solution

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$$OPT(u, 0, 0) = w(u) + \sum_{v \in C_u} OPT(v, 1, 0)$$

Case u is not included: Then u needs to be covered by some child.

We do a min over all children.

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Since one of these cases has to be true, we take the min of the values in the above two cases to compute OPT(u, 0, 0).

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Case u is not included: This does not arise because u has to cover its parent.

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Caution: Not including u may appear to be always advantageous but it is not true.

OPT(u, 1, 1): Value of a minimum dominating set in T_u where we assume that u's parent is included and u needs to cover its parent.

This subproblem does not make sense since if u's parent is included then u does not need to cover it.

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- In particular? Ans.: post-order traversal.

```
DominatingSet-Tree(T):

Let v_1, v_2, \ldots, v_n be a post-order traversal of nodes of T.

Allocate array M[1..n, 0..1, 0..1] to store OPT(v_i, pi, cp) values for i=1 to n do

Compute OPT(v_i, 0, 0), OPT(v_i, 1, 0) and OPT(v_i, 0, 1) using values of children of v_i stored in M, or via base cases if v_i is leaf

Store computed values in M for use by parent of v_i. return OPT(v_n, 0, 0) (* Note: v_n is the root of T *)
```

Exercise: Work out details and prove an O(n) time implementation.

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Recap

- To obtain recursive solution we introduced additional variables based on "information" needed to decompose
- Decomposition depends both on structure (trees decompose via separators) and objective function
- Subproblems and recursion are almost defined hand in hand

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