cs473: Algorithms Lecture 4: Dynamic Programming

Michael A. Forbes

University of Illinois at Urbana-Champaign

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logistics:

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■ pset1 out,

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lacksquare pset1 out, due R5 — can submit in *groups* of ≤ 3

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last lecture:

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- recursion
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- dynamic programming on trees
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dynamic programming:

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remarks:

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Dynamic Programming

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- memoizing a recursive algorithm does not necessarily lead to an efficient algorithm (e.g., knapsack problem) — you need the *right* recursion
- recognizing that dynamic programming applies to a problem can be non-obvious

fact:

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- dynamic programming on trees often generalizes to graphs that have low treewidth

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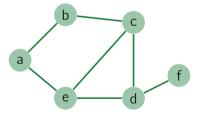
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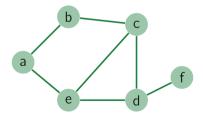
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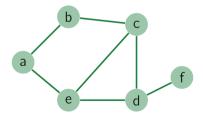


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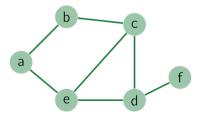


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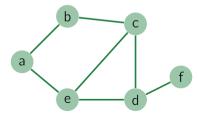
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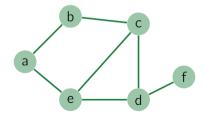


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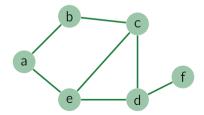
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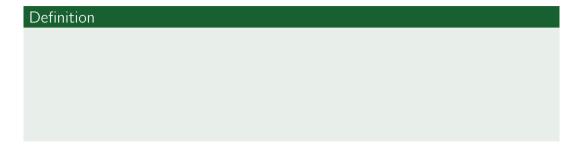
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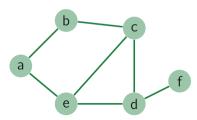
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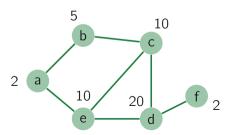
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- MIS is efficiently solvable if the underlying graph is a *tree*

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$$MIS(G) = \max \left\{ MIS(G - v), MIS(G - v - N(v)) + w(v) \right\}.$$

Proof.

For any set S independent in G, either $v \notin S$ or $v \in S$.

- G v: any set $T \subseteq V \setminus \{v\}$ independent in G v has $T \subseteq V$ independent in G
- G v N(v): any set $T \subseteq V \setminus (\{v\} \cup N(v))$ independent in G v N(v) has $T \cup \{v\} \subseteq V$ independent in G

Any set S independent in G must be of the above two cases. Now maximize.

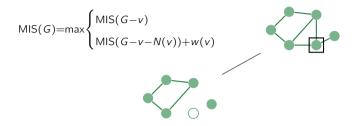
$$MIS(G) = \max \begin{cases} MIS(G-v) \\ MIS(G-v-N(v)) + w(v) \end{cases}$$

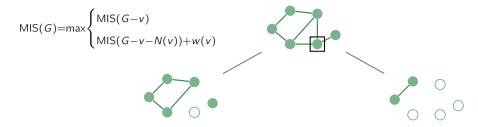
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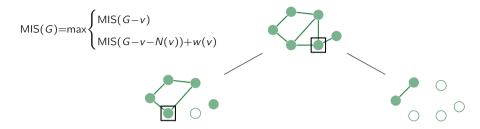


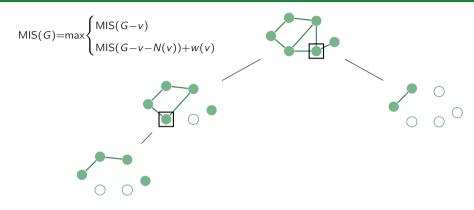
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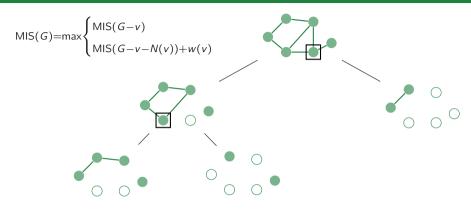


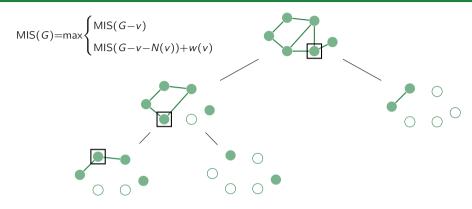


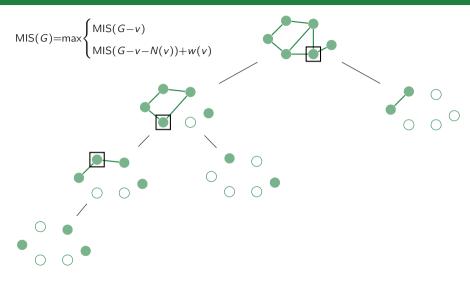


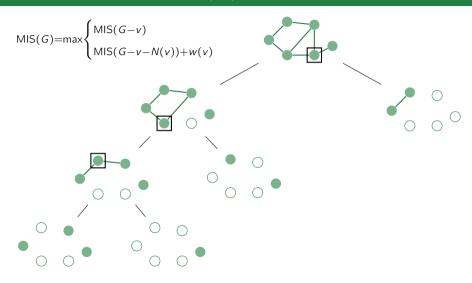


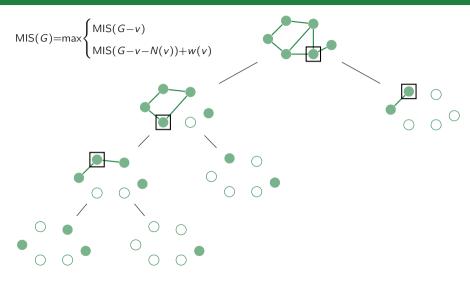


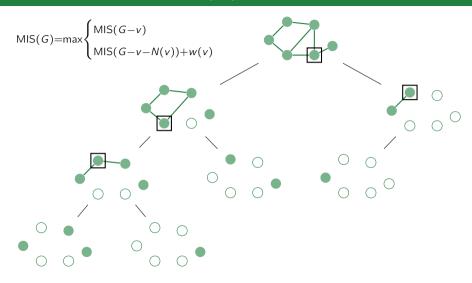


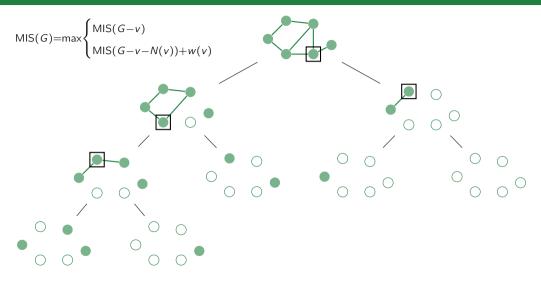












recursive-MIS($G = (V, E), w : V \rightarrow \mathbb{N}$):

```
recursive-MIS(G = (V, E), w : V \to \mathbb{N}): if V = \emptyset
```

```
recursive-MIS(G = (V, E), w : V \to \mathbb{N}): if V = \emptyset return 0
```

```
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if V = \emptyset

return 0

choose v \in V
```

```
 \begin{aligned} & \text{recursive-MIS}(G = (V, E), w : V \to \mathbb{N}): \\ & & \text{if } V = \emptyset \\ & & \text{return } 0 \\ & & \text{choose } v \in V \\ & & \text{return } \max \left( \right. \end{aligned}
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```
\begin{split} & \text{recursive-MIS}(G = (V, E), w : V \to \mathbb{N}): \\ & \text{if } V = \emptyset \\ & \text{return 0} \\ & \text{choose } v \in V \\ & \text{return max} \left( \text{recursive-MIS}(G - v), \right. \end{split}
```

```
\begin{split} & \text{recursive-MIS}(G = (V, E), w : V \to \mathbb{N}): \\ & \text{ if } V = \emptyset \\ & \text{ return } 0 \\ & \text{ choose } v \in V \\ & \text{ return } \max \left( \text{recursive-MIS}(G - v), \text{recursive-MIS}(G - v - N(v)) + w(v) \right) \end{split}
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correctness: clear complexity: n := |V| \qquad T(0), T(1) \ge \Omega(1).
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 $\implies T(n) \ge 2T(n-1)$

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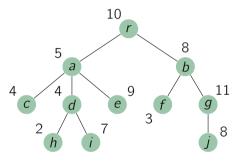
- when G has no edges then clearly MIS(G) = |V|, but this worst-case runtime is hard to avoid
- memoization does not obviously help subproblems correspond to subgraphs, of which there are possibly exponentially many

question:

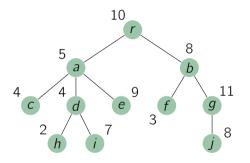
question: maximum weight independent set,

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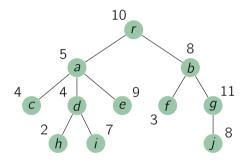


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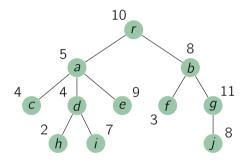
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question:

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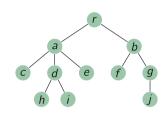
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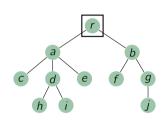
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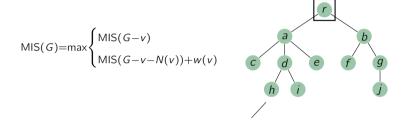
- how to bound the number of subproblems in recursive algorithm?
- how to pick which vertex $v \in V$ to eliminate?

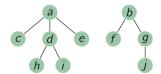
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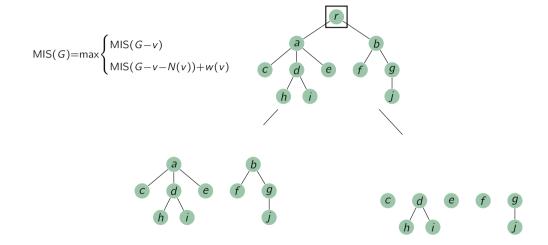


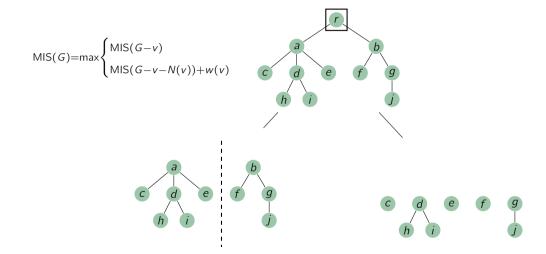
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Let T = (V, E) be a tree. Pick a root $r \in V$ for T to create the rooted tree (T, r).

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Corollary

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Corollary

Let T = (V, E) be a tree. Pick a root $r \in V$ for T to create the rooted tree (T, r). Running recursive-MIS on T and eliminating nodes closest to r in T, then the result subproblems exactly correspond to forests of rooted subtrees of (T, r),

Lemma

Let T = (V, E) be a tree, with **root** $v \in V$. Then

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Let T = (V, E) be a tree. Pick a root $r \in V$ for T to create the rooted tree (T, r). Running recursive-MIS on T and eliminating nodes closest to r in T, then the result subproblems exactly correspond to forests of rooted subtrees of (T, r), and disjoint rooted subtrees can be solved independently

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- \blacksquare subproblems are rooted subtrees of (T, r)
- \blacksquare a subtree T(v) depends on all of subtrees T(u) where u is a descendent of v
- \implies iterating over V in post-order traversal of ${\mathcal T}$ will satisfy the dependency graph

iterative algorithm:

 $iter-MIS-tree(T = (V, E), w : V \rightarrow \mathbb{N}):$

```
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correctness:

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```
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correctness: clear
complexity:

■ O(n) space to store $M[\cdot]$

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```

correctness: clear

- O(n) space to store $M[\cdot]$
- time

iterative algorithm:

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 - naive:

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question:

question: why does dynamic programming work on trees?

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- lacktriangle every tree T has a balanced separator consisting of a single node
- dynamic-programming + small balanced separators $\implies 2^{O(\sqrt{n})}$ -time MIS algorithm for *planar* graphs

Minimum Dominating Set

Definition

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Let G = (V, E) be an undirected (simple) graph.

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Definition

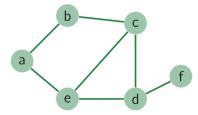
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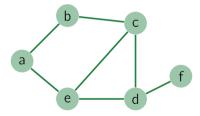
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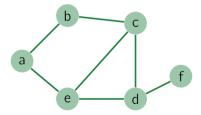


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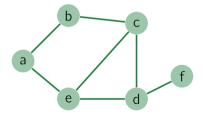


Dominating sets include $\{a, b, c, d, e, f\}$, $\{e, c, f\}$,

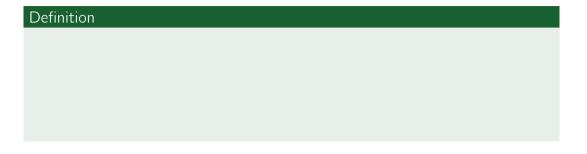
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ex:



Dominating sets include $\{a, b, c, d, e, f\}$, $\{e, c, f\}$, and $\{a, b, f\}$.



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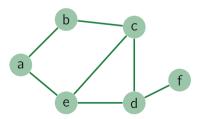
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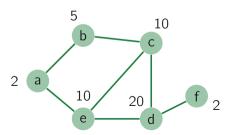
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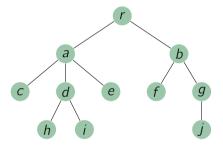
remarks:

- minimum (weight) dominating set is solvable via brute force: try *all* possible subsets \implies solvable in time $O(n^{O(1)}2^n)$
- no efficient algorithm *currently* known
- lacktriangleright minimum weight dominating set is NP-hard \Longrightarrow an efficient algorithm not expected to exist
- minimum weight dominating set is efficiently solvable if the underlying graph is a tree

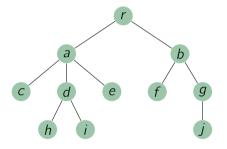
question:

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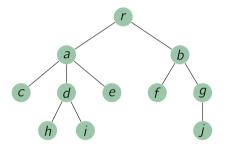


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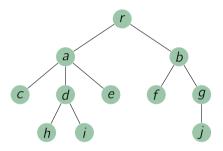
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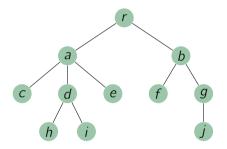
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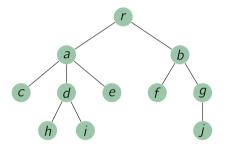


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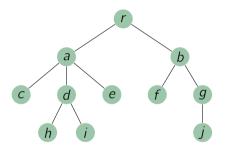
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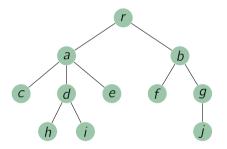
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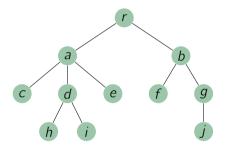
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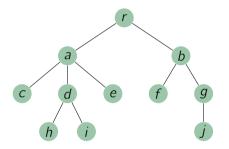
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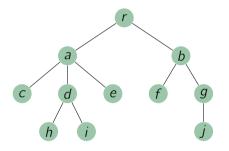
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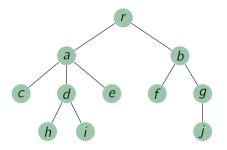


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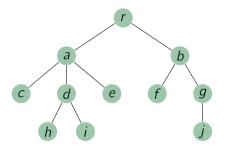


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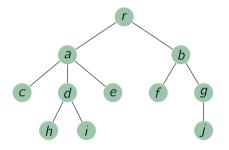
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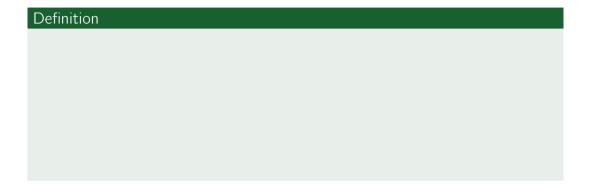


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question: how to parameterize these subproblems?



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$$\mathsf{OPT}_0(r) = \min \ \begin{cases} \left(\sum_{v \in N(r)} \mathsf{OPT}_2(v) \right) + w(r) \\ \min_{v \in N(r)} \left(\mathsf{OPT}_1(v) + \sum_{u \in N(r) \setminus \{v\}} \mathsf{OPT}_0(u) \right) \end{cases}$$

Proof.

- in optimum S, $r \in S$
- in optimum S, $r \notin S$ and r dominated by child $v \in S$

T rooted tree with root r. T(v) is subtree rooted at v.

- **type-0**: regular dominating set
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$$OPT_2(r) = min$$

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Proof.

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recursive algorithm:

■ $3 \cdot n$ subproblems

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 follow post-order traversal of rooted tree to satisfy dependencies

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details are an **exercise**

remarks:

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- dynamic program is about finding the correct recursion, and the correct recursion is intimately tied to understand the structure and number of subproblems
- trees can be easily decomposed into a (small) number of subtrees, this allows a small number of resulting subproblems
- dynamic programming on trees can often be generalized to graphs of small treewidth

Overview (II)

today:

- dynamic programming on trees
- maximum independent set
- dominating set

next lecture:

more dynamic programming

logistics:

lacksquare pset1 out, due R5 — can submit in *groups* of ≤ 3

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