cs473: Algorithms Lecture 3: Dynamic Programming

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September 2, 2019

logistics:

pset0 due R5,

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- pset1 out tomorrow,

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last lecture:

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recursion

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- recursion
- dynamic programming

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example (Karatsuba, Strassen, ...):

- reduce problem instances of size n to problem instances of size n/2
- terminate recursion at O(1)-size problem instances, solve straightforwardly as a base case

recursive paradigms:

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- dynamic programming: expend effort to reduce given problem to multiple correlated smaller problems. Naive recursion often not efficient, use memoization to avoid wasteful recomputation.

foo(X)

foo(X) **if** X is a base case

foo(X)if X is a base case solve it

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foo(X)

if X is a base case solve it return solution
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if X is a base case solve it return solution else
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if X is a base case solve it return solution else do stuff
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analysis:

- recursion tree: each instance X spawns new children X_1, X_2, X_3
- dependency graph: each instance X links to sub-problems X_1, X_2, X_3

Fibonacci Numbers

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Definition (Fibonacci 1200,)

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The Fibonacci sequence $F_0, F_1, F_2, F_3, \ldots \in \mathbb{N}$ is the sequence of numbers defined by

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- $\implies 1 \varphi \approx -.618 \cdots \implies |(1 \varphi)^n| \le 1, \text{ and further } (1 \varphi)^n \to_{n \to \infty} 0$ $\implies F_n = \Theta(\varphi^n).$

question:

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answer:

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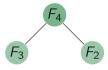
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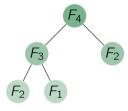
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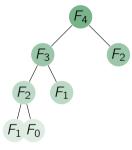
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- \blacksquare \Longrightarrow $T(n) = F_{n-1} = \Theta(\varphi^n) \implies$ exponential time!

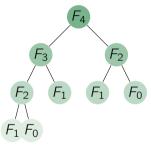
recursion tree:



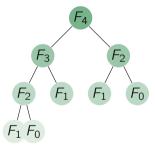






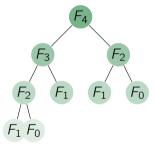


recursion tree: for F_4

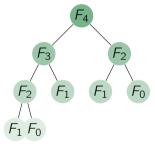


dependency graph:

recursion tree: for F_4

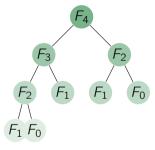


recursion tree: for F_4





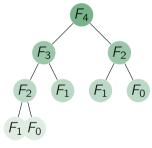
recursion tree: for F_4







recursion tree: for F_4

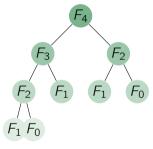








recursion tree: for F_4



dependency graph: for F_4

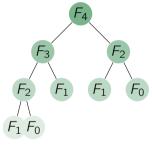
 F_4

 F_3

 F_2

 F_1

recursion tree: for F_4



dependency graph: for F_4

 F_4

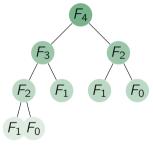
 F_3

 F_2

 F_1

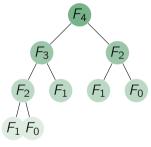
 F_0

recursion tree: for F_4



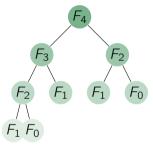


recursion tree: for F_4





recursion tree: for F_4





iterative algorithm:

fib-iter(n):

```
fib-iter(n):

if n = 0

return 0

if n = 1

return 1
```

```
\begin{aligned} & \textbf{fib-iter}(n): \\ & & \textbf{if} \ n = 0 \\ & & & \textbf{return} \ 0 \\ & & \textbf{if} \ n = 1 \\ & & & \textbf{return} \ 1 \\ & & & & F[0] = 0 \\ & & & & F[1] = 1 \end{aligned}
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```

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fib-iter(n):

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F[0] = 0

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for 2 \le i \le n

F[i] = F[i-1] + F[i-2]

return F[n]
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iterative algorithm:

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F[i] = F[i-1] + F[i-2]

return F[n]
```

correctness:

iterative algorithm:

```
fib-iter(n):

if n = 0

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if n = 1

return 1

F[0] = 0

F[1] = 1

for 2 \le i \le n

F[i] = F[i - 1] + F[i - 2]

return F[n]
```

correctness: clear

iterative algorithm:

```
fib-iter(n):

if n = 0

return 0

if n = 1

return 1

F[0] = 0

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F[i] = F[i-1] + F[i-2]

return F[n]
```

correctness: clear

complexity:

iterative algorithm:

```
fib-iter(n):

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correctness: clear

complexity: O(n) additions

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complexity: O(n) additions

remarks:

iterative algorithm:

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```

correctness: clear

complexity: O(n) additions

remarks:

$$F_n = \Theta(\varphi^n)$$

iterative algorithm:

```
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F[i] = F[i-1] + F[i-2]

return F[n]
```

correctness: clear

complexity: O(n) additions

remarks:

• $F_n = \Theta(\varphi^n) \implies F_n \text{ takes } \Theta(n) \text{ bits}$

iterative algorithm:

```
\begin{aligned} &\textbf{fib-iter}(n):\\ &\textbf{if } n = 0\\ &\textbf{return } 0\\ &\textbf{if } n = 1\\ &\textbf{return } 1\\ &F[0] = 0\\ &F[1] = 1\\ &\textbf{for } 2 \leq i \leq n\\ &F[i] = F[i-1] + F[i-2]\\ &\textbf{return } F[n] \end{aligned}
```

correctness: clear

complexity: O(n) additions

remarks:

■ $F_n = \Theta(\varphi^n) \implies F_n$ takes $\Theta(n)$ bits \implies each addition takes $\Theta(n)$ steps

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fib-iter(n):

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for 2 \le i \le n

F[i] = F[i-1] + F[i-2]

return F[n]
```

correctness: clear

complexity: O(n) additions

remarks:

■ $F_n = \Theta(\varphi^n) \implies F_n$ takes $\Theta(n)$ bits \implies each addition takes $\Theta(n)$ steps $\implies O(n^2)$ is the *actual* runtime

recursive paradigms for F_n :

naive recursion:

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■ naive recursion: recurse on subproblems,

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Definition

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Definition

Dynamic programming is the method of speeding up naive recursion through memoization.

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If number of subproblems is polynomially bounded,

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recursive paradigms for F_n :

- naive recursion: recurse on subproblems, solves the *same* subproblem multiple times
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Definition

Dynamic programming is the method of speeding up naive recursion through memoization.

remarks:

- If number of subproblems is polynomially bounded, often implies a polynomial-time algorithm
- Memoizing a recursive algorithm is done by tracing through the dependency graph

question:

question: how to memoize exactly?

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fib(n):

```
question: how to memoize exactly?  \begin{array}{c} \mathtt{fib}(n): \\ \mathbf{if} \ n=0 \\ \mathbf{return} \ 0 \\ \mathbf{if} \ n=1 \\ \mathbf{return} \ 1 \end{array}
```

```
question: how to memoize exactly?

fib(n):
    if n = 0
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    if n = 1
        return 1
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        return stored value fib(n)
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explicitly: just do it!

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question: how to memoize exactly?

- explicitly: just do it!
- *implicitly*: allow clever data structures to do this automatically

global F[·]

```
global F[\cdot] fib(n):
```

```
global F[⋅]
fib(n):
    if n = 0
        return 0
    if n=1
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        F[n] = fib(n-1) + fib(n-2)
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■ *explicit* memoization: we decide *ahead* of time what types of objects *F* stores

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 - e.g., *F* is an array

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 - \blacksquare e.g., F is an array
 - requires more deliberation on problem structure, but can be more efficient
- implicit memoization: we let the data structure for F handle whatever comes its way
 - e.g., F is an dictionary
 - requires less deliberation on problem structure, and can be less efficient
 - sometimes can be done automatically by functional programming languages (LISP, etc.)

question: how much *space* do we need to memoize?

fib-iter(n):

```
fib-iter(n):

if n = 0

return 0
```

```
 \begin{aligned} & \text{fib-iter}(n): \\ & & \text{if } n = 0 \\ & & \text{return } 0 \\ & & F_{\text{prevprev}} = 0 \end{aligned}
```

```
\begin{aligned} & \textbf{fib-iter}(n): \\ & \textbf{if} \ \ n = 0 \\ & \textbf{return} \ \ 0 \\ & F_{\text{prevprev}} = 0 \\ & \textbf{if} \ \ n = 1 \\ & \textbf{return} \ \ 1 \end{aligned}
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```

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```
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```

```
fib-iter(n):
       if n=0
              return 0
       F_{\text{prevprev}} = 0
       if n=1
              return 1
       F_{
m prev}=1
       for 2 \le i \le n
              F_{\text{cur}} = F_{\text{prev}} + F_{\text{prevprev}}
              F_{\text{prevprev}} = F_{\text{prev}}
              F_{\text{prev}} = F_{\text{cur}}
       return F_{cur}
```

```
fib-iter(n):
       if n=0
               return 0
       F_{\text{prevprev}} = 0
       if n=1
               return 1
       F_{\text{prev}} = 1
       for 2 \le i \le n
              F_{\text{cur}} = F_{\text{prev}} + F_{\text{prevprev}}
              F_{\text{prevprev}} = F_{\text{prev}}
              F_{\text{prev}} = F_{\text{cur}}
       return F_{cur}
```

question: how much space do we need to memoize?

```
fib-iter(n):
       if n=0
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       F_{\text{prev}} = 1
       for 2 \le i \le n
              F_{\text{cur}} = F_{\text{prev}} + F_{\text{prevprev}}
              F_{\text{prevprev}} = F_{\text{prev}}
             F_{
m prev} = F_{
m cur}
       return F_{cur}
```

correctness:

question: how much space do we need to memoize?

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fib-iter(n):
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       F_{\text{prev}} = 1
       for 2 \le i \le n
              F_{\text{cur}} = F_{\text{prev}} + F_{\text{prevprev}}
              F_{\text{prevprev}} = F_{\text{prev}}
              F_{\text{prev}} = F_{\text{cur}}
       return F_{cur}
```

correctness: clear

question: how much space do we need to memoize?

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fib-iter(n):
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              F_{\text{prevprev}} = F_{\text{prev}}
              F_{\text{prev}} = F_{\text{cur}}
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```

correctness: clear

complexity:

Fibonacci Numbers (V)

question: how much space do we need to memoize?

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fib-iter(n):
       if n=0
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       F_{\text{prev}} = 1
       for 2 \le i \le n
               F_{\text{cur}} = F_{\text{prev}} + F_{\text{prevprev}}
              F_{\text{prevprev}} = F_{\text{prev}}
              F_{\text{prev}} = F_{\text{cur}}
       return F_{cur}
```

correctness: clear

complexity: O(n) additions,

Fibonacci Numbers (V)

question: how much space do we need to memoize?

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       if n=0
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       if n=1
               return 1
       F_{\text{prev}} = 1
       for 2 < i < n
              F_{\text{cur}} = F_{\text{prev}} + F_{\text{prevprev}}
              F_{\text{prevprev}} = F_{\text{prev}}
              F_{\text{prev}} = F_{\text{cur}}
       return F_{cur}
```

correctness: clear

complexity: O(n) additions, O(1) numbers stored

Fibonacci Numbers (V)

question: how much space do we need to memoize?

```
fib-iter(n):
       if n=0
               return 0
       F_{\text{prevprev}} = 0
       if n=1
               return 1
       F_{\text{prev}} = 1
       for 2 \le i \le n
               F_{\text{cur}} = F_{\text{prev}} + F_{\text{prevprev}}
              F_{\text{prevprev}} = F_{\text{prev}}
               F_{\text{prev}} = F_{\text{cur}}
       return F_{cur}
```

correctness: clear

complexity: O(n) additions, O(1) numbers stored $\implies O(n)$ bits stored

Definition

Dynamic programming is the method of speeding up naive recursion through memoization.

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Dynamic programming is the method of speeding up naive recursion through memoization.

- Given a recursive algorithm, analyze the complexity of its memoized version.
- Find the *right* recursion that can be memoized.
- Recognize when dynamic programming will efficiently solve a problem.
- Further optimize time- and space-complexity of dynamic programming algorithms.

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 $\underline{\mathsf{m}}\mathsf{oney} \to$

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 $\underline{\mathsf{m}}\mathsf{oney} \to \mathsf{boney}$

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■ edit distance ≤ 4

Definition

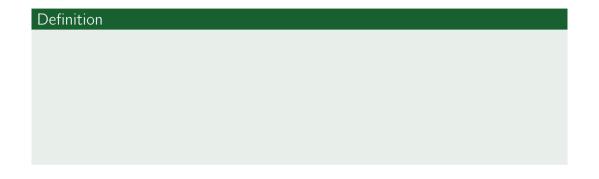
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remarks:

- edit distance ≤ 4
- intermediate strings can be arbitrary in Σ^*



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17/33

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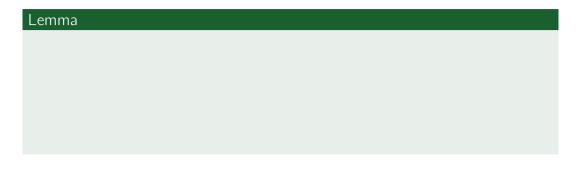
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- widely solved in practice, e.g., the BLAST heuristic for DNA edit distance



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$$\operatorname{dist}(x \circ a, y \circ b) = \min \left\{ \right.$$

Lemma

$$dist(x \circ a, y \circ b) = min \begin{cases} dist(x, y) + 1[a \neq b] \end{cases}$$

Lemma

$$\operatorname{dist}(x \circ a, y \circ b) = \min \left\{ egin{aligned} \operatorname{dist}(x, y) + \mathbb{1}\llbracket a
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- a is deleted,

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recursive algorithm:

dist(x)

$$dist(x = x_1x_2 \cdots x_n,$$

$$dist(x = x_1x_2 \cdots x_n, y)$$

$$\texttt{dist}(x = x_1 x_2 \cdots x_n, y = y_1 y_2 \cdots y_m)$$

dist
$$(x = x_1x_2 \cdots x_n, y = y_1y_2 \cdots y_m)$$

if $n = 0$, return m

$$\begin{aligned} \operatorname{dist}(x &= x_1 x_2 \cdots x_n, y = y_1 y_2 \cdots y_m) \\ & \quad \text{if } n = 0, \text{ return } m \\ & \quad \text{if } m = 0, \text{ return } n \end{aligned}$$

$$\begin{aligned} \text{dist}(x = x_1 x_2 \cdots x_n, y = y_1 y_2 \cdots y_m) \\ & \text{if } n = 0 \text{, return } m \\ & \text{if } m = 0 \text{, return } n \\ & d_1 = \text{dist}(x_{< n}, y_{< m}) + \mathbb{1}[\![x_n \neq y_m]\!] \end{aligned}$$

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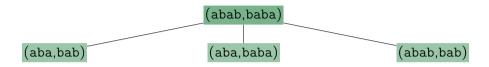
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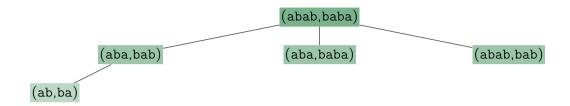
correctness: clear
complexity: ???

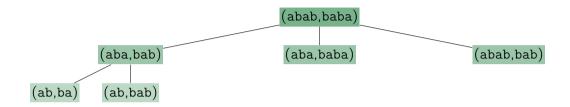
(abab,baba)

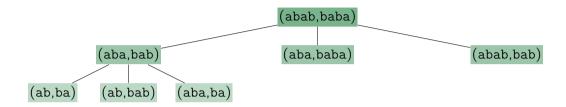


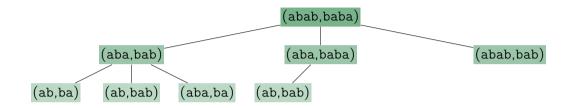


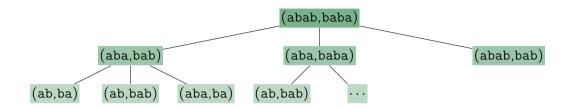


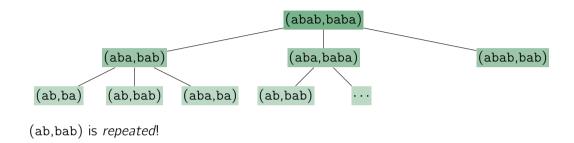


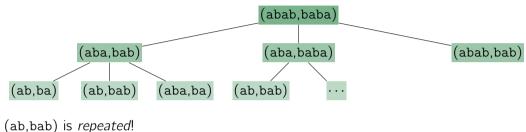




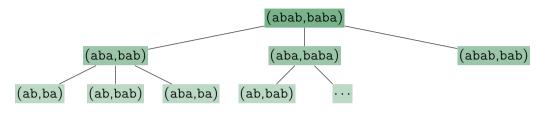








memoization:



(ab,bab) is repeated!

memoization: define subproblem (i,j) as computing $\operatorname{dist}(x_{\leq i},y_{\leq j})$

memoized algorithm:

global $d[\cdot][\cdot]$

global
$$d[\cdot][\cdot]$$
 dist $(x_1x_2\cdots x_n, y_1y_2\cdots y_m,$

```
global d[\cdot][\cdot] dist(x_1x_2\cdots x_n, y_1y_2\cdots y_m, (i,j))
```

```
 \begin{array}{c} \textbf{global} \ d[\cdot][\cdot] \\ \texttt{dist}(x_1x_2\cdots x_n, y_1y_2\cdots y_m, (i,j)) \\ \textbf{if} \ d[i][j] \ \text{initialized} \\ \textbf{return} \ d[i][j] \end{array}
```

```
 \begin{array}{l} \textbf{global} \ d[\cdot][\cdot] \\ \texttt{dist}(x_1x_2\cdots x_n, y_1y_2\cdots y_m, (i,j)) \\ \textbf{if} \ d[i][j] \ \textbf{initialized} \\ \textbf{return} \ d[i][j] \\ \textbf{if} \ i=0 \end{array}
```

```
 \begin{array}{l} \textbf{global} \ d[\cdot][\cdot] \\ \texttt{dist}(x_1x_2\cdots x_n, y_1y_2\cdots y_m, (i,j)) \\ \textbf{if} \ d[i][j] \ \text{initialized} \\ \textbf{return} \ d[i][j] \\ \textbf{if} \ i = 0 \\ d[i][j] = j \end{array}
```

```
 \begin{array}{l} \textbf{global} \ \ d[\cdot][\cdot] \\ \text{dist}(x_1x_2\cdots x_n, y_1y_2\cdots y_m, (i,j)) \\ \textbf{if} \ \ d[i][j] \ \ \text{initialized} \\ \textbf{return} \ \ d[i][j] \\ \textbf{if} \ \ i=0 \\ d[i][j]=j \\ \textbf{elif} \ \ j=0 \\ d[i][j]=i \end{array}
```

```
 \begin{aligned} &\textbf{global} \ d[\cdot][\cdot] \\ & \text{dist}(x_1x_2\cdots x_n,y_1y_2\cdots y_m,(i,j)) \\ & \textbf{if} \ d[i][j] \ \text{initialized} \\ & \textbf{return} \ d[i][j] \\ & \textbf{if} \ i = 0 \\ & d[i][j] = j \\ & \textbf{elif} \ j = 0 \\ & d[i][j] = i \\ & \textbf{else} \\ & d_1 = \textbf{dist}(x,y,(i-1,j-1)) + \mathbb{1}[x_i \neq y_j] \end{aligned}
```

```
 \begin{aligned} &\textbf{global} \ d[\cdot][\cdot] \\ &\textbf{dist}(x_1x_2\cdots x_n,y_1y_2\cdots y_m,(i,j)) \\ &\textbf{if} \ d[i][j] \ &\textbf{initialized} \\ &\textbf{return} \ d[i][j] \\ &\textbf{if} \ i = 0 \\ &d[i][j] = j \\ &\textbf{elif} \ j = 0 \\ &d[i][j] = i \\ &\textbf{else} \\ &d_1 = \textbf{dist}(x,y,(i-1,j-1)) + \mathbb{1}[x_i \neq y_j] \\ &d_2 = \textbf{dist}(x,y,(i-1,j)) + 1 \end{aligned}
```

```
global d[\cdot][\cdot]
dist(x_1x_2\cdots x_n, y_1y_2\cdots y_m, (i, j))
      if d[i][j] initialized
            return d[i][j]
      if i = 0
            d[i][i] = i
      elif i = 0
            d[i][i] = i
      else
             d_1 = \operatorname{dist}(x, y, (i-1, j-1)) + \mathbb{1}[x_i \neq y_i]
             d_2 = \mathbf{dist}(x, y, (i-1, j)) + 1
             d_3 = \mathbf{dist}(x, y, (i, j-1)) + 1
```

```
qlobal d[\cdot][\cdot]
dist(x_1x_2\cdots x_n, y_1y_2\cdots y_m, (i, j))
      if d[i][j] initialized
            return d[i][j]
      if i = 0
            d[i][i] = i
      elif i = 0
            d[i][i] = i
      else
            d_1 = \mathbf{dist}(x, y, (i-1, j-1)) + \mathbb{1}[x_i \neq y_i]
            d_2 = \mathbf{dist}(x, y, (i-1, j)) + 1
            d_3 = \mathbf{dist}(x, y, (i, i-1)) + 1
            d[i][j] = \min(d_1, d_2, d_3)
```

```
qlobal d[\cdot][\cdot]
dist(x_1x_2\cdots x_n, v_1v_2\cdots v_m, (i, j))
      if d[i][j] initialized
            return d[i][j]
      if i = 0
            d[i][i] = i
      elif i = 0
            d[i][i] = i
      else
            d_1 = \mathbf{dist}(x, y, (i-1, j-1)) + \mathbb{1}[x_i \neq y_i]
            d_2 = \mathbf{dist}(x, y, (i-1, j)) + 1
            d_3 = \mathbf{dist}(x, y, (i, i-1)) + 1
            d[i][j] = \min(d_1, d_2, d_3)
      return d[i][j]
```

```
global d[\cdot][\cdot]
dist(x_1x_2\cdots x_n, y_1y_2\cdots y_m, (i, j))
      if d[i][j] initialized
            return d[i][j]
      if i = 0
            d[i][i] = i
      elif i = 0
            d[i][i] = i
      else
            d_1 = \mathbf{dist}(x, y, (i-1, j-1)) + \mathbb{1}[x_i \neq y_i]
            d_2 = \mathbf{dist}(x, y, (i-1, j)) + 1
            d_3 = \mathbf{dist}(x, y, (i, j-1)) + 1
            d[i][j] = \min(d_1, d_2, d_3)
      return d[i][j]
```

dependency graph:

n m

dependency graph:

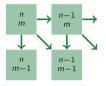
n m m-1

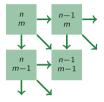


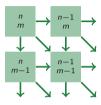
dependency graph:

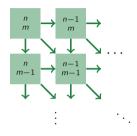
 $\begin{array}{ccc}
 n & n-1 \\
 m & m-1 \\
 m-1 & m-1
 \end{array}$

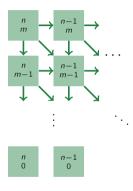


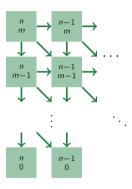


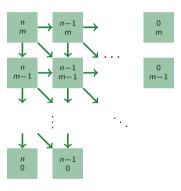


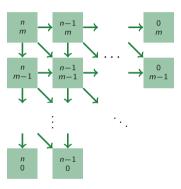


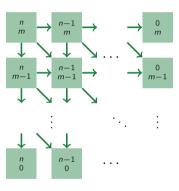


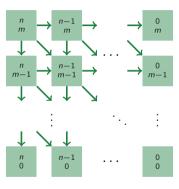






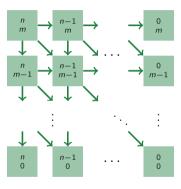






Edit Distance (VIII)

dependency graph:



$$dist(x_1x_2\cdots x_n, y_1y_2\cdots y_m)$$

$$\operatorname{dist}(x_1x_2\cdots x_n,y_1y_2\cdots y_m)$$
 for $0\leq i\leq n$

```
\begin{aligned} \operatorname{dist}(x_1 x_2 \cdots x_n, y_1 y_2 \cdots y_m) \\ \operatorname{for} & 0 \leq i \leq n \\ & d[i][0] = i \end{aligned}
```

```
\begin{aligned} \operatorname{dist}(x_1x_2\cdots x_n,y_1y_2\cdots y_m) \\ & \quad \text{for } 0 \leq i \leq n \\ & \quad d[i][0] = i \\ & \quad \text{for } 0 \leq j \leq m \end{aligned}
```

```
\begin{array}{l} \operatorname{dist}(x_1x_2\cdots x_n,y_1y_2\cdots y_m) \\ \text{for } 0\leq i\leq n \\ d[i][0]=i \\ \text{for } 0\leq j\leq m \\ d[0][j]=j \end{array}
```

```
\begin{aligned} \operatorname{dist}(x_1x_2\cdots x_n,y_1y_2\cdots y_m) \\ & \quad \text{for } 0\leq i\leq n \\ & \quad d[i][0]=i \\ & \quad \text{for } 0\leq j\leq m \\ & \quad d[0][j]=j \\ & \quad \text{for } 0\leq i\leq n \\ & \quad \text{for } 0\leq j\leq m \end{aligned}
```

```
\begin{aligned} \operatorname{dist}(x_1 x_2 \cdots x_n, y_1 y_2 \cdots y_m) \\ & \quad \text{for } 0 \leq i \leq n \\ & \quad d[i][0] = i \\ & \quad \text{for } 0 \leq j \leq m \\ & \quad d[0][j] = j \\ & \quad \text{for } 0 \leq i \leq n \\ & \quad \text{for } 0 \leq j \leq m \end{aligned}
```

```
\begin{aligned} \operatorname{dist}(x_1x_2\cdots x_n,y_1y_2\cdots y_m) \\ & \quad \text{for } 0\leq i\leq n \\ & \quad d[i][0]=i \\ & \quad \text{for } 0\leq j\leq m \\ & \quad d[0][j]=j \\ & \quad \text{for } 0\leq i\leq n \\ & \quad \text{for } 0\leq j\leq m \end{aligned}
```

```
\begin{aligned} \operatorname{dist}(x_1 x_2 \cdots x_n, y_1 y_2 \cdots y_m) \\ & \quad \text{for } 0 \leq i \leq n \\ & \quad d[i][0] = i \\ & \quad \text{for } 0 \leq j \leq m \\ & \quad d[0][j] = j \\ & \quad \text{for } 0 \leq i \leq n \\ & \quad \text{for } 0 \leq j \leq m \end{aligned}
d[i][j] = \min \left\{ d[i-1][j-1] + \mathbb{1}[x_i \neq y_j] \right\}
```

```
\begin{aligned} \operatorname{dist}(x_1 x_2 \cdots x_n, y_1 y_2 \cdots y_m) \\ & \quad \text{for } 0 \leq i \leq n \\ & \quad d[i][0] = i \\ & \quad \text{for } 0 \leq j \leq m \\ & \quad d[0][j] = j \\ & \quad \text{for } 0 \leq i \leq n \\ & \quad \text{for } 0 \leq j \leq m \\ \\ & \quad d[i][j] = \min \left\{ \begin{aligned} d[i-1][j-1] + \mathbb{1}[x_i \neq y_j] \\ d[i-1][j] + 1 \end{aligned} \right. \end{aligned}
```

```
dist(x_1x_2\cdots x_n, V_1V_2\cdots V_m)
       for 0 < i < n
              d[i][0] = i
       for 0 < j < m
              d[0][i] = i
       for 0 < i < n
              for 0 \le j \le m
                    d[i][j] = \min \begin{cases} d[i-1][j-1] + \mathbb{1}[x_i \neq y_j] \\ d[i-1][j] + 1 \\ d[i][j-1] + 1 \end{cases}
       return d[n][m]
```

```
dist(x_1x_2\cdots x_n, V_1V_2\cdots V_m)
       for 0 < i < n
              d[i][0] = i
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       for 0 < i < n
              for 0 \le j \le m
                   d[i][j] = \min \begin{cases} d[i-1][j-1] + \mathbb{1}[x_i \neq y_j] \\ d[i-1][j] + 1 \\ d[i][j-1] + 1 \end{cases}
       return d[n][m]
```

iterative algorithm:

```
dist(x_1x_2\cdots x_n, V_1V_2\cdots V_m)
       for 0 < i < n
              d[i][0] = i
       for 0 < j < m
              d[0][i] = i
       for 0 < i < n
              for 0 \le j \le m
                    d[i][j] = \min \begin{cases} d[i-1][j-1] + \mathbb{1}[x_i \neq y_j] \\ d[i-1][j] + 1 \\ d[i][j-1] + 1 \end{cases}
       return d[n][m]
```

correctness:

iterative algorithm:

```
dist(x_1x_2\cdots x_n, V_1V_2\cdots V_m)
      for 0 < i < n
             d[i][0] = i
      for 0 < j < m
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      for 0 < i < n
             for 0 \le j \le m
                   d[i][j] = \min \begin{cases} d[i-1][j-1] + 1 [x_i \neq y_j] \\ d[i-1][j] + 1 \\ d[i][j-1] + 1 \end{cases}
       return d[n][m]
```

correctness: clear

iterative algorithm:

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dist(x_1x_2\cdots x_n, V_1V_2\cdots V_m)
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       return d[n][m]
```

correctness: clear

complexity:

iterative algorithm:

```
dist(x_1x_2\cdots x_n, V_1V_2\cdots V_m)
      for 0 < i < n
             d[i][0] = i
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             for 0 \le j \le m
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       return d[n][m]
```

correctness: clear

complexity: O(nm) time,

iterative algorithm:

```
dist(x_1x_2\cdots x_n, V_1V_2\cdots V_m)
      for 0 < i < n
              d[i][0] = i
      for 0 < j < m
             d[0][i] = i
      for 0 < i < n
             for 0 \le j \le m
                   d[i][j] = \min \begin{cases} d[i-1][j-1] + 1 [x_i \neq y_j] \\ d[i-1][j] + 1 \\ d[i][j-1] + 1 \end{cases}
       return d[n][m]
```

correctness: clear

complexity: O(nm) time, O(nm) space

Corollary

Corollary

Given two strings $x,y\in \Sigma^\star$ can compute the minimum cost alignment

Corollary

Given two strings $x, y \in \Sigma^*$ can compute the minimum cost alignment in O(nm)-time and O(nm)-space.

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Proof.

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Exercise.

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Given two strings $x, y \in \Sigma^*$ can compute the minimum cost alignment in O(nm)-time and O(nm)-space.

Proof.

Exercise. Hint:

Corollary

Given two strings $x, y \in \Sigma^*$ can compute the minimum cost alignment in O(nm)-time and O(nm)-space.

Proof.

Exercise. Hint: follow how each subproblem was solved.

Corollary

Given two strings $x, y \in \Sigma^*$ can compute the minimum cost alignment in O(nm)-time and O(nm)-space.

Proof.

Exercise. *Hint:* follow *how* each subproblem was solved.

template:

develop recursive algorithm

- develop recursive algorithm
- understand structure of subproblems

- develop recursive algorithm
- understand structure of subproblems
- memoize

- develop recursive algorithm
- understand structure of subproblems
- memoize
 - implicitly,

- develop recursive algorithm
- understand structure of subproblems
- memoize
 - implicitly, via data structure

- develop recursive algorithm
- understand structure of subproblems
- memoize
 - implicitly, via data structure
 - explicitly,

- develop recursive algorithm
- understand structure of subproblems
- memoize
 - implicitly, via data structure
 - explicitly, converting to iterative algorithm

- develop recursive algorithm
- understand structure of subproblems
- memoize
 - implicitly, via data structure
 - explicitly, converting to iterative algorithm to traverse dependency graph

- develop recursive algorithm
- understand structure of subproblems
- memoize
 - implicitly, via data structure
 - explicitly, converting to iterative algorithm to traverse dependency graph via topological sort

- develop recursive algorithm
- understand structure of subproblems
- memoize
 - implicitly, via data structure
 - explicitly, converting to iterative algorithm to traverse dependency graph via topological sort
- analysis

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- understand structure of subproblems
- memoize
 - implicitly, via data structure
 - explicitly, converting to iterative algorithm to traverse dependency graph via topological sort
- analysis (time,

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- understand structure of subproblems
- memoize
 - implicitly, via data structure
 - explicitly, converting to iterative algorithm to traverse dependency graph via topological sort
- analysis (time, space)

- develop recursive algorithm
- understand structure of subproblems
- memoize
 - implicitly, via data structure
 - explicitly, converting to iterative algorithm to traverse dependency graph via topological sort
- analysis (time, space)
- further optimization

the knapsack problem:

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input: knapsack capacity $W \in \mathbb{N}$

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the knapsack problem:

input: knapsack capacity $W \in \mathbb{N}$ (in pounds). n items with weights $w_1, \ldots, w_n \in \mathbb{N}$, and values $v_1, \ldots, v_n \in \mathbb{N}$.

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goal: a subset $S \subseteq [n]$ of items

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goal: a subset $S \subseteq [n]$ of items that fit in the knapsack, with maximum value

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goal: a subset $S \subseteq [n]$ of items that fit in the knapsack, with maximum value

$$\max_{S\subseteq[n]} \quad \sum_{i\in S} v_i$$

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goal: a subset $S \subseteq [n]$ of items that fit in the knapsack, with maximum value

$$\max_{S \subseteq [n]} \sum_{i \in S} v_i$$
$$\sum_{i \in S} w_i \le W$$

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remarks:

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remarks:

■ prototypical problem in *combinatorial optimization*,

the knapsack problem:

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remarks:

 prototypical problem in combinatorial optimization, can be generalized in numerous ways

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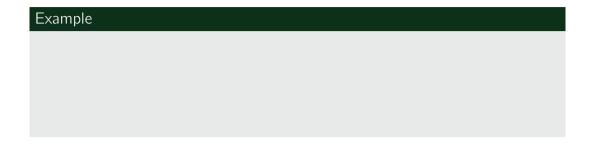
goal: a subset $S \subseteq [n]$ of items that fit in the knapsack, with maximum value

$$\max_{S \subseteq [n]} \sum_{i \in S} v_i$$

$$\sum_{i \in S} w_i \le W$$

remarks:

- prototypical problem in combinatorial optimization, can be generalized in numerous ways
- needs to be solved in practice



Example

item	1	2	3	4	5
weight	1	2	5	6	7
value	1	6	18	22	28

Example

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weight	1	2	5	6	7
value	1	6	18	22	28

For W=11,

Example

item	1	2	3	4	5
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For W=11, the best is $\{3,4\}$ giving value 40.

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Definition

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Definition

In the special case of when $v_i = w_i$ for all i,

Example

item	1	2	3	4	5
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value	1	6	18	22	28

For W = 11, the best is $\{3,4\}$ giving value 40.

Definition

In the special case of when $v_i = w_i$ for all i, the knapsack problem is called the **subset sum** problem.

item	1	2	3	4	5
value	1	6	16	22	28
weight	1	2	5	6	7

item	1	2	3	4	5
value	1	6	16	22	28
weight	1	2	5	6	7

and weight limit W = 15.

item	1	2	3	4	5
value	1	6	16	22	28
weight	1	2	5	6	7

and weight limit W = 15. What is the best solution value?

Knapsack (III)

item	1	2	3	4	5
value	1	6	16	22	28
weight	1	2	5	6	7

and weight limit W = 15. What is the best solution value?

- (a) 22
- (b) 28
- (c) 38
- (d) 50
- (e) 56

greedy approaches:

greedy approaches:

■ greedily select by maximum value:

greedy approaches:

■ greedily select by maximum value:

item	1	2	3
value	2	2	3
weight	1	1	2

greedy approaches:

greedily select by maximum value:

item	1	2	3
value	2	2	3
weight	1	1	2

For W = 2,

greedy approaches:

greedily select by maximum value:

item	1	2	3
value	2	2	3
weight	1	1	2

For W=2, greedy-value will pick $\{3\}$,

greedy approaches:

greedily select by maximum value:

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■ greedily select by minimum weight:

greedy approaches:

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For W=2, greedy-value will pick $\{3\}$, but optimal is $\{1,2\}$.

■ greedily select by minimum weight:

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item	1	2
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For W=2, greedy-value will pick $\{3\}$, but optimal is $\{1,2\}$.

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For W=2, greedy-weight will pick $\{1\}$, but optimal is $\{2\}$.

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value	2	2	3
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For W = 2, greedy-value will pick $\{3\}$, but optimal is $\{1, 2\}$.

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item	1	2
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For W = 2, greedy-weight will pick $\{1\}$, but optimal is $\{2\}$.

greedily select by maximum value/weight ratio:

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greedily select by maximum value/weight ratio:

item	1	2	3
value	3	3	5
weight	2	2	3

greedy approaches:

greedily select by maximum value:

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For
$$W = 4$$
,

greedy approaches:

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item	1	2	3
value	2	2	3
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For W=2, greedy-value will pick $\{3\}$, but optimal is $\{1,2\}$.

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item	1	2
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For W = 2, greedy-weight will pick $\{1\}$, but optimal is $\{2\}$.

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value	1	3
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For W = 2, greedy-weight will pick $\{1\}$, but optimal is $\{2\}$.

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item	1	2	3
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remark:

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remark: while greedy algorithms fail to get the *best* result,

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remark: while greedy algorithms fail to get the *best* result, they can still be useful for getting solutions that are *approximately* the best



Lemma

Consider the instance W, $(v_i)_{i=1}^n$, and $(w_i)_{i=1}^n$,

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Consider the instance W, $(v_i)_{i=1}^n$, and $(w_i)_{i=1}^n$, with optimal solution $S \subseteq [n]$. Then,

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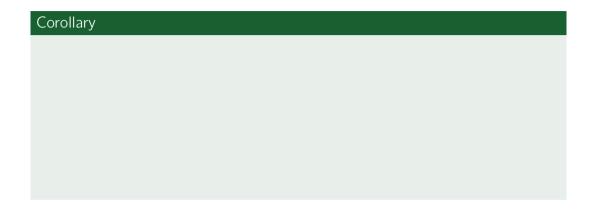
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Corollary

Fix an instance W, v_1, \ldots, v_n , and w_1, \ldots, w_n .

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Corollary

Fix an instance W, v_1, \ldots, v_n , and w_1, \ldots, w_n . Define $\mathsf{OPT}(i, w)$ to be the maximum value of the knapsack instance w, v_1, \ldots, v_i and w_1, \ldots, w_i . Then,

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 \implies from instance W, v_1, \ldots, v_n , and w_1, \ldots, w_n we generate $O(n \cdot W)$ -many subproblems $(i, w)_{i \in [n], w < W}$.

an iterative algorithm:

an iterative algorithm: M[i, w] will compute OPT(i, w)

```
an iterative algorithm: M[i, w] will compute \mathsf{OPT}(i, w) for 0 \le w \le W
M[0, w] = 0
```

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an iterative algorithm: M[i, w] will
 compute OPT(i, w)
for 0 < w < W
    M[0, w] = 0
for 1 < i < n
   for 1 < w < W
        if w_i > w
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            M[i, w] = \max(M[i-1, w],
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\begin{aligned} & \text{for } 0 \leq w \leq W \\ & M[0,w] = 0 \\ & \text{for } 1 \leq i \leq n \\ & \text{for } 1 \leq w \leq W \\ & \text{if } w_i > w \\ & M[i,w] = M[i-1,w] \\ & \text{else} \\ & M[i,w] = \max(M[i-1,w], \\ & M[i-1,w-w_i] + v_i) \end{aligned}
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correctness:

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O(nW) time,

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correctness: clear

complexity:

• O(nW) time, but *input size* is O(n

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correctness: clear

complexity:

• O(nW) time, but *input size* is $O(n + \log W)$

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complexity:

■ O(nW) time, but input size is $O(n + \log W + \sum_{i=1}^{n} (\log v_i + \log w_i))$

■ e.g., $W = 2^n$ has O(n) bits but requires $\Omega(2^n)$ runtime

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complexity:

- e.g., $W = 2^n$ has O(n) bits but requires $\Omega(2^n)$ runtime \implies running time is **not** polynomial in the input
- Algorithm is pseudo-polynomial:

an iterative algorithm: M[i, w] will compute OPT(i, w)

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correctness: clear

complexity:

- e.g., $W = 2^n$ has O(n) bits but requires $\Omega(2^n)$ runtime \implies running time is **not** polynomial in the input
- Algorithm is pseudo-polynomial: running time is polynomial in magnitude of the input numbers

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■ O(nW) time, but input size is $O(n + \log W + \sum_{i=1}^{n} (\log v_i + \log w_i))$

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correctness: clear complexity:

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punchline: had to correctly *parameterize* knapsack sub-problems $(v_j)_{j \le i}, (w_j)_{j \le i}$ by *also* considering arbitrary w.

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punchline: had to correctly *parameterize* knapsack sub-problems $(v_j)_{j \le i}, (w_j)_{j \le i}$ by *also* considering arbitrary w. This is a common theme in dynamic programming problems.

Today

today:

- recursion
- dynamic programming
 - fibonacci numbers
 - edit distance
 - knapsack

next time: more dynamic programming logistics:

- pset0 due R5, (aka, tomorrow) submit *individually*!
- pset1 out tomorrow, due R5 (next week)
- piazza signup

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